

INTERNATIONAL STANDARD

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INTERNATIONAL SPECIAL COMMITTEE ON RADIO INTERFERENCE COMITÉ INTERNATIONAL SPÉCIAL DES PERTURBATIONS RADIOÉLECTRIQUES

BASIC EMC PUBLICATION PUBLICATION FONDAMENTALE EN CEM

Specification for radio disturbance and immunity measuring apparatus and methods – Part 1-1: Radio disturbance and immunity measuring apparatus – Measuring apparatus

https://standards.ite

Spécifications des méthodes et des appareils de mesure des perturbations radioélectriques et de l'immunité aux perturbations radioélectriques – Partie 1-1: Appareils de mesure des perturbations radioélectriques et de l'immunité aux perturbations radioélectriques – Appareils de mesure



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colour inside

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INTERNATIONAL ELECTROTECHNICAL COMMISSION INTERNATIONAL SPECIAL COMMITTEE ON RADIO INTERFERENCE

SPECIFICATION FOR RADIO DISTURBANCE AND IMMUNITY MEASURING APPARATUS AND METHODS –

Part 1-1: Radio disturbance and immunity measuring apparatus – Measuring apparatus

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International Standard CISPR 16-1-1 has been prepared by CISPR subcommittee A: Radiointerference measurements and statistical methods.

This third edition cancels and replaces the second edition published in 2006, and its Amendments 1 (2006) and 2 (2007). It is a technical revision.

This main technical change with respect to the previous edition consists of the addition of new provisions for the use of spectrum analyzers for compliance measurements.

It has the status of a basic EMC publication in accordance with IEC Guide 107, *Electromagnetic compatibility – Guide to the drafting of electromagnetic compatibility publications*.

The text of this standard is based on the following documents:

| FDIS | Report on voting |
|------------------|------------------|
| CISPR/A/867/FDIS | CISPR/A/881/RVD |

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of the CISPR 16 series can be found, under the general title Specification for radio disturbance and immunity measuring apparatus and methods, on the IEC website.

The committee has decided that the contents of this publication will remain unchanged until the maintenance result date indicated on the IEC web site under "http://webstore.jec.ch" in the data related to the specific publication. At this date, the publication will be

- reconfirmed;
- withdrawn;
- replaced by a revised edition; or
- amended.

The contents of the corrigenda 1 (October 2010) and 2 (October 2011) have been included in this copy.

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INTRODUCTION

The CISPR 16 series, published under the general title *Specification for radio disturbance and immunity measuring apparatus and methods,* is comprised of the following sets of standards and reports:

- CISPR 16-1 five parts covering measurement instrumentation specifications;
- CISPR 16-2 five parts covering methods of measurement;
- CISPR 16-3 a single publication containing various technical reports (TRs) with further information and background on CISPR and radio disturbances in general;
- CISPR 16-4 five parts covering uncertainties, statistics and limit modelling.

CISPR 16-1 consists of the following parts, under the general title Specification for radio disturbance and immunity measuring apparatus and methods – Radio disturbance and immunity measuring apparatus:

- Part 1-1: Measuring apparatus
- Part 1-2: Ancillary equipment Conducted disturbances
- Part 1-3: Ancillary equipment Disturbance power
- Part 1-4: Ancillary equipment Radiated disturbances
- Part 1-5: Antenna calibration test sites for 30 MHz to 1 000 MHz

The International Electrotechnical Commission (IEC) draws attention to the fact that it is claimed that compliance with this document may involve the use of a patent concerning the measuring receiver with rms-average detector (patent no DE 10126830) given in Clause 7.

IEC takes no position concerning the evidence, validity and scope of this patent right.

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SPECIFICATION FOR RADIO DISTURBANCE AND IMMUNITY MEASURING APPARATUS AND METHODS –

Part 1-1: Radio disturbance and immunity measuring apparatus – Measuring apparatus

1 Scope

This part of CISPR 16 specifies the characteristics and performance of equipment for the measurement of radio disturbance in the frequency range 9 kHz to 18 GHz. In addition, requirements are provided for specialized equipment for discontinuous disturbance measurements.

NOTE In accordance with IEC Guide 107, CISPR 16-1-1 is a basic EMC standard for use by product committees of the IEC. As stated in Guide 107, product committees are responsible for determining the applicability of the EMC standard. CISPR and its sub-committees are prepared to co-operate with product committees in the evaluation of the value of particular EMC tests for specific products.

The specifications in this standard apply to EMI receivers and spectrum analyzers. The term "measuring receiver" used in this standard refers to both EMI receivers and spectrum analyzers.

Further guidance on the use of use of spectrum analyzers and scanning receivers can be found in Annex B of any one of the following standards: CISPR 16-2-1, CISPR 16-2-2 or CISPR 16-2-3.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

CISPR 11:2009, Industrial, scientific and medical equipment – Radio-frequency disturbance characteristics – Limits and methods of measurement

CISPR 14-1:2005, Electromagnetic compatibility – Requirements for household appliances, electric tools and similar apparatus – Part 1: Emission Amendment 1 (2008)

CISPR 16-2-1:2008, Specification for radio disturbance and immunity measuring apparatus and methods – Part 2-1: Methods of measurement of disturbances and immunity – Conducted disturbance measurements

CISPR 16-2-2:2003, Specification for radio disturbance and immunity measuring apparatus and methods – Part 2-2: Methods of measurement of disturbances and immunity – Measurement of disturbance power Amendment 1 (2004) Amendment 2 (2005)

CISPR 16-2-3:2006, Specification for radio disturbance and immunity measuring apparatus and methods – Part 2-3: Methods of measurement of disturbances and immunity – Radiated disturbance measurements

CISPR/TR 16-3:2003, Specification for radio disturbance and immunity measuring apparatus and methods – Part 3: CISPR technical reports Amendment 1 (2005) Amendment 2 (2006)

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IEC 60050-161:1990, International Electrotechnical Vocabulary (IEV) – Chapter 161: Electromagnetic compatibility Amendment 1 (1997) Amendment 2 (1998)

3 Terms and definitions

For the purposes of this document, the terms and definitions given in IEC 60050-161, and the following apply.

3.1

bandwidth

B_n

width of the overall selectivity curve of the receiver between two points at a stated attenuation, below the midband response

NOTE *n* is the stated attenuation in dB.

3.2

CISPR indication range

range specified by the manufacturer which gives the maximum and the minimum meter indications within which the measuring receiver meets the requirements of this part of CISPR 16

3.3

electrical charge time constant

T_{C}

time needed after the instantaneous application of a constant sine-wave voltage to the stage 2010 immediately preceding the input of the detector for the output voltage of the detector to reach 63 % of its final value

NOTE This time constant is determined as follows: a sine-wave signal of constant amplitude and having a frequency equal to the nid-band frequency of the IF amplifier is applied to the input of the stage immediately preceding the detector. The indication, *D*, of an instrument having no inertia (e.g. an oscilloscope) connected to a terminal in the d.c. amplifier circuit so as not to affect the behaviour of the detector, is noted. The level of the signal is chosen such that the response of the stages concerned remains within the linear operating range. A sine-wave signal of this level, applied for a limited time only and having a wave train of rectangular envelope is gated such that the deflection registered is 0,63 *D*. The duration of this signal is equal to the charge time of the detector.

3.4

electrical discharge time constant

 T_{D}

time needed after the instantaneous removal of a constant sine-wave voltage applied to the stage immediately preceding the input of the detector for the output of the detector to fall to 37 % of its initial value

NOTE The method of measurement is analogous to that for the charge time constant, but instead of a signal being applied for a limited time, the signal is interrupted for a definite time. The time taken for the deflection to fall to 0,37 D is the discharge time constant of the detector.

3.5 impulse area

 A_{imp} voltage-time area of a pulse defined by the integral:

$$A_{\rm imp} = \int_{-\infty}^{+\infty} V(t) dt \tag{1}$$

- 11 -

NOTE 1 Impulse area, sometimes referred to as impulse strength, is typically expressed in μ Vs or dB(μ Vs).

NOTE 2 Spectral density (*D*) is related to impulse area and expressed in μ V/MHz or dB(μ V/MHz). For rectangular impulses of pulse duration *T* at frequencies *f* << 1/*T*, the relationship *D* (μ V/MHz) = $\sqrt{2} \times 10^{6} A_{imp}$ (μ Vs) applies.

3.6 impulse bandwidth

B_{imp}

$$B_{\rm imp} = \frac{A(t)_{\rm max}}{2G_0 \times A_{\rm imp}}$$

110

where

 $A(t)_{max}$ is the peak of the envelope at the IF output of the receiver with an inpulse area A_{imp} applied at the receiver input;

(2)

(3)

 G_0 is the gain of the circuit at the centre frequency.

Specifically for two critically-coupled tuned transformers

$$B_{\rm imp} = 1,05 \times B_6 = 1,31 \times B_3$$

where B_6 and B_3 are respectively the bandwidths at the -6 dB and -3 dB points

NOTE See A.2 for further information.

3.7

measuring receiver

instrument, such as a tunable voltmeter, an EM receiver or a spectrum analyzer with or without preselection, that meets the requirements of the relevant parts of this standard

NOTE 1 The term "measuring receiver" used in this standard refers to both EMI receivers and spectrum analyzers.

NOTE 2 See Annex for further information

3.8

mechanical time constant of a critically damped indicating instrument $T_{\rm M}$

$$T_{\mathsf{M}} = \frac{T_{\mathsf{L}}}{2\pi} \tag{4}$$

where $T_{\rm L}$ is the period of free oscillation of the instrument with all damping removed.

NOTE 1 For a critically damped instrument, the equation of motion of the system may be written as:

$$T_{\rm M}^2 \left(\frac{d^2 \alpha}{dt^2}\right) + 2T_{\rm M}\frac{d\alpha}{dt} + \alpha = ki$$
(5)

where

 α is the deflection;

- i is the current through the instrument; and
- *k* is a constant.

It can be deduced from this relation that this time constant is also equal to the duration of a rectangular pulse (of constant amplitude) that produces a deflection equal to 35 % of the steady deflection produced by a continuous current having the same amplitude as that of the rectangular pulse.

NOTE 2 The methods of measurement and adjustment are deduced from one of the following:

- a) the period of free oscillation having been adjusted to $2\pi T_{\rm M}$, damping is added so that $\alpha T = 0.35 \alpha_{\rm max}$.
- b) when the period of oscillation cannot be measured, the damping is adjusted to be just below critical such that the overswing is not greater than 5 % and the moment of inertia of the movement is such that $\alpha T = 0.35 \alpha_{max}$.

3.9

overload factor

ratio of the level that corresponds to the range of practical linear function of a circuit (or a group of circuits) to the level that corresponds to full-scale deflection of the indicating instrument

NOTE The maximum level at which the steady-state response of a circuit (or group of circuits) does not depart by more than 1 dB from ideal linearity defines the range of practical linear function of the circuit (or group of circuits).

3.10

symmetric voltage

radio-frequency disturbance voltage appearing between the two wires in a two-wire circuit, such as a single-phase mains supply. This is sometimes called the differential mode voltage. If V_a is the vector voltage between one of the mains terminals and earth and V_b is the vector voltage between the other mains terminal and earth, the symmetric voltage is the vector difference $(V_a - V_b)$

3.11

weighting (of e.g. impulsive disturbance)

pulse-repetition-frequency (PRF) dependent conversion (mostly reduction) of a peak-detected impulse voltage level to an indication that corresponds to the interference effect on radio reception

NOTE 1 For the analogue receiver, the psychophysical annoyance of the interference is a subjective quantity (audible or visual, usually not a certain number of misunderstandings of a spoken text)

NOTE 2 For the digital receiver, the interference effect is an objective quantity that may be defined by the critical bit error ratio (BER) or bit error probability (BEP) for which perfect error correction can still occur or by another, objective and reproducible parameter

3.11.1

weighted disturbance measurement

measurement of disturbance using a weighting detector

3.11.2

weighting characteristic

peak voltage level as a function of PRF for a constant effect on a specific radiocommunication system, i.e. the disturbance is weighted by the radiocommunication system itself

3.11.3

weighting detector

detector which provides an agreed weighting function

3.11.4

weighting factor

value of the weighting function relative to a reference PRF or relative to the peak value

NOTE Weighting factor is expressed in dB.