



Designation: E879 – 20

Standard Specification for Thermistor Sensors for General Purpose and Laboratory Temperature Measurements¹

This standard is issued under the fixed designation E879; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon (ϵ) indicates an editorial change since the last revision or reapproval.

1. Scope

1.1 This specification covers the general requirements for Negative Temperature Coefficient (NTC) thermistor-type sensors intended to be used for laboratory temperature measurements or control, or both, within the range from $-10\text{ }^{\circ}\text{C}$ to $105\text{ }^{\circ}\text{C}$.

1.2 This specification also covers the detailed requirements for ASTM designated sensors.

1.3 This specification also covers the requirements for general purpose, Negative Temperature Coefficient (NTC) thermistor-type sensors intended for use with Digital Contact Thermometers (also known as Digital Thermometers) within the range from $-50\text{ }^{\circ}\text{C}$ to $+150\text{ }^{\circ}\text{C}$.

1.4 The values stated in SI units are to be regarded as the standard. The values given in parentheses are for information only.

1.5 *This standard does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety, health, and environmental practices and determine the applicability of regulatory limitations prior to use.*

1.6 *This international standard was developed in accordance with internationally recognized principles on standardization established in the Decision on Principles for the Development of International Standards, Guides and Recommendations issued by the World Trade Organization Technical Barriers to Trade (TBT) Committee.*

2. Referenced Documents

2.1 ASTM Standards:²

[E344 Terminology Relating to Thermometry and Hydrometry](#)

¹ This specification is under the jurisdiction of ASTM Committee E20 on Temperature Measurement and is the direct responsibility of Subcommittee E20.03 on Resistance Thermometers.

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² For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

[E563 Practice for Preparation and Use of an Ice-Point Bath as a Reference Temperature](#)

[E1502 Guide for Use of Fixed-Point Cells for Reference Temperatures](#)

[E1750 Guide for Use of Water Triple Point Cells](#)

[E2488 Guide for the Preparation and Evaluation of Liquid Baths Used for Temperature Calibration by Comparison](#)

[F29 Specification for Dumet Wire for Glass-to-Metal Seal Applications](#)

2.2 *NIST Documents:*³

[NIST Monograph 126 Platinum Resistance Thermometry](#)

[NIST Special Publication 250-22 Platinum Resistance Thermometer Calibration](#)

[NIST Technical Note 1265 Guidelines for Realizing the International Temperature Scale of 1990](#)

2.3 *Other Documents:*

[JCGM 100:2008 Evaluation of measurement data – Guide to the expression of uncertainty in measurement](#)⁴

[ANSI/NCSL Z540.3-2006 \(R2013\) Requirements for the Calibration of Measuring and Test Equipment](#)⁵

3. Terminology

3.1 *Definitions*—The definitions given in Terminology E344 shall apply to this specification.

3.2 *Definitions of Terms Specific to This Standard:*

3.2.1 *dissipation constant, δ, n* —the ratio of the change in energy dissipated per unit time (power) in a thermistor, $\Delta P = P_2 - P_1$, to the resultant temperature change of the thermistor, $\Delta T = T_2 - T_1$.

$$\delta = \frac{\Delta P}{\Delta T} \quad (1)$$

The dimensions of the dissipation constant are watts per kelvin (W/K). Note that many NTC thermistors are very small devices, and as such, the dissipation constant dimensions are frequently expressed in terms of milliwatts per kelvin (mW/K).

³ Available from National Institute of Standards and Technology (NIST), 100 Bureau Dr., Stop 1070, Gaithersburg, MD 20899-1070, <http://www.nist.gov>.

⁴ Available from the BIPM, Sevres, France, <http://www.bipm.org>.

⁵ Available from American National Standards Institute (ANSI), 25 W. 43rd St., 4th Floor, New York, NY 10036, <http://www.ansi.org>.

For this specification, T_1 is in the range from 20 °C to 38 °C and $\Delta T = 10$ °C.

3.2.2 *dumet*, n —round, copper-coated 42 % nickel-iron wire intended primarily for sealing to soft glass. Also known as CuNiFe in some communities; see Specification **F29** for additional information.

3.2.3 *insulation resistance*, dc , n —the resistance at a specified direct-current voltage between the insulated leads of a thermistor sensor and the metallic enclosure of the sensor, if such an enclosure is present, or else between the sensor leads and a conductive medium in which the sensor is immersed.

3.2.4 *qualification test*, n —a series of tests conducted by the procuring agency or an agent thereof to determine conformance of thermistor sensors to the requirements of a specification, normally for the development of a qualified products list under the specification.

3.2.5 *response time*, n —the time required for a sensor to change a specified percentage of the total difference between its initial and final temperatures as determined from zero-power resistances when the sensor is subjected to a step function change in temperature.

3.2.6 *time constant*, n —the 63.2 % response time of a sensor that exhibits a single-exponential response.

3.2.7 *zero-power resistance*, n —the dc resistance of a device, at a specified temperature, calculated for zero-power.

3.2.7.1 *Discussion*—Accurate zero-power resistance is obtained by extrapolating to zero-power the resistance values obtained from measurements at three or more levels of power with the sensor immersed in a constant temperature medium. For the purpose of this specification, this is obtained from measurements at a single power level that is adjusted or otherwise determined to be not greater than one-fifth the product of the dissipation constant specified in **Table 1** (see **3.2.1** and **7.3**) and the appropriate tolerance requirement of **Table 3**. Accordingly, the applied power levels required to satisfy the zero-power resistance criterion as defined above can be as little as 2 μW (for a Type W sensor with accuracy class 1) to as much as 600 μW (for Types J, K or P sensors with accuracy class 6). The known excitation current or voltage of the measurement system along with the resistance of the sensor at the selected temperature (from the nominal resistance and ratio values given in **Table 2**) can be used to compute the actual applied power to the unit under test (UUT) and to determine if this power level meets the zero-power criterion. When making repeat measurements over a specified time period to determine the stability of a sensor, the power level shall be kept constant.

4. Classification

4.1 Thermistor sensors covered by this specification shall be classified with a unique identification code that includes the ASTM detailed specification number followed by a descriptive type designation code, an operating temperature range code, an accuracy class code, and a calibration type code. (See **Fig. 1**.)

4.2 *ASTM Specification Number*—The ASTM specification number specifies uniquely the design and construction of the sensor including the type designation if more than one type appears in the same specification.

4.2.1 *Type Designation*—The type designation code shall be a letter symbol to indicate the design and construction of the thermistor sensor followed by a number to indicate the subset of specific features as shown on the detailed specification drawing whenever there are design options. (See **Fig. 2** through **Fig. 10**).

4.2.1.1 *Type S*—Silicone rubber-coated glass probe with tinned Dumet extension leads (see **Fig. 2**).

4.2.1.2 *Type E*—Epoxy-coated glass probe with silver-plated copper extension leads (see **Fig. 3**).

4.2.1.3 *Type G*—General purpose four-wire sensor in stainless steel housing (see **Fig. 4**).

4.2.1.4 *Type H*—General purpose two-wire sensor in stainless steel housing (see **Fig. 5**).

4.2.1.5 *Type V*—Interchangeable sensor enclosed in 1.2 mm vinyl tube (see **Fig. 6**).

4.2.1.6 *Type W*—Non-interchangeable sensor enclosed in 0.9 mm vinyl tube (see **Fig. 7**).

4.2.1.7 *Type P*—Interchangeable sensor with flexible cable and sealed plastic tip (see **Fig. 8**).

4.2.1.8 *Type J*—Interchangeable sensor enclosed in stainless steel housing (see **Fig. 9**).

4.2.1.9 *Type K*—Interchangeable sensor enclosed in stainless steel housing with threaded pipe fitting (see **Fig. 10**).

4.3 *Operating Temperature Range*—The operating temperature range shall be designated by a letter symbol (see **Table 4**).

4.4 *Accuracy Class*—The accuracy class shall be designated by a single-digit number (see **Table 3**).

4.5 *Calibration Type*—The type of calibration required for each unit shall be designated by a letter symbol. The letter *I* shall be used to denote units that are interchangeable with respect to a single resistance-temperature relationship. The letter *N* shall be used to denote non-interchangeable units for which resistance-temperature information must be furnished for each unit. For Calibration Type N sensors, serial number identification must be provided.

4.6 *Zero-power Resistance at 25 °C*—Each of the individual thermistor sensor types shall have nominal zero-power resistance values at 25 °C as specified in **Table 1** and as shown on the individual detailed specification drawings. Each nominal resistance value specified shall also have an associated resistance ratio-versus-temperature value that is characteristic of the thermistor material formulation employed in the sensor. The resistance ratio-versus-temperature data for the selected thermistor material formulations are shown in **Table 2**. Other nominal resistance values at 25 °C, or at another reference temperature, may be agreed upon by the manufacturer and end user provided that this information is clearly communicated in all appropriate documentation; and, that the unique identification code (see **Fig. 4.1**) is not used under such circumstances.

4.7 *Terminations*—The detailed specification drawings (see **Fig. 2** through **Fig. 10**) show the sensors with the most common type of termination for that type designation. All sensors, regardless of type designation, may be terminated with any suitable electrical connector (as agreed upon by manufacturer and end user) such that it allows the sensor to interface with a specific thermometer system. It is recommended that the

TABLE 1 Specification for ASTM Laboratory Thermistor Sensors

	E879 Type S	E879 Type E	E879 Type G	E879 Type H	E879 Type V	E879 Type W	E879 Type P	E879 Type J	E879 Type K
Description	Silicone Rubber Coated Glass Probe	Epoxy Coated Glass Probe	4-Wire Non-interchangeable Sensor in S.S. Housing	2-Wire Non-interchangeable Sensor in S.S. Housing	Interchangeable Sensor Enclosed in 1.17 mm Plastic Tube	Non-interchangeable Sensor Enclosed in 0.92 mm Plastic Tube	Interchangeable Sensor with flexible cable and plastic tip	Interchangeable Sensor in S.S. Housing	Interchangeable Sensor in S.S. Housing with 1/8-27 NPT body
Design and Construction	Fig. 2	Fig. 3	Fig. 4	Fig. 5	Fig. 6	Fig. 7	Fig. 8	Fig. 9	Fig. 10
Major Applications	General Purpose Laboratory Temperature Measurement	General Purpose Laboratory Temperature Measurement	General Purpose Laboratory Temperature Measurement	General Purpose Laboratory Temperature Measurement	Cuvette Thermometry	Cuvette Thermometry	General Purpose Laboratory Temperature Measurement	General Purpose Laboratory Temperature Measurement	General Purpose Laboratory Temperature Measurement
Design Exposure Temperature Limits									
minimum	-50 °C	-20 °C	-20 °C	-20 °C	-20 °C	-20 °C	-20 °C	-50 °C	-50 °C
maximum	125 °C	105 °C	105 °C	105 °C	70 °C	70 °C	105 °C	105 °C	150 °C
Available Accuracy Classes	1 (± 0.01 °C) 2 (± 0.02 °C) 3 (± 0.05 °C) 4 (± 0.10 °C)	1 (± 0.01 °C) 2 (± 0.02 °C) 3 (± 0.05 °C) 4 (± 0.10 °C)	1 (± 0.01 °C) 2 (± 0.02 °C) 3 (± 0.05 °C) 4 (± 0.10 °C)	1 (± 0.01 °C) 2 (± 0.02 °C) 3 (± 0.05 °C) 4 (± 0.10 °C)	4 (± 0.10 °C) 5 (± 0.20 °C)	4 (± 0.10 °C) 5 (± 0.20 °C)	4 (± 0.10 °C) 5 (± 0.20 °C)	4 (± 0.10 °C) 5 (± 0.20 °C)	4 (± 0.10 °C) 5 (± 0.20 °C) 6 (± 0.50 °C)
Available Operating Temperature Ranges	A (-10 °C to 105 °C) B (-10 °C to 60 °C) C (0 °C to 60 °C) D (0 °C to 70 °C) E (0 °C to 100 °C)	A (-10 °C to 105 °C) B (-10 °C to 60 °C) C (0 °C to 60 °C) D (0 °C to 70 °C) E (0 °C to 100 °C)	A (-10 °C to 105 °C) B (-10 °C to 60 °C) C (0 °C to 60 °C) D (0 °C to 70 °C) E (0 °C to 100 °C)	A (-10 °C to 105 °C) B (-10 °C to 60 °C) C (0 °C to 60 °C) D (0 °C to 70 °C) E (0 °C to 100 °C)	B (-10 °C to 60 °C) C (0 °C to 60 °C) D (0 °C to 70 °C)	B (-10 °C to 60 °C) C (0 °C to 60 °C) D (0 °C to 70 °C)	B (-10 °C to 60 °C) C (0 °C to 60 °C) D (0 °C to 70 °C) E (0 °C to 100 °C) F (-50 °C to 50 °C)	A (-10 °C to 105 °C) B (-10 °C to 60 °C) C (0 °C to 60 °C) D (0 °C to 70 °C) E (0 °C to 100 °C) F (-50 °C to 50 °C)	A (-10 °C to 105 °C) B (-10 °C to 60 °C) C (0 °C to 60 °C) D (0 °C to 70 °C) E (0 °C to 100 °C) F (-50 °C to 50 °C)
Accuracies for Other Temperatures Within Specified Temperature Range	n/a	n/a	n/a	n/a	Class 3 (± 0.05 °C) Over 24 °C to 45 °C	Class 3 (± 0.05 °C) Over 24 °C to 45 °C	n/a	n/a	n/a
Calibration Type	Non-interchangeable	Non-interchangeable	Non-interchangeable	Non-interchangeable	Non-interchangeable	Non-interchangeable	Interchangeable	Interchangeable	Interchangeable
Type of Immersion	water, air	water, oil, air	all fluids compatible with Type 304 S.S.	all fluids compatible with Type 304 S.S.	water	water	water, oil, air	all fluids compatible with Type 304 S.S.	all fluids compatible with Type 304 S.S.
Nominal Resistance at 25 °C in Ohms with applicable Curve (Ratio 25/125)	2500 (19.86) 10 000 (22.73)	2500 (19.86) 10 000 (22.73)	5000 (19.86) 10 000 (22.06)	5000 (19.86) 10 000 (22.06)	11 000 (20.37) 44 000 (20.37)	10 000 (19.86) 22 000 (20.37)	2252 (29.25) 10 000 (29.25)	2252 (29.25) 10 000 (29.25)	2252 (29.25) 10 000 (29.25)
Dissipation Constant	3.5 \pm 0.9 mW/K	5.0 \pm 1.2 mW/K	4.8 \pm 1.2 mW/K	4.8 \pm 1.2 mW/K	1.1 \pm 0.3 mW/K	0.8 \pm 0.2 mW/K	6.0 \pm 1.5 mW/K	6.0 \pm 1.5 mW/K	6.0 \pm 1.5 mW/K
63.2% Response Time	0.55 \pm 0.16 s	0.45 \pm 0.11	4.5 \pm 1.1 s	4.5 \pm 1.1 s	0.5 \pm 0.12 s	0.26 \pm 0.06 s	4.5 \pm 1.1 s	4.5 \pm 1.1 s	4.5 \pm 1.1 s

TABLE 2 Resistance-temperature Data for ASTM Laboratory Thermistor Sensors

Curve Designation	(19.86)	(20.37)	(22.06)	(22.73)	(29.25)
Applicable Nominal Resistance at 25 °C (Ohms)	2500 4000 5000 10 000	11 000 22 000 44 000	5000 10 000	10 000 15 000	2252 10 000
Resistance ratio 25 °C to 125 °C	19.86 ± 10 %	20.37 ± 10 %	22.06 ± 10 %	2.73 ± 10 %	29.25 ± 10 %
Resistance ratio 0 °C to 50 °C	7.04 ± 6 %	7.08 ± 6 %	7.44 ± 6 %	7.58 ± 6 %	9.06 ± 6 %
Resistance ratio 0 °C to 70 °C	13.33 ± 8 %	13.45 ± 8 %	14.37 ± 8 %	14.75 ± 8 %	18.65 ± 8 %
Nominal ratio data:					
-50 °C	40.15	40.07	44.97	46.74	67.01
-40 °C	22.06	22.07	24.16	24.96	33.65
-30 °C	12.59	12.60	13.53	13.89	17.70
-20 °C	7.433	7.448	7.863	8.025	9.707
-10 °C	4.534	4.543	4.728	4.800	5.532
0 °C	2.849	2.853	2.932	2.962	3.265
10 °C	1.840	1.841	1.870	1.881	1.990
20 °C	1.840	1.219	1.224	1.227	1.249
25 °C	1.0000	1.0000	1.0000	1.0000	1.0000
30 °C	0.8262	0.8253	0.8215	0.8197	0.8057
40 °C	0.5725	0.5711	0.5633	0.5600	0.5327
50 °C	0.4048	0.4032	0.3942	0.3906	0.3603
60 °C	0.2917	0.2899	0.2811	0.2776	0.2487
70 °C	0.2138	0.2121	0.2040	0.2008	0.1751
80 °C	0.1593	0.1576	0.1504	0.1477	0.1255
90 °C	0.1206	0.1189	0.1126	0.1102	0.09156
100 °C	0.09245	0.0909	0.08547	0.08346	0.06784
105 °C	0.08138	0.0799	0.07484	0.07298	0.05876
110 °C	0.07186	0.0704	0.06573	0.06402	0.05107
120 °C	0.05654	0.0552	0.05117	0.04971	0.03896
125 °C	0.05036	0.0491	0.04534	0.04400	0.03419
130 °C	0.04487	0.0438	0.04029	0.03905	0.03010
140 °C	0.03619	0.0351	0.03209	0.03100	0.02352
150 °C	0.02953	0.0284	0.02577	0.02485	0.01859

TABLE 3 Equivalent Temperature Tolerances for Different Class Sensors (See 4.1 and 4.4)

Accuracy Class	Temperature Tolerance, °C
1	±0.02
2	±0.03
3	±0.05
4	±0.1
5	±0.2
6	±0.5

zero-power resistance measurements be performed only after any such modifications have taken place. Examples of such terminations shall include (but are not limited to) phone plugs; stereo plugs; multiple pin DIN type plugs; multiple pin “Deutsches Institut für Normung” (DIN) circular connectors; or, gold-plated terminals.

5. Requirements

5.1 Specifications—Sensors shall comply with the general requirements specified herein as well as with the applicable detailed specifications of **Table 1**, **Table 2**, and **Fig. 2** through **Fig. 10**. In the event of conflict between this requirement subsection and the detailed specification of **Table 1**, **Table 2**, and **Fig. 2** through **Fig. 10**, the latter shall govern.

5.2 Zero-Power Resistance Versus Temperature Relationship—The zero-power resistance versus temperature relationship shall be presented in a form such that any temperature within the specified operating temperature range can be obtained from that relationship and have an uncertainty no greater than one-tenth the specified tolerance in **Table 3**.

When tested in accordance with **7.2**, the zero-power resistance versus temperature relationship for interchangeable parts shall comply to within the tolerance specified in **Table 3**. The manufacturer of the sensor shall, for non-interchangeable parts, supply this relationship with each part shipped. This relationship may be supplied in the form of data tables, or by providing the constants for one or more of the following thermistor equations, or both.

Equations representing this relationship use the standard curve fitting technique of considering the natural logarithm of the zero-power resistance to be a polynomial in reciprocal temperature, or vice versa. Although the polynomial equation can be of any higher order, historically it has been shown that a third order polynomial (**Eq 2 and 3**) provides excellent results over the relatively narrow temperature ranges of thermistor sensor applications. Furthermore, Steinhart and Hart have proven in oceanographic research studies over the range of -2 °C to +30 °C that satisfactory results are obtained when the squared term is omitted (**Eq 4 and 5**).⁶

Eq 4 and 5 have three unknown constants that are derived by the simultaneous solution of three equations based upon three calibration data points. **Eq 2 and 3** have four unknown constants and thus a minimum of four calibration data points are required to solve for the constants. Frequently, more than four calibration data points are obtained and a polynomial regression analysis is performed to derive the constants for equations **Eq 2 and 3**. This has the benefit of statistically improving the accuracy of the data.

⁶ Steinhart, J.S., and Hart, S.R., “Calibration Curves for Thermistors,” *Deep Sea Research*, Vol 15, No. 497, 1968.

E 8 7 9 S 1 A 2 N

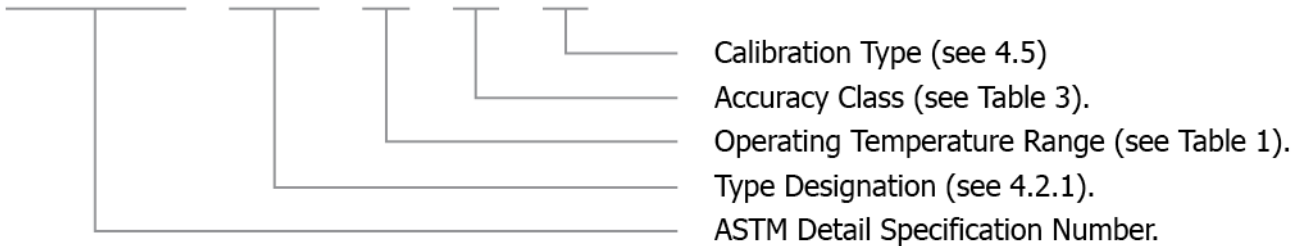
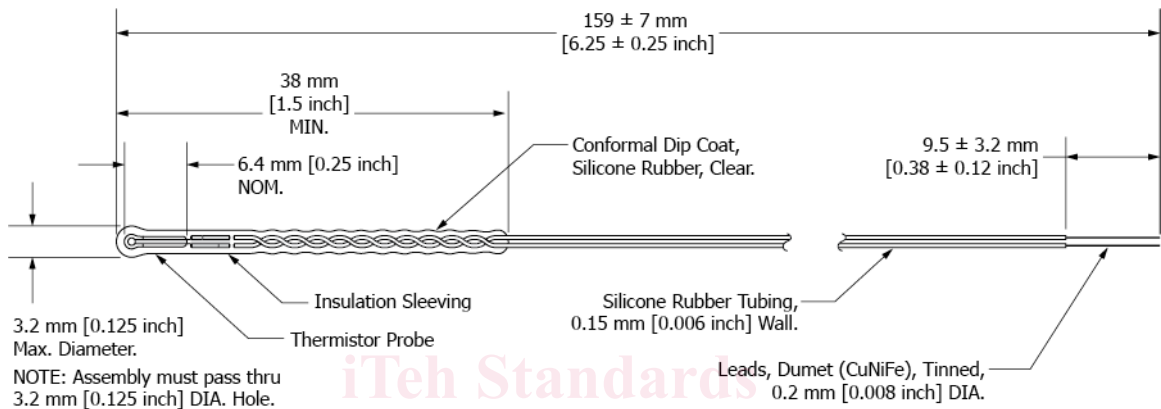


FIG. 1 Thermistor Sensor Type Designation Code



Type Code	Resistance at 25 °C	Curve Ratio
S1	2500 Ohms	19.86
S2	10000 Ohms	22.73

TYPE - S: Silicone rubber-coated glass probe with tinned Dumet extension leads.

NOTE: METRIC [ENGLISH] --- ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE INDICATED.

FIG. 2 Silicone Rubber Coated Glass Probe (Type S)

$$\ln R_T = [A_0 + A_1/T + A_2/T^2 + A_3/T^3] \quad (2)$$

$$1/T = a_0 + a_1 \ln(R_T) + a_2 \ln(R_T)^2 + a_3 \ln(R_T)^3 \quad (3)$$

$$\ln R_T = [B_0 + B_1/T + B_3/T^3] \quad (4)$$

$$1/T = b_0 + b_1 \ln(R_T) + b_3 \ln(R_T)^3 \quad (5)$$

where:

A_n, a_n = unique constants derived from calibrations performed at four or more specified data points,

B_n, b_n = unique constants derived from calibrations performed at three specified data points,

T = is the absolute temperature in kelvins, and

R_T = is the zero-power resistance at temperature T .

5.2.1 Accuracy—The resistance-temperature relationship, provided in Table 2, or with the sensor, or both, shall not differ from that obtained from measurements made in accordance with 7.2 by more than the tolerances specified in Table 3 for the applicable intervals specified in Table 1. When additional temperature intervals are specified within the operating temperature range, the accuracy class for each interval shall be clearly indicated by the manufacturer.

5.3 Thermal Requirements:

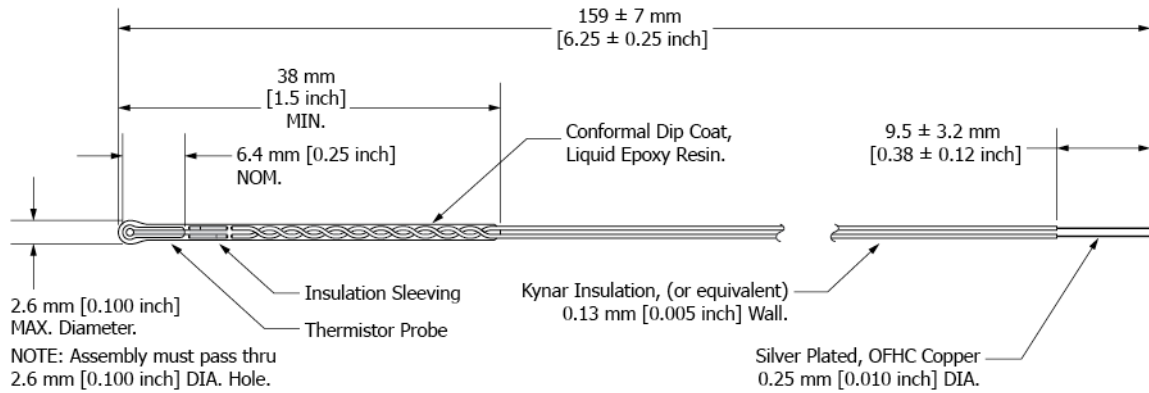
5.3.1 Dissipation Constant—When tested in accordance with 7.3, the dissipation constant shall be as specified in the detailed specification.

5.3.2 Response Time—When tested in accordance with 7.4, the response time or time constant, or both, shall be as specified in the detailed specification.

5.4 Environmental Requirements:

5.4.1 Operating Temperature Range—The operating temperature range shall be as specified in the type designation code (see 4.1 and 4.3).

5.4.2 Storage Temperature Range—Sensors shall be capable of meeting all requirements specified herein as well as those listed in the applicable detailed specification after storage at any temperature (or combination thereof) in the range from -50 °C minimum (or the design limit for minimum exposure temperature, whichever is higher) up to 60 °C maximum (or the design limit for maximum exposure temperature, whichever is lower) for a period of 1 year. Sensors subjected to operation or storage at temperatures that exceed

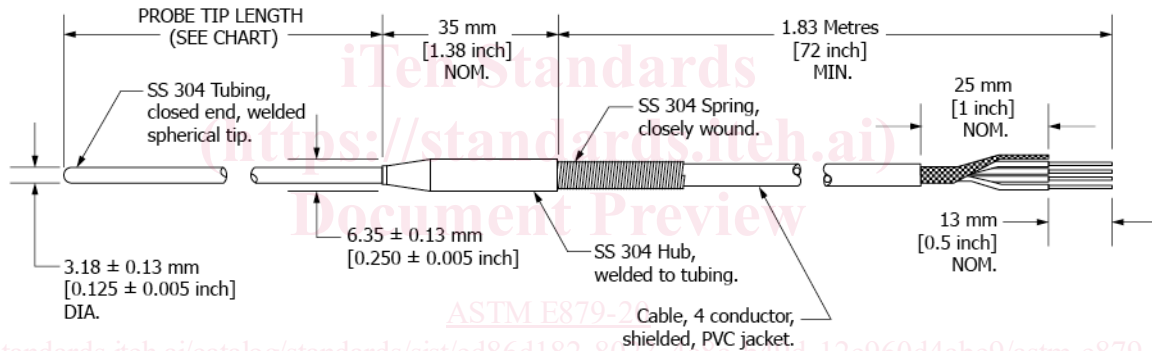


Type Code	Resistance at 25 °C	Curve Ratio
E1	2500 Ohms	19.86
E2	10000 Ohms	22.73

TYPE - E: Epoxy-coated glass probe with silver-plated copper extension leads.

NOTE: METRIC [ENGLISH] --- ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE INDICATED.

FIG. 3 Epoxy Coated Glass Probe (Type E)



Type Code	Probe Tip Length	Resistance at 25 °C	Curve Ratio
G1	114 ± 2 mm [4.5 ± 0.08 inch]	5000 Ohms	19.86
G2	152 ± 2 mm [6.0 ± 0.08 inch]	10000 Ohms	22.06
G3	165 ± 2 mm [6.5 ± 0.08 inch]	5000 Ohms	19.86
G4	229 ± 2 mm [9.0 ± 0.08 inch]	10000 Ohms	22.06

TYPE - G: General purpose four-wire sensor in stainless steel housing.

NOTE: METRIC [ENGLISH] --- ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE INDICATED.

FIG. 4 General Purpose Four-wire Sensor in Stainless Steel Housing (Type G)

their design limits may experience mechanical damage, degraded stability, or both, as well as unreliable performance.

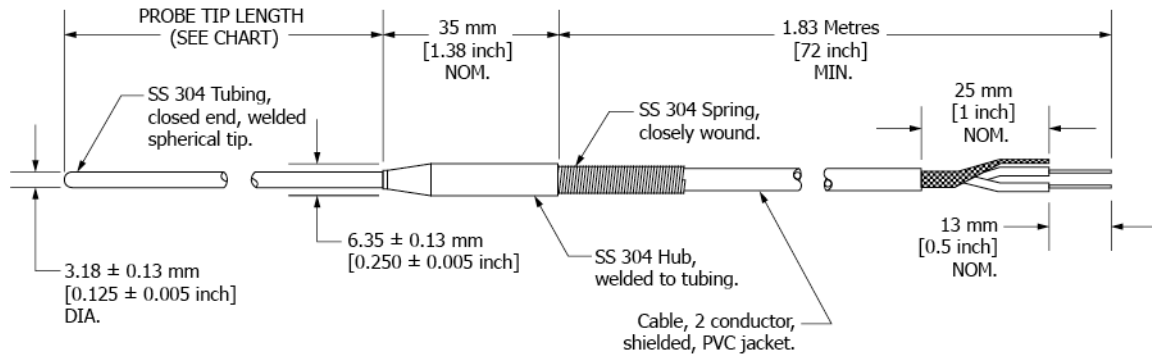
5.4.3 *Humidity Requirement*—Sensors shall be capable of being operated or stored at relative humidity from 0 to 95 % without condensation.

5.5 *Stability:*

5.5.1 *Short-term Stability* (10 days)—When tested in accordance with 7.5.1, the equivalent temperature shift shall be no

greater than 10 % of the tolerance shown in Table 3 for the accuracy class specified.

5.5.2 *Long-term Stability* (120 days)—When tested in accordance with 7.5.2, the equivalent temperature shift shall be no greater than 25 % of the tolerance shown in Table 3 for the accuracy class specified.

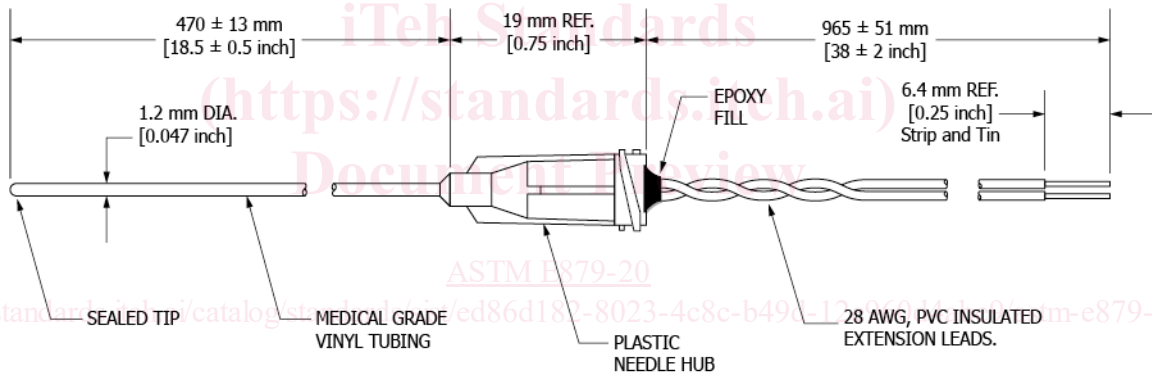


Type Code	Probe Tip Length	Resistance at 25 °C	Curve Ratio
H1	114 ± 2 mm [4.5 ± 0.08 inch]	5000 Ohms	19.86
H2	152 ± 2 mm [6.0 ± 0.08 inch]	10000 Ohms	22.06
H3	165 ± 2 mm [6.5 ± 0.08 inch]	5000 Ohms	19.86
H4	229 ± 2 mm [9.0 ± 0.08 inch]	10000 Ohms	22.06

TYPE - H: General Purpose two-wire sensor in stainless steel housing.

NOTE: METRIC [ENGLISH] --- ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE INDICATED.

FIG. 5 General Purpose Two-wire Sensor in Stainless Steel Housing (Type H)



Type Code	Resistance at 25 °C	Curve Ratio
V1	11000 Ohms	20.37
V2	44000 Ohms	20.37

TYPE - V: interchangeable sensor enclosed in 1.2 mm sealed vinyl tubing.

NOTE: METRIC [ENGLISH] --- ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE INDICATED.

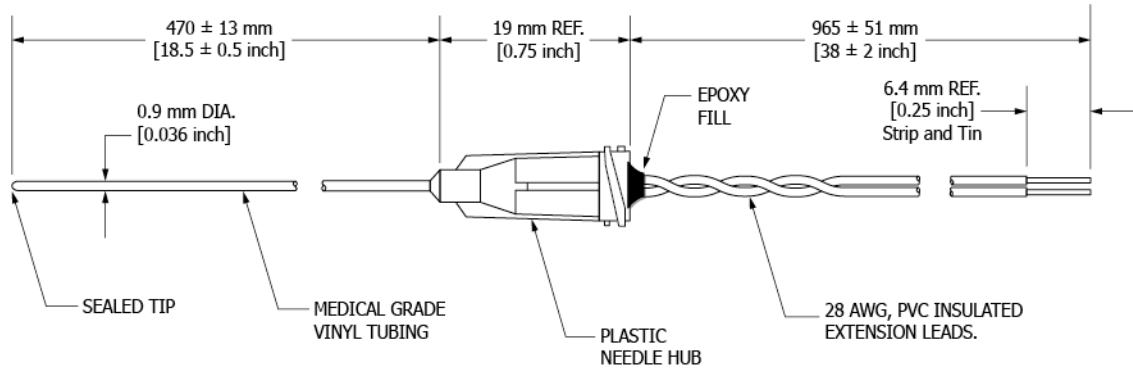
FIG. 6 Interchangeable Sensor Enclosed in 1.2 mm Vinyl Tube (Type V)

5.6 *Low-temperature Storage*—When tested in accordance with 7.6, there shall be no evidence of mechanical damage and the sensor shall comply with the accuracy requirements of 5.2.

5.7 *Thermal Shock*—When tested in accordance with 7.7, there shall be no evidence of mechanical damage and the sensor shall comply with the accuracy requirements of 5.2.

5.8 *Insulation Resistance*:

5.8.1 *Dry Test*—This requirement shall apply to sensors that have exposed metallic surfaces, but are not designed for immersion in conductive fluids. When tested in accordance with 7.8.1, there shall be no evidence of mechanical damage and the insulation resistance shall be sufficiently high that its

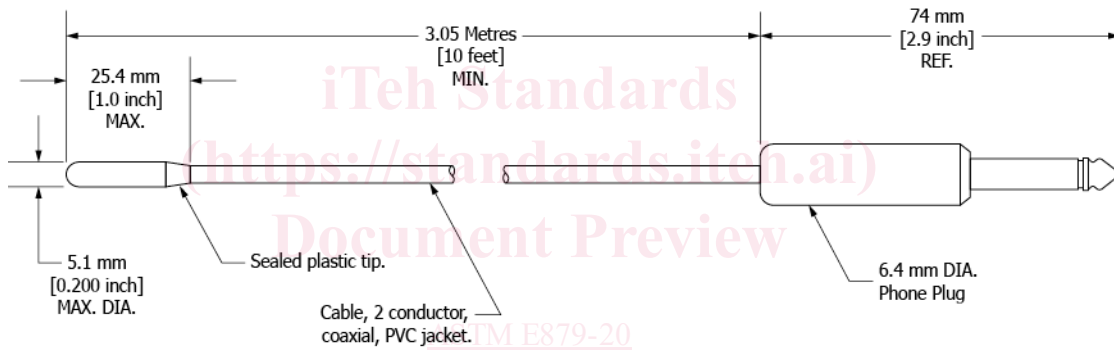


Type Code	Resistance at 25 °C	Curve Ratio
W1	10000 Ohms	19.86
W2	22000 Ohms	20.37

TYPE - W: Non-interchangeable sensor enclosed in 0.9 mm sealed vinyl tubing.

NOTE: METRIC [ENGLISH] --- ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE INDICATED.

FIG. 7 Non-Interchangeable Sensor Enclosed in 0.9 mm Vinyl Tube



Type Code	Resistance at 25 °C	Curve Ratio
P1	2252 Ohms	29.25
P2	10000 Ohms	29.25

TYPE - P: General Purpose interchangeable sensor with flexible cable and sealed plastic tip.

NOTE: METRIC [ENGLISH] --- ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE INDICATED.

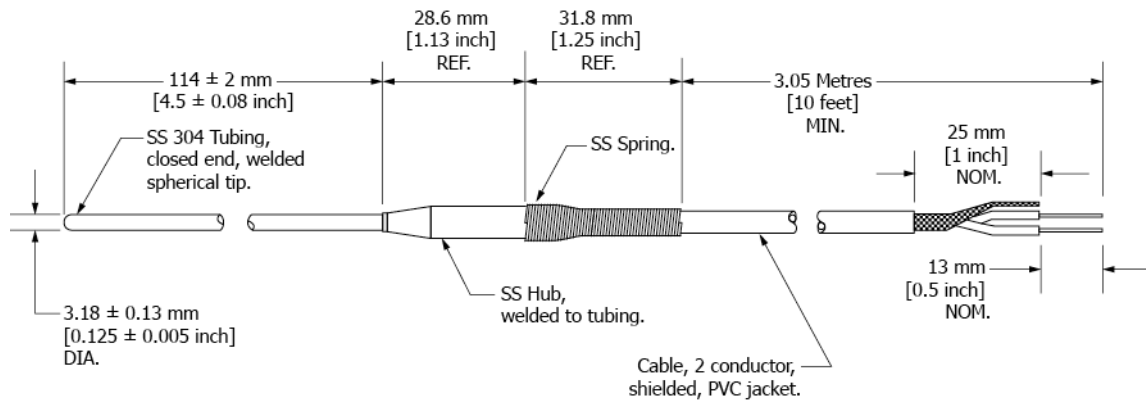
FIG. 8 Interchangeable Sensor with Flexible Cable and Sealed Plastic Tip (Type P)

shunting effect will not prevent the unit from complying with the accuracy requirement of Table 3. In no case shall the insulation resistance be less than $10^8 \Omega$.

5.8.2 *Wet Test*—This requirement shall apply to sensors that are designed for use in conductive solutions. When tested in accordance with 7.8.2, there shall be no evidence of mechanical damage and the insulation resistance shall be sufficiently high that its shunting effect will not prevent the unit from complying with the accuracy requirement of Table 3. In no case shall the insulation resistance be less than $10^8 \Omega$.

6. Quality Assurance Provisions

6.1 *General*—The methods of examination and tests contained in Section 7 are to be used to determine the conformance of sensors to the requirements of this specification. Each manufacturer or distributor who represents his products as conforming to this specification may, as agreed upon between the purchaser and seller, use statistically based sampling plans that are appropriate for each inspection lot. Records shall be kept as necessary to document the claim that all of the requirements of this specification are met. The tests specified in

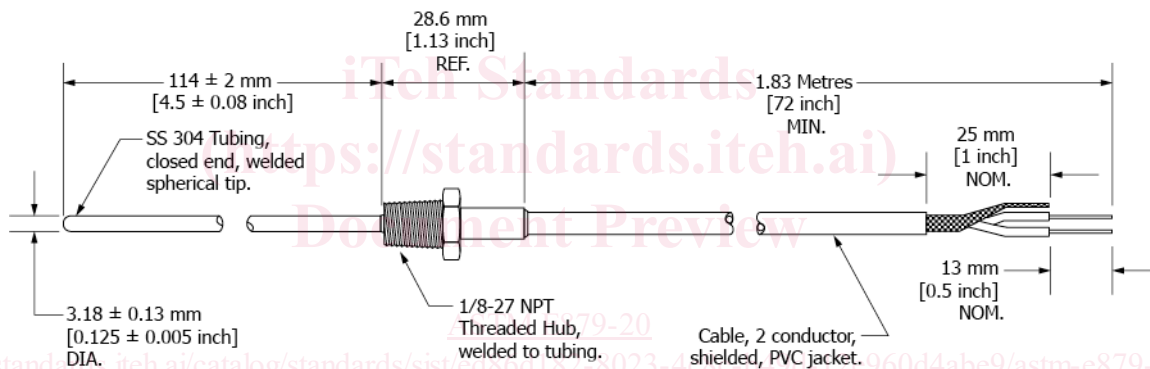


Type Code	Resistance at 25 °C	Curve Ratio
J1	2252 Ohms	29.25
J2	10000 Ohms	29.25

TYPE - J: General Purpose interchangeable sensor in stainless steel housing.

NOTE: METRIC [ENGLISH] --- ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE INDICATED.

FIG. 9 Interchangeable Sensor In Stainless Steel Housing (Type J)



Type Code	Resistance at 25 °C	Curve Ratio
K1	2252 Ohms	29.25
K2	10000 Ohms	29.25

TYPE - K: General Purpose interchangeable sensor in stainless steel housing with pipe fitting body.

NOTE: METRIC [ENGLISH] --- ALL DIMENSIONS IN MILLIMETRES UNLESS OTHERWISE INDICATED.

FIG. 10 Interchangeable Sensor In Stainless Steel Housing With Pipe Fitting (Type K)

TABLE 4 Letter Symbol Designation of Operating Temperature Ranges (See 4.1 and 4.3)

Operating Temperature Range	Letter Symbol
-10 °C to 105 °C	A
-10 °C to 60 °C	B
0 °C to 60 °C	C
0 °C to 70 °C	D
0 °C to 100 °C	E
-50 °C to 50 °C	F

this section are intended as minimum requirements. Additional sampling and testing of the product, as may be agreed upon between the purchaser and the seller, are not precluded by this section.

6.2 Classification of Inspection:

6.2.1 *Qualification Tests*—Qualification tests shall be performed for each basic design manufactured in accordance with this specification. The sample size required for the tests conducted shall be in accordance with [Table 5](#). In order for a design to qualify, there shall be no failures resulting from any of the tests.

6.2.2 *Responsibility for Qualification Testing*—The manufacturer shall perform qualification testing, at least once, for each basic design for which this specification applies. If a basic design incorporates more than one resistance value of a specific material formulation or a particular style of thermistor, or both, different resistance values may be combined for the qualification sample. The highest and lowest resistance values for a specified thermistor design (type, material formulation, and geometry) must be included in the qualification sample. Qualification testing, by the manufacturer, must be repeated whenever a design change which may affect the performance of the sensor with regard to [Section 5](#) of this specification is introduced.

6.2.3 *Manufacturing Screening Tests*—During manufacture, all parts produced in accordance with this specification shall receive 100 % testing for compliance with the requirements of [Table 6](#).

7. Methods of Examination and Test

7.1 *Visual and Mechanical Examination*—Examine sensors to verify that their design, construction, physical dimensions, markings, and workmanship comply with the detailed specification.

7.2 *Zero-power Resistance versus Temperature Relationship*.^{7,8,9}

7.2.1 *Traceability*—All measurements shall be traceable to the International System of Units (SI) through a National Metrology Institute (NMI) such as the National Institute of

⁷ Mangum, B. W., “Platinum Resistance Thermometer Calibration,” *NBS Special Publication 250-22*, 1987.

⁸ Mangum, B. W., and Furukawa, G. T., “Guidelines for Realizing the International Temperature Scale of 1990 (ITS-90),” *NIST Technical Note 1265*, 1990.

⁹ Riddle, J. L., Furukawa, G. T., and Plumb, H. H., “Platinum Resistance Thermometry,” *NBS Monograph 126*, 1973.

TABLE 5 Qualification Tests Required for Each Basic Design

Examination or Test	Requirement Section(s)	Method Section(s)	Sample Size
Visual and mechanical	5.1	7.1	10
Zero-power resistance versus temperature relationship	5.2	7.2	10
Dissipation constant	5.3.1	7.3	5
Response time	5.3.2	7.4	5
Short-term stability	5.5.1	7.5.1	10
Long-term stability	5.5.2	7.5.2	10
Low-temperature storage	5.6	7.6	10
Thermal shock	5.7	7.7	10
Insulation resistance	5.8	7.8	10

TABLE 6 Manufacturing Screening Tests

Examination or Test	Requirement Section	Test Method Section
Visual and mechanical	5.1	7.1
Zero-power resistance versus temperature relationship	5.2	7.2
Insulation resistance	5.8	7.8

Standards and Technology (NIST) using suitable reference standards with documentation.

7.2.1.1 *Measurement System Uncertainties*—Uncertainties exist in all measurements and these must be properly evaluated in order to have confidence in the measurement results. An uncertainty budget is an analysis tool that should be used before the zero-power measurements are taken in order to determine if the measurement system is capable of achieving the desired results. The uncertainty budget will identify the sources of uncertainty and their individual contributions to the overall uncertainty of the measurement system. The result of the analysis is a combined expanded uncertainty, symbol U, for the measurement system. Typically, U is given at a coverage factor of 2, approximating to a 95 % confidence level. For the purpose of performing the zero-power resistance-versus-temperature measurements herein, it is recommended that the resulting combined expanded uncertainty for the measurement system in use should not exceed 25 % of the allowable tolerance for the accuracy class of the sensor to be tested. This provides a desired test uncertainty ratio, TUR, of 4:1 and thus there is a reasonable degree of confidence in the measurement data. Refer to [Appendix X2](#) for a more in-depth discussion of the concepts and sources of measurement uncertainty, as well as examples. Also refer to ANSI/NCSL Z540.3 for additional guidance on requirements for calibration of measuring and test equipment.

7.2.2 *Temperature-controlled Medium*:

7.2.2.1 *Comparison Baths*—Make all zero-power resistance versus temperature relationship measurements in a temperature-controlled liquid bath (such as a water bath). The volume of the liquid should be at least 1000 times the volume of the sensor(s) under test, but shall not be less than 1 L. Baths having volumes as large as 100 L have been found to be convenient to use and to be satisfactory with respect to temperature control. Ensure that the bath medium is sufficiently well-stirred so that temperature gradients are small compared with the temperature accuracy required. Survey the bath with a thermometer to ensure that its temperature is uniform and stable to the extent necessary to perform the tests. For further information refer to [Guide E2488](#) which describes methods to define the working space of a bath and to evaluate the temperature uniformity and stability within this space. Ideally, the working space will be as close as possible to isothermal. If needed, a thermal integrating block (equalization block) can be utilized to enhance performance and thus minimize the uncertainty contributed by the comparison bath.

7.2.2.2 *Fixed-point temperatures*—If the operating temperature range of the thermistor sensor includes the ice-point temperature, the water triple-point temperature, or the gallium melting-point temperature, then an ice-point bath, a water

triple-point cell, or a gallium melting-point cell may be used as the temperature-controlled medium at that respective temperature. Refer to Practice E563 and Guides E1502 and E1750 for additional guidance and information on the use of fixed-point temperatures.

7.2.3 Temperature Monitoring and Control—While performing the zero-power resistance versus temperature measurements, observe the temperature fluctuations of the bath with a check standard thermometer having a response time that is shorter than or equal to that of the unit under test. The total uncertainty resulting from the combined uncertainties of the check standard thermometer and the bath temperature (due to temperature fluctuations and bath gradients within the working volume) shall comply with the desired TUR of 4:1.

7.2.4 Resistance Measurement: Evaluate the contributions to overall system uncertainty for all test instruments used to perform the zero-power resistance measurements to ensure that the total uncertainty complies with the desired TUR of 4:1 for the specific accuracy class as specified in Table 3.

7.2.5 Test Procedure:

7.2.5.1 Temperature Stabilization—After inserting the sensor into the bath, allow enough time for the sensor and bath to come to equilibrium (see 7.2.3).

7.2.5.2 Immersion—Best results will be obtained when measurements are made with the sensor totally immersed. The manufacturer shall specify the minimum immersion length required to obtain the specified tolerance within the temperature range permitted. (See Table 3.)

7.2.5.3 Zero-power Resistance:

(a) *Sensors Designed for Operating Temperature Ranges With Code Letter Symbols B, C, or D*—Determine the zero-power resistance of the sensor at $0\text{ }^{\circ}\text{C} \pm 0.3\text{ }^{\circ}\text{C}$, $30\text{ }^{\circ}\text{C} \pm 0.3\text{ }^{\circ}\text{C}$, and $60\text{ }^{\circ}\text{C} \pm 0.5\text{ }^{\circ}\text{C}$.

(b) *Sensors Designed for Operating Temperature Ranges With Code Letter Symbols A or E*—Determine the zero-power resistance of the sensor at $0\text{ }^{\circ}\text{C} \pm 0.3\text{ }^{\circ}\text{C}$, $30\text{ }^{\circ}\text{C} \pm 0.3\text{ }^{\circ}\text{C}$, $60\text{ }^{\circ}\text{C} \pm 0.5\text{ }^{\circ}\text{C}$, and $105\text{ }^{\circ}\text{C} \pm 1.0\text{ }^{\circ}\text{C}$.

(c) *Sensors Designed for Operating Temperature Range With Code Letter Symbol F*—Determine the zero-power resistance of the sensor at $-20\text{ }^{\circ}\text{C} \pm 1.0\text{ }^{\circ}\text{C}$, $0\text{ }^{\circ}\text{C} \pm 0.3\text{ }^{\circ}\text{C}$, $30\text{ }^{\circ}\text{C} \pm 0.3\text{ }^{\circ}\text{C}$, and $50\text{ }^{\circ}\text{C} \pm 0.5\text{ }^{\circ}\text{C}$.

7.2.5.3.1 Discussion—While performing the zero-power resistance measurements at any of the specified calibration temperatures above, verify that the applied power level to the unit under test (UUT) does not exceed the zero-power resistance criterion as described in 3.2.7 (Discussion).

Example—A thermistor sensor with ASTM specification number E879G2B2N is to be measured per the requirements of 7.2.5.3(a). This thermistor sensor is defined by type designation “G2” (10 000 Ω nominal at 25 $^{\circ}\text{C}$ with a curve ratio value of 22.06); an operating temperature range “B” ($-10\text{ }^{\circ}\text{C}$ to 60 $^{\circ}\text{C}$); an accuracy class “2” ($\pm 0.02\text{ }^{\circ}\text{C}$), and a minimum dissipation constant of 3.6 mW/K. Using the nominal resistance as well as the ratio values of Table 2, we can determine the UUT resistance will be approximately 29 320, 8215, and 2811 Ω at the specified calibration temperatures of 0 $^{\circ}\text{C}$, 30 $^{\circ}\text{C}$, and 60 $^{\circ}\text{C}$ respectively. To meet the zero-power resistance criterion for these measurements the maximum applied power

to this type of sensor must not exceed 14.4 μW (one fifth the product of the dissipation constant and the temperature tolerance requirement of Table 3). If the measurement system uses an instrument that applies a constant current, then the worst case condition will occur when the thermistor resistance is at its maximum (29 320 Ω at 0 $^{\circ}\text{C}$). In this case, the maximum value of the applied current may not exceed 2.2 μA . If the measurement system uses an instrument that applies a constant voltage, then the worst case condition will occur when the thermistor resistance is at its minimum value (2811 Ω at 60 $^{\circ}\text{C}$). In this case, the maximum value of the applied voltage may not exceed 200 mV.

7.3 Dissipation Constant—Determine the dissipation constant in water unless another fluid is specified. As determined here, the dissipation constant is for the specific environment described in 7.3.1. Measurements made with the sensor in air, oil, still water, etc. will yield different values.

7.3.1 Mount the sensor in a fluid bath that is controlled at some temperature, T_i , in the range from 24 $^{\circ}\text{C}$ to 38 $^{\circ}\text{C}$. The fluid specified for the bath shall have a velocity of no less than 1 m/s and its volume shall be no less than 1000 times the volume of the sensor. Determine the zero-power resistance, R_i , from measurements made in accordance with 7.2.

7.3.2 Increase the measuring current (or voltage) until the sensor indicates a resistance R_{i+10} , equivalent to that at a temperature of T_{i+10} , a temperature which is 10 $^{\circ}\text{C}$ higher than that of the initial temperature T_i .

7.3.3 Measure the sensor current (or voltage) to within an uncertainty of $\pm 1\%$ and compute the dissipation constant from Eq 6:

$$\delta = \Delta P / \Delta T = (I^2 \cdot R_{(i+10)}) / 10 = E^2 / (10 \cdot R_{(i+10)}) \quad (6)$$

where:

- δ = dissipation constant,
- Δ = change in applied power,
- Δ = resulting change in thermistor temperature,
- I = measured current,
- E = measured voltage, and
- $R_{(i+10)}$ = resistance of thermistor at a temperature 10 $^{\circ}\text{C}$ above the initial temperature, T_i .

7.4 Response Time—Determine the response time in water unless another fluid is specified. As determined here, the response time is for the specific environment described in 7.4.2. Measurements made with the sensor in air, oil, still water, etc. will yield different values.

7.4.1 Connect the sensor to an instrument that continuously records the sensor output signal. It is desirable that the recorded signal be linearly related to temperature. See Appendix X3 for information on the design of a thermistor voltage divider circuit that provides a linear output signal.

7.4.2 Mount the sensor in a *plunger-type* fixture above a fluid bath having a minimum volume of 1000 times the sensor volume and a temperature somewhere in the range from 0.01 $^{\circ}\text{C}$ to 5 $^{\circ}\text{C}$ that is constant during the time of measurement. The fluid specified for the bath shall have a velocity of no less than 1 m/s.

7.4.3 Allow the sensor to come to equilibrium in air at room temperature in the range of 20 $^{\circ}\text{C}$ to 25 $^{\circ}\text{C}$.