



Edition 1.0 2007-08

INTERNATIONAL STANDARD

NORME INTERNATIONALE

Ultrasonics – Hydrophones FANDARD PREVIEW Part 2: Calibration for ultrasonic fields up to 40 MHz (standards.iten.al)

Ultrasons – Hydrophones – Partie 2: Etalonnage des champs ultrasoniques jusqu'à 40 MHz 18069dd7887friec-62127-2-2007





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INTERNATIONAL ELECTROTECHNICAL COMMISSION

COMMISSION ELECTROTECHNIQUE INTERNATIONALE

PRICE CODE CODE PRIX

ICS 17.140.50

ISBN 978-2-83220-136-7

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CONTENTS

FOREWORD				
INT	RODI	JCTION.		7
1	Scop	e		8
2	Norm	ative ref	erences	8
3	Term	s, definit	ions and symbols	9
4	List c	of symbol	S	.13
5			alibration procedures	
Ū	5.1		es	
	5.2	•	ry of calibration procedures	
	5.3		ng of results	
	5.4	•	nended calibration periods	
6			rements of a hydrophone calibration system	
-	6.1	-	ical positioning	
	0.1		General	
			Accuracy of the axial hydrophone position	
			Accuracy of the lateral hydrophone position	
	6.2		ature measurements and temperature stability	
	6.3	Hydroph	none size	. 20
	6.4	Measure	ement vessel and water properties ten.ai)	20
	6.5	Measure	ement of output voltage	20
7	Elect	rical con	siderations IEC 62127-2:2007 https://standards.iteh.ai/catalog/standards/sist/ee6f911b-8810-48d0-af25-	21
	7.1	Signal t	https://standards.iten.av/catalog/standards/sist/ee01911b-8810-48d0-at25- ype	21
	7.2]	
	7.3	Measure	ement of hydrophone output voltage	.21
		7.3.1	General	21
		7.3.2	Electrical loading by measuring instrument	.21
			Electrical loading by extension cables	
			Noise	
			Cross-talk (radio-frequency rf pick-up) and acoustic interference	
			Integral hydrophone pre-amplifiers	
8	Prepa	aration of	f hydrophones	23
	8.1		l	
	8.2	0		
	8.3	• •	none support	
	8.4		e of cable	
9			procity calibration	
	9.1			
	9.2	•		
	9.3		principles	
			General	
			Three-transducer reciprocity calibration method	
			Self-reciprocity calibration method	
	0.4		Two-transducer reciprocity calibration method	
	9.4		nsducer reciprocity calibration method	
		9.4.1	Apparatus	24

		9.4.2	Procedure	
10	Free	field cal	ibration by planar scanning	. 25
	10.1		l	
		•		
			I principle	
	10.4		ural requirements	
			Hydrophone scanning	
	10.5		ure	
			Power measurement	
			Transducer mounting Measurement conditions	
			Measurements	
	10.6		ions and sources of uncertainty	
11			ibration by optical interferometry	
			le	
12		•	/ comparison using a standard hydrophone	
12	12.1			
		-		
	12.5	Proced	le ural requirements ANDARD PREVIEW	23
	12.7			
		12.4.2	Source transducer drive signal	
			Measurement system . _{IEC 62127-2.2007}	
	12.5		urettps://standards.iteh.ai/catalog/standards/sist/ce6f911b-8810-48d0-af25	
			Measurements (Type4).7determination-of the directional response of a hydrophone	
		12.5.2	Measurements (Type II): calibration by comparison using a standard hydrophone	
	12.6	Maxim	um hydrophone size	
	•			
			tive) Assessment of uncertainty in free field calibration of	32
•	•		tive) Behaviour of PVDF polymer sensors in high intensity ultrasonic	
				. 34
Anr	nex C	(informa	tive) Electrical loading corrections	37
			tive) Absolute calibration of hydrophones using the planar scanning	38
Anr	nex E	(informa	tive) Properties of water	46
		•	tive) The absolute calibration of hydrophones by optical	-
			to 40 MHz	48
Anr	nex G	(informa	tive) Waveform concepts	. 58
Anr	nex H	(informa	tive) Time delay spectrometry – requirements and a brief review of	
				. 68
Anr	nex I (informat	ive) Determination of the phase response of hydrophones	71
			tive) Maximum size considerations for the active element of a	
hyd	lropho	ne		77

Bibliography	79
Figure F.1 – Experimental set-up of the interferometric foil technique	51
Figure F.2 – End-of-cable open-circuit sensitivity, $M_{\rm C}$, of a coplanar membrane hydrophone	53
Figure F.3 – Hydrophone waveform generated by a 9 μ m coplanar membrane hydrophone positioned at the focus of a 5 MHz transducer (focal length 51 mm)	54
Figure F.4 – Interferometer (displacement) waveform generated with the pellicle positioned at the focus of the 5 MHz transducer (focal position 51 mm)	55
Figure F.5 – Frequency spectrum of the displacement waveform (lower curve) and the differentiated displacement waveform (upper curve)	55
Figure F.6 – Sensitivity of a 0,2 mm active element diameter of a 9 μ m bilaminar membrane hydrophone determined at 5 MHz intervals over the frequency range 5 MHz to 60 MHz	56
Figure G.1 – Coordinates of a field point, P, in the near field of a plane- circular source transducer of radius, a_t	65
Figure I.1 – Phase of end-of-cable open-circuit sensitivity for two membrane hydrophones	73
Figure I.2 – Phase of end-of-cable open-circuit sensitivity for a Ø0,2 mm needle hydrophone	75
Table 1 – List of typical uncertainty values obtained by the calibration methods specified in this standard and for the frequency range listed here	17
Table E.1 – Speed of sound c [,] and specific acoustic impedance, ρc , as a function of temperature, for propagation in water	46
Table G.1 – Temporal waveform and hydrophone position concepts described in this Annex	

Table I.1 – Example of uncertainties (where a coverage factor, k = 2, is used) for a	
HTDS phase calibration of a needle hydrophone with a diameter of 0,2 mm, expressed	
at a confidence level of 95 %7	3

- 4 -

INTERNATIONAL ELECTROTECHNICAL COMMISSION

ULTRASONICS – HYDROPHONES –

Part 2: Calibration for ultrasonic fields up to 40 MHz

FOREWORD

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International Standard IEC 62127-2 has been prepared by IEC technical committee 87: Ultrasonics.

IEC 62127-1, IEC 62127-2 and IEC 62127-3 are being published simultaneously. Together these cancel and replace IEC 60866:1987, IEC 61101:1991, IEC 61102:1991, IEC 61220:1993 and IEC 62092:2001.

This bilingual version (2012-06) corresponds to the monolingual English version, published in 2007-08.

The text of this standard is based on the following documents:

Enquiry draft	Report on voting
87/353/CDV	87/372/RVC

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

The French version of this standard has not been voted upon.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of IEC 62127 series, published under the general title Ultrasonics -Hydrophones, can be found on the IEC website.

NOTE Words in **bold** in the text are defined in Clause 3.

The committee has decided that the contents of this publication will remain unchanged until the maintenance result date indicated on the IEC website under "http://webstore.iec.ch" in the data related to the specific publication. At this date, the publication will be

- reconfirmed; •
- withdrawn;
- replaced by a revised edition; or
- (standards.iteh.ai) amended.

The contents of the corrigendum of August 2008 have been included in this copy.

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INTRODUCTION

The spatial and temporal distribution of acoustic pressure in an ultrasonic field in a liquid medium is commonly determined using miniature ultrasonic **hydrophones**. These devices are not absolute measurement instruments and require calibration. The purpose of this part of IEC 62127 is to specify those calibration methods to be used in determining the response of a **hydrophone** in the ultrasonic range, i.e. above 20 kHz up to a frequency of 40 MHz. The main **hydrophone** application in this context lies in the measurement of ultrasonic fields emitted by medical diagnostic equipment in water. **Hydrophone** behaviour over this wide frequency band is required in order to reliably characterize the acoustic parameters of the applied acoustic field. In particular, the frequency range above 15 MHz is important to fully characterize this equipment, primarily due to the increased appearance of high-frequency components in the ultrasonic signals, caused by non-linear propagation. In addition, the number of medical ultrasonic systems that use frequencies above 15 MHz, particularly intra-operative probes, is growing. It has turned out in recent years that the **hydrophone** response below 0,5 MHz is also required to reliably determine the peak-negative (rarefactional) acoustic pressure.

While the term "hydrophone" can be used in a wider sense, it is understood here as referring to miniature piezoelectric hydrophones. It is this instrument type that is used today in various areas of medical ultrasonics and, in particular, to characterize quantitatively the field structure of medical diagnostic instruments. With regard to other pressure sensor types, such as those based on fibre optics, some of the requirements of this standard are applicable to these as well but others are not. If in the future these other "hydrophone" types gain more importance in field measurement practice, their characteristics and calibration will have to be dealt with in a revised version of this standard or in a separate one.

NOTE This standard covers the ultrasonic frequency range, from 20 kHz to an upper frequency of 40 MHz. Standards dealing with hydrophone properties (IEC 62127-3) and hydrophone use (IEC 62127-1) are being developed in parallel as part of a programme of maintenance activities aimed at restructuring and merging, where possible, all existing ultrasonic hydrophone standards. This will eventually lead to unified standards covering the whole field of practical hydrophone application talog/standards/sist/ee6f911b-8810-48d0-af25-

18069dd7887f/iec-62127-2-2007

ULTRASONICS – HYDROPHONES –

Part 2: Calibration for ultrasonic fields up to 40 MHz

1 Scope

This part of IEC 62127 specifies:

- absolute hydrophone calibration methods;
- relative (comparative) hydrophone calibration methods.

Recommendations and references to accepted literature are made for the various relative and absolute calibration methods in the frequency range covered by this standard.

This standard is applicable to

 hydrophones used for measurements made in water and in the ultrasonic frequency range up to 40 MHz;

NOTE 1 Although some physiotherapy medical applications of medical ultrasound are developing which operate in the frequency range 40 kHz to 100 kHz, the primary frequency range of diagnostic imaging remains above 2 MHz. It has recently been established that, even in the latter case, the **hydrophone** response at substantially lower frequencies can influence measurements made of key acoustic parameters [1].

 hydrophones employing circular piezoelectric sensor elements, designed to measure the pulsed wave and continuous wave ultrasonic fields generated by ultrasonic equipment;

NOTE 2 Some hydrophones can have non-circular active elements, arising from slight deviations from a circular structure caused, for example by electrode structure, or conversely, the active elements can actually be squares. The clauses within this standard/remain valid, although, in these cases, special attention should be paid to the directional response and to the effective radii of the active element through various axes of rotation.

• hydrophones with or without a hydrophone pre-amplifier.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60050-801:1994, International Electrotechnical Vocabulary – Chapter 801: Acoustics and electro-acoustics

IEC 60565, Underwater acoustics – Hydrophones – Calibration in the frequency range 0,01 Hz to 1 MHz

IEC 61161:2006, Ultrasonics – Power measurement – Radiation force balances and performance requirements

IEC 61828:2006, Ultrasonics – Focusing transducers – Definitions and measurement methods for the transmitted fields

IEC 62127-1, Ultrasonics – Hydrophones – Part 1: Measurement and characterization of medical ultrasonic fields up to 40 MHz

IEC 62127-3, Ultrasonics – Hydrophones – Part 3: Properties of hydrophones for ultrasonic fields up to 40 MHz

3 Terms, definitions and symbols

For the purposes of this document, the terms and definitions given in IEC 62127-1 and the following apply.

3.1

acoustic centre

point on or near a transducer from which the spherically divergent sound waves emitted by the transducer, and observable at remote points, appear to diverge

3.2

beam axis

straight line that passes through the **beam centrepoints** of two planes perpendicular to the line which connects the point of maximal **pulse-pressure-squared integral** with the centre of the **external transducer aperture**

NOTE 1 The location of the first plane is the location of the plane containing the maximum **pulse-pressure-squared integral** or, alternatively, is one containing a single main lobe which is in the focal Fraunhofer zone. The location of the second plane is as far as is practicable from the first plane and parallel to the first with the same two orthogonal scan lines (*x* and *y* axes) used for the first plane.

NOTE 2 In a number of cases, the term **pulse-pressure-squared integral** is replaced in the above definition by any linearly related quantity, for example

- a) in the case of a continuous wave signal the term **pulse-pressure-squared integral** is replaced by mean square acoustic pressure as defined in IEC 61689, NDARD PREVIEW
- b) in cases where signal synchronisation with the scanframe is not available the term **pulse-pressure-squared** integral may be replaced by temporal average intensity. Iten.al)

NOTE 3 See Figure 1 of IEC 62127-1.

IEC 62127-2:2007

NOTE 4 Definition adopted:/fromdECs62127/datalog/standards/sist/ee6f911b-8810-48d0-af25-18069dd7887f/iec-62127-2-2007

3.3

beam centrepoint

position determined by the intersection of two lines passing through the **beamwidth midpoints** of two orthogonal planes, xz and yz

NOTE Definition adopted from IEC 61828:2001.

3.4 beamwidth w₆, w₁₂, w₂₀

greatest distance between two points on a specified axis perpendicular to the **beam axis** where the **pulse-pressure-squared integral** falls below its maximum on the specified axis by a specified amount

NOTE 1 In a number of cases, the term **pulse-pressure-squared integral** is replaced in the above definition by any linearly related quantity, for example

- a) in the case of a continuous wave signal the term **pulse-pressure-squared integral** is replaced by mean square acoustic pressure as defined in IEC 61689,
- b) in cases where signal synchronisation with the scanframe is not available the term **pulse-pressure-squared integral** may be replaced by **temporal average intensity**.

NOTE 2 Commonly used **beamwidths** are specified at $-6 \, \text{dB}$, $-12 \, \text{dB}$ and $-20 \, \text{dB}$ levels below the maximum. The decibel calculation implies taking 10 times the logarithm of the ratios of the integrals.

NOTE 3 Beamwidth is expressed in metres (m).

NOTE 4 Definition adopted from IEC 62127-1.

3.5

beamwidth midpoint

linear average of the location of the centres of **beamwidths** in a plane

NOTE 1 The average is taken over 20 beamwidth levels corresponding to intervals in the -0.1 dB to -26 dB range (see IEC 61828, Clause B.2).

NOTE 2 Definition adopted from IEC 61828:2001.

3.6

beam centre

point in a plane in the **far field**, usually perpendicular to the **beam axis**, at which the **spatialpeak temporal-peak acoustic pressure** occurs

3.7

diametrical beam scan

set of measurements of the hydrophone output voltage made while moving the hydrophone in a straight line passing through a point on the beam axis and in a direction normal to the beam axis

NOTE 1 The diametrical beam scan may extend to different distances on either side of the beam axis.

NOTE 2 Definition adopted from IEC 62127-1.

3.8

directional response

description, generally presented graphically, of the response of a hydrophone, as a function of direction of propagation of the incident plane sound wave, in a specified plane through the reference centre and at a specified frequency (S.Iten.al)

NOTE Definition adopted from IEC 60565. IEC 62127-2:2007

https://standards.iteh.ai/catalog/standards/sist/ee6f911b-8810-48d0-af25-

effective radius of a non-focused ultrasonic transducer

at

3.9

radius of a perfect disc piston-like ultrasonic source transducer that has a predicted axial acoustic pressure distribution approximately equivalent to the observed axial acoustic pressure distribution over an axial distance until at least the last axial maximum has passed

NOTE 1 The effective radius of an non-focused ultrasonic transducer is expressed in metres (m).

NOTE 2 Definition adopted from IEC 62127-1.

3.10

effective hydrophone radius

a_h, a_{h3}, a_{h6}

radius of a stiff disc receiver **hydrophone** that has a predicted **directional response** function with an angular width equal to the observed angular width

NOTE 1 The angular width is determined at a specified level below the peak of the **directional response** function. For the specified levels of 3 dB and 6 dB, the radii are denoted by a_{h3} and a_{h6} respectively.

NOTE 2 The effective hydrophone radius is expressed in metres (m).

NOTE 3 The radius is usually a function of frequency. For representative experimental data, see [2].

NOTE 4 Definition adopted from IEC 62127-3.

3.11 electric load impedance Z_{L}

complex electric input impedance (consisting of a real and an imaginary part) to which the **hydrophone assembly** output cable is connected or is to be connected

NOTE 1 The electric load impedance is expressed in ohms (Ω).

NOTE 2 Definition adopted from IEC 62127-3.

3.12 end-of-cable loaded sensitivity end-of-cable loaded sensitivity of a hydrophone (or hydrophone-assembly) $M_L(f)$

ratio of the instantaneous voltage at the end of any integral cable or output connector of a **hydrophone** or **hydrophone-assembly**, when connected to a specified **electric load impedance**, to the **instantaneous acoustic pressure** in the undisturbed free field of a plane wave in the position of the reference centre of the **hydrophone** if the **hydrophone** were removed

NOTE 1 End-of-cable loaded sensitivity is expressed in volts per pascal (V/Pa).

NOTE 2 Definition adopted from IEC 62127-3.

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end-of-cable open-circuit sensitivity dards itch.ai) end-of-cable open-circuit sensitivity of a hydrophone

M_c(f)

3.13

ratio of the instantaneous open-circuit voltage at the end of any integral cable or output connector of a **hydrophone** to the **instantaneous acoustic pressure** in the undisturbed free field of a plane wave in the position of the **reference centre** of the **hydrophone** if the **hydrophone** were removed

NOTE 1 End-of-cable open-circuit sensitivity is expressed in volts per pascal (V/Pa).

NOTE 2 Definition adopted from IEC 62127-3.

3.14

external transducer aperture

part of the surface of the **ultrasonic transducer** or **ultrasonic transducer element group** assembly that emits ultrasonic radiation into the propagation medium.

NOTE 1 This surface is either directly in contact with the patient or is in contact with a water or liquid path to the patient (see Figure 2 of IEC 62127-1).

NOTE 2 Definition adopted from IEC 61828:2001.

3.15

far field

acoustic (sound) field at distances from an **ultrasonic transducer** where the values of the **instantaneous acoustic pressure** and particle velocity are substantially in phase (see also IEC 60050-801, 801-23-30)

NOTE 1 In the **far field**, the sound pressure appears to be spherically divergent from a point on or near the radiating surface. Hence, the pressure produced by the sound source is approximately inversely proportional to the distance from the source.

NOTE 2 The term **"far field**" is used in this standard only in connection with non-focusing source transducers. For focusing transducers a different terminology for the various parts of the transmitted field applies (see IEC 61828).

3.16

free field

sound field in a homogeneous and isotropic medium in which the effects of boundaries are negligible

NOTE Definition adopted from IEC 60565: 2006, 3.13.

3.17

hydrophone

transducer that produces electric signals in response to waterborne acoustic signals.

NOTE Definition adopted from IEC 60050-801, 801-32-26.

3.18

hydrophone assembly

combination of hydrophone and hydrophone pre-amplifier

NOTE 2 Definition adopted from IEC 62127-3.

3.19

hydrophone axis

nominal symmetry axis of the hydrophone active element

NOTE 1 Unless stated otherwise (explicitly and quantitatively) by the manufacturer, it is understood for the purposes of this standard that this is given by the apparent geometrical symmetry axis of the **hydrophone**.

(standards.iteh.ai)

NOTE 2 Definition adopted from IEC 62127-3.

3.20

hydrophone geometrical radius

geometrical radius of a hydrophone active element 2007

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18069dd7887f/iec-62127-2-2007

radius defined by the dimensions of the active element of a hydrophone

NOTE 1 The hydrophone geometrical radius is expressed in metres (m)

NOTE 2 Definition adopted from IEC 62127-3.

3.21

hydrophone pre-amplifier

active electronic device connected to, or to be connected to, a particular hydrophone and reducing its output impedance

NOTE 1 A hydrophone pre-amplifier requires a supply voltage (or supply voltages).

NOTE 2 The **hydrophone pre-amplifier** may have a forward voltage transmission factor of less than one, i.e. it need not necessarily be a voltage amplifier in the strict sense.

NOTE 3 Definition adopted from IEC 62127-3.

3.22

instantaneous acoustic pressure

p(t)

pressure minus the ambient pressure at a particular instant in time and at a particular point in an acoustic field (see also IEC 60050-801, 801-21-19)

NOTE 1 Instantaneous acoustic pressure is expressed in pascal (Pa).

NOTE 2 Definition adopted from IEC 62127-1.

3.23 instantaneous intensity *I(t)*

acoustic energy transmitted per unit time in the direction of acoustic wave propagation per unit area normal to this direction at a particular instant in time and at a particular point in an acoustic field

NOTE 1 Instantaneous intensity is the product of instantaneous acoustic pressure and particle velocity. It is difficult to measure intensity in the ultrasound frequency range. For the measurement purposes referred to in this standard, and if it is reasonable to assume **far field** conditions, the **instantaneous intensity**, *I* is approximated as

$$I(t) = \frac{p(t)^2}{\rho c} \tag{1}$$

where

p(t) is the **instantaneous acoustic pressure**;

 ρ is the density of the medium;

c is the velocity of sound in the medium.

NOTE 2 Instantaneous intensity is expressed in watts per metre squared (W/m²).

3.24

reference centre

point on or near a hydrophone about which its acoustic receiving sensitivity is defined

NOTE Unless stated otherwise (explicitly and quantitatively) by the manufacturer, it is understood for the purposes of this standard that this is given by the geometrical centre of the front surface of the **hydrophone** active element.

(See IEC 60565: 2006, 3.25)

3.25) <u>IEC 62127-2:2007</u> https://standards.iteh.ai/catalog/standards/sist/ee6f911b-8810-48d0-af25-

3.25 uncertainty

parameter, associated with the result of a measurement, that characterizes the dispersion of the values that could reasonably be attributed to the measurand

18069dd7887f/iec-62127-2-2007

NOTE See the ISO Guide to the Expression of Uncertainty in Measurement [3], 2.2.3.

4 List of symbols

a _h	effective hydrophone radius (a_{h3} , a_{h6} : with special reference to a 3 dB or 6 dB definition, respectively)
a g	hydrophone geometrical radius
a _{max}	maximum effective radius for a specific hydrophone application
a P	lateral distance from the beam axis (a_{PmaxE} , a_{PmaxH} : maximum values with respect to avoiding edge wave and head wave interference, respectively)
at	effective radius of an non-focused ultrasonic transducer
Ag	geometrical area of an ultrasonic transducer
B/A	Fox-Wallace non-linearity parameter
С	speed of sound in a medium (usually water)
C _H	end-of-cable capacitance of the hydrophone including any integral cable and connector
D (θ)	normalized directional response function
е	base of natural logarithms
f	frequency
f _f	fundamental drive frequency of a signal used to generate non-linear distortion