

# INTERNATIONAL STANDARD

# NORME INTERNATIONALE



AMENDMENT 1  
AMENDEMENT 1

**Lamps and light sources for road vehicles – Dimensional, electrical and luminous requirements**

**Lampes et sources lumineuses pour véhicules routiers – Exigences dimensionnelles, électriques et lumineuses**

[IEC 60809:2021/AMD1:2023](https://standards.iteh.ai/catalog/standards/sist/522a0eb6-cf84-4c29-b503-0f1c19f15604/iec-60809-2021-amd1-2023)

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**LAMPS AND LIGHT SOURCES FOR ROAD VEHICLES –  
DIMENSIONAL, ELECTRICAL AND LUMINOUS REQUIREMENTS****AMENDMENT 1****FOREWORD**

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Amendment 1 to IEC 60809:2021 has been prepared by subcommittee 34A: Electric light sources, of IEC technical committee 34: Lighting.

The text of this Amendment is based on the following documents:

Draft	Report on voting
34A/2370/FDIS	34A/2378/RVD

Full information on the voting for its approval can be found in the report on voting indicated in the above table.

The language used for the development of this Amendment is English.

This document was drafted in accordance with ISO/IEC Directives, Part 2, and developed in accordance with ISO/IEC Directives, Part 1 and ISO/IEC Directives, IEC Supplement, available at [www.iec.ch/members\\_experts/refdocs](http://www.iec.ch/members_experts/refdocs). The main document types developed by IEC are described in greater detail at [www.iec.ch/publications/](http://www.iec.ch/publications/).

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## 2 Normative references

Replace the existing reference to IEC 60810 with the following:

IEC 60810:2017, *Lamps, light sources and LED packages for road vehicles – Performance requirements*

IEC 60810:2017/AMD1:2019

IEC 60810:2017/AMD2:2022

Add the following new reference:

IEC 62707-1:2013, *LED-binning – Part 1: General requirements and white colour grid intended for automotive applications*

IEC 62707-1:2013/AMD1:2018

## 3 Terms and definitions

Add, at the end of Clause 3, the following new terminological entries 3.19, 3.20 and 3.21:

### 3.19

#### matrix light source

##### MLS

LED light source consisting of a grid of individually operated pixels in two perpendicular directions

Note 1 to entry: The grid consists of  $m$  pixels in direction  $x$  (row) and  $n$  pixels in direction  $y$  (column).

### 3.20

#### pitch $p_x$ and pitch $p_y$

nominal distance (centre-to-centre) in direction  $x$  respectively in direction  $y$  between adjacent pixels in an MLS having a rectilinear grid pattern

**3.21  
pixel**

smallest element of a matrix light source that is capable of being operated individually

**6.5 Lamp dimensions**

Replace, in the second paragraph, "Lx5B<sup>5</sup>", with "Lx5B, Lx6A, Lx6B<sup>5</sup>".

**8.2 List of specific lamp types**

**Table 3**

Replace the last four rows (Sheet no. in R.E.5: L3, LR4, L5 and L1/6) of the existing Table 3, before footnotes "a" and "b", with the following new rows:

**Table 3 – List of specific lamp types**

IEC sheet no. <sup>a</sup>	Sheet no. <sup>b</sup> in R.E.5	Category	Voltage	Wattage	Cap
			V	W	
-	Lx3	LR3A / LR3B	12	3	PGJ18,5d-1
		LW3A / LW3B	12	4	PGJ18,5d-24
		LY3A / LY3B	12	4	PGJ18,5d-15
-	LR4	LR4A / LR4B	12	3 / 075	PGJ18,5t-5
-	Lx5	LR5A / LR5B	12	3	PGJ18,5d-10
		LW5A / LW5B	12	6	PGJ18,5d-28
		LY5A / LY5B	12	6	PGJ18,5d-19
-	Lx6	LR6A / LR6B	12	7	PGJ18,5d-33
		LW6A / LW6B	12	7	PGJ18,5d-12
		LY6A / LY6B	12	7	PGJ18,5d-7
-	L1	L1A/6 / L1B/6	12	6	PGJ18,5d-29
-	C5W/LED	C5W/LEDK	12	2	SVX8.5
-	PY21W/LED	PY21W/LED	12	7	BAU15s-3(110°)
			24	7	BAU15s-3(110°)
-	R5W/LED	R5W/LED	12	2	BA15s-3(110°)
			24	2	BA15s-3(110°)
-	W5W/LED	W5W/LEDK	12	2	WX2.1x9.5d
			24	2	WX2.1x9.5d
		WY5W/LED	12	2	WX2.1x9.5d
			24	2	WX2.1x9.5d
-	H11/LED	H11/LED/6	12	18	PGJX19-2
			24	18	PGJX19-2
-	C5W_LED <sub>r</sub>	C5W (LED <sub>r</sub> )	12	3	SV8.5
-	H11_LED <sub>r</sub>	H11 (LED <sub>r</sub> )	12	27	PGJ19-2
			24	27	PGJ19-2

Add, at the end of the existing Clause 8, the following new Clause 9:

## 9 Requirements and test conditions for matrix light sources (MLSs)

### 9.1 General requirements

Matrix light sources shall be so designed as to be and to remain in good working order when in normal use. They shall, moreover, exhibit no fault in design or manufacture.

This Clause 9 applies to matrix light sources with a Lambertian-like intensity distribution, i.e.  $I(\theta) \approx I_0 \cdot \cos(\theta)$  (see 9.2.5.4).

Matrix light sources may consist of areas with different pitch  $p_x$  and pitch  $p_y$ , for example a central area with a smaller pitch  $p_x$  and outer areas with a larger pitch  $p_x$ .

NOTE In the case of an MLS with areas of different pitch  $p_x$  and pitch  $p_y$ , it can be necessary to evaluate each area separately, and some deviations from the specified procedures can be necessary.

This Clause 9 is intended to be applied to matrix light sources with a number of pixels in the order of one hundred or less.

### 9.2 Photometrical requirements and test conditions

#### 9.2.1 Measurement methods

Appropriate measurement methods capable of dealing with the requirements of 9.2.4.2, 9.2.4.3, 9.2.5.2, 9.2.5.3, 9.2.5.4, 9.2.5.5, 9.2.5.6, 9.2.5.7 and 9.2.6.1 shall apply.

#### 9.2.2 Reference system

The reference system for the (x, y) reference plane shall be specified in the manufacturer's data sheet. The (z) reference axis shall be normal to the (x, y) reference plane and intersect the centre point of the grid.

#### 9.2.3 Operating conditions

For testing purposes, one of the following operating conditions shall apply:

- pulsed operation, defined by
  - pulse definition and measurement intervals according to IEC 62707-1:2013, and IEC 62707-1:2013/AMD1:2018, 5.3;
  - drive current  $I_f$ , according to the manufacturer's data sheet;
  - ambient temperature  $23 \text{ °C} \pm 5 \text{ °C}$  (see IEC 62707-1:2013, and IEC 62707-1:2013/AMD1:2018, 5.2);
- steady state operation, defined by
  - drive current  $I_f$ , according to the manufacturer's data sheet;
  - PWM duty cycle, according to the manufacturer's data sheet;
  - position of  $T_b$ -point, according to the manufacturer's data sheet;
  - stabilization temperature  $T_b$  (within  $\pm 3 \text{ °C}$ ) at the  $T_b$ -point, according to the manufacturer's data sheet.

All measurements shall be performed under pulsed operation, unless otherwise specified in the manufacturer's data sheet.

## 9.2.4 Parameters determined by all pixels

### 9.2.4.1 General

Subclause 9.2.4 covers parameters which are determined by the entirety of all pixels.

### 9.2.4.2 Partial luminous flux

The partial luminous flux  $\Phi_{\text{cone}}$  of an MLS is the luminous flux emitted into a cone of  $\theta = 45^\circ$  around the z axis according to:

$$\Phi_{\text{cone}} = \int_{\theta=0^\circ}^{\theta=45^\circ} \int_{\varphi=0}^{\varphi=2\pi} I \sin\theta d\theta d\varphi$$

The partial luminous flux  $\Phi_{\text{cone}}$  shall comply with the limiting values given in the manufacturer's data sheet.

### 9.2.4.3 Colour

The colour of an MLS is the colour of the light emitted into a cone of  $\theta = 45^\circ$  around the z axis. The chromaticity coordinates shall comply with the limiting values given in the manufacturer's data sheet.

## 9.2.5 Parameters determined per pixel

### 9.2.5.1 General

Subclause 9.2.5 covers parameters which are determined for each pixel individually.

Measurements of pixel parameters are made along the z-axis of the MLS.

The minimum distance between the grid and the aperture of the measurement equipment shall be 10-times the diameter of the smallest circle containing all pixels of the MLS.

### 9.2.5.2 Partial luminous flux

The partial luminous flux  $\Phi_{\text{cone},i}$  of a single-pixel "i" is the luminous flux emitted by this single pixel into a cone of  $\theta = 45^\circ$  around the z axis according to:

$$\Phi_{\text{cone},i} = \int_{\theta=0^\circ}^{\theta=45^\circ} \int_{\varphi=0}^{\varphi=2\pi} I_i \sin\theta d\theta d\varphi$$

for all pixels  $i = 1, \dots, (m \cdot n)$ .

The arithmetic average  $\Phi_{\text{cone,ave}}$  of the partial luminous flux of all pixels is:

$$\Phi_{\text{cone,ave}} = \sum_{i=1}^{m \cdot n} \Phi_{\text{cone},i} / (m \cdot n)$$

The relative deviation  $\Delta\Phi_{\text{cone},i} = |\Phi_{\text{cone},i} - \Phi_{\text{cone,ave}}|$  of each pixel shall comply with the limiting value given in the manufacturer's data sheet.



### 9.2.5.3 Colour

The colour of each pixel is the colour of the light emitted by this single pixel into a cone of  $\theta = 45^\circ$  around the z axis. The chromaticity coordinates shall comply with the limiting values given in the manufacturer's data sheet.

### 9.2.5.4 Luminous intensity distribution

The deviation of the luminous intensity distribution  $I(\theta)$  from a Lambertian distribution is tested in the following directions:

- $0^\circ$  (corresponding to the z-axis);
- $\pm 22,5^\circ$  and  $\pm 45^\circ$  (in the x-z plane);
- $\pm 22,5^\circ$  and  $\pm 45^\circ$  (in the y-z plane).

In each of these directions, the relative deviation characterized by the coefficient  $k$

$$k = | I(\theta) / (I(0^\circ) \cdot \cos\theta) - 1 |$$

shall comply with the upper limit  $k_{\max}$  given in the manufacturer's data sheet, whereby  $k_{\max}$  shall be 0,3 or less.

### 9.2.5.5 Luminance uniformity

The light emitting area (LEA) of a pixel is determined from the luminance measurements of an area with dimensions pitch  $p_x$  and pitch  $p_y$  which contains the whole pixel. The value  $L_{98}$  is the 98<sup>th</sup> percentile of all values of these luminance measurements.

The LEA of a pixel is the smallest circumferential rectangle having the same orientation as the grid and containing all luminance measurements with a value of 20 % or more of the value  $L_{98}$ .

In case the luminance does not drop below 20 % of the value  $L_{98}$  in this area, the nominal size of the pitch ( $p_x, p_y$ ) shall determine the LEA of a pixel.

The value  $L_{\text{ave}}$  is the arithmetic average of the values of all luminance measurements within the LEA.

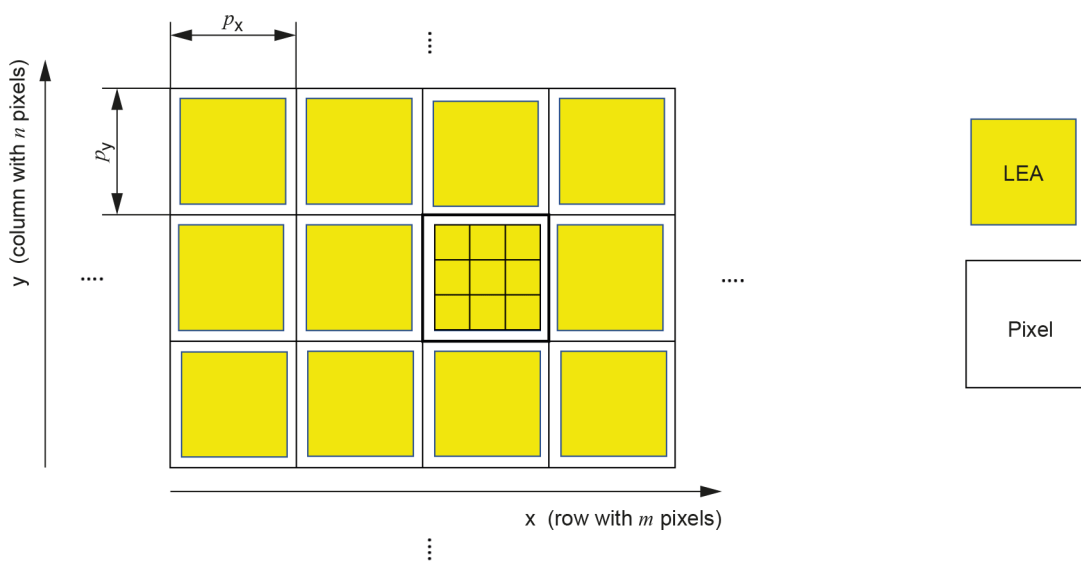
The LEA is subdivided into nine subsections (three by three rectangles of equal size), see Figure 1.

For each of the subsection ( $i = 1, \dots, 9$ ) the value  $L_i$  is the arithmetic average of the values of all luminance measurements in the corresponding subsection.

The value  $\Delta L$  is the maximum relative deviation of all luminance values  $L_i$  from the luminance value  $L_{\text{ave}}$ .

$$\Delta L = \text{Max} \{ |(L_i - L_{\text{ave}})/L_{\text{ave}}|; i = 1, \dots, 9 \}$$

The maximum relative deviation  $\Delta L$  shall comply with the limiting values given in the manufacturer's data sheet.



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**Figure 1 – Illustration of a grid of pixels with corresponding LEAs and subsections of pixels under test**

It is recommended to use a luminance camera with minimum 30 camera pixels for the smaller value of the pitch  $p_x$  and pitch  $p_y$ .

#### 9.2.5.6 Spatial colour uniformity

The LEA of a pixel and the subsections of the LEA shall be determined according to 9.2.5.5.

For each of the subsections ( $i = 1, \dots, 9$ ) the chromaticity coordinates  $x_i$  and  $y_i$  shall be determined.

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The spatial colour uniformity described by the values  $\Delta x$  and  $\Delta y$  according to

$$\Delta x = \text{Max } \{x_i\} - \text{Min } \{x_i\}; i = 1, \dots, 9$$

$$\Delta y = \text{Max } \{y_i\} - \text{Min } \{y_i\}; i = 1, \dots, 9$$

shall comply with the limiting values given in the manufacturer's data sheet.

#### 9.2.5.7 Gap width

The gap width shall be determined for all direct neighbour pixels in the x and y directions, while (at least) the two neighbour pixels are switched on, see Figure 2.

The gap width in the x-direction is determined from the luminance profile  $L(x)$ , averaging along the y axis over a width of LEA/3, starting from the centre of the LEA of the "pixel under test" with the nominal value of the pitch  $p_x$ .

The gap width in the y-direction is determined from the luminance profile  $L(y)$ , averaging along the x axis over a width of LEA/3, starting from the centre of the LEA of the "pixel under test" with the nominal value of the pitch  $p_y$ .

The gap width is characterized by the parameters  $g_{50}$  and  $g_{90}$ , which are determined at a luminance level of 50 %, respectively 90 %, of the average luminance of the corresponding luminance profiles ( $L(x)$  and  $L(y)$  respectively), see Figure 3. In case the luminance profile does not drop below 50 % of the average, the  $g_{50}$  value is zero.

The gap widths  $g_{50}$  and  $g_{90}$  for all pairs of neighbour pixels shall comply with the limiting values given in the manufacturer's data sheet.

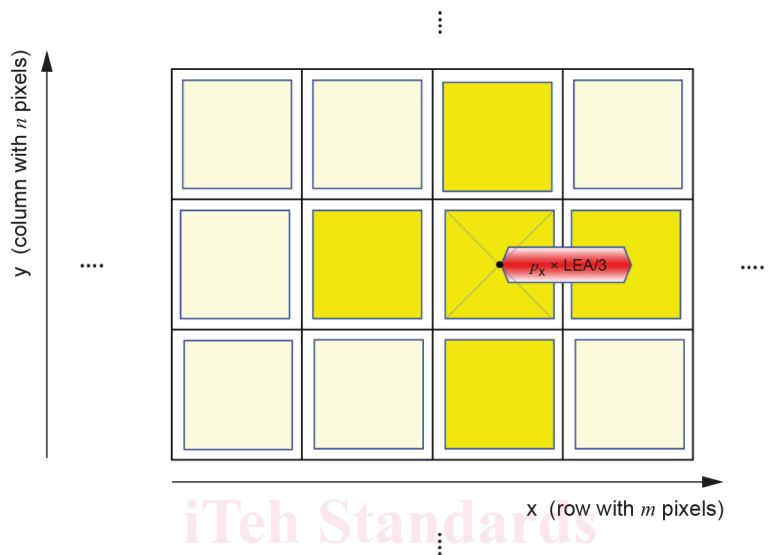


Figure 2 – Illustration of method to determine the gap width

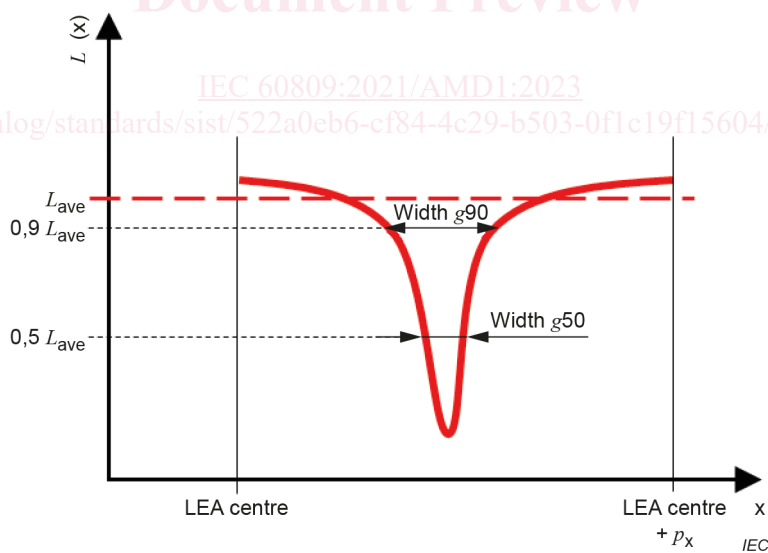


Figure 3 – Example of gap width characterization (luminance profile)

It is recommended to use a luminance camera with minimum 30 camera pixels for the smaller value of the pitch  $p_x$  and pitch  $p_y$  which is able to detect a luminance contrast ratio of at least 200.

### 9.2.6 Characteristic parameters for luminance contrast behaviour

The luminance contrast shall be determined for each row and column separately, while the row, respectively column under test is switched on and the neighbour row(s), respectively column(s) are switched off.