

# INTERNATIONAL STANDARD

## NORME INTERNATIONALE

Rotating electrical machines –  
Part 16-1: Excitation systems for synchronous machines – Definitions

Machines électriques tournantes –  
Partie 16-1: Systèmes d'excitation pour machines synchrones – Définitions

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IEC Central Office  
3, rue de Varembe  
CH-1211 Geneva 20  
Switzerland  
Email: [inmail@iec.ch](mailto:inmail@iec.ch)  
Web: [www.iec.ch](http://www.iec.ch)

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Tél.: +41 22 919 02 11  
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## ROTATING ELECTRICAL MACHINES –

Part 16-1: Excitation systems for synchronous machines –  
Definitions

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International Standard IEC 60034-16-1 has been prepared by IEC technical committee 2: Rotating machinery.

This second edition cancels and replaces the first edition, issued in 1991, and constitutes a technical revision.

The major technical changes with regard to the previous edition are as follows:

Clause or subclause	Change
2.1.1	Additional definition for digital excitation system
2.1.2	Additional definition for reversible excitation system
2.3	Edited definition of excitation control

- 2.4 Additional definition for excitation control system. Added block diagram of excitation control system
- 2.17 Additional definition for excitation system negative ceiling voltage  $U_n$
- 2.19 Edited definition of excitation system on-load ceiling voltage  $U_{pL}$
- 2.20 Additional definition for excitation system on-load negative ceiling voltage  $U_{nL}$
- 2.22 Additional definition for excitation system voltage response time
- 2.23 Additional definition for high initial response excitation system
- 3.1 Edited definition of rotating exciter
- 3.1.2 Edited definition of AC exciter
- 3.2.3 Additional definition for auxiliary winding source static exciter
- 3.3 Additional definition for pilot exciter
- 4.1 to 4.7 Edited definitions of control functions

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The text of this standard is based on the following documents.

CDV	Report on voting
2/1598/CDV	2/1617/RVC

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Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

NOTE A table of cross-references of all IEC TC 2 publications can be found on the IEC TC 2 dashboard on the IEC website.

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- reconfirmed,
- withdrawn,
- replaced by a revised edition, or
- amended.

## ROTATING ELECTRICAL MACHINES –

### Part 16-1: Excitation systems for synchronous machines – Definitions

#### 1 Scope

This part of IEC 60034 defines terms applicable to the excitation systems of synchronous rotating electrical machines.

#### 2 General

##### 2.1

##### **excitation system**

equipment providing the field current of a machine, including all regulating and control elements, as well as field discharge or suppression equipment and protective devices

##### 2.1.1

##### **digital excitation system**

excitation system of a machine where some, if not all, of regulating, control, limiting and protective functionality is implemented using digital technology

NOTE As a minimum, the voltage regulation function must be implemented digitally in such a system.

##### 2.1.2

##### **reversible excitation system**

excitation system providing compulsory change of sign of magnetic flux, created by a winding or excitation windings of a synchronous machine

##### 2.2

##### **exciter**

source of the electrical power, providing field voltage and current of a synchronous machine, regulated by excitation control

NOTE Examples of the source are:

a rotating machine, either d.c. or a.c. with associated rectifiers;

one or several transformers with associated rectifiers.

##### 2.3

##### **excitation control**

control of excitation system modifying the excitation power, responding to signals characteristic of the state of the system encompassing the synchronous machine, its exciter, and the network to which it is connected

NOTE Synchronous machine voltage is predominantly the controlled quantity.

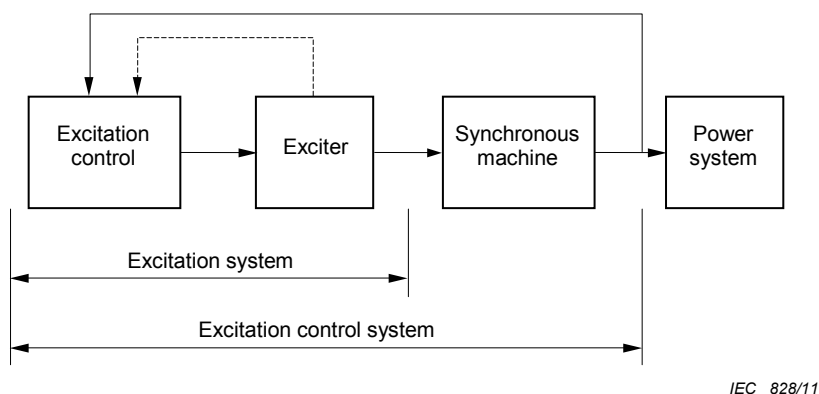
##### 2.4

##### **excitation control system**

feedback control system that includes the synchronous machine operating in the power system and its excitation system

NOTE 1 The term is used to distinguish the performance of the synchronous machine and excitation system in closed loop control conjunction with the power system from that of the excitation system alone.

NOTE 2 Figure 1 shows a block diagram of an excitation control system.



**Figure 1 – Block diagram of excitation control system**

## 2.5

### **field winding terminals**

place of input to the field winding of the machine

NOTE 1 If there are brushes and slip-rings, these are considered to be part of the field winding.

NOTE 2 In a brushless machine, the connecting points between the rotating rectifier and the leads of the machine field winding are the field winding terminals.

## 2.6

### **excitation system output terminals**

place of output from the equipment comprising the excitation system

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NOTE Excitation system output terminals may be different from the field winding terminals.

## 2.7

### **rated field current $I_{fN}$**

direct current in the field winding of the machine when operating at rated voltage, current, power-factor and speed

## 2.8

### **rated field voltage $U_{fN}$**

direct voltage at the field winding terminals of the machine required to produce rated field current with the field winding at the temperature resulting from rated loading and rated conditions and with the primary coolant at its maximum temperature

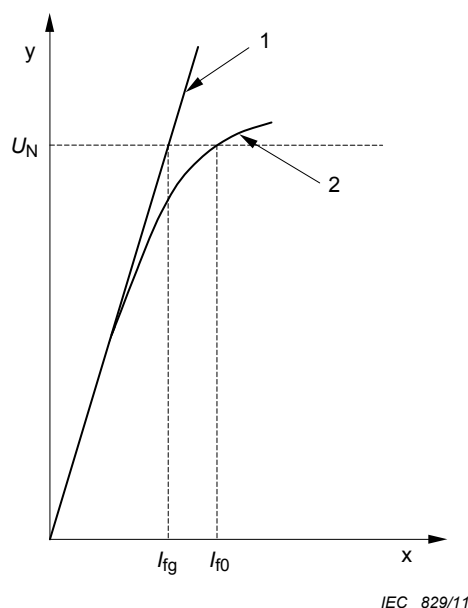
NOTE If the machine has a duty cycle which does not result in a steady field winding temperature being reached, then  $U_{fN}$  is based upon the maximum field winding temperature reached in the duty cycle.

## 2.9

### **no-load field current $I_{f0}$**

direct current in the field winding of the machine required to produce rated voltage at no-load and rated speed (see Figure 2)



**Key**

y Terminal voltage  $U$  ( $U_N$  is the rated voltage of the synchronous machine)

x Field current  $I_f$

1 Air gap line characteristic

2 No-load characteristic

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Figure 2 – Determination of no-load field current  $I_{f0}$   
and air-gap field current  $I_{fg}$   
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NOTE The air-gap field current is the base value for use in computer representation models of excitation systems.

**2.10****no-load field voltage  $U_{f0}$** 

direct voltage at the field winding terminals of the machine required to produce the no-load field current with the field winding at 25 °C

**2.11****air-gap field current  $I_{fg}$** 

current in the field winding of the synchronous machine which theoretically would be required to produce rated voltage at no-load on the air-gap line (see Figure 2)

**2.12****air-gap field voltage  $U_{fg}$** 

direct voltage at the field winding terminals of the synchronous machine which is required to produce the air-gap field current when the field winding resistance is equal to  $U_{fN}/I_{fN}$

NOTE The air-gap field voltage is the base value for use in computer representation models of excitation systems.

**2.13****excitation system rated current  $I_{eN}$** 

direct current at the excitation system output terminals which the excitation system can supply under defined conditions of operation, taking into account the most demanding excitation requirements of the machine (generally resulting from machine voltage and frequency variations)

**2.14**

**excitation system rated voltage  $U_{eN}$**

direct voltage at the excitation system output terminals which the excitation system can provide when delivering excitation system rated current, under defined conditions of operation

NOTE The excitation system rated voltage is at least that value required by the field of the machine under the most demanding excitation requirements (generally resulting from machine voltage and frequency variations).

**2.15**

**excitation system ceiling current  $I_p$**

maximum direct current which the excitation system is able to supply from its terminals for a specified time, starting from continuously supplying rated field current

NOTE The specified time is counted from the achievement of 95 % of the current final steady value.

**2.16**

**excitation system positive ceiling voltage  $U_p$**

maximum direct voltage, which the excitation system is able to provide from its terminals under defined conditions

NOTE 1 For excitation systems whose supply depends on the machine voltage and (if applicable) current, the nature of the power system disturbance and specific design parameters of the excitation system and the synchronous machine influence the excitation system output. For such systems, the ceiling voltage is determined considering an appropriate defined voltage drop and (if applicable) current increase.

NOTE 2 For excitation systems employing a rotating exciter, the ceiling voltage is defined at rated speed and at rated working conditions of exciter.

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**2.17**

**excitation system negative ceiling voltage  $U_n$**

most negative (direct) voltage, if any, which the excitation system is able to provide from its terminals under defined conditions

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**2.18**

**excitation system no-load ceiling voltage  $U_{p0}$**

maximum direct voltage which the excitation system is able to provide from its terminals when it is not loaded

**2.19**

**excitation system on-load positive ceiling voltage  $U_{pL}$**

maximum direct voltage which the excitation system is able to provide from its terminals at initial current equal to rated field current at rated conditions of the machine

**2.20**

**excitation system on-load negative ceiling voltage  $U_{nL}$**

most negative (direct) voltage, if any, which the excitation system is able to provide at initial current equal to rated field current at rated conditions of the machine

**2.21**

**excitation system nominal response  $V_e$**

rate of increase of the excitation system output voltage (see Figure 3), determined from the excitation system voltage response curve divided by the rated field voltage according to the equation:

$$V_e = \frac{\Delta U_e}{0,5U_{fN}} \text{ s}^{-1}$$

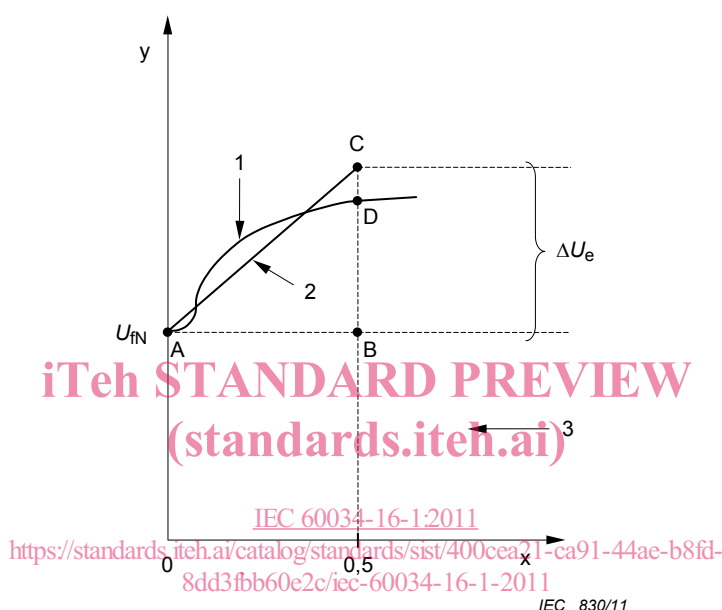
NOTE 1 This rate, if maintained constant (line A–C in Figure 3), would develop the same voltage-time area as obtained from the actual curve (line A–D in Figure 3) over the first half-second interval (or different time interval, if specified).

NOTE 2 The excitation system nominal response is defined with the excitation system loaded with a resistance equal to  $U_{fN}/I_{fN}$  and sufficient inductance so that voltage drop effects and current and voltage waveform are reasonably accounted for.

NOTE 3 The excitation system nominal response is defined with the excitation system voltage initially equal to the rated field voltage of the synchronous machine, after which the excitation system ceiling voltage is rapidly attained by introducing a specified voltage error step.

NOTE 4 For excitation systems whose supply depends on the synchronous machine voltage and (if applicable) current, the nature of the power system disturbance and specific design parameters of the excitation system and the synchronous machine influence the excitation system output. For such systems, the excitation system nominal response is defined taking into consideration an appropriate voltage drop and (if applicable) current increase.

NOTE 5 For excitation systems employing a rotating exciter, the excitation system nominal response is defined at rated speed and at rated working conditions of exciter.



#### Key

y excitation system voltage  $U_e$

x time in s

1 Actual build-up curve

2 Slope

3 Area  $ABC = ABD$

**Figure 3 – Determination of excitation system nominal response,  $V_e$**

#### 2.22 excitation system voltage response time

time in seconds for the excitation voltage to attain 95 % of the difference between ceiling voltage and rated field voltage, counted from the moment of specified step change in synchronous machine terminal voltage

#### 2.23 high initial response excitation systems

excitation systems whose voltage response time is 0,1 s or less

NOTE For high initial response excitation systems, the response time is very short relative to the synchronous machine field time constant and to power system characteristic swings, and the shape of initial response is not of concern.