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Field device tool (FDT) interface specification –
Part 303-1: Communication profile integration – IEC 61784 CP 3/1 and CP 3/2
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Spécification des interfaces des outils des dispositifs de terrain (FDT) –
Partie 303-1: Intégration des profils de communication – CEI 61784 CP 3/1
et CP 3/2
7f8087b2af2a/iec-62453-303-1-2009



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CONTENTS

FOREWORD.....	5
INTRODUCTION.....	7
1 Scope.....	8
2 Normative references	8
3 Terms, definitions, symbols, abbreviated terms and conventions	9
3.1 Terms and definitions	9
3.2 Symbols and abbreviated terms.....	9
3.3 Conventions	9
3.3.1 Data type names and references to data types	9
3.3.2 Vocabulary for requirements	9
3.3.3 Use of UML	9
4 Bus category	10
5 Access to instance and device data	10
5.1 Process Channel objects provided by DTM.....	10
5.2 DTM services to access instance and device data	10
6 Protocol specific behavior.....	10
6.1 PROFIBUS device model	10
6.2 Configuration and parameterization of PROFIBUS devices	11
6.2.1 General	11
6.2.2 Monolithic DTM for a modular PROFIBUS device	12
6.2.3 Modular DTM for a modular PROFIBUS device.....	12
6.3 Support for DPV0 configuration.....	13
6.4 PROFIBUS slaves operating without a cyclic PROFIBUS master	13
6.5 PROFIBUS-related information of a slave DTM	13
6.5.1 General	13
6.5.2 Bus Master Configuration Part (BMCP).....	14
7 Protocol specific usage of general data types	24
8 Protocol specific common data types	26
9 Network management data types	26
9.1 General	26
9.1.1 Configuration.....	26
9.1.2 Process Channel	27
9.1.3 Parameterization	27
9.2 Master-bus parameter set.....	28
9.3 Slave bus parameter set.....	28
9.4 Module and channel data	29
9.5 GSD information.....	32
9.5.1 General	32
9.5.2 GSD for gateway devices	32
10 Communication data types	33
10.1 General.....	33
10.2 Error information provided by Communication Channel	33
10.3 DPV0 communication	33
10.4 DPV1 communication	40
11 Channel parameter data types.....	43

12	Device identification	46
12.1	General	46
12.2	Protocol specific handling of the data type STRING	46
12.3	Common device type identification data types	46
12.4	Topology scan data types	51
12.5	Scan identification data types	52
12.6	Device type identification data types – provided by DTM	54
12.7	Identification information in GUI	57
13	ProfiSafe	57
13.1	Motivation	57
13.2	General parameter handling	57
13.3	ProfiSafe individual device parameter	58
	Bibliography	60
	Figure 1 – Part 303-1 of the IEC 62453 series	7
	Figure 2 – FDT PROFIBUS device model	11
	Figure 3 – Example for IO data within datagrams	30
	Figure 4 – F-Parameter and individual device parameter	58
	Figure 5 – Data structure of ProfiSafe individual device parameters	59
	Table 1 – Protocol identifiers	10
	Table 2 – Physical layer identifiers	10
	Table 3 – BMPC Part1 – General configuration	15
	Table 4 – BMPC Part2 – Parameter data	15
	Table 5 – BMPC Part3 – Configuration data	16
	Table 6 – Part 4: Address table and slave user parameters	17
	Table 7 – Part 4: Extended Prm data	17
	Table 8 – Complete BMCP	18
	Table 9 – Protocol specific usage of general data types	24
	Table 10 – Bus parameter set for master device	28
	Table 11 – Bus parameter set for slave device	29
	Table 12 – Signal channels within the data frame	31
	Table 13 – Simple DPV0 communication data types	34
	Table 14 – Structured DPV0Communication data types	34
	Table 15 – Availability of services for Master Class1 (C1)	39
	Table 16 – Availability of services for Master Class2 (C2)	39
	Table 17 – Simple DPV1 communication data types	40
	Table 18 – Structured DPV1 communication data types	41
	Table 19 – Mapping of DPV1 data types to FDT data types	43
	Table 20 – Simple ChannelParameter data types	44
	Table 21 – Structured ChannelParameter data types	45
	Table 22 – Identification data types with Profibus DP specific mapping	47
	Table 23 – Identification data types with Profibus I&M specific mapping	48
	Table 24 – Identification data types with Profibus PA specific mapping	50

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Table 25 – Simple identification data types with protocol independent semantics 51
Table 26 – Structured identification data types with protocol independent semantics 51
Table 27 – Simple topology scan data types 51
Table 28 – Structured topology scan data types 51
Table 29 – Simple scan identification data types 52
Table 30 – Structured scan identification data types 52
Table 31 – Structured device identification data types 55

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<https://standards.iteh.ai/catalog/standards/sist/f621fef8-d88a-44c7-8c63-7f8087b2af2a/iec-62453-303-1-2009>

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FIELD DEVICE TOOL (FDT) INTERFACE SPECIFICATION –

**Part 303-1: Communication profile integration –
IEC 61784 CP 3/1 and CP 3/2**

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International Standard IEC 62453-303-1 been prepared by subcommittee 65E: Devices and integration in enterprise systems, of IEC technical committee 65: Industrial-process measurement, control and automation.

This part, in conjunction with the other parts of the first edition of the IEC 62453 series cancels and replaces IEC/PAS 62453-1, IEC/PAS 62453-2, IEC/PAS 62453-3, IEC/PAS 62453-4 and IEC/PAS 62453-5 published in 2006, and constitutes a technical revision.

Each part of the IEC 62453-3xy series is intended to be read in conjunction with IEC 62453-2.

This bilingual version (2012-12) corresponds to the monolingual English version, published in 2009-06.

The text of this standard is based on the following documents:

FDIS	Report on voting
65E/127/FDIS	65E/140/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

The French version of this standard has not been voted upon.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of the IEC 62453 series, under the general title *Field Device Tool (FDT) interface specification*, can be found on the IEC website.

The committee has decided that the contents of this publication will remain unchanged until the maintenance result date indicated on the IEC web site under "<http://webstore.iec.ch>" in the data related to the specific publication. At this date, the publication will be

- reconfirmed,
- withdrawn,
- replaced by a revised edition, or
- amended.

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INTRODUCTION

This part of IEC 62453 is an interface specification for developers of FDT (Field Device Tool) components for function control and data access within a client/server architecture. The specification is a result of an analysis and design process to develop standard interfaces to facilitate the development of servers and clients by multiple vendors that need to interoperate seamlessly.

With the integration of fieldbuses into control systems, there are a few other tasks which need to be performed. In addition to fieldbus- and device-specific tools, there is a need to integrate these tools into higher-level system-wide planning- or engineering tools. In particular, for use in extensive and heterogeneous control systems, typically in the area of the process industry, the unambiguous definition of engineering interfaces that are easy to use for all those involved is of great importance.

A device-specific software component, called DTM (Device Type Manager), is supplied by the field device manufacturer with its device. The DTM is integrated into engineering tools via the FDT interfaces defined in this specification. The approach to integration is in general open for all kinds of fieldbuses and thus meets the requirements for integrating different kinds of devices into heterogeneous control systems.

Figure 1 shows how IEC 62453-303-1 is aligned in the structure of the IEC 62453 series.

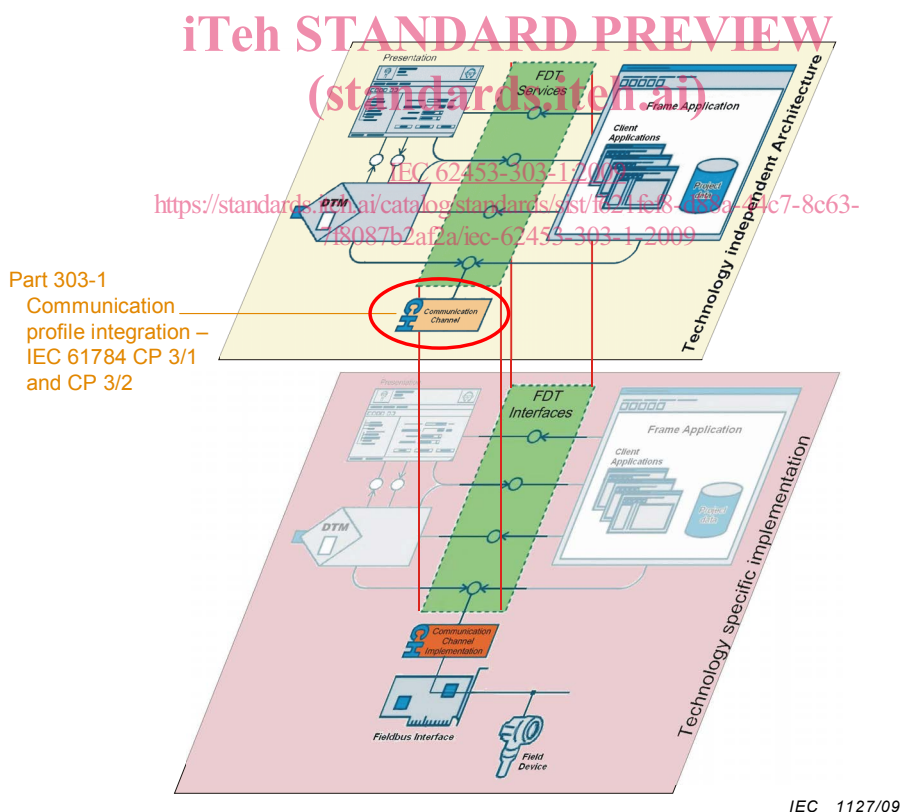


Figure 1 – Part 303-1 of the IEC 62453 series

FIELD DEVICE TOOL (FDT) INTERFACE SPECIFICATION –

Part 303-1: Communication profile integration – IEC 61784 CP 3/1 and CP 3/2

1 Scope

Communication Profile 3/1 and Communication Profile 3/2 (commonly known as PROFIBUS™¹) defines communication profiles based on IEC 61158-2 Type 3, IEC 61158-3-3, IEC 61158-4-3, IEC 61158-5-3, and IEC 61158-6-3. The basic profiles CP 3/1 (PROFIBUS DP) and CP 3/2 (PROFIBUS PA) are defined in IEC 61784-1.

This part of IEC 62453 provides information for integrating the PROFIBUS protocol into the FDT interface specification (IEC 62453–2).

This part of the IEC 62453 specifies communication and other services.

This specification neither contains the FDT specification nor modifies it.

2 Normative references

The following referenced documents are indispensable for the application of this specification. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 61131-3:2003, *Programmable controllers – Part 3: Programming languages*

IEC 61158 (all parts), *Industrial communication networks – Fieldbus specifications*

IEC 61158-2, *Industrial communication networks – Fieldbus specifications – Part 2: Physical layer specification and service definition*

IEC 61158-3-3, *Industrial communication networks – Fieldbus specifications – Part 3-3: Data-link layer service definition – Type 3 elements*

IEC 61158-4-3 *Industrial communication networks – Fieldbus specifications – Part 4-3: Data-link layer protocol specification – Type 3 elements*

IEC 61158-5-3: *Industrial communication networks – Fieldbus specifications – Part 5-3: Application layer service definition – Type 3 elements*

IEC 61158-6-3, *Industrial communication networks – Fieldbus specifications – Part 6-3: Application layer protocol specification – Type 3 elements*

IEC 61784-1, *Industrial communication networks – Profiles – Part 1: Fieldbus profiles*

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IEC 62453-1:2009, *Field Device Tool (FDT) interface specification – Part 1: Overview and guidance*

IEC 62453-2:2009, *Field Device Tool (FDT) interface specification – Part 2: Concepts and detailed description*

3 Terms, definitions, symbols, abbreviated terms and conventions

3.1 Terms and definitions

For the purposes of this document, the terms and definitions given in IEC 62453-1 and IEC 62453-2 apply.

3.1.1

bus interface module

module of a field device that provides the connection to the fieldbus

3.1.2

CP 3/1

Communication profile of CPF3, featuring asynchronous transmission; RS 485 (ANSI TIA/EIA RS-485-A); optional RS 485-IS; plastic fiber; glass multi mode fiber or glass single mode fiber; PCF fiber

3.1.3

CP 3/2

Communication profile of CPF3, featuring synchronous transmission; manchester coded and bus powered (MBP); optional intrinsically safe (MBP-IS) and lower power (MBP-LP)

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3.2 Symbols and abbreviated terms

For the purposes of this document, the symbols and abbreviations given in IEC 62453-1, IEC 62453-2 and the following apply.

BIM	Bus Interface Module
BMCP	Bus Master Configuration Part
GSD	General Station Description

3.3 Conventions

3.3.1 Data type names and references to data types

The conventions for naming and referencing of data types are explained in IEC 62453-2, Clause A.1

3.3.2 Vocabulary for requirements

The following expressions are used when specifying requirements.

Usage of “shall” or “mandatory”	No exceptions allowed.
Usage of “should” or “recommended”	Strong recommendation. It may make sense in special exceptional cases to differ from the described behaviour.
Usage of “can” or “optional”	Function or behaviour may be provided, depending on defined conditions.

3.3.3 Use of UML

Figures in this document are using the UML notation as defined in Annex A of IEC 62453-1.

4 Bus category

CP 3/1 and CP 3/2 protocols are identified in the protocolId element of the structured data type 'fdt:BusCategory' by the following unique identifiers (Table 1):

Table 1 – Protocol identifiers

Identifier value	ProtocolId name	Description
036D1497-387B-11D4-86E1-00E0987270B9	'Profibus DP/V0'	Support of Profibus DP V0 protocol
036D1499-387B-11D4-86E1-00E0987270B9	'Profibus DP/V1'	Support of Profibus DP V1 protocol

CP 3/1 AND CP 3/2 protocols are using the following unique identifiers in physicalLayer members within PhysicalLayer data type (Table 2):

Table 2 – Physical layer identifiers

Identifier value	Description
036D1590-387B-11D4-86E1-00E0987270B9	IEC 61158-2 (Profibus PA)
036D1591-387B-11D4-86E1-00E0987270B9	RS485
036D1592-387B-11D4-86E1-00E0987270B9	Fiber
036D1593-387B-11D4-86E1-00E0987270B9	Ethernet

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5 Access to instance and device data

5.1 Process Channel objects provided by DTM

The minimum set of provided data should be: Process values modelled as channel objects including the ranges and scaling

5.2 DTM services to access instance and device data

The services InstanceDataInformation and DeviceDataInformation shall provide access to at least all parameters of the Physical Block and the status and Out value of the Function Blocks shall be exposed.

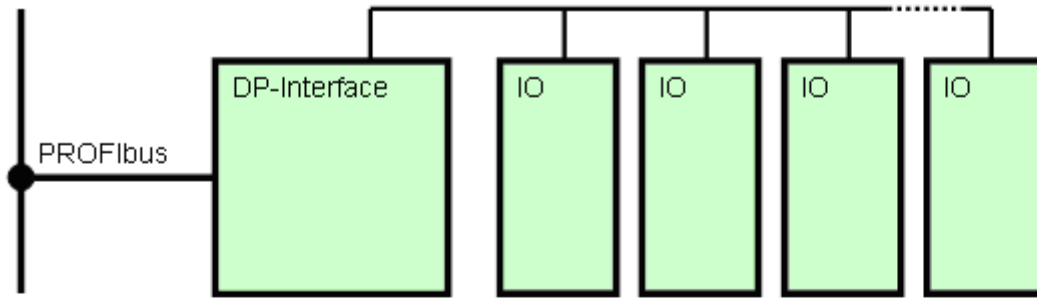
According to IEC 62453-2, at least one set of semantic information (one per supported fieldbus protocol) shall be provided for each accessible data object, using the 'SemanticInformation' general data type. The corresponding data type 'applicationDomain' shall have a value defined for Profibus and the data type 'semanticId' shall have an appropriate value, as specified in Table 9.

6 Protocol specific behavior

6.1 PROFIBUS device model

FDT extends the PROFIBUS device model by using Process Channels for description of I/O values (see Figure 2).

Classical View of PROFIBUS device



PROFIBUS notations from a monolithic DPV1 or PA device DTMs point of view

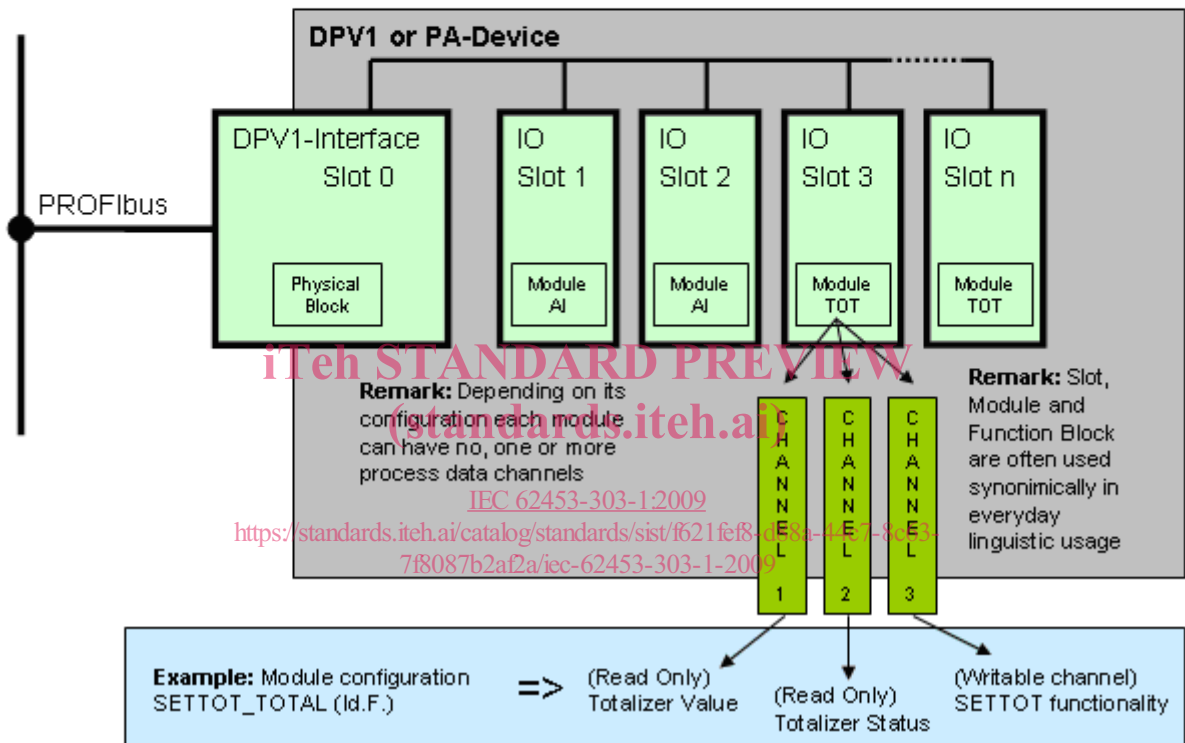


Figure 2 – FDT PROFIBUS device model

6.2 Configuration and parameterization of PROFIBUS devices

6.2.1 General

In a GSD-based configuration tool the user defines the configuration and sets the appropriate parameters for the modules. The configuration tool creates the configuration string and the parameter string that are used to set up the slave properly.

With FDT the configuration and parameterization of the devices is no longer executed only by a central component; it moved partly into the DTMs. A DTM is responsible for providing configuration and parameterization information for the cyclic master that puts the PROFIBUS slaves in operation.

A DTM is used to adjust a field device to its specific application. Within PROFIBUS, there are three different aspects of adjustment:

- parameterization: usr prm data (used in the PROFIBUS service SET_PRM for setting up the cyclic communication and the specific behavior of the device);

- application parameterization: application specific parameters (transmitted via acyclic read/write PROFIBUS services);
- configuration: configuration data (used in the PROFIBUS service CHK_CFG for definition of the format and length of the input/output data that are transmitted within cyclic communication).

The application parameterization transmitted via acyclic communication is not in the scope of this document. Within this document the term parameterization represents communication parameterization (SET_PRM).

6.2.2 Monolithic DTM for a modular PROFIBUS device

A monolithic DTM is one single DTM that represents the complete device with its Bus Interface Module (BIM) and its I/O modules. In general, such a DTM offers a configuration dialog (presentation object) that allows definition of the used BIM and modules. The configuration dialog must be available via the FDT standard function "Configure" (see [1] 4.3 Operation Configuration).

Not all PROFIBUS devices require a configuration dialog. That is why not all DTMs provide the "Configure" function. This is valid only for non-modular PROFIBUS devices if the Usr_Prm-Data cannot be changed.

The configuration dialog allows changing the data only in offline mode if the data set can be locked.

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6.2.3 Modular DTM for a modular PROFIBUS device

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Separate DTMs represent the BIM (Device DTM) and the particular I/O modules (Module DTMs). The effort developing such a modular DTM is normally higher than in the case of a monolithic DTM, because:

- a private protocol has to be implemented between BIM and I/O modules to ensure that only a Module DTM can be added to the BIM DTM. This requires an own protocol ID and the adaptation / creation of communication;
- in some cases, additional private interfaces are necessary to exchange information between Device DTM for BIM and Module DTMs.

Implementing a Modular DTM results in the following advantages:

- the project represents the device structure;
- the user is able to access module-related information directly as a function of the Module DTM;
- the FDT specification defines a mechanism to identify DTMs. With these mechanisms it is possible to provide support for scanning the modules below the BIM and generate the topology automatically;
- supporting a new type of BIM or I/O module requires an additional DTM "only" and does not affect existing components. This may result in reduced test effort.

The configuration data to set up the PROFIBUS configuration must be provided by the Device DTM (representing the BIM). This configuration data may be generated from information of the instantiated Child DTMs and by using a configuration dialog.

Modular DTMs should be provided for modular devices (e.g. a plant operator may add/remove modules). Monolithic DTMs are used to represent devices that show no modularity (e.g. PA devices).

6.3 Support for DPV0 configuration

A PROFIBUS slave is configured by a cyclic master and communicates via PROFIBUS DP. In addition to this the slave may support DPV1 communication.

A Gateway DTM for a PROFIBUS slave does not have to provide communication for the DPV0 communication schema. For example, there is a remote I/O system with HART modules. It may have a Gateway DTM that requires the DPV1 protocol and provides the HART protocol (defined in the information document and in the parameter document). This enables HART Device DTMs to communicate with their devices via the Gateway DTM and via Communication DTM for DPV1. Following the specification the Gateway DTM delivers channel parameter documents for both protocols DPV1 and HART. The protocolId is a member of NetworkManagementInfo data type.

The Process Channels must provide ChannelParameter documents for DPV1 including all information to allow integration into the control system (e.g. DPAddress of the IO value if available).

6.4 PROFIBUS slaves operating without a cyclic PROFIBUS master

In most cases, a PROFIBUS slave is configured and parameterized by a cyclic PROFIBUS master device. So a running master device in the network is required.

Some slaves are able to allow acyclic communication without a running cyclic master. Especially in the case of gateway functionality this is an eminent advantage because they allow the parameterization of field devices connected to them by using an acyclic bus master. So instrument specialists are able to work with field devices also in case the controller is not yet working.

If a master starts communication, these devices start to detect bus speed and settings to react properly. This may take some time.

In the following, two cases are described that a user may keep in mind when working with such devices.

Use case 1:

The user performs a network scan. The Communication DTM tries to read diagnostic data via a GetDiagnose Request but does not receive a response. The device is not detected by the Communication DTM. This occurs mostly when the device has a low PROFIBUS address. The reason is that the device has not completed bus speed / bus setting detection as it was asked for their diagnostic data. The workaround is to give these devices a higher PROFIBUS address.

Use Cases 2:

The user tries to connect a field device linked to the gateway that supports DPV1 without a running cyclic master. This can lead to an error message because the gateway device has not completed bus speed / bus setting detection as it was asked for a connection. So the user has to try to connect again. This happens only in very rare situations.

6.5 PROFIBUS-related information of a slave DTM

6.5.1 General

The information used by a cyclic master device to set up the PROFIBUS network properly and allow cyclic communication between control system and slave devices is provided by a DTM in