

SLOVENSKI STANDARD SIST EN 60565:2008 01-januar-2008

DcXjcXbUU_ighj_U'!<]XfcZcb]'!'?U]VfUVj/Uj'ZfY_jYb bYa cVac 1 cX'\$漭%<n'Xc %A<n'fH97'*\$)*).&\$\$**と

Underwater acoustics - Hydrophones - Calibration in the frequency range 0,01 Hz to 1 MHz (IEC 60565:2006)

Wasserschall - Hydrophone - Kalibrierung im Frequenzbereich von 0,01 Hz bis 1 MHz (IEC 60565:2006)

iTeh STANDARD PREVIEW

Acoustique sous-marine - Hydrophones - Etalonnage dans la bande de fréquences de 0,01 Hz a 1 MHz (IEC 60565:2006)

SIST EN 60565:2008 https://standards.iteh.ai/catalog/standards/sist/86d20b26-9def-4841-a677-Ta slovenski standard je istoveten zie9150/EN 60565:2007

<u>ICS:</u>

17.140.50 Elektroakustika

Electroacoustics

SIST EN 60565:2008

en,fr,de

iTeh STANDARD PREVIEW (standards.iteh.ai)

<u>SIST EN 60565:2008</u> https://standards.iteh.ai/catalog/standards/sist/86d20b26-9def-4841-a677-9759578e9150/sist-en-60565-2008

EUROPEAN STANDARD NORME EUROPÉENNE EUROPÄISCHE NORM

EN 60565

January 2007

ICS 17.140.50

English version

Underwater acoustics -Hydrophones -Calibration in the frequency range 0,01 Hz to 1 MHz (IEC 60565:2006)

Acoustique sous-marine -Hvdrophones -Etalonnage dans la bande de fréquences de 0,01 Hz à 1 MHz (CEI 60565:2006)

Wasserschall -Hvdrophone -Kalibrierung im Frequenzbereich von 0,01 Hz bis 1 MHz (IEC 60565:2006)

iTeh STANDARD PREVIEW

This European Standard was approved by CENELEC on 2006-12-01. CENELEC members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration 5:2008

https://standards.iteh.ai/catalog/standards/sist/86d20b26-9def-4841-a67 Up-to-date lists and bibliographical references concerning such national standards may be obtained on application to the Central Secretariat or to any CENELEC member.

This European Standard exists in three official versions (English, French, German). A version in any other language made by translation under the responsibility of a CENELEC member into its own language and notified to the Central Secretariat has the same status as the official versions.

CENELEC members are the national electrotechnical committees of Austria, Belgium, Cyprus, the Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, the Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland and the United Kingdom.

CENELEC

European Committee for Electrotechnical Standardization Comité Européen de Normalisation Electrotechnique Europäisches Komitee für Elektrotechnische Normung

Central Secretariat: rue de Stassart 35, B - 1050 Brussels

© 2007 CENELEC -All rights of exploitation in any form and by any means reserved worldwide for CENELEC members.

Foreword

The text of document 87/357/FDIS, future edition 2 of IEC 60565, prepared by IEC TC 87, Ultrasonics, was submitted to the IEC-CENELEC parallel vote and was approved by CENELEC as EN 60565 on 2006-12-01.

The following dates were fixed:

_	latest date by which the EN has to be implemented at national level by publication of an identical national standard or by endorsement	(dop)	2007-09-01
-	latest date by which the national standards conflicting with the EN have to be withdrawn	(dow)	2009-12-01

Annex ZA has been added by CENELEC.

Endorsement notice

The text of the International Standard IEC 60565:2006 was approved by CENELEC as a European Standard without any modification.

iTeh STANDARD PREVIEW (standards.iteh.ai)

<u>SIST EN 60565:2008</u> https://standards.iteh.ai/catalog/standards/sist/86d20b26-9def-4841-a677-9759578e9150/sist-en-60565-2008

Annex ZA

(normative)

Normative references to international publications with their corresponding European publications

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

NOTE When an international publication has been modified by common modifications, indicated by (mod), the relevant EN/HD applies.

Publication	Year	Title	<u>EN/HD</u>	<u>Year</u>
IEC 60050-801	_1)	International Electrotechnical Vocabulary (IEV) Chapter 801: Acoustics and electroacoustics	-	-
IEC 60500	1974	IEC standard hydrophone	-	-
IEC 60866	1987	Characteristics and calibration of hydrophones for operation in the frequency range 0,5 MHz to 15 MHz	-	-

iTeh STANDARD PREVIEW (standards.iteh.ai)

SIST EN 60565:2008

https://standards.iteh.ai/catalog/standards/sist/86d20b26-9def-4841-a677-9759578e9150/sist-en-60565-2008

¹⁾ Undated reference.

iTeh STANDARD PREVIEW (standards.iteh.ai)

<u>SIST EN 60565:2008</u> https://standards.iteh.ai/catalog/standards/sist/86d20b26-9def-4841-a677-9759578e9150/sist-en-60565-2008

NORME INTERNATIONALE INTERNATIONAL STANDARD

CEI IEC 60565

Deuxième édition Second edition 2006-11

Acoustique sous-marine – Hydrophones – Étalonnage dans la bande de fréquences de 0,01 Hz à 1 MHz

-

iTeh STANDARD PREVIEW Underwater acoustics – Hydrophones rds.iteh.ai)

Calibration in the frequency SISTEN 60565:2008 https://riangetc0.0alalHzatord1/sMHz0b26-9def-4841-a677-9759578e9150/sist-en-60565-2008

© IEC 2006 Droits de reproduction réservés — Copyright - all rights reserved

Aucune partie de cette publication ne peut être reproduite ni utilisée sous quelque forme que ce soit et par aucun procédé, électronique ou mécanique, y compris la photocopie et les microfilms, sans l'accord écrit de l'éditeur. No part of this publication may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying and microfilm, without permission in writing from the publisher.

International Electrotechnical Commission, 3, rue de Varembé, PO Box 131, CH-1211 Geneva 20, Switzerland Telephone: +41 22 919 02 11 Telefax: +41 22 919 03 00 E-mail: inmail@iec.ch Web: www.iec.ch



Commission Electrotechnique Internationale International Electrotechnical Commission Международная Электротехническая Комиссия



Pour prix, voir catalogue en vigueur For price, see current catalogue

CONTENTS

FOI	REWO	DRD	9
1	Scop	e	. 13
2	Norm	ative references	.13
3	Term	s and definitions	.13
4	Symb	ools and abbreviated terms	.25
5	Proce	edures for calibrations	.29
	5.1	Principles	.29
	5.2	Field limitations	.31
	5.3	Schematic survey of procedures	.31
	5.4	Reporting of results	.31
	5.5	Recalibration periods	. 33
_	5.6	Temperature and pressure considerations for calibration	.33
6	Prep	aration of transducers	.33
	6.1	Wetting	.33
	6.2	Hydrophone support	. 33
7	6.3	ring manager STANDARD PREVIEW	.33
1	Elect		. 35
	7.1 7.2	Signal type	.35
	7.2 7.3	Earthing	. 35
	7.5	Measurement of hydrophone <u>sourper Monagens</u>	.37
	7.5	Measurement of transfer/impedanceist-en-60565-2008	. 39
8	Free-	field reciprocity calibration	.39
-	8.1	General principle	39
	8.2	Theory	.41
	8.3	Separation distance	.51
	8.4	Minimum distance from transducers to boundary surface	.51
	8.5	Frequency limitation	.51
	8.6	Measurements and checks	.53
	8.7	Uncertainty	. 59
9	Free-	field calibration by comparison	. 59
	9.1	Principle	.59
	9.2	Comparison with a standard hydrophone	. 59
4.0	9.3	Calibration with a calibrated projector	.61
10	Calib	ration by hydrostatic excitation	.63
	10.1	Principle	63
	10.2	Determination of equivalent pressure	.63
	10.3	Design of vibration system	. / 1
	10.4	Uncertainty	75
	10.6	Alternative method for hydrostatic excitation	. 75
11	Calib	ration by piezoelectric compensation	.75
	11 1	Principle	75
	11.2	Procedure	
			-

	11.3 Design of the calibration chamber	81
	11.4 Practical limitations of the piezoelectric compensation method	85
	11.5 Uncertainty	85
12	Acoustic coupler reciprocity calibration	85
	12.1 Principle	85
	12.2 Procedure	85
	12.3 Theory	87
	12.4 Acoustic compliance	
	12.5 High-frequency limit	
	12.6 Low-frequency limit	89
	12.7 Measurement	89
	12.8 Uncertainty	91
	12.9 Limitations	91
	12.10 Acoustic-coupler calibration using a reference coupler with two reciprocal	
	transducers and an auxiliary coupler with the same two transducers and a	
	hydrophone to be calibrated	91
	12.11 Acoustic-coupler calibration using a reference coupler with two reciprocal transducers and an auxiliary coupler with the same two transducers.	
	hydrophone to be calibrated, and a sound source	95
	12.12 Acoustic-coupler calibration using a coupler, a reciprocal transducer, a	
	projector, a hydrophone to be calibrated, and a subsidiary body of known	
	compliance i.T.e.hS.T.A.N.D.A.R.D. .P.R.F.V.I.F.W.	99
13	Calibration with a pistonphone	103
	13.1 Principle	103
	13.2 Procedure	103
	13.3 Limitations	109
	13.4 Uncertainty	111
14	Calibration with a vibrating column	111
	14.1 Principle	111
	14.2 Procedure	113
	14.3 Expression for the pressure	115
	14.4 Determination of the sensitivity	115
	14.5 Conditions of measurement	119
	14.6 Uncertainty	121
Anr	nex A (informative) Directional response of a hydrophone	123
Anr	nex B (informative) Electrical loading corrections	
Δnr	nex C (informative) Pulsed techniques in free-field calibrations	131
A	nex C (informative) Assessment of uncertainty in the collibrations of hydrophones	101
AUL	The combinative Assessment of uncertainty in the calibration of hydrophones	149
Anr	nex E (Informative) Equivalent circuit of the excitation system for calibration with a rating column	167
VID		107
Bib	liography	159

Figure 1 – Left-hand co-ordinate system	15
Figure 2 – Measurement framework for supporting in-line the three transducers: a projector P, a reciprocal transducer T, and a hydrophone H to be calibrated	49
Figure 3 – Diagram of the method of hydrostatic excitation	65
Figure 4 – Schematic drawing of the measuring system	77
Figure 5 – Diagram of the chamber for high-frequency	83
Figure 6 – Reciprocity coupler with three transducers; a projector P , a reciprocal transducer T , and a hydrophone H to be calibrated	87
Figure 7 – Reference coupler with two transducers: a projector P and a reciprocal transducer T	93
Figure 8 – Auxiliary coupler with three transducers: a projector P , a reciprocal transducer T , and a hydrophone H to be calibrated	93
Figure 9 – Auxiliary coupler with four transducers; a projector P , a reciprocal transducer T , a sound source S , and a hydrophone H to be calibrated	97
Figure 10 – Schematic drawing of the measuring system.	103
Figure 11 – Pistonphone	111
Figure 12 – Vibrating column	113
Figure C.1 – Schematic diagram of a projector and receiver in a water tank showing the main sources of reflections	135
Figure C.2 – Echo arrival time in a 6 m \times 6 m \times 5 m tank with optimally placed transducers.	137
Figure C.3 – Hydrophone signals for a pair of spherical transducers [projector: 18 kHz resonance frequency, <i>Q</i> factor of 3.5; hydrophone: 350 kHz resonance frequency;	400
drive trequency: 2 kHz (left) and 185kHz (right) then-60565-2008	139
Figure E.1 – Simplified equivalent circuit of the vibrating column	157

INTERNATIONAL ELECTROTECHNICAL COMMISSION

UNDERWATER ACOUSTICS – HYDROPHONES – CALIBRATION IN THE FREQUENCY RANGE 0,01 Hz TO 1 MHz

FOREWORD

- 1) The International Electrotechnical Commission (IEC) is a worldwide organization for standardization comprising all national electrotechnical committees (IEC National Committees). The object of IEC is to promote international co-operation on all questions concerning standardization in the electrical and electronic fields. To this end and in addition to other activities, IEC publishes International Standards, Technical Specifications, Technical Reports, Publicly Available Specifications (PAS) and Guides (hereafter referred to as "IEC Publication(s)"). Their preparation is entrusted to technical committees; any IEC National Committee interested in the subject dealt with may participate in this preparatory work. International, governmental and non-governmental organizations for Standardization (ISO) in accordance with conditions determined by agreement between the two organizations.
- The formal decisions or agreements of IEC on technical matters express, as nearly as possible, an international consensus of opinion on the relevant subjects since each technical committee has representation from all interested IEC National Committees.
- 3) IEC Publications have the form of recommendations for international use and are accepted by IEC National Committees in that sense. While all reasonable efforts are made to ensure that the technical content of IEC Publications is accurate, IEC cannot be held responsible for the way in which they are used or for any misinterpretation by any enduser.
- 4) In order to promote international uniformity, IEC National Committees undertake to apply IEC Publications transparently to the maximum extent possible in their national and regional publications. Any divergence between any IEC Publication and the corresponding national or regional publication shall be clearly indicated in the latter.
- 5) IEC provides no marking procedure to indicate its approval and cannot be rendered responsible for any equipment declared to be in conformity with an EC Publication d20b26-9def-4841-a677-
- 6) All users should ensure that they have the latest edition of this publication.
- 7) No liability shall attach to IEC or its directors, employees, servants or agents including individual experts and members of its technical committees and IEC National Committees for any personal injury, property damage or other damage of any nature whatsoever, whether direct or indirect, or for costs (including legal fees) and expenses arising out of the publication, use of, or reliance upon, this IEC Publication or any other IEC Publications.
- 8) Attention is drawn to the Normative references cited in this publication. Use of the referenced publications is indispensable for the correct application of this publication.
- 9) Attention is drawn to the possibility that some of the elements of this IEC Publication may be the subject of patent rights. IEC shall not be held responsible for identifying any or all such patent rights.

International Standard IEC 60565 has been prepared by IEC technical committee 87: Ultrasonics.

This second edition cancels and replaces the first edition published in 1977 and its first supplement IEC 60565A (1980). This edition constitutes a technical revision. The significant technical changes with respect to the previous edition are as follows:

- updating of procedures to reflect the use of digital acquisition and signal processing techniques as opposed to the analogue techniques described in the first edition;
- inclusion of more detailed information regarding the preparation of hydrophones for measurement, and the influences of environmental conditions on hydrophone calibration;
- revision of procedures for magnitude calibration of hydrophone response by the method of three-transducer spherical-wave reciprocity;
- inclusion of procedures for phase calibration into the method of three-transducer spherical-wave reciprocity;

- revision of procedures for calibration of hydrophones by the comparison methods;
- inclusion of procedures for low frequency hydrophone calibration utilising the method of hydrostatic excitation;
- revision of the procedures for low frequency hydrophone calibration utilising the method of piezoelectric compensation;
- inclusion of procedures for low frequency hydrophone calibration utilising the method of coupler reciprocity;
- revision of the procedures for low frequency hydrophone calibration utilising the pistonphone method;
- revision of procedures for low frequency hydrophone calibration utilising the method of vibrating column (previously issued as a supplement to the standard);
- deletion of Appendix A of first edition (transfer impedance by substitution method) since method no longer used;
- deletion of Appendix B of first edition (transfer impedance by direct read-out method) since method no longer used;
- retention of Appendix C of first edition, but now substantially updated and included as Annex C (informative);
- retention of Appendix D of first edition, now included as Annex A (informative);
- addition of new Annex B describing methods for accounting for electrical loading of hydrophones by pre-amplifiers;
- addition of new Annex D describing the assessment of uncertainty in free-field hydrophone calibrations;
- addition of new Annex E describing an equivalent electrical circuit of the excitation system for calibration with a vibrating column.

The text of this standard is based on the following documents:

FDIS	t-en-60565-2008 Report on voting
87/357/FDIS	87/360/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

The committee has decided that the contents of this publication will remain unchanged until the maintenance result date indicated on the IEC web site under "http://webstore.iec.ch" in the data related to the specific publication. At this date, the publication will be

- reconfirmed,
- withdrawn,
- replaced by a revised edition, or
- amended.

UNDERWATER ACOUSTICS – HYDROPHONES – CALIBRATION IN THE FREQUENCY RANGE 0,01 Hz TO 1 MHz

1 Scope

This International Standard specifies methods for calibration of hydrophones or reversible transducers when used as a hydrophone, particularly in the frequency range from 0,01 Hz to 1 MHz. Rules for the presentation of the calibration data are established.

2 Normative references

The following referenced data are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60050-801, International Electrotechnical Vocabulary - Chapter 801: Acoustics and electroacoustics

IEC 60500:1974, IEC Standard hydrophone ARD PREVIEW

IEC 60866:1987, Characteristics tand calibration to hydrophones for operation in the frequency range 0,5 MHz to 15 MHz

SIST EN 60565:2008 3 Terms and definitions 9759578e9150/sist-en-60565-2008

For the purposes of this document, the following terms and definitions apply.

3.1

angular deviation loss

sensitivity level of the transducer on the principal axis minus the sensitivity level of the transducer for a specified direction

[IEV 801-25-69]

3.2

co-ordinate system

system used to designate the directivity pattern of the transducer



- 15 -

Figure 1 – Left-hand co-ordinate system

Line transducer: central line of symmetry along the Z-axis;

Dipole transducer: both components equidistant from the origin, along the +Z and –Z axis;

Piston transducer: piston plane in ZOY-plane; principal axis along X-axis.

NOTE 1 The terms 'horizontal directivity pattern' and 'vertical directivity pattern' are often used for representation of directivity in the XY- and XZ- (or YZ-) planes respectively.

NOTE 2 See Annex A, [1]¹, [2].

3.3

coupler

apparatus comprising a rigid fluid-filled chamber of small dimensions into which transducers and hydrophones can be inserted ANDARD PREVIEW

3.4

(standards.iteh.ai)

diffraction factor

ratio of the average pressure over the part of the hydrophone designed to receive sound to the free-field sound pressure that would exist at the reference centre of the hydrophone 9759578e9150/sist-en-60565-2008

3.5

directional response

description, generally presented graphically, of the response of an electro-acoustic transducer, as a function of the direction of propagation of the radiated or incident sound in a specified plane through the reference centre and at a specified frequency

NOTE See Annex A.

3.6

dynamic range

ratio of the maximum free field sound pressure that produces an undistorted hydrophone output to the equivalent noise pressure at the hydrophone

3.7

electrical impedance of a transducer

complex ratio of the instantaneous voltage applied across the electrical terminals of a transducer at a given frequency, to the resulting instantaneous current

NOTE 1 The unit is the ohm, $\Omega.$

NOTE 2 Because the electrical impedance depends on the field conditions, the hydrostatic pressure, water temperature and the length of the cable attached to the transducer, these parameters, as well as the frequency and the electrical terminals where the electrical impedance is measured should be specified.

¹ Numbers in square brackets refer to the bibliography

3.8

electrical terminals of a reciprocal transducer

terminals across which the open circuit hydrophone voltage, as well as the projector current are measured

NOTE If the transducer is immersed in water, the electrical terminal with the lowest electrical impedance with respect to water is called the 'low terminal'. Consequently, the other electrical terminal is called the 'high terminal'.

3.9

electrical transfer impedance magnitude

magnitude of the electrical transfer impedance of a transducer pair

NOTE The unit is the ohm, Ω .

3.10

electrical transfer impedance of a transducer pair

complex ratio of the open circuit instantaneous voltage $U_{\rm H}$ across the hydrophone electrical terminals to the instantaneous current $I_{\rm p}$ through the projector, if projector and hydrophone are mounted in a free field with their principal axes in line and directed towards each other

NOTE 1
$$Z_{\rm PH} = \frac{U_{\rm H}}{I_{\rm P}}$$
 (1)

NOTE 2 The unit is the ohm, Ω .

NOTE 3 The electrical transfer impedance is a complex quantity. It has both real and imaginary components and can be represented as a magnitude $|Z_{_{
m PH}}|$ times a phase term $\exp{(j\varphi)}$, where φ is the phase angle between the real and imaginary impedance components.

NOTE 4 The definition of principal axis is given in 323.605652008

NOTE 5 See 7.5. https://standards.iteh.ai/catalog/standards/sist/86d20b26-9def-4841-a677-9759578e9150/sist-en-60565-2008

3.11

equivalent noise pressure

sound pressure applied at the hydrophone to cause a voltage at the hydrophone electrical terminals, in the absence of noise, that is equal to the noise voltage present at the same electrical terminals when the sound pressure is absent

NOTE When the equivalent noise pressure cannot be measured, it can be calculated from the equivalent series resistance [2].

3.12

far field

sound field at a distance from the sound source where the instantaneous values of sound pressure and particle velocity are substantially in phase

NOTE 1 In the far field, the sound pressure appears to be spherically divergent from a point on or near the radiating surface. Hence, the pressure produced by the sound source is inversely proportional to the distance from that source.

NOTE 2 For all practical calibrations, the separation distance between the sound source and the point where the pressure is measured is sufficiently large that the sound pressure is measured in the far field of the source.

3.13

free field

sound field in a homogeneous and isotropic medium in which the effects of the boundaries are negligible