

# INTERNATIONAL STANDARD



**Maritime navigation and radiocommunication equipment and systems –  
Digital interfaces –  
Part 3: Serial data instrument network**

Document Preview

IEC 61162-3:2008

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## INTERNATIONAL ELECTROTECHNICAL COMMISSION

**MARITIME NAVIGATION AND RADIOCOMMUNICATION  
EQUIPMENT AND SYSTEMS –  
DIGITAL INTERFACES –****Part 3: Serial data instrument network**

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**In this Redline version, a vertical line in the margin shows where the technical content is modified by amendments 1 and 2. Additions and deletions are displayed in red, with deletions being struck through. A separate Final version with all changes accepted is available in this publication.**

International Standard IEC 61162-3 has been prepared by IEC technical committee 80: Maritime navigation and radiocommunication equipment and systems.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of the IEC 61162 series, under the general title *Maritime navigation and radiocommunication equipment and systems – Digital interfaces*, can be found on the IEC website.

The committee has decided that the contents of the base publication and its amendments will remain unchanged until the stability date indicated on the IEC web site under "http://webstore.iec.ch" in the data related to the specific publication. At this date, the publication will be

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## INTRODUCTION

This part of IEC 61162 has been developed by the IEC technical committee 80 working group 6, to meet the requirement for a versatile and economic means of connecting a wide range of marine navigation and radiocommunications equipment aboard SOLAS vessels. The National Marine Electronics Association's Standard Committee has developed the NMEA 2000®<sup>1</sup> standard. The NMEA<sup>2</sup> 2000 Standard provides for capabilities across all classes of vessels. The development of NMEA 2000 began in 1994 and was completed in 1999. More than a dozen manufacturers worldwide conducted a two-year beta test. The finalised NMEA 2000 standard version 1.000 was published in 2001. IEC and NMEA have worked together since 1999 to ensure that the NMEA 2000 standard fully supports SOLAS applications. NMEA 2000 version 1.200 was published in 2004, with expanded support for redundant messaging and for equipments such as AIS.

The need for an improved standard, compared with IEC 61162-1 and IEC 61162-2, has arisen due to the increased complexity of the latest equipment and systems. This requires multiple links between equipment and greatly improved communication speed.

The parts 400 of the IEC 61162 series have already been issued and cater for the most complex systems to be found on board a ship.

This new part 3 of IEC 61162 adopts the controller area network (CAN) technology, already well established for many industrial systems. This permits a versatile system to be established with the minimum of effort and reasonable cost. The equipment types supported and the sentence data content developed for IEC 61162-1 has been retained.

IEC 61162-3 describes a low cost, moderate capacity, bi-directional multi-transmitter/multi-receiver instrument network to interconnect marine electronic equipment. The connectors and cables used are compatible with industrial bus systems for instance DeviceNet<sup>TM3</sup> and Profibus<sup>TM4</sup>.

IEC 61162-3 provides for the application of NMEA 2000 aboard SOLAS vessels. Exceptions, additions and specific requirements for implementation upon SOLAS vessels are contained in this document.

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<sup>1</sup> NMEA 2000® is the registered trademark of the National Marine Electronics Association, Inc. This information is given for the convenience of users of this International Standard and does not constitute an endorsement by IEC of the trademark holder or any of its products. Compliance to this profile does not require use of the trade name. Use of the trade name requires permission of the trade holder.

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## INTRODUCTION to Amendment 1

The amendment updates the normative reference for NMEA 2000 Appendix B to a later version which includes five new sentences: PGN # 129807 - AIS Class B Group Assignment, PGN # 129809 - AIS Class B "CS" Static Report Part A, PGN # 129810 - AIS Class B, PGN # 129039 - AIS Class B Position Report, and PGN # 129040 - AIS Class B Extended Position Report.

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## INTRODUCTION to Amendment 2

The amendment updates the normative references for NMEA 2000 Main Document, NMEA 2000 Appendix A and NMEA 2000 Appendix D to a later version.

The amendment further updates the normative reference for NMEA 2000 Appendix B to a later version which includes the following new parameter groups:

- 126983– Alert
- 126984– Alert response
- 129041– AIS Aids to Navigation (AtoN) report
- 130316– Temperature- extended range

and the following revised parameter groups:

- 126992– System time
- 128259– Speed, water referenced
- 128267– Water depth
- 129285– Navigation – Route/WP information
- 129033– Time and date
- 129038– AIS Class A position report
- 129039– AIS Class B position report
- 129040– AIS Class B extended position report
- 129550– GNSS differential correction receiver
- 129793– AIS UTC and date report
- 129794– AIS Class A static and voyage related data
- 129796– AIS acknowledge
- 129798– AIS SAR aircraft position report
- 129800– AIS UTC/date inquiry
- 129801– AIS addressed safety related message
- 129802– AIS safety related broadcast message
- 129803– AIS interrogation
- 129804– AIS assignment mode command
- 129805– AIS data link management message
- 129806– AIS channel management
- 129807– AIS group assignment
- 129809– AIS Class B “CS” static data report, Part A
- 129810– AIS Class B “CS” static data report, Part B

The amendment further adds a new informative Annex B which shows the relationships between IEC 61162-1 sentences and IEC 61162-3 parameter group numbers.

# MARITIME NAVIGATION AND RADIOCOMMUNICATION EQUIPMENT AND SYSTEMS – DIGITAL INTERFACES –

## Part 3: Serial data instrument network

### 1 Scope

This part of IEC 61162 is based upon the NMEA 2000 standard. The NMEA 2000 standard contains the requirements for the minimum implementation of a serial-data communications network to interconnect marine electronic equipment onboard vessels. Equipment designed to this standard will have the ability to share data, including commands and status, with other compatible equipment over a single signalling channel.

Data messages are transmitted as a series of data frames, each with robust error check confirmed frame delivery and guaranteed latency times. As the actual data content of a data frame is at best 50 % of the transmitted bits, this standard is primarily intended to support relatively brief data messages, which may be periodic, transmitted as needed, or on-demand by use of query commands. Typical data includes discrete parameters such as position latitude and longitude, GPS status values, steering commands to autopilots, finite parameter lists such as waypoints, and moderately sized blocks of data such as electronic chart database updates. This standard is not necessarily intended to support high-bandwidth applications such as radar, electronic chart or other video data, or other intensive database or file transfer applications.

This standard defines all of the pertinent layers of the International Standards Organisation Open Systems Interconnect (ISO/OSI) model, from the application layer to the physical layer, necessary to implement the required IEC 61162-3 network functionality.

This standard defines data formats, network protocol, and the minimum physical layer necessary for devices to interface. SOLAS applications shall employ redundant designs (for instance dual networks, redundant network interface circuits) to reduce the impact of single point failures. The NMEA 2000 standard provides the fundamental tools and methods to support redundant equipment, buses and messaging. Specific shipboard installation designs are beyond the scope of this standard, however some guidance is given in Annex A.

Relationships between IEC 61162-1 sentences and IEC 61162-3 parameter group numbers are given in Annex B.

### 2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60945, *Maritime navigation and radiocommunication equipment and systems – General requirements – Methods of testing and required test results*

ISO 11783 (all parts), *Tractors and machinery for agriculture and forestry – Serial control and communications data network*

ISO 11783-3, *Tractors and machinery for agriculture and forestry – Serial control and communications data network – Part 3: Data link layer*

ISO 11783-5:2001, *Tractors and machinery for agriculture and forestry – Serial control and communications data network – Part 5 Network management (including its corrigendum 1 (2002))*

NMEA 2000 Main document, Version ~~1.200~~ 1.210: ~~October 2004~~ January 2013, *Serial-Data Networking Of Marine Electronic Devices*<sup>5</sup>

NMEA 2000, Appendix A, Version ~~1.200~~ 2.000: ~~October 2004~~ January 2013, *Serial-Data Networking Of Marine Electronic Devices – Application Layer (Parameter Group Definitions)*

NMEA 2000, Appendix B, Version ~~1.210~~ 2.000: ~~September 2006~~ January 2013 *Serial-Data Networking Of Marine Electronic Devices – Data Base*)

NMEA 2000, Appendix C, Version 1.200: October 2004, *Serial-Data Networking Of Marine Electronic Devices – Certification Criteria and Test Methods*)

NMEA 2000, Appendix D, Version ~~1.200~~ 1.210: ~~October 2004~~ January 2013, *Serial-Data Networking Of Marine Electronic Devices – Application Notes*)

IMO 1974, *International Convention for the Safety of Life at Sea (SOLAS), as amended – Chapter V – Safety of navigation*

### 3 Terms, definitions and conventions

#### 3.1 Terms and definitions

For the purposes of this document, the following definitions apply.

##### 3.1.1

###### **bit**

the smallest element of information on the communication channel

NOTE Bits are grouped into bit fields of one or more bits. A bit is of constant time duration set by the signalling rate specified in this standard and has one of two logical values, dominant or recessive. When dominant and recessive levels are impressed on the communications channel at the same time the resulting level is dominant.

##### 3.1.2

###### **bridge**

device that joins two network segments using the same network protocol and address space

NOTE Data rate and physical media may differ on the two sides of a bridge. A bridge may perform message filtering.

##### 3.1.3

###### **byte**

eight bits

##### 3.1.4

###### **Controller area network (CAN) frame**

series of bits transmitted on the communications channel

NOTE CAN frames convey the following types of information:

- data frame. Carries data from a transmitter to the receivers.
- error frame. Transmitted by a unit detecting a bus error.
- overload frame. Transmitted to provide a delay between preceding and succeeding data frames.

<sup>5</sup> Available from National Marine Electronics Association (USA), [www.nmea.org](http://www.nmea.org).

The CAN data frame has defined start of frame and end of frame bit fields and is separated from preceding fields by an interframe space. CAN error and overload frames, when used, are appended directly to the preceding frame without an interframe space.

**3.1.5**  
**class 1 devices**

refers to devices that have a single level A or level B network interface connection

**3.1.6**  
**class 2 devices**

describes devices that have two level A or two level B network interface connections

NOTE Class 2 devices are intended for use on dual redundant bus systems. In addition to providing either level A or level B capabilities, class 2 devices provide a means to identify messages that are received from redundant buses as being the same or different.

**3.1.7**  
**default operation**

operation or settings that exist when standard equipment is first shipped from the manufacturer

**3.1.8**  
**device**

a product or equipment which, through a node, is connected to an IEC 61162-3 network

**3.1.9**  
**gateway**

device that joins a network to another network or system

**3.1.10**  
**interframe space**

bit field that separates data frames from preceding frames

**3.1.11**  
**level A devices**

support the ISO transport layer and the complete set of network management parameter groups

**3.1.12**  
**level B devices**

support address claim, ISO request PGN, and the product information parameter group

**3.1.13**  
**listen only device**

device on the network that receives messages but does not participate in bus activity

NOTE This device cannot send any frames on the network (data, error, or acknowledge).

**3.1.14**  
**load equivalency number**

a node's power rating reported in units of network load

**3.1.15**  
**message**

consists of one or more data frames, as specified in this standard, that contain the parameter group information to be communicated from a network address

NOTE A message contains the message priority code, parameter group number, destination network address, source network address, and data fields. The destination network address may be a specific address or global.