



SLOVENSKI STANDARD
SIST ISO 5290:1997
01-december-1997

Jermenski pogoni - Profil žleba jermenice za vzporedno vezane ozke klinaste jermene - Sekcije žlebov vrste 9J, 15J, 20J in 25J

Belt drives -- Grooved pulleys for joined narrow V-belts -- Groove sections 9J, 15J, 20J, and 25J (effective system)

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Transmissions par courroies -- Poulies à gorges pour courroies trapézoïdales jumelées étroites -- Sections de gorge 9J, 15J, 20J et 25J (système effectif)

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Ta slovenski standard je istoveten z: ISO 5290:1993

ICS:

21.220.10	Jermenski pogoni in njihovi deli	Belt drives and their components
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INTERNATIONAL STANDARD

ISO
5290

Third edition
1993-04-15

Belt drives — Grooved pulleys for joined narrow V-belts — Groove sections 9J, 15J, 20J and 25J (effective system)

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*Transmissions par courroies — Poulies à gorges pour courroies
trapézoïdales jumelées étroites — Sections de gorge 9J, 15J, 20J et 25J
(système effectif)*

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Reference number
ISO 5290:1993(E)

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

International Standard ISO 5290 was prepared by Technical Committee ISO/TC 41, *Pulleys and belts (including veebelts)*, Sub-Committee SC 1, *Veebelts and grooved pulleys*.

This third edition cancels and replaces the second edition (ISO 5290:1985), which has been technically revised. In particular, clauses 3, 5 and 6 have been added.

Annexes A and B of this International Standard are for information only.

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Belt drives — Grooved pulleys for joined narrow V-belts — Groove sections 9J, 15J, 20J and 25J (effective system)

1 Scope

This International Standard specifies the principal characteristics of grooved pulleys (for groove sections 9J, 15J, 20J and 25J), intended to take joined narrow V-belts for industrial power transmission drives.

Some background information on the series of effective diameters is given in annex A.

NOTES

1 The effective width of a groove is regarded as the basic dimension of standardization for grooves and for the corresponding joined V-belts considered as a whole.

2 The pitch line position can only be given, approximately. The approximate pitch diameter of a pulley can be calculated by the formula

$$d_p = d_e - 2b_e$$

2 Normative references

The following standards contain provisions which, through reference in this text, constitute provisions of this International Standard. At the time of publication, the editions indicated were valid. All standards are subject to revision, and parties to agreements based on this International Standard are encouraged to investigate the possibility of applying the most recent editions of the standards indicated below. Members of IEC and ISO maintain registers of currently valid International Standards.

ISO 254:1990, *Belt drives — Pulleys — Quality, finish and balance.*

ISO 1081:1980, *Drives using V-belts and grooved pulleys — Terminology.*

ISO 9980:1990, *Belt drives — Grooved pulleys for V-belts (system based on effective width) — Geometrical inspection of grooves.*

3 Definitions and symbols

For the purposes of this International Standard, the terms and symbols relating to drives using V-belts (i.e. belts and grooved pulleys) defined in ISO 1081 apply.

4 Specifications

4.1 Groove profiles

4.1.1 Groove angle, α

The groove angle (see figure 1) shall have one of the following values:

- $\alpha = 36^\circ$ (for groove section 9J only)
- $\alpha = 38^\circ$
- $\alpha = 40^\circ$
- $\alpha = 42^\circ$

The relationship between the groove angle and the range of effective diameters which should be used is given in table 3.

4.1.2 Profile dimensions

The dimensions shown in figures 1 and 2 shall have the values specified in table 1.

NOTE 3 The straight sides of the groove should be at least as high as $d_e - 2\delta h_2$.

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4.2 Effective diameter, d_e

4.2.1 Series of effective diameters

See table 2.

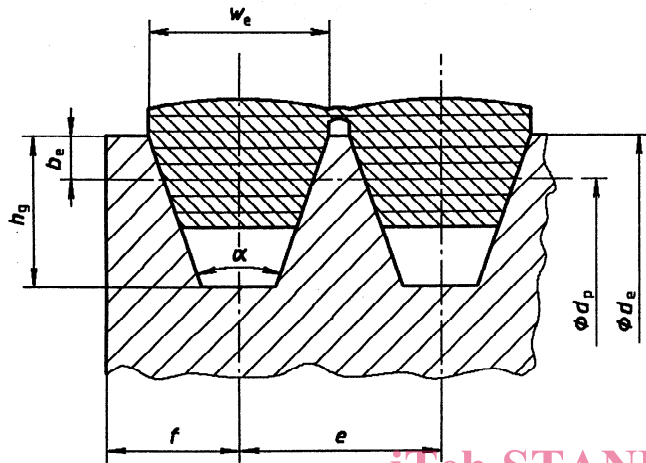


Figure 1

4.2.2 Groove angles in relation to given effective diameters

See table 3.

4.2.3 Smallest effective diameters in relation to given groove sections

See table 4.

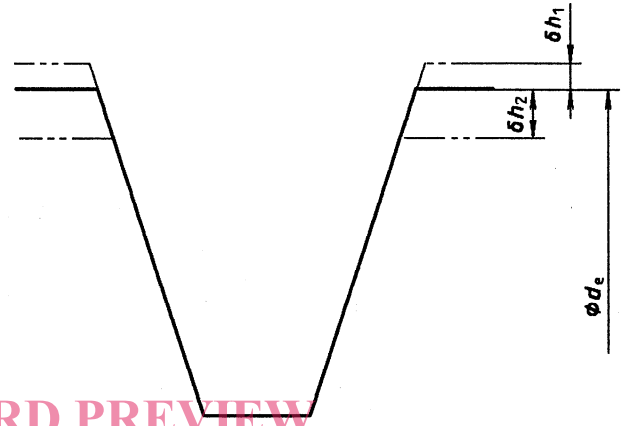


Figure 2

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Table 1 — Profile dimensions

Dimensions and tolerances in millimetres

Groove section ¹⁾	w_e	δh_1	δh_2	b_e	h_g min.	e	Tolerance on e ²⁾	Sum of deviations of e ³⁾	f min.
9J	8,9	0,2	0,3	0,6	8,9	10,3	$\pm 0,25$	$\pm 0,5$	9
15J	15,2	0,25	0,4	1,3	15,2	17,5	$\pm 0,25$	$\pm 0,5$	13
20J	20,9	0,3	0,45	1,8	20,9	24,4	$\pm 0,3$	$\pm 0,6$	17
25J	25,4	0,3	0,5	2,5	25,4	28,6	$\pm 0,4$	$\pm 0,8$	19

1) It will be left to the discretion of the individual national standards organizations whether either groove section 20J or groove section 25J will be adopted in their national standards.

2) This tolerance applies to the distance between the axes of two consecutive groove profiles.

3) The sum of all deviations from the nominal value e for all grooves in any one pulley should not exceed the value stated in this table.

Table 2 — Series of effective diameters

Dimensions in millimetres

nom.	d_e min.	Groove sections							
		9J		15J		20J		25J	
		Status ¹⁾	d_e max.	Status ¹⁾	d_e max.	Status ¹⁾	d_e max.	Status ¹⁾	d_e max.
67 71	67 71	* **	71 75						
75 80	75 80	* **	79 84						
85 90	85 90	* **	89 94						
95 100	95 100	* **	99 104						
106 112	106 112	* **	110 116						
118 125	118 125	* **	122 129						
132 140	132 140	* **	136 144						
150 160	150 160	* **	154 164						
170 180	170 180	*	184	*	187				
190 200	190 200	**	204	* **	197 207				
212 224	212 224	*	228	* **	219 231				
236 250	236 250	**	254	* **	243 257				
265 280	265 280	*	284,5	* **	272 287	* **	274,6 289,6		
300 315	300 315	**	320	* **	307 322	* **	309,6 324,6	**	320
335 355	335 355	*	360,7	*	362	* **	344,6 364,6	* **	340,4 360,7
375 400	375 400	**	406,4	**	407	* **	384,6 409,6	* **	381 406,4
425 450	425 450	*	457,2	*	457,2	* **	434,6 459,6	* **	431,8 457,2
475 500	475 500	**	508	**	508	* **	484,6 509,6	* **	482,6 508
530 560	530 560	*	569	*	569	*	569,6	* **	538,5 569

nom.	d_e min.	Groove sections							
		9J		15J		20J		25J	
		Status ¹⁾	d_e max.	Status ¹⁾	d_e max.	Status ¹⁾	d_e max.	Status ¹⁾	d_e max.
600 630	600 630	*	640,1	**	640,1	**	640,1	*	609,6 640,1
670 710	670 710	*	721,4	*	721,4	*	721,4	*	721,4
750 800	750 800	*	812,8	**	812,8	**	812,8	**	812,8
850 900	850 900			*	914,4	*	914,4	*	914,4
950 1 000	950 1 000			**	1 016	**	1 016	**	1 016
1 060 1 120	1 060 1 120			*	1 137,9	*	1 137,9	*	1 137,9
1 180 1 250	1 180 1 250			**	1 270	**	1 270	**	1 270
1 320 1 400	1 320 1 400			*	1 422,4	*	1 422,4	*	1 422,4
1 500 1 600	1 500 1 600			*	1 625,6	**	1 625,6	**	1 625,6
1 700 1 800	1 700 1 800			*	1 828,8	*	1 828,8	*	1 828,8
1 900 2 000	1 900 2 000			**	2 032	**	2 032	**	2 032
2 120 2 240	2 120 2 240							*	2 275,8
2 360 2 500	2 360 2 500							**	2 540

1) Effective diameters marked with a double asterisk (**) are especially recommended.
Effective diameters marked with a single asterisk (*) are recommended.

Table 3 — Groove angles

Dimensions in millimetres

Groove section	Groove angles, α			
	36°	38°	40°	42°
	Effective diameters, d_e			
9J	$d_e \leq 90$	$90 < d_e \leq 150$	$150 < d_e \leq 300$	$d_e > 300$
15J		$d_e \leq 250$	$250 < d_e \leq 400$	$d_e > 400$
20J		$d_e \leq 335$	$335 < d_e \leq 500$	$d_e > 500$
25J		$d_e \leq 400$	$400 < d_e \leq 560$	$d_e > 560$

Table 4 — Smallest effective diameters

Groove section	Smallest effective diameter
	mm
9J	67
15J	180
20J	265
25J	315

5 Geometrical inspection of grooves

5.1 Groove profile

The corresponding limit gauges in accordance with 3.2.3 of ISO 9980:1990 shall be used.

5.2 Groove spacing

A groove spacing locator incorporating sets of interchangeable balls as indicated in 5.3 and in accordance with clause 4 of ISO 9980:1990 shall be used.

5.3 Effective diameter

Cylindrical checking balls shall be used with the values of the correction term given in table 5, in accordance with clause 5 of ISO 9980:1990.

5.4 Run-out tolerances

In accordance with clause 6 of ISO 9980:1990, the tolerances on radial and axial run-outs shall be checked using the values given in table 6.

6 Quality, surface finish and balancing of pulleys

The quality, surface finish and balancing of pulleys are specified in ISO 254.

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Table 5 — Checking balls or rods and correction terms

Dimensions in millimetres

Groove section	Groove angle α	Diameter of balls or rods		Rounded correction term $2h_s$
		nom.	d tol. ¹⁾	
9J	36° to 42°	9	$\begin{matrix} 0 \\ -0,036 \end{matrix}$	11
15J	38° to 42°	14,7	$\begin{matrix} 0 \\ -0,043 \end{matrix}$	16
20J	38° to 42°	20	$\begin{matrix} 0 \\ -0,052 \end{matrix}$	21
25J	38°	25	$\begin{matrix} 0 \\ -0,052 \end{matrix}$	28
	40°			28
	42°			29

1) Tolerances are in accordance with ISO 286-2:1988, tolerance grade h9.