

Edition 2.0 2010-04

# **INTERNATIONAL STANDARD**

# **NORME** INTERNATIONALE

Functional safety of electrical/electronic/programmable electronic safety-related systems -

Part 7: Overview of techniques and measures 1.

Sécurité fonctionnelle des systèmes électriques/électroniques/électroniques programmables relatifs à la sécurité triec-61508-7-2010

Partie 7: Présentation de techniques et mesures





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IEC 61508-7:2010

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Edition 2.0 2010-04

# INTERNATIONAL **STANDARD**

# **NORME** INTERNATIONALE

Functional safety of electrical/electronic/programmable electronic safety-related

Part 7: Overview of techniques and measures

Sécurité fonctionnelle des systèmes électriques/électroniques/électroniques programmables relatifs à la sécurité Liec-61508-7-2010 Partie 7: Présentation de techniques et mesures

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#### INTERNATIONAL ELECTROTECHNICAL COMMISSION

# FUNCTIONAL SAFETY OF ELECTRICAL/ELECTRONIC/ PROGRAMMABLE ELECTRONIC SAFETY-RELATED SYSTEMS –

## Part 7: Overview of techniques and measures

#### **FOREWORD**

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International Standard IEC 61508-7 has been prepared by subcommittee 65A: System aspects, of IEC technical committee 65: Industrial-process measurement, control and automation.

This second edition cancels and replaces the first edition published in 2000. This edition constitutes a technical revision.

This edition has been subject to a thorough review and incorporates many comments received at the various revision stages.

The text of this standard is based on the following documents:

| FDIS         | Report on voting |
|--------------|------------------|
| 65A/554/FDIS | 65A/578/RVD      |

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of the IEC 61508 series, published under the general title *Functional safety* of electrical / electronic / programmable electronic safety-related systems, can be found on the IEC website.

The committee has decided that the contents of this publication will remain unchanged until the stability date indicated on the IEC web site under "http://webstore.iec.ch" in the data related to the specific publication. At this date, the publication will be

- · reconfirmed.
- · withdrawn,
- replaced by a revised edition, or
- amended.

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<u>IEC 61508-7:2010</u> https://standards.iteh.ai/catalog/standards/sist/60d19b74-074b-4ce3-9c2e-d837235812fb/iec-61508-7-2010

#### INTRODUCTION

Systems comprised of electrical and/or electronic elements have been used for many years to perform safety functions in most application sectors. Computer-based systems (generically referred to as programmable electronic systems) are being used in all application sectors to perform non-safety functions and, increasingly, to perform safety functions. If computer system technology is to be effectively and safely exploited, it is essential that those responsible for making decisions have sufficient guidance on the safety aspects on which to make these decisions.

This International Standard sets out a generic approach for all safety lifecycle activities for systems comprised of electrical and/or electronic and/or programmable electronic (E/E/PE) elements that are used to perform safety functions. This unified approach has been adopted in order that a rational and consistent technical policy be developed for all electrically-based safety-related systems. A major objective is to facilitate the development of product and application sector international standards based on the IEC 61508 series.

NOTE 1 Examples of product and application sector international standards based on the IEC 61508 series are given in the bibliography (see references [21], [22] and [37]).

In most situations, safety is achieved by a number of systems which rely on many technologies (for example mechanical, hydraulic, pneumatic, electrical, electronic, programmable electronic). Any safety strategy must therefore consider not only all the elements within an individual system (for example sensors, controlling devices and actuators) but also all the safety-related systems making up the total combination of safety-related systems. Therefore, while this International Standard is concerned with E/E/PE safety-related systems, it may also provide a framework within which safety-related systems based on other technologies may be considered.

It is recognized that there is a great variety of application sectors and covering a wide range of complexity, hazard and risk potentials. In any particular application, the required safety measures will be dependent on many factors specific to the application. This International Standard, by being generic, will enable such measures to be formulated in future product and application sector international standards and in revisions of those that already exist.

### This International Standard

- considers all relevant overall, E/E/PE system and software safety lifecycle phases (for example, from initial concept, through design, implementation, operation and maintenance to decommissioning) when E/E/PE systems are used to perform safety functions;
- has been conceived with a rapidly developing technology in mind; the framework is sufficiently robust and comprehensive to cater for future developments;
- enables product and application sector international standards, dealing with E/E/PE safety-related systems, to be developed; the development of product and application sector international standards, within the framework of this standard, should lead to a high level of consistency (for example, of underlying principles, terminology etc.) both within application sectors and across application sectors; this will have both safety and economic benefits:
- provides a method for the development of the safety requirements specification necessary to achieve the required functional safety for E/E/PE safety-related systems;
- adopts a risk-based approach by which the safety integrity requirements can be determined;
- introduces safety integrity levels for specifying the target level of safety integrity for the safety functions to be implemented by the E/E/PE safety-related systems;

NOTE 2 The standard does not specify the safety integrity level requirements for any safety function, nor does it mandate how the safety integrity level is determined. Instead it provides a risk-based conceptual framework and example techniques.

- sets target failure measures for safety functions carried out by E/E/PE safety-related systems, which are linked to the safety integrity levels;
- sets a lower limit on the target failure measures for a safety function carried out by a single E/E/PE safety-related system. For E/E/PE safety-related systems operating in
  - a low demand mode of operation, the lower limit is set at an average probability of a dangerous failure on demand of  $10^{-5}$ ;
  - a high demand or a continuous mode of operation, the lower limit is set at an average frequency of a dangerous failure of 10<sup>-9</sup> [h<sup>-1</sup>];

NOTE 3 A single E/E/PE safety-related system does not necessarily mean a single-channel architecture.

NOTE 4 It may be possible to achieve designs of safety-related systems with lower values for the target safety integrity for non-complex systems, but these limits are considered to represent what can be achieved for relatively complex systems (for example programmable electronic safety-related systems) at the present time.

- sets requirements for the avoidance and control of systematic faults, which are based on experience and judgement from practical experience gained in industry. Even though the probability of occurrence of systematic failures cannot in general be quantified the standard does, however, allow a claim to be made, for a specified safety function, that the target failure measure associated with the safety function can be considered to be achieved if all the requirements in the standard have been met;
- introduces systematic capability which applies to an element with respect to its confidence that the systematic safety integrity meets the requirements of the specified safety integrity level;
- adopts a broad range of principles, techniques and measures to achieve functional safety for E/E/PE safety-related systems, but does not explicitly use the concept of fail safe. However, the concepts of "fail safe" and "inherently safe" principles may be applicable and adoption of such concepts is acceptable providing the requirements of the relevant clauses in the standard are met.

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# FUNCTIONAL SAFETY OF ELECTRICAL/ELECTRONIC/ PROGRAMMABLE ELECTRONIC SAFETY-RELATED SYSTEMS –

### Part 7: Overview of techniques and measures

### 1 Scope

**1.1** This part of IEC 61508 contains an overview of various safety techniques and measures relevant to IEC 61508-2 and IEC 61508-3.

The references should be considered as basic references to methods and tools or as examples, and may not represent the state of the art.

- **1.2** IEC 61508-1, IEC 61598-2, IEC 61508-3 and IEC 61508-4 are basic safety publications, although this status does not apply in the context of low complexity E/E/PE safety-related systems (see 3.4.3 of IEC 61508-4). As basic safety publications, they are intended for use by technical committees in the preparation of standards in accordance with the principles contained in IEC Guide 104 and ISO/IEC Guide 51. IEC 61508-1, IEC 61508-2, IEC 61508-3 and IEC 61508-4 are also intended for use as stand-alone publications. The horizontal safety function of this international standard does not apply to medical equipment in compliance with the IEC 60601 series.
- 1.3 One of the responsibilities of a technical committee is, wherever applicable, to make use of basic safety publications in the preparation of its publications. In this context, the requirements, test methods or test conditions of this basic safety publication will not apply unless specifically referred to ion included in the publications prepared by those technical committees.

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- **1.4** Figure 1 shows the overall framework for parts 1 to 7 of IEC 61508 and indicates the role that IEC 61508-7 plays in the achievement of functional safety for E/E/PE safety-related systems.

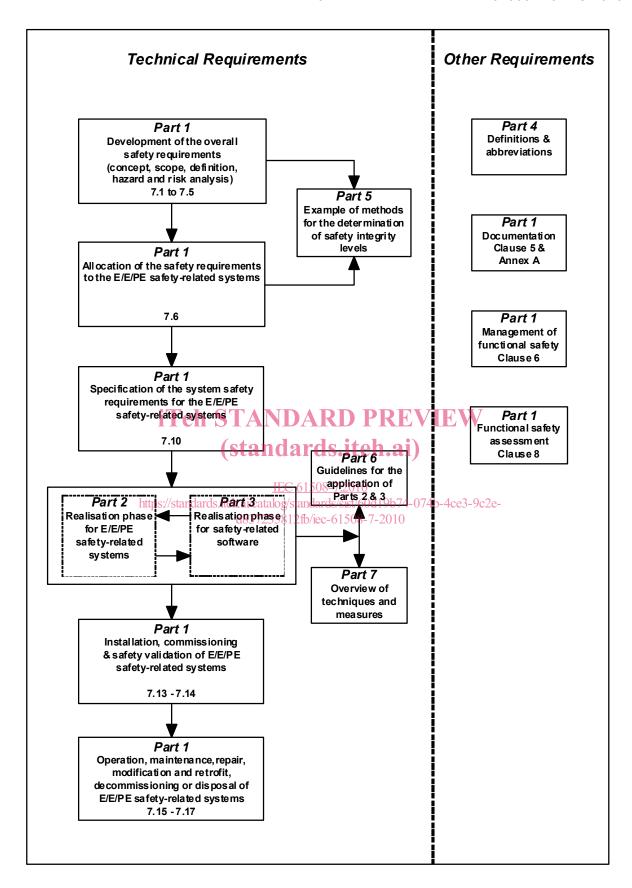


Figure 1 - Overall framework of IEC 61508

### 2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 61508-4:2010 Functional safety of electrical/electronic/programmable electronic safety-related systems – Part 4: Definitions and abbreviations

# 3 Definitions and abbreviations

For the purposes of this document, the definitions and abbreviations given in IEC 61508-4 apply.

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<u>IEC 61508-7:2010</u> https://standards.iteh.ai/catalog/standards/sist/60d19b74-074b-4ce3-9c2e-d837235812fb/iec-61508-7-2010

## Annex A

(informative)

# Overview of techniques and measures for E/E/PE safety-related systems: control of random hardware failures (see IEC 61508-2)

#### **A.1 Electric**

Global objective: To control failures in electromechanical components.

#### A.1.1 Failure detection by on-line monitoring

NOTE This technique/measure is referenced in Tables A.2, A.3, A.7 and A.13 to A.18 of IEC 61508-2.

Aim: To detect failures by monitoring the behaviour of the E/E/PE safety-related system in response to the normal (on-line) operation of the equipment under control (EUC).

Description: Under certain conditions, failures can be detected using information about (for example) the time behaviour of the EUC. For example, if a switch, which is part of the E/E/PE safety-related system, is normally actuated by the EUC, then if the switch does not change state at the expected time, a failure will have been detected. It is not usually possible to localise the failure localise the failure.

# Monitoring of relay contacts (standards.iteh.ai)

A.1.2

NOTE This technique/measure is referenced in Tables A/2 and IA.14 of IEC 61508-2.

https://standards.iteh.ai/catalog/standards/sist/60d19b74-074b-4ce3-9c2e-

Aim: To detect failures (for example welding) of relay contacts.

**Description:** Forced contact (or positively guided contact) relays are designed so that their contacts are rigidly linked together. Assuming there are two sets of changeover contacts, a and b, if the normally open contact, a, welds, the normally closed contact, b, cannot close when the relay coil is next de-energised. Therefore, the monitoring of the closure of the normally closed contact b when the relay coil is de-energised may be used to prove that the normally open contact a has opened. Failure of normally closed contact b to close indicates a failure of contact a, so the monitoring circuit should ensure a safe shut-down, or ensure that shut-down is continued, for any machinery controlled by contact a.

#### References:

Zusammenstellung und Bewertung elektromechanischer Sicherheitsschaltungen für Verriegelungseinrichtungen. F. Kreutzkampf, W. Hertel, Sicherheitstechnisches Informations- und Arbeitsblatt 330212, BIA-Handbuch. 17. Lfg. X/91, Erich Schmidt Verlag, Bielefeld. www.BGIA-HANDBUCHdigital.de/330212

#### A.1.3 Comparator

NOTE This technique/measure is referenced in Tables A.2, A.3, A.4 of IEC 61508-2.

Aim: To detect, as early as possible, (non-simultaneous) failures in an independent processing unit or in the comparator.

Description: The signals of independent processing units are compared cyclically or continuously by a hardware comparator. The comparator may itself be externally tested, or it may use self-monitoring technology. Detected differences in the behaviour of the processors lead to a failure message.

#### A.1.4 **Majority voter**

NOTE This technique/measure is referenced in Tables A.2, A.3 and A.4 of IEC 61508-2.

Aim: To detect and mask failures in one of at least three hardware channels.

**Description:** A voting unit using the majority principle (2 out of 3, 3 out of 3, or m out of n) is used to detect and mask failures. The voter may itself be externally tested, or it may use selfmonitoring technology.

#### References:

Guidelines for Safe Automation of Chemical Processes. CCPS, AIChE, New York, 1993, ISBN-10: 0-8169-0554-1, ISBN-13: 978-0-8169-0554-6

#### A.1.5 Idle current principle (de-energised to trip)

NOTE This technique/measure is referenced in Table A.16 of IEC 61508-2.

**Aim:** To execute the safety function if power is cut or lost.

**Description:** The safety function is executed if the contacts are open and no current flows. For example, if brakes are used to stop a dangerous movement of a motor, the brakes are opened by closing contacts in the safety-related system and are closed by opening the contacts in the safety-related system.

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#### Reference:

(standards.iteh.ai)

Guidelines for Safe Automation of Chemical Processes. CCPS, AIChE, New York, 1993, ISBN-10: 0-8169-0554-1, ISBN-13: 978-0-8169-0554-6

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#### **A.2 Electronic**

**Global objective:** To control failure in solid-state components.

#### A.2.1 Tests by redundant hardware

NOTE This technique/measure is referenced in Tables A.3, A.15, A.16 and A.18 of IEC 61508-2.

Aim: To detect failures using hardware redundancy, i.e. using additional hardware not required to implement the process functions.

Description: Redundant hardware can be used to test at an appropriate frequency the specified safety functions. This approach is normally necessary for realising A.1.1 or A.2.2.

#### A.2.2 Dynamic principles

NOTE This technique/measure is referenced in Table A.3 of IEC 61508-2.

**Aim:** To detect static failures by dynamic signal processing.

**Description:** A forced change of otherwise static signals (internally or externally generated) helps to detect static failures in components. This technique is often associated with electromechanical components.

### Reference:

Elektronik in der Sicherheitstechnik. H. Jürs, D. Reinert, Sicherheitstechnisches Informationsund Arbeitsblatt 330220, BIA-Handbuch, Erich-Schmidt Verlag, Bielefeld, 1993. http://www.bgia-handbuchdigital.de/330220

#### A.2.3 Standard test access port and boundary-scan architecture

NOTE This technique/measure is referenced in Tables A.3, A.15 and A.18 of IEC 61508-2.

Aim: To control and observe what happens at each pin of an IC.

**Description:** Boundary-scan test is an IC design technique which increases the testability of the IC by resolving the problem of how to gain access to the circuit test points within it. In a typical boundary-scan IC, comprised of core logic and input and output buffers, a shift-register stage is placed between the core logic and the input and output buffers adjacent to each IC pin. Each shift-register stage is contained in a boundary-scan cell. The boundary-scan cell can control and observe what happens at each input and output pin of an IC, via the standard test access port. Internal testing of the IC core logic is accomplished by isolating the on-chip core logic from stimuli received from surrounding components, and then performing an internal self-test. These tests can be used to detect failures in the IC.

#### Reference:

IEEE 1149-1:2001, IEEE standard test access port and boundary-scan architecture, IEEE Computer Society, 2001, ISBN: 0-7381-2944-5

# iTeh STANDARD PREVIEW

#### A.2.4 (Not used

# (standards.iteh.ai)

### A.2.5 Monitored redundancy

NOTE This technique/measure is referenced in Table A(3 of 1EC)61508-2.

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Aim: To detect failure, by providing several functional units, by monitoring the behaviour of each of these to detect failures, and by initiating a transition to a safe condition if any discrepancy in behaviour is detected.

**Description:** The safety function is executed by at least two hardware channels. The outputs of these channels are monitored and a safe condition is initiated if a fault is detected (i.e. if the output signals from all channels are not identical).

### References:

*Elektronik in der Sicherheitstechnik*. H. Jürs, D. Reinert, Sicherheitstechnisches Informationsund Arbeitsblatt 330220, BIA-Handbuch, Erich-Schmidt Verlag, Bielefeld, 1993. http://www.bgia-handbuchdigital.de/330220

Dependability of Critical Computer Systems 1. F. J. Redmill, Elsevier Applied Science, 1988, ISBN 1-85166-203-0

#### A.2.6 Electrical/electronic components with automatic check

NOTE This technique/measure is referenced in Table A.3 of IEC 61508-2.

Aim: To detect faults by periodic checking of the safety functions.

**Description:** The hardware is tested before starting the process, and is tested repeatedly at suitable intervals. The EUC continues to operate only if each test is successful.

#### References:

Elektronik in der Sicherheitstechnik. H. Jürs, D. Reinert, Sicherheitstechnisches Informationsund Arbeitsblatt 330220, BIA-Handbuch, Erich-Schmidt Verlag, Bielefeld, 1993. http://www.bgia-handbuchdigital.de/330220

Dependability of Critical Computer Systems 1. F. J. Redmill, Elsevier Applied Science, 1988, ISBN 1-85166-203-0

#### A.2.7 **Analogue signal monitoring**

NOTE This technique/measure is referenced in Tables A.3 and A.13 of IEC 61508-2.

Aim: To improve confidence in measured signals.

Description: Wherever there is a choice, analogue signals are used in preference to digital on/off states. For example, trip or safe states are represented by analogue signal levels, usually with signal level tolerance monitoring. The technique provides continuity monitoring and a higher level of confidence in the transmitter, reducing the necessary proof-test frequency of the transmitter sensing function. External interfaces, for example impulse lines. will also require testing.

#### A.2.8 De-rating

NOTE This technique/measure is referenced in 7.4.2.13 of IEC 61508-2.

Aim: To increase the reliability of hardware components.

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Description: Hardware components are operated at levels which are guaranteed by the design of the system to be well below the maximum specification ratings. De-rating is the practice of ensuring that under all normal operating circumstances, components are operated well below their maximum stress levels. IEC 61508-7:2010

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d837235812fb/iec-61508-7-2010

#### **A.3 Processing units**

Global objective: To recognise failures which lead to incorrect results in processing units.

#### A.3.1 Self-test by software: limited number of patterns (one-channel)

NOTE This technique/measure is referenced in Table A.4 of IEC 61508-2.

**Aim:** To detect, as early as possible, failures in the processing unit.

Description: The hardware is built using standard techniques which do not take any special safety requirements into account. The failure detection is realised entirely by additional software functions which perform self-tests using at least two complementary data patterns (for example 55hex and AAhex).

#### A.3.2 Self-test by software: walking bit (one-channel)

NOTE This technique/measure is referenced in Table A.4 of IEC 61508-2.

Aim: To detect, as early as possible, failures in the physical storage (for example registers) and instruction decoder of the processing unit.

Description: The failure detection is realised entirely by additional software functions which perform self-tests using a data pattern (for example walking-bit pattern) which tests the physical storage (data and address registers) and the instruction decoder. However, the diagnostic coverage is only 90 %.