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Standard Terminology for Exoskeletons and Exosuits¹

This standard is issued under the fixed designation F3323; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon (ε) indicates an editorial change since the last revision or reapproval.

1. Scope

- 1.1 This terminology covers terms associated with exoskeletons and exosuits. By providing a common and consistent lexicon, the purpose of this terminology is to facilitate communication between individuals who may be involved in the research, design, deployment, and use of exoskeletons and exosuits in applications, including but not limited to industrial, military, emergency response, recreational, and medical areas.
- 1.2 For the terminology to be harmonious with the practices in the fields, definitions have been drawn from other standards, the literature, or other public sources when possible. When no definition is available, is similar but requires change for use within standards produced by Committee F48, or in dispute, a consensus-based approach will be used to resolve definitions and add them to the lexicon. The development of this terminology is taking place in close coordination with corresponding efforts in all Committee F48 subcommittees to ensure comprehensive and consistent coverage.
- 1.3 This standard does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety, health, and environmental practices and determine the applicability of regulatory limitations prior to use.
- 1.4 This international standard was developed in accordance with internationally recognized principles on standardization established in the Decision on Principles for the Development of International Standards, Guides and Recommendations issued by the World Trade Organization Technical Barriers to Trade (TBT) Committee.

2. Referenced Documents

2.1 ASTM Standards:²

F3200 Terminology for Driverless Automatic Guided Industrial Vehicles

2.2 Other Standards:

ISO 8373:2012 Robots and Robotic Devices—Vocabulary³

MIL-HDBK-1908:1995 Definitions of Human Factors Terms⁴

IEC 60601-1-8:2012 Medical electrical equipment – Part 71–8: General requirements for basic safety and essential performance – Collateral standard: General requirements, tests and guidance for alarm systems in medical electrical equipment and medical electrical systems

ISO 13482:2014 Robots and robotic devices – Safety requirements for personal care robots⁵

29 CFR 1910.132 Occupational Safety and Health Standards, Personal Protective Equipment, General Requirements⁶

ANSI/ITSDF B56.5 Safety Standard for Driverless, Automatic Guided Industrial Vehicles and Automated Functions of Manned Industrial Vehicles⁷

3. Terminology

activity—execution of a task or action by a user or their exoskeleton or exosuit, or both.

¹ This terminology is under the jurisdiction of ASTM Committee F48 on Exoskeletons and Exosuits and is the direct responsibility of Subcommittee F48.91 on Terminology.

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² For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

³ Available from International Organization for Standardization (ISO), ISO Central Secretariat, BIBC II, Chemin de Blandonnet 8, CP 401, 1214 Vernier, Geneva, Switzerland, http://www.iso.org.

⁴ Available from U.S. Government Printing Office, Superintendent of Documents, 732 N. Capitol St., NW, Washington, DC 20401-0001, http://www.access.gpo.gov.

⁵ Available from International Organization for Standardization (ISO), ISO Central Secretariat, BIBC II, Chemin de Blandonnet 8, CP 401, 1214 Vernier, Geneva, Switzerland, http://www.iso.org.

⁶ Available from U.S. Government Printing Office, Superintendent of Documents, 732 N. Capitol St., NW, Washington, DC 20401-0001, http://www.access.gpo.gov.
⁷ Available from American National Standards Institute (ANSI), 25 W. 43rd St., 4th Floor, New York, NY 10036, http://www.ansi.org.



adaptive control, *n*—control scheme whereby the control system parameters are adjusted from conditions detected during the process.

ISO 8373:2012

alarm condition—state of the alarm system when it has determined that a potential or actual hazardous situation exists for which operator or user awareness or response is required.

<u>Discussion—</u>	
An alarm condition can be invalid, that is, a false positive alarm condition.	
Discussion—	
An alarm condition can be missed, that is, a false negative alarm condition.	
Discussion—	
An alarm condition can be invalid, that is, a false positive alarm condition.	
Discussion	
An alarm condition can be missed, that is, a false negative alarm condition.	IEC 60601-1-8:2012
nthropometric dimensions —measured dimensions that describe the size and shape often presented in the form of summary statistics that describe the range of body di	
attempting and/or performing a task compared to not using an exoskeleton (see al	
ssistive product, medical—any product (including devices, equipment, instrume generally available, used to aid a person with an injury or disability: (1) for part protect, support, train, measure, or substitute for body functions/structures and activilimitations, or participation restrictions.	icipation in activities of daily living, (2) to
evelopmental test and evaluation (DT&E)—test and evaluation performed technological limitations of the alternative concepts and design options being cost-performance trade-offs, (3) support the identification and description of design risk), (4) substantiate that contract technical performance and manufacturing process support the decision to certify the system ready for operational test and evaluation	pursued, (2) support the identification or risks (for example, human safety, functional served requirements have been achieved, and (5).
	MTL-HDBK-1908 11 December 1995
coskeleton —wearable device that augments, enables, assists, and/or enhances phys with the body.	ical activity through mechanical interaction
Discussion—	
An exoskeleton may include rigid or soft components, or both (see exosuit).	
Discussion—	
Physical activity may be static or dynamic.	
orce, gripping—magnitude of the contact force applied by an exoskeleton, user, or	combination thereof, to seize and hold (also

force, gripping—magnitude of the contact force applied by an exoskeleton, user, or combination thereof, to seize and hold (also known as grasping force).

<u>force, maximum</u>—peak force that can be applied by, to, or combination thereof, the exoskeleton without causing any damage to the exoskeleton while the user is wearing it.

harm—physical or psychological injury or damage to health.

hazard—potential source of harm.

ISO 13482:2014

hazard, acute—hazard that has an obvious and immediate impact.