
International Standard



7134

INTERNATIONAL ORGANIZATION FOR STANDARDIZATION • МЕЖДУНАРОДНАЯ ОРГАНИЗАЦИЯ ПО СТАНДАРТИЗАЦИИ • ORGANISATION INTERNATIONALE DE NORMALISATION

Earth-moving machinery — Graders — Terminology and commercial specifications

Engins de terrassement — Niveleuses — Terminologie et spécifications commerciales

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Descriptors : earth moving equipment, excavating equipment, graders, vocabulary.

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work.

Draft International Standards adopted by the technical committees are circulated to the member bodies for approval before their acceptance as International Standards by the ISO Council. They are approved in accordance with ISO procedures requiring at least 75 % approval by the member bodies voting.

International Standard ISO 7134 was prepared by Technical Committee ISO/TC 127, *Earth-moving machinery*.

Users should note that all International Standards undergo revision from time to time and that any reference made herein to any other International Standard implies its latest edition, unless otherwise stated.

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Earth-moving machinery — Graders — Terminology and commercial specifications

1 Scope

This International Standard establishes terminology and the content of commercial literature specifications for self-propelled graders and their equipment.

2 Field of application

This International Standard applies to graders as defined in clause 4.

3 References

ISO 1585, *Road vehicles — Engine test code — Net power.*

ISO 3450, *Off-highway earth-moving machinery — Minimum performance criteria for brake systems.*

ISO 5010, *Earth-moving machinery — Rubber-tired machines — Steering systems.*

ISO 6014, *Earth-moving machinery — Determination of ground speed.*

ISO 6165, *Earth-moving machinery — Basic types — Vocabulary.*

ISO 6746, *Earth-moving machinery — Definitions of dimensions and symbols —*

Part 1 : Base machine.

Part 2 : Equipment.

ISO 7457, *Earth-moving machinery — Measurement of turning dimensions of wheeled machines.*

4 General definitions

4.1 grader : A self-propelled wheeled machine having an adjustable blade, positioned between front and rear axles, which cuts, moves and spreads materials usually to grade requirements. (See ISO 6165.)

4.2 base machine : A grader without equipment as described by the manufacturer specifications. The machine should be provided with the necessary mountings to secure attachments as shown in clause 6.

4.3 equipment : A set of components mounted onto the base machine to fulfil the primary design function.

4.4 attachment : An optional assembly of components that can be mounted onto the base machine for a specific use.

4.5 component : A part or an assembly of parts of a base machine, equipment or an attachment.

5 Base machine

5.1 Types of graders

5.1.1 Undercarriage — Number of wheels

5.1.1.1 Four wheel (figure 1)

5.1.1.2 Six wheel (figure 2)

5.1.2 Number of engines

5.1.2.1 One engine (figure 3)

5.1.2.2 Two engine (figure 4)

5.1.3 Engine location

5.1.3.1 Front engine (figure 5)

5.1.3.2 Rear engine (figure 6)

5.1.4 Steering system

5.1.4.1 Front wheel steer (figure 7)

5.1.4.2 Front wheel and rear wheel steer (figure 8)

5.1.4.3 Front wheel and rear bogie steer (figure 9)

5.1.4.4 Front wheel and articulated frame steer (figure 10)

5.1.4.5 Double articulated frame steer (figure 11)

5.1.5 Drive system

5.1.5.1 Two wheel drive (figure 12)

5.1.5.2 Four wheel drive (figure 13)

5.1.5.3 Six wheel drive (figure 14)

Undercarriage — Number of wheels (see 5.1.1)

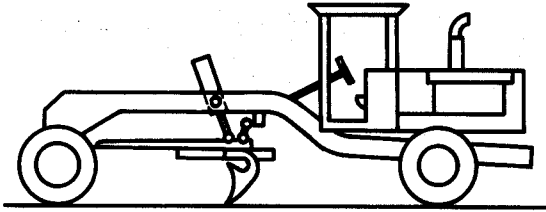


Figure 1 — Four wheel grader

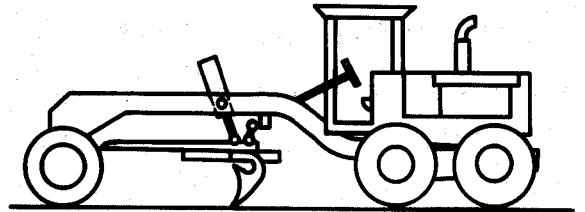


Figure 2 — Six wheel grader

Number of engines (see 5.1.2)

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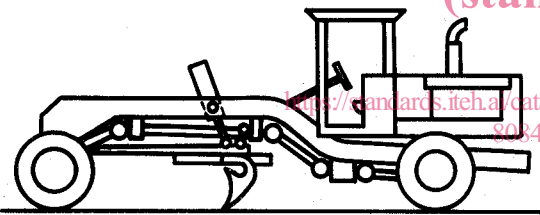


Figure 3 — One engine grader

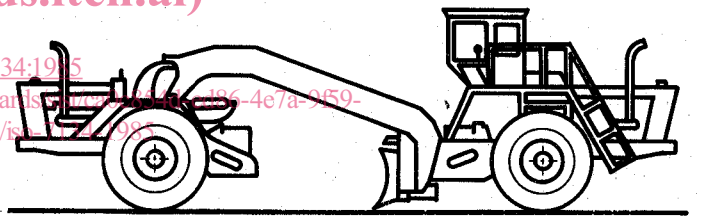


Figure 4 — Two engine grader

Engine location (see 5.1.3)

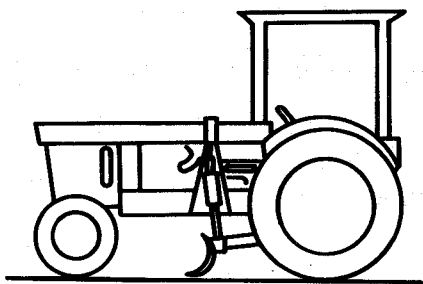


Figure 5 — Front engine grader

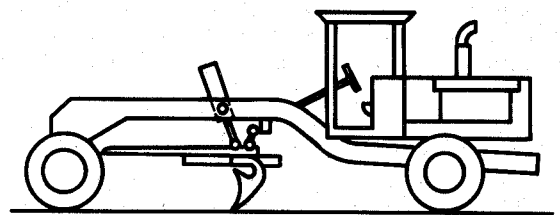


Figure 6 — Rear engine grader

Steering system (see 5.1.4)

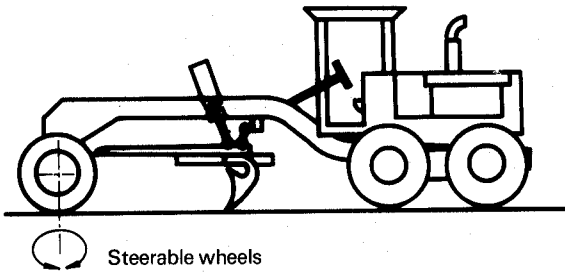


Figure 7 — Front wheel steer grader

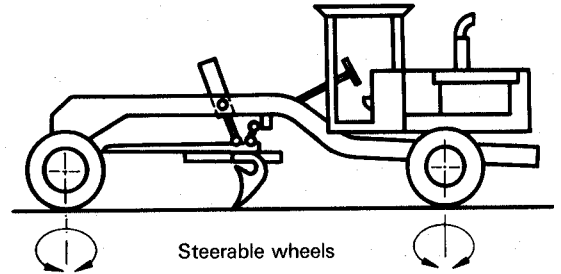


Figure 8 — Front wheel and rear wheel steer grader

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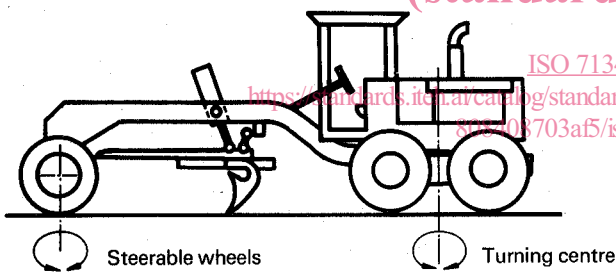


Figure 9 — Front wheel and rear bogie steer grader

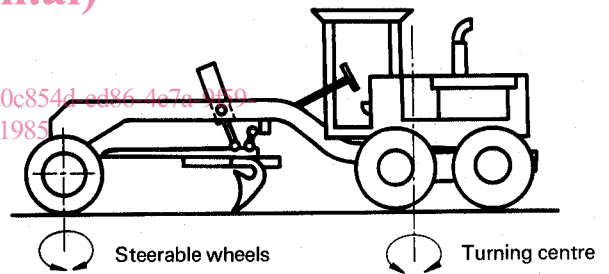


Figure 10 — Front wheel and articulated frame steer grader

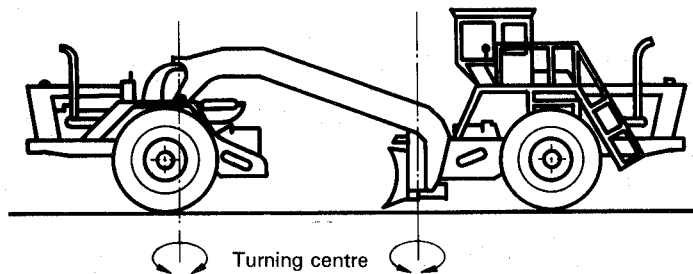


Figure 11 — Double articulated frame steer grader

Drive system (see 5.1.5)

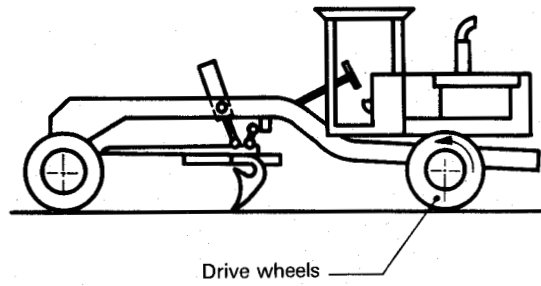


Figure 12 — Two wheel drive grader

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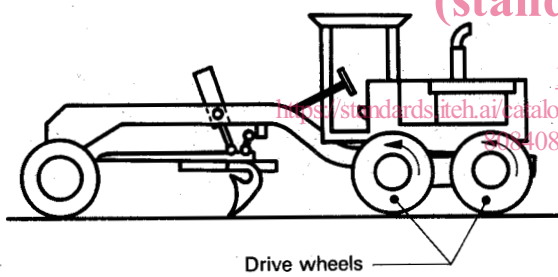


Figure 13a) — Four wheel drive grader

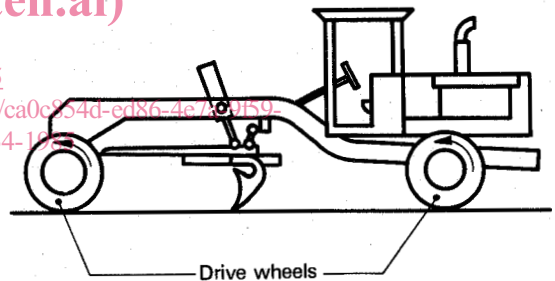


Figure 13b) — Four wheel drive grader

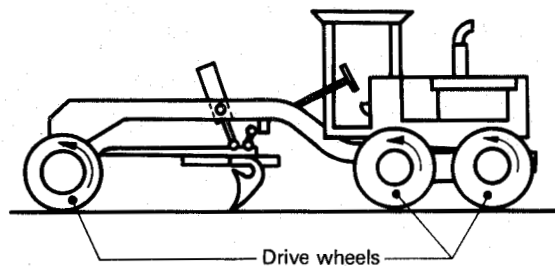
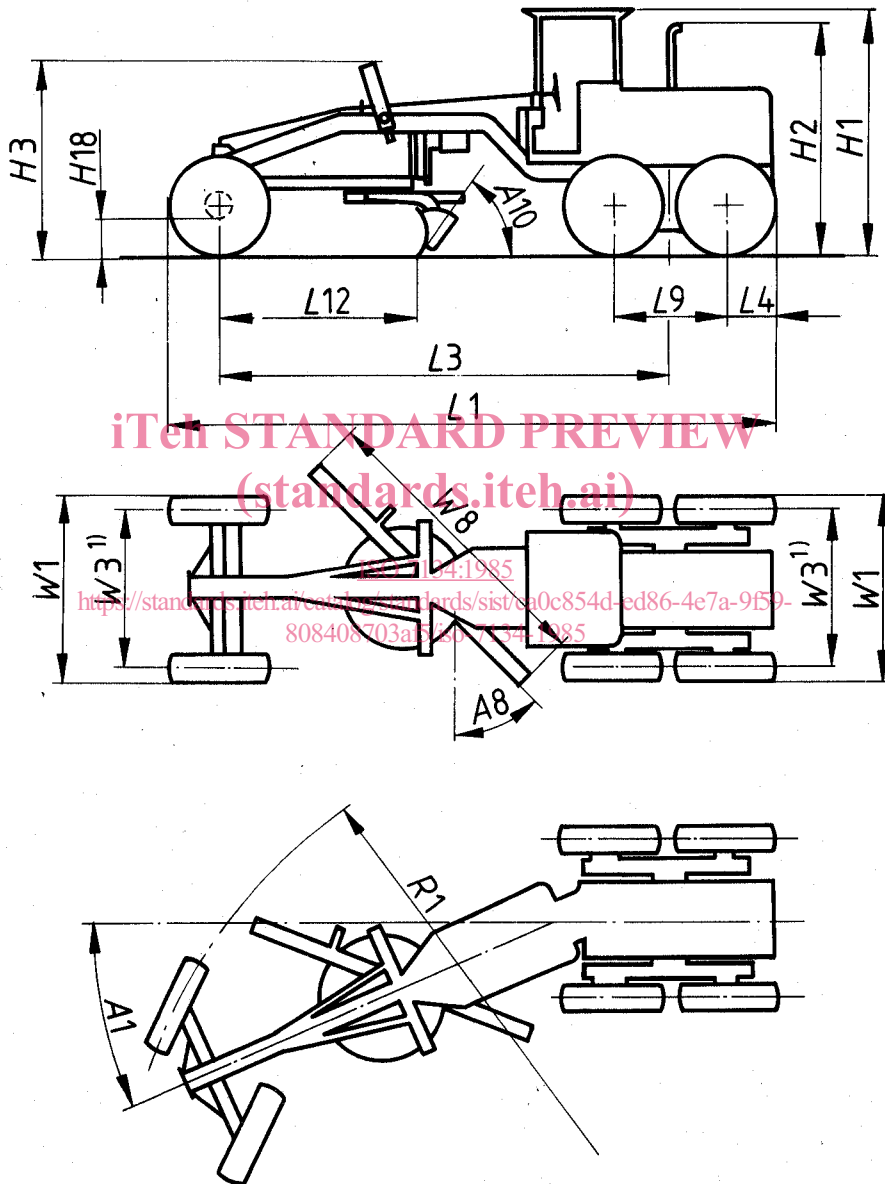


Figure 14 — Six wheel drive grader

5.2 Dimensions (see figure 15)

For definitions of dimensions, see ISO 6746/1.

For definitions of dimensions strictly related to graders, and dimensions $H18$, $H19$, $W9$, $W14$, $W15$, $A9$, $A11$, $A12$, see annex A.



1) Wheel tread ($W3$) can be different for front and rear tyres.

Figure 15 – Dimensions of base machine (grader)

5.3 Masses

5.3.1 operating mass : The mass of the base machine, equipment specified by the manufacturer, operator (75 kg), full fuel tank, and full lubricating, hydraulic and cooling systems.

5.3.2 shipping mass : The mass of the base machine without operator, with full lubricating, hydraulic and cooling system, 10 % of fuel tank capacity and with or without equipment, cab, canopy, ROPS¹⁾ or FOPS²⁾, as stated by the manufacturer.

5.3.3 cab, canopy, ROPS or FOPS mass (if optional attachment) : The mass of cab, canopy, ROPS or FOPS with all their components and mountings required to secure these to the base machine.

5.4 Component nomenclature (see diagram numbers)

- 1 Blade
- 2 Cutting edge
- 3 Bit, end
- 4 Arm, blade
- 5 Bracket, blade pitch
- 5A Cylinder, blade pitch
- 6 Circle
- 7 Drawbar
- 8 Link, blade lift
- 8A Cylinder, blade lift
- 9 Lift, blade
- 10 Drive, circle
- 11 Link, circle sideshift
- 11A Cylinder, circle sideshift
- 12 Circle sideshift
- 13 Frame, main
- 14 Drive, tandem
- 15 Axle, front
- 16 Cylinder, wheel lean
- 17 Tie bar, wheel lean
- 18 Pin, axle pivot
- 19 Control, power
- 20 Drive, front, mechanical
- 20A Drive, front (hydraulic)
- 21 Drive, rear
- 22 Canopy, ROPS
- 23 Cab, ROPS
- 24 Frame, engine
- 25 Lock, lift arm
- 26 Arm, lift
- 27 Cylinder, blade sideshift
- 28 Cylinder, rear steer
- 29 Plate, attachment

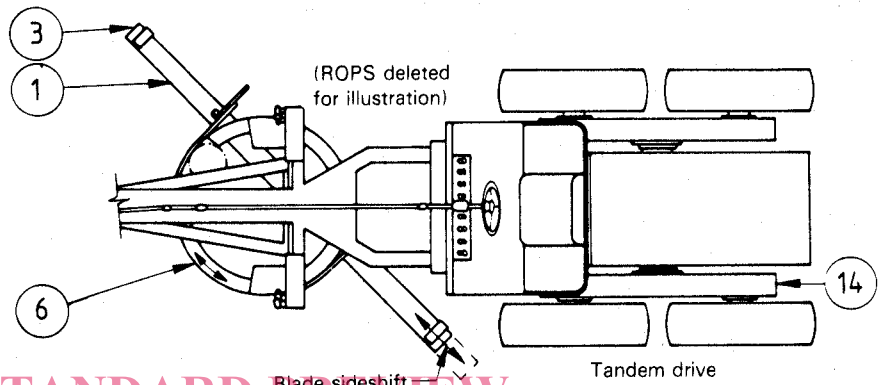
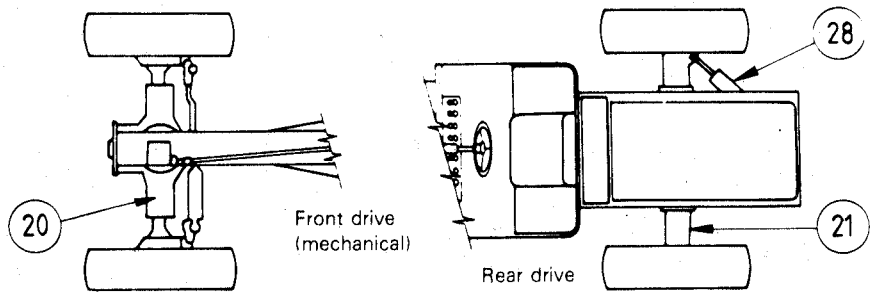
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1) ROPS — Roll-over protective structure.

2) FOPS — Falling object protective structure.



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