

EC 62555:2013



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# INTERNATIONAL STANDARD

# NORME INTERNATIONALE

Ultrasonics – Power measurement – High intensity therapevtic ultrasound (HITU) transducers and systems (standards.iteh.ai)

Ultrasons – Mesurage de puissance – Transducteurs et systèmes ultrasonores thérapeutiques de haute intensité (HITU) s/sist/03809949-8a5b-4e85-bdd2-

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

COMMISSION ELECTROTECHNIQUE INTERNATIONALE



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Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

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### INTRODUCTION

In ultrasound fields at megahertz frequencies, output power is typically determined by measuring the force on a target using a radiation force balance [1],[2],[3]. However, the relationship between the radiation force and the output power is affected by the focusing or other geometrical aspects of the field, by the type and shape of the target, by the distance of the target from the transducer, by absorption (including 'shock-loss') in the water path, and by acoustic streaming currents. Whilst many of these effects are small for typical diagnostic or physiotherapy ultrasound fields, they cannot generally be ignored for HITU fields (particularly for those often referred to as high intensity focused ultrasound HIFU) [4]. Furthermore, in HITU, the quantity of interest is the power incident on the patient rather than the output power at the transducer face. Since it is common to have a water stand-off between the transducer and the patient, attenuation and shock-loss in the water path may be significant and will vary depending upon the chosen distance.

The purpose of this International Standard is to establish standard methods of measurement of ultrasonic power of HITU devices in liquids in the lower megahertz frequency range based on the measurement of the radiation force using a gravimetric balance, and calorimetry (based on the measurement of thermal expansion). This standard identifies the sources of errors and describes a systematic step-by-step procedure to assess overall measurement uncertainty as well as the precautions that should be undertaken and uncertainties that should be taken into account while performing power measurements. Practical guidance is given for the determination of acoustic power from the very wide range of transducer geometries used for HITU. Unlike radiation force approaches in IEC 61161 that deal with "time average power," other power measurement methods are described in this document.

The structure and content of **parts of this International S**tandard are largely based on IEC 61161:2013 but there are differences that are summarised below. In this standard the prime measurand is considered to be the incident power, and not the output power. Output power is always the quantity of interest in IEC 61161, which specifies that measurements are made with the target placed close to the transducer. However, this may not always be possible for strongly convergent transducers and there are cases where it is more relevant to measure the incident power which reaches a specified surface at some substantial distance from the transducer (this surface may represent the skin surface of the patient, for instance). This extra distance may result in significant nonlinear loss in the water path even at low megahertz frequencies. Consequently, in this International Standard the prime measurand is considered to be the incident power, and not the output power. The incident power may of course be the basis for determining the output power using an appropriate model with its own uncertainties.

# ULTRASONICS – POWER MEASUREMENT – HIGH INTENSITY THERAPEUTIC ULTRASOUND (HITU) TRANSDUCERS AND SYSTEMS

# 1 Scope

This International Standard

- establishes general principles relevant to **HITU** fields for the use of **radiation force** balances in which an obstacle (**target**) intercepts the sound field to be measured;
- specifies a calorimetric method of determining the total emitted acoustic power of ultrasonic transducers based on the measurement of thermal expansion of a fluid-filled target;
- specifies requirements related to the statement of electrical power characteristics of ultrasonic transducers;
- provides guidance related to the avoidance of acoustic cavitation during measurement;
- provides guidance related to the measurement of HITU transducers of different construction and geometry, including collimated, diverging and convergent transducers, and multi-element transducers;
- provides guidance on the choice of the most appropriate measurement method;
- provides information on assessment of overall measurement uncertainties.

This International Standard is applicable to the measurement of ultrasonic power generated by **HITU equipment** up to 500 W in the frequency range from 0.5 MHz to 5 MHz. **HITU equipment** may generate convergent, collimated or divergent fields.

For frequencies less than 500 kHz, no validations exist and the user should assess the uncertainties of the power measurement and measurement system at the frequencies of operation.

This International Standard does not apply to:

• ultrasound equipment used for physiotherapy, for lithotripsy for general pain relief.

# 2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 61161:2013, Ultrasonics – Power measurement – Radiation force balances and performance requirements

IEC/TR 62781, Ultrasonics – Conditioning of water for ultrasonic measurements

# 3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

# 3.1 acoustical efficiency

 $\eta_{\rm a}$  ratio of the acoustic **output power** from an **ultrasonic transducer** to the **transducer** electrical power

Note 1 to entry: **Acoustical efficiency** is unitless.

#### 3.2

#### acoustic streaming

bulk fluid motion initiated by a sound field

[SOURCE: IEC 61161:2013, 3.1]

#### 3.3 buoyancy sensitivity S

ratio of the increase in the buoyancy force on an **expansion target** to the amount of absorbed energy in the absence of thermal losses

Note 1 to entry: This ratio may be temperature dependent.

Note 2 to entry: The **buoyancy sensitivity** for a fluid filled expansion target immersed in water is most conveniently and most accurately determined by calibration using electrical heating (see 7.2.9). It can also be calculated from the product of the **expansion ratio**, the density of the water and the acceleration due to gravity but, in practice, this leads to higher uncertainties. DARD PREVIEW

Note 3 to entry: Since most sensitive balances display weight in grams or milligrams, the **buoyancy sensitivity** is often more conveniently expressed as mass-equivalent **buoyancy sensitivity** in terms of a mass-equivalent unit, such as mg J<sup>-1</sup>.

Note 4 to entry: **Buoyancy sensitivity** is expressed in Newton per Joule, N J<sup>-1</sup>.

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# 3.4

#### expansion ratio

 $R_{\rm V}$ 

ratio of the increase in volume of the liquid inside an **expansion target** to the amount of absorbed energy in the absence of thermal losses

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Note 1 to entry: Subject to certain assumptions, the **expansion sensitivity** for a fluid-filled **expansion target** can be calculated from the ratio of the volume expansivity of the fluid to its volumetric heat capacity. The ratio may be temperature dependent.

Note 2 to entry: **Expansion ratio** is expressed in cubic metre per Joule, m<sup>3</sup> J<sup>-1</sup>.

#### 3.5

#### expansion target

a liquid-filled device specially designed to intercept and absorb substantially all of the ultrasonic field and to undergo thermal expansion

#### 3.6

#### free field

sound field in a homogeneous isotropic medium whose boundaries exert a negligible effect on the sound waves

[SOURCE: IEC 60050-801:1994, 801-23-28, modified – the term no longer contains "sound"]

#### 3.7

#### high intensity therapeutic ultrasound (HITU) equipment

equipment for the generation and application of ultrasound to a patient for therapeutic purposes with the intention to destroy, disrupt or denature living tissues or non-tissue elements (for example, liquids, bubbles or micro-capsules) and which aims notably at making

treatments through actions of ultrasound having mechanical, thermal or more generally physical, chemical or biochemical effects

Note 1 to entry: Essentially **HITU equipment** comprises a generator of electric high-frequency power and a transducer for converting this to ultrasound. In a lot of cases this equipment also includes a targeting and monitoring device.

Note 2 to entry: HITU may as a side effect by its operation induce hyperthermia, however it should not be confused with this technique, which heats much less rapidly and to much lower therapeutic temperatures (in general 42  $^{\circ}$ C to 50  $^{\circ}$ C and thermal equivalent times of 0,2 min to 120 min). **HITU equipment** typically causes temperature rises in excess of 55  $^{\circ}$ C and for much shorter times: alternatively, HITU may also induce bioeffects by non-thermal mechanisms.

Note 3 to entry: This definition does not apply to: ultrasound equipment used for physiotherapy, ultrasound equipment used for lithotripsy or ultrasound equipment used for general pain relief.

[SOURCE: IEC 60601-2-62:2013, 201.3.218, modified – the Note 3 to entry refers to "general pain relief" instead of "dedicated hyperthermia".]

### 3.8

#### incident power

 $P_{i}$ 

time-average ultrasonic power reaching a specified plane or surface after being emitted by an **ultrasonic transducer** into an approximately **free field**, under specified conditions and in a specified medium, preferably water

Note 1 to entry: Incident power is expressed in watt, W

#### 3.9 multi-element transducer

# (standards.iteh.ai)

a source of ultrasound comprising two or more spatially separated ultrasonic transducers

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Note 1 to entry transducer. In this context, a single piezoelectric element in a phased array is considered to be an ultrasonic f9bf9a0b49c4/iec-62555-2013

#### 3.10

#### nonlinear loss

loss of energy from an ultrasound beam due to the absorption of harmonic components which arise from nonlinear propagation effects

Note 1 to entry: In general, **nonlinear loss** does not occur uniformly throughout an ultrasound field but occurs preferentially where the pressure amplitude is greatest, resulting in a change in the relative distribution of ultrasound energy.

#### 3.11 output power

P

time-average ultrasonic power emitted by an **ultrasonic transducer** into an approximately **free field** under specified conditions in a specified medium, preferably water

Note 1 to entry: **Output power** is expressed in watt, W

#### [SOURCE: IEC 61161:2013, 3.3]

# 3.12 radiation conductance

G

ratio of the acoustic **output power** and the squared r.m.s. transducer input voltage.

Note 1 to entry: It is used to characterize the electrical to acoustical transfer of ultrasonic transducers.

Note 2 to entry: The r.m.s. drive voltage is used (rather than, for instance, peak-to-peak drive voltage) because its value is less affected by distortion of the applied electrical signal.

Note 3 to entry: This term is not the same as the real part of transducer admittance.

Note 4 to entry: Radiation conductance is expressed in siemens, S

[SOURCE: IEC 61161:2013, 3.8, modified -two notes to entry relevant to HITU have been added]

#### 3.13 radiation force acoustic radiation force *F*

time-average force acting on a body in a sound field and caused by the sound field, excluding the component due to **acoustic streaming** 

Note 1 to entry: More generally: time-average force (excluding the component due to **acoustic streaming**) in a sound field, appearing at the boundary surface between two media of different acoustic properties

Note 2 to entry: Radiation force is expressed in Newton, N

[SOURCE; IEC 61161:2013, 3.4 modified – the second part of the original definition is presented as a note to entry, but without the phrase "or within a single attenuating medium"]

# 3.14

#### radiation force target

device specially designed to intercept substantially all of the ultrasonic field and to serve as the object which is acted upon by the **radiation force** 

# 3.15 **iTeh STANDARD PREVIEW**

### target

device specially designed to intercept substantially all of the ultrasonic field

# 3.16

#### IEC 62555:2013

 $P_{\mathsf{el}}$ 

rate at which time-average electrical energy is converted by an **ultrasonic transducer** into other forms of energy (typically into heat and the energy of the ultrasonic field)

Note 1 to entry: Electrical power which is reflected from the **ultrasonic transducer** is not part of the **transducer electrical power**.

Note 2 to entry: Transducer electrical power is expressed in Watt, W

# 3.17

#### ultrasonic transducer

device capable of converting electrical energy to mechanical energy within the ultrasonic frequency range and/or reciprocally of converting mechanical energy to electrical energy

Note 1 to entry: An **ultrasonic transducer** may include connected cables and components for electrical matching.

# 4 List of symbols

а	radius of a	circular	ultrasonic	source transducer	•

- $b_x$  and  $b_y$  half-dimensions of a rectangular **ultrasonic transducer** in x and y direction, respectively (so that  $2b_x$  and  $2b_y$  are the transducer's side lengths)
- *B* change in the buoyancy force acting on an **expansion target** immersed in a sound propagating medium (usually water)
- c speed of sound (usually in water)
- $d_x$  and  $d_y$  geometrical focal lengths of a convergent ultrasonic transducer in the x-z and the y-z plane, respectively

d	geometrical focal length of a convergent ultrasonic transducer, in the case that $d_x = d_y = d$
С	the volumetric heat capacity
Ε	the volumetric expansion coefficient
F	radiation force on a target in the direction of the incident ultrasonic wave
g	acceleration due to gravity
G	radiation conductance
$h_{d}$	half the diagonal of a rectangular transducer, $h_{d} = (b_x^2 + b_y^2)^{1/2}$
h <sub>h</sub>	harmonic mean of $b_x$ and $b_y$ , $h_h = 2 / (1/b_x + 1/b_y)$
k	circular wavenumber $(2\pi/\lambda)$
L	the fraction of <b>acoustic streaming</b> momentum recovered by a <b>target</b>
М	the time-varying weight of a <b>target</b> or <b>expansion target</b> as it is displayed by the supporting balance (often in mass-equivalent units)
Р	output power of an ultrasonic transducer
$P_{el}$	the transducer electrical power
P <sub>i</sub>	incident power on a target or expansion target
R <sub>c</sub>	radius of curvature of a focused bowl transducer
R <sub>V</sub>	the <b>expansion ratio</b> of an <b>expansion target</b>
S	normalized distance from an ultrasonic transducer (s = $z/\lambda / a^2$ )
S	the buoyancy sensitivity of an expansion target
t <sub>0</sub>	the duration of insonation
Z	distance between a target <u>(and 2the</u> radiating surface of an ultrasonic transducer measured along the beam taxis)9949-8a5b-4e85-bdd2-
α	amplitude attenuation coefficient of plane waves in a medium (usually water)
$eta_{x}$ and $eta_{y}$	focus (half-)angles of a convergent <b>ultrasonic transducer</b> in the <i>x</i> - <i>z</i> and the <i>y</i> - <i>z</i> plane, respectively; $\beta_x$ = arctan( $b_x/d_x$ ), $\beta_y$ = arctan( $b_y/d_y$ ) if the transducer is planar and the focal lengths are counted from the planar transducer surface
γ	focus (half-)angle of a circular convergent <b>ultrasonic transducer</b> ; $\gamma = \arcsin(a/d)$ if the transducer is spherically curved and the focal length is counted from the "bottom" of the "bowl"; $\gamma = \arctan(a/d)$ if the focal length is counted from the plane defined by the rim of the active part of the "bowl" or if the transducer is planar
$\eta_{a}$	the acoustic efficiency of an ultrasonic transducer
θ	angle between the direction of the incident ultrasonic wave and the normal to the surface of a <b>target</b>
$\phi$	angle between the direction of the incident ultrasonic wave and the sensitive axis (usually vertical) of a balance
λ	ultrasonic wavelength in the sound-propagating medium (usually water)
ρ	(mass) density of the sound-propagating medium (usually water).
NOTE The dir field axis, i.e., i	rection of the incident wave mentioned above under F and $\theta$ is understood to be the direction of the it is understood in a global sense rather than in a local sense.

# 5 **Power measurement for HITU equipment**

Measurement of **output power** is well established for collimated (and weakly convergent or weakly divergent) ultrasound fields at powers up to 20 W using the **radiation force** method [IEC 61161]. Clause 6 of this International Standard is based on IEC 61161:2013 but some

changes are introduced to make it more appropriate for **HITU equipment** which in general is not collimated and has higher **output power**. IEC 61161 specifies that measurements are made with the **target** placed close to the transducer. However, this may not always be possible for strongly convergent transducers and there are cases where it is more relevant to measure the **incident power** which reaches a specified surface at some substantial distance from the transducer (this surface may represent the skin surface of the patient, for instance). This extra distance may result in significant **nonlinear loss** in the water path. Consequently, in this International Standard the prime measurand is considered to be the **incident power**, and not the **output power**. The **incident power** may of course be the basis for determining the **output power** using an appropriate model with its own uncertainties (guidance is given in Annex E). Although the buoyancy change method determines the time-average power incident on the **target** during the insonation time, the **radiation force** method actually determines the turn-on and turn-off power. These two values may be different to each other, and the average of the two is not necessarily equal to the time-average power. In general, insonation time is adjusted as appropriate to the measuring device to account for device limitations.

### 6 Radiation force on a target

#### 6.1 General

The **radiation force** balance shall consist of a **target** which is connected to a balance. The ultrasonic beam shall be directed vertically upwards or downwards or horizontally on the **target** and the **radiation force** exerted by the ultrasonic beam shall be measured by the balance. The incident ultrasonic power shall be determined from the difference between the force measured with and without ultrasonic radiation. Calibration of the balance can be carried out by means of small precision weights of known mass.

# (standards.iteh.ai)

The **target** shall be chosen so as to closely approach one of the two extreme cases, i.e. perfect absorber or perfect reflector. IEC 62555:2013

#### https://standards.iteh.ai/catalog/standards/sist/03809949-8a5b-4e85-bdd2-

For a plane incident wave only, 0 the 0 acoustic 2 incident power  $P_i$  from the ultrasonic transducer shall be calculated from the radiation force component F on the target in the propagation direction using Equation 1 or 2 as appropriate:

For a perfectly absorbing **target**:

$$P_{i} = cF \tag{1}$$

For a perfectly reflecting **target**:

$$P_{i} = cF / (2\cos^{2}\theta) \tag{2}$$

where

- *c* is the speed of sound in the sound-propagating fluid (water);
- $\theta$  is the angle between the propagation direction of the incident wave and the normal to the reflecting surface

NOTE 1 The direction of the incident wave mentioned above is understood to be the direction of the field axis, i.e., it is understood in a global sense rather than in a local sense.

The relationship between **radiation force** and **incident power** depends in principle on assumptions about the radiated field and its interaction with the **target** and the measurement tank. For any non-plane wave (e.g. convergent, divergent or arising from multiple simultaneous sources), the correct relationship between **radiation force** and **incident power** shall be determined. The uncertainty in the **incident power** due to the non-plane nature of the field shall be estimated.