

Edition 1.0 2013-03

INTERNATIONAL STANDARD





THIS PUBLICATION IS COPYRIGHT PROTECTED Copyright © 2013 IEC, Geneva, Switzerland

All rights reserved. Unless otherwise specified, no part of this publication may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying and microfilm, without permission in writing from either IEC or IEC's member National Committee in the country of the requester.

If you have any questions about IEC copyright or have an enquiry about obtaining additional rights to this publication, please contact the address below or your local IEC member National Committee for further information.

IEC Central Office Tel.: +41 22 919 02 11 3, rue de Varembé Fax: +41 22 919 03 00

CH-1211 Geneva 20 info@iec.ch Switzerland www.iec.ch

About the IEC

The International Electrotechnical Commission (IEC) is the leading global organization that prepares and publishes International Standards for all electrical, electronic and related technologies.

About IEC publications

The technical content of IEC publications is kept under constant review by the IEC. Please make sure that you have the latest edition, a corrigenda or an amendment might have been published.

Useful links:

IEC publications search - www.iec.ch/searchpub

The advanced search enables you to find IEC publications by a variety of criteria (reference number, text, technical committee,...).

It also gives information on projects, replaced and withdrawn publications.

IEC Just Published - webstore.iec.ch/justpublished

Stay up to date on all new IEC publications. Just Published details all new publications released. Available on-line and also once a month by email.

Electropedia www.electropedia.org

The world's leading online dictionary of electronic and electrical terms containing more than 30 000 terms and definitions in English and French, with equivalent terms in additional languages. Also known as the International Electrotechnical Vocabulary (IEV) on-line.

Customer Service Centre - webstore.iec.ch/csc

If you wish to give us your feedback on this publication or need further assistance, please contact the Customer Service Centre: csc@iec.ch.

https://standards.iteh.aiv.ata.kg/sta.kd.vds/s

7c30-823a-4c90-88td-ta58c0ae8a81/iec

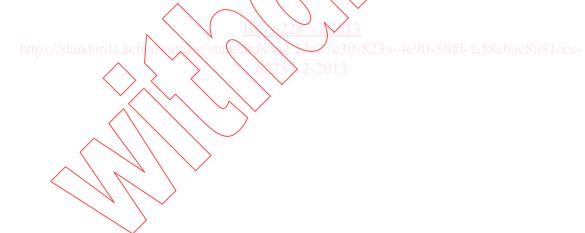


Edition 1.0 2013-03

INTERNATIONAL STANDARD



Maritime navigation and radiocommunication equipment and systems – Class B shipborne equipment of the automatic identification system (AIS) – Part 2: Self-organising time division multiple access (SOTDMA) techniques



INTERNATIONAL ELECTROTECHNICAL COMMISSION

PRICE CODE

ICS 47.020.70 ISBN 978-2-83220-682-9

Warning! Make sure that you obtained this publication from an authorized distributor.

CONTENTS

FO	REW	ORD	7	
1	Scop	cope		
2	Norm	lormative references		
3	Abbr	Abbreviations		
4	Gene	General requirements		
	4.1	General		
		4.1.1 Capabilities of the Class B "SO" AIS		
		4.1.2 Quality assurance 4.1.3 Safety of operation	11	
		4.1.4 Additional features	12	
		4.1.5 Functionality	12	
	4.2	Manuals	12	
	4.3	Marking and identification	12	
5	Envi	ronmental, power supply, interference and safety requirements	12	
6	Perfo	ormance requirements		
	6.1	Internal processes Operating frequency channels	13	
	6.2	Operating frequency channels	14	
	6.3	Internal GNSS receiver for position reporting	1/	
	6.4	Identification	1/	
	6.5	AIS Information	14	
		6.5.1 Information content	14	
		6.5.2 Information reporting intervals	15	
		6.5.2 Information reporting intervals6.5.3 Short safety-related messages6.5.4 Permissible initialisation period	16	
		6.5.4 Permissible initialisation period	16	
	6.6	Alarms and indications, fall-back arrangements	16	
		6.6.1 Built-in integrity tests (BIIT)	16	
		6.6.2 Transmitter shutdown procedure	17	
		6.6.3 Rosition sensor fallback conditions	18	
	6.7	User interface		
	<	6.7.1 Indication and display		
		6.7.2 Static data input		
		6.7.3 External interfaces		
	6.8	Protection from invalid control commands		
7	Technical requirements			
	7.1	General	19	
	7.2	Physical layer	20	
		7.2.1 General		
		7.2.2 Receiver characteristics		
		7.2.3 Other characteristics		
		7.2.4 Transmitter requirements		
	7.3	Link layer		
		7.3.1 General		
		7.3.2 Link sub-layer 1: Medium Access Control (MAC)		
		7.3.3 Link sub-layer 2: Data Link Service (DLS)		
		7.3.4 Link sub-layer 3: Link Management Entity (LME)		
	7.4	Network layer	29	

		7.4.1	General	29
		7.4.2	Management of regional operating settings	29
		7.4.3	Multi-channel operation	30
	7.5	Transp	ort layer	30
	7.6	Presen	tation Interface	31
	7.7	DSC re	eceive capability	31
8	Test	conditio	ns	31
	8.1	Genera	al	31
	8.2		test conditions	
		8.2.1	Temperature and humidity	
		8.2.2	Power supply	
	8.3		e test conditions	
	8.4	Test si	gnals	
		8.4.1	Standard test signal number 1	
		8.4.2	Standard test signal number 2	_
		8.4.3	Standard test signal number 3	
		8.4.4	Standard test signal number 4	
	8.5			
	0.0	8.5.1	Test setup Sensor test input Synchronisation	33
		8.5.2	Sensor test input	33
		8.5.3	Synchronisation	33
		8.5.4	Test signals applied to the receiver input	33
		8.5.5	Waiver for receivers	
		8.5.6	Artificial antenna (dummy load)	34
		8.5.7	Modes of operation of the transmitter	
		8.5.8		
			Measurement uncertainties 2.7013.	
9	Powe		environmental and EMC tests	
•	9.1		ımmary	
	9.2		on .	
	9.2		Divendad	26
		9.2.1	Method of measurement	
	<		Required results	
	9.3	Shock.		
	9.5	9.3.1	Purpose	
		9.3.2	Method of measurement	
		9.3.3	Required result	
	9.4		nance tests / checks	
	9.5		voltage test (brown out)	
	9.5	9.5.1	Purpose	
		9.5.2	Method of test	
		9.5.3	Required result	
	9.6		voltage test (short term)	
	9.0	9.6.1	Purpose	
		9.6.1	Method of test	
		9.6.2	Required result	
10	Oper		•	
10	Operational tests			
	1() 1	Genera	al	37
			Tests by inspection	<u> </u>

		10.1.2 Safety of operation	38
		10.1.3 Additional features	38
	10.2	Modes of operation	38
		10.2.1 Autonomous mode	38
		10.2.2 Single messages	40
		10.2.3 Polled mode / Interrogation response	43
	10.3	Channel selection	44
		10.3.1 Valid channels	
		10.3.2 Invalid channels	44
	10.4	Internal GNSS receiver	
	10.5	AIS information.	
		10.5.1. Information content	15
		10.5.2 Information content 10.6.1 Purpose	45
	10.6	Initialisation period	47
		10.6.1 Purpose	47
		10.6.2 Method of measurement	47
		10.6.3 Required results	
	10 7	Alarme and indications fall-back arrangements	17
	10.7	10.7.1 Built in integrity test	47
		10.7.2. Transceiver protection	48
		10.7.3 Transmitter shutdown procedure	48
		10.7.4 Position sensor fallback conditions	40 48
	10.8	User interface	
	10.0	10.8.1 Status indication	40
		10.8.2 Message display	40 مر
		10.8.2 Message display	5 0
11	Dhyei	ical tests	,50 51
	1 11y3	TDMA transmitter	51
	11.1	11.1.1 Frequency error	51
		11.1.1 Frequency error	51
		11.1.2 Carrier power	
		11.1.3 Transmission spectrum	
		11.1.4 Modulation accuracy	
		11.15 Transmitter output power versus time function	
	11.2	TDMA receivers	
		11.2.1 Sensitivity	
		11.2.2 Error behaviour at high input levels	
		11.2.3 Co-channel rejection	
		11.2.4 Adjacent channel selectivity	
		11.2.5 Spurious response rejection	
		11.2.6 Intermodulation response rejection	
		11.2.7 Blocking or desensitisation	
	11.3	Conducted spurious emissions	
		11.3.1 Spurious emissions from the receiver	
		11.3.2 Spurious emissions from the transmitter	63
12	Spec	ific tests of Link layer	63
	12.1	TDMA synchronisation	64
		12.1.1 Synchronisation test using UTC direct and indirect	64
		12.1.2 Synchronisation test without UTC, EUT receiving semaphore	64
	12.2	Time division (frame format)	65

		12.2.1 Purpose	65
		12.2.2 Method of measurement	65
		12.2.3 Required results	65
	12.3	Synchronisation jitter	65
		12.3.1 Definition	65
		12.3.2 Purpose	65
		12.3.3 Method of measurement	65
		12.3.4 Required results	
	12.4	Data encoding (bit stuffing)	
		12.4.1 Purpose	
		12.4.2 Method of measurement	
		12.4.3 Required results	
	12.5		66
		40 F 4 D	66
		12.5.2 Method of measurement	66
		12.5.3 Required results	66
	12.6	Slot allocation (Channel access protocols)	66
		12.5.3 Required results Slot allocation (Channel access protocols) 12.6.1 Network entry	66
		12.6.2 Autonomous scheduled transmissions (SOTDMA)	66
		12.6.3 Autonomous scheduled transmissions (ITDMA)	67
		12.6.4 Transmission of Messages 24A and 24B (ITDMA)	67
		12.6.5. Assigned operation	67
		12.6.6. Group assignment	69
		12.6.7 Base station reservations	73
	12 7	Message formats	74
	https://	12.6.5 Assigned operation 12.6.6 Group assignment 12.6.7 Base station reservations Message formats 12.7.1 Received messages	74
		12.7.2 Transmitted messages	74
3	Snec	ific tests of network layer	74
Ŭ		Regional area designation by VDL Message	
	13.1	13.1.1 Purpose	
		13.1.2 Method of measurement	
		13.1.3 Required results	
	12 0		
	13.2	Channel management by addressed Message 22	
		13.2.1 Purpose	
		13.2.2 Method of measurement	
	10.0	13.2.3 Required results	
	13.3	Invalid regional operating areas	
		13.3.1 Purpose	
		13.3.2 Method of measurement	
		13.3.3 Required test results	
	13.4	Continuation of autonomous mode reporting interval	
		13.4.1 Purpose	
		13.4.2 Method of test	
		13.4.3 Required result	
	13.5	Slot reuse and FATDMA reservations	
		13.5.1 Method of measurement	
		13.5.2 Required results	
		Other features	
nı	nex A	(normative) DSC channel management	78

Annex B (normative) Calculation of area size	86
Bibliography	87
Figure 1 – OSI layer model	
Figure 2 – Power versus time mask	
Figure 3 – Format for repeating four-packet cluster	
Figure 4 – Measurement arrangement for carrier power	
Figure 5 – Emission mask	
Figure 6 – Measurement arrangement for modulation accuracy	53
Figure 7 – Measurement arrangement	55
Figure 8 – Measurement arrangement with two generators	57
Figure 9 – SINAD or PER/BER measuring equipment	59
Figure 10 – Measurement arrangement for intermodulation	61
Figure 11 – Regional transitional zones	75
Table 1 – Dynamic information autonomous reporting intervals for Class B "80" AIS	
Table 2 – BIIT and reaction to malfunctions	
Table 3 – Position sensor fallback conditions	
Table 4 – Required receiver performance	
Table 5 – Transceiver characteristics	21
Table 6 – Transmitter characteristics	23
Table 7 – Definitions of timing for Figure 2	25
Table 8 – Use of VDL Messages by a Class B "SO" AIS	
Table 9 - Content of first two packets	ec- 32
Table 10 – Fixed PRS data derived from Recommendation ITU-T 0.153	33
Table 11 – Test	35
Table 12 – Peak frequency deviation versus time	54
Table 13 – Frequencies for intermodulation test	61
Table 14 – Regional area scenario	75
Table 15 - Required channels in use	75
Table A.1 – DSC monitoring times	79
Table B.1 – Coordinate points	86

INTERNATIONAL ELECTROTECHNICAL COMMISSION

MARITIME NAVIGATION AND RADIOCOMMUNICATION EQUIPMENT AND SYSTEMS – CLASS B SHIPBORNE EQUIPMENT OF THE AUTOMATIC IDENTIFICATION SYSTEM (AIS) –

Part 2: Self-organising time division multiple access (SOTDMA) techniques

FOREWORD

- 1) The International Electrotechnical Commission (IEC) is a worldwide organization for standardization comprising all national electrotechnical committees (IEC National Committees). The object of IEC is to promote international co-operation on all questions concerning standardization in the electrical and electronic fields. To this end and in addition to other activities, IEC publishes International Standards, Technical Specifications, Technical Reports, Publicly Available Specifications (PAS) and Guides (hereafter referred to as "IEC Publication(s)"). Their preparation is entrusted to technical committees, any IEC National Committee interested in the subject dealt with may participate in this preparatory work. International, governmental and non-governmental organizations liaising with the IEC also participate in this preparation. IEC collaborates closely with the International Organization for Standardization (ISO) in accordance with conditions determined by agreement between the two organizations.
- 2) The formal decisions or agreements of IEC on technical matters express, as nearly as possible, an international consensus of opinion on the relevant subjects since each technical committee has representation from all interested IEC National Committees.
- 3) IEC Publications have the form of recommendations for international use and are accepted by IEC National Committees in that sense. While all reasonable efforts are made to ensure that the technical content of IEC Publications is accurate, IEC cannot be held responsible for the way in which they are used or for any misinterpretation by any end user.
- 4) In order to promote international uniformity, IEC National Committees undertake to apply IEC Publications transparently to the maximum extent possible in their national and regional publications. Any divergence between any IEC Publication and the corresponding national or regional publication shall be clearly indicated in the latter.
- 5) IEC itself does not provide any attestation of conformity. Independent certification bodies provide conformity assessment services and, in some areas, access to IEC marks of conformity. IEC is not responsible for any services carried out by independent certification bodies.
- 6) All users should ensure that they have the latest edition of this publication.
- 7) No liability shall attach to IEC or its directors, employees, servants or agents including individual experts and members of its technical committees and IEC National Committees for any personal injury, property damage or other damage of any nature whatsoever, whether direct or indirect, or for costs (including legal fees) and expenses arising out of the publication, use of, or reliance upon, this IEC Publication or any other IEC Publications.
- 8) Attention is drawn to the Normative references cited in this publication. Use of the referenced publications is indispensable for the correct application of this publication.
- 9) Attention is drawn to the possibility that some of the elements of this IEC Publication may be the subject of patent rights. IEC shall not be held responsible for identifying any or all such patent rights.

International Standard IEC 62287-2 has been prepared by IEC technical committee 80: Maritime navigation and radiocommunication equipment and systems.

The text of this standard is based on the following documents:

FDIS	Report on voting
80/685/FDIS	80/691/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts in the IEC 62287 series, published under the general title Maritime navigation and radiocommunication and systems — Class B shipborne equipment of the automatic identification system (AIS), can be found on the IEC website.

The committee has decided that the contents of this publication will remain unchanged until the stability date indicated on the IEC web site under "http://webstore.iec.ch" in the data related to the specific publication. At this date, the publication will be

- reconfirmed,
- withdrawn,
- · replaced by a revised edition, or
- · amended.

A bilingual version of this publication may be issued at a later date.

indicates that it contains colours which are considered to be useful for the correct understanding of its contents. Users should therefore print this document using a colour printer.

Stan (222) 2213

https://standards.itel.apy.o/sta.doc/sls/10/2/2013

https://standards.itel.apy.o/sta.doc/sls/10/2/2013

IMPORTANT - The 'colour inside' logo on the cover page of this publication

MARITIME NAVIGATION AND RADIOCOMMUNICATION EQUIPMENT AND SYSTEMS – CLASS B SHIPBORNE EQUIPMENT OF THE AUTOMATIC IDENTIFICATION SYSTEM (AIS) –

Part 2: Self-organising time division multiple access (SOTDMA) techniques

1 Scope

This part of IEC 62287 specifies operational and performance requirements, methods of testing and required test results for Class B "SO" shipborne AlS equipment using Self-organised TDMA (SOTDMA) techniques as described in Recommendation ITU-R M.1371. This standard takes into account other associated IEC International Standards and existing national standards, as applicable.

The main differences between Class B "CS" (IEC 62287-1) and Class B "SO" units are that the Class B "SO":

- covers all 25 kHz channels listed in Recommendation LTU-R M.1084-5;
- only uses the internal GNSS, no position sensor input is allowed;
- requires use of VDL Message 17 for correction of the internal GNSS;
- has a presentation interface;
- has additional reporting intervals, down to 5's;
- Thas two power settings, with a high level of 5 W; 823a-4c90-88fd-fa58c0ac8a81/icc-
- has the capability to transmit binary messages.

It is applicable for AIS equipment used on craft that are not covered by a mandatory carriage requirement of AIS under SQLAS Chapter V.

2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60945:2002, Maritime navigation and radiocommunication equipment and systems – General requirements – Methods of testing and required test results

IEC 61108 (all parts), Maritime navigation and radio communication equipment and systems – Global navigation satellite systems (GNSS)

IEC 61108-4, Maritime navigation and radio communication equipment and systems – Global navigation satellite systems (GNSS) – Part 4: Shipborne DGPS and DGLONASS maritime radio beacon receiver equipment – Performance requirements, methods of testing and required test results

IEC 61162 (all parts), Maritime navigation and radiocommunication equipment and systems – Digital interfaces

IEC 61162-1, Maritime navigation and radiocommunication equipment and systems – Digital interfaces – Part 1: Single talker and multiple listeners

IEC 61993-2, Maritime navigation and radio communication equipment and systems – Automatic identification systems (AIS) – Part 2: Class A shipborne equipment of the universal automatic identification system (AIS) – Operational and performance requirements, methods of test and required test results

ITU Radio regulations 2012, Appendices

ITU-R Recommendation M.825-3:1998, Characteristics of a transponder system using digital selective calling techniques for use with vessel traffic services and ship-to-ship identification

ITU-R Recommendation M.1084-5, Interim solutions for improved efficiency in the use of the band 156-174 MHz by stations in the maritime mobile service

ITU-R Recommendation M.1371-4:2010, Technical characteristics for an automatic identification system using time division multiple access in the VHF maritime mobile band

3 Abbreviations

RAIM

AIS	Automatic Identification System
BER	Bit Error Rate
BIIT	Built-In Integrity Tests
ВТ	Bandwidth Time
COG	Course over ground
CRC	Cyclic Redundancy Check
CSD indare	Compass Safe Distance 7030-823a-
DGNSS	Differential Global Navigation Satellite Service
DLS	Data Link Service
DSC	Digital Selective Calling
EUT	Equipment under test
FM	Frequency Modulation
GMSK	Gaussian Minimum Shift Keying
GNSS	Global Navigation Satellite Service
IMO	International Maritime Organization
ITDMA	Incremental Time Division Multiple Access
ITU	International Telecommunication Union
LME	Link Management Entity
MAC	Medium access control
MMSI	Maritime Mobile Service Identity
MSSA	Multi-channel slot selection access
NM	Nautical mile (1 NM = 1 852 m)
NRZI	Non Return to Zero Inverted
OSI	Open Systems Interconnection model
PER	Packet Error Rate
PI	Presentation Interface

Receiver autonomous integrity monitoring

RATDMA Random Access Time Division Multiple Access

RF Radio Frequency
RR Radio Regulations

Rx Receive

SAR Search and rescue

SINAD Signal Interference Noise and Distortion ratio

SOG Speed over ground

SOTDMA Self Organised Time Division Multiple Access

TDMA Time Division Multiple Access

Tx Transmit

UTC Universal Time Co-ordinated

VDL VHF Data Link

VHF Very High Frequency

VSWR Voltage Standing Wave Ratio

VTS Vessel Traffic Services

NOTE Abbreviations included in the IEC 61162 series are not specified in the above list. Refer to this series of International Standards for these abbreviations.

4 General requirements

4.1 General

4.1.1 Capabilities of the Class B "SO" AIS

The Class B "SO" AIS shall improve the safety of navigation by assisting in the efficient navigation of ships and small craft, protection of the environment, and operation of Vessel Traffic Services (VTS).

The Class B "SO" AIS station shall be inter-operable and compatible with all AIS stations operating on the AIS VHF Data Link. In particular, Class B "SO" AIS stations shall not degrade the integrity of the AIS VHF Data Link.

The Class B "SO" Als shall be capable of providing information from the craft, automatically, continuously and with the required accuracy and update rate

- in a ship-to-ship mode for collision avoidance,
- as a means for littoral States to obtain information about the craft, and
- as a VTS tool, i.e. ship-to-shore (traffic management).

4.1.2 Quality assurance

(See 10.1.1)

Manufacturers shall have a quality control system audited by a competent authority to ensure continuous compliance with the requirements of this standard. Alternatively, the manufacturer may use final product verification procedures where a competent authority verifies compliance with the requirements of this standard before the product is put to the market.

NOTE The ISO 9000 series, as applicable, meets the requirements of a quality control system.

4.1.3 Safety of operation

(See 10.1.2)

It shall not be possible for the operator to augment, amend or erase any program software required for operation in accordance with this equipment standard. The manufacturer may provide means to install software updates.

Data used during operation and stored in the system shall be protected in such a way that necessary modifications and amendments by the user cannot endanger its integrity and correctness.

4.1.4 Additional features

(See 10.1.3, 13.6)

Where equipment provides a feature that is additional to the minimum requirements and options of this standard, the operation and, as far as is reasonably practicable, the malfunction of such additional features shall not degrade the performance of the equipment.

4.1.5 Functionality

The equipment shall operate in three modes (see 7.3.4.3):

- autonomous (default mode);
- · assigned;
- · interrogation.

4.2 Manuals Ch S A

(See 10.1.1)

The manuals shall include the

- type of external connectors, if applicable,
- information for correct installation and positioning of the antennas, id-fa58c0ae8a81/iec-
- information for compass safe distance.

4.3 Marking and identification

(See 10.1.1)

In addition to the requirements of IEC 60945:2002, 4.9, the markings shall include:

- details of the power supply from which the equipment is intended to be operated;
- if applicable, the date by which batteries need to be replaced.

5 Environmental, power supply, interference and safety requirements

(See Clause 9)

In addition to the specific requirements of this standard, the Class B "SO" AIS shall fulfil the following general requirements as detailed in IEC 60945:

- inter-unit connection (electrical interfaces other than IEC 61162 are permissible);
- power supply;
- extreme power supply;
- excessive conditions;
- power supply short-term variation and power supply failure;
- durability and resistance to environmental conditions;
- interference;

- · electromagnetic compatibility;
- · compass safe distance;
- safety precautions;
- protection against accidental access to dangerous voltages;
- · electromagnetic radiofrequency radiation.

The Class B "SO" AIS shall not enter an undefined or unstable state in case of under voltage.

The manufacturer shall declare the category of the equipment as follows:

- a) portable;
- b) protected from the weather;
- c) exposed to the weather;
- d) submerged or in continuous contact with sea water.

The Class B "SO" AIS shall be tested for compliance with the environmental, power supply, special-purpose and safety requirements of IEC 60945.

- AIS equipment declared for protected installation shall meet the requirements described in Table 3 column "Protected" of IEC 60945:2002:
- exposed AIS equipment shall meet the requirements described in Table 3, column "Exposed" of IEC 60945;
- portable AIS equipment shall meet the requirements of Table 3 of IEC 60945:2002
 "Protected" or "Exposed" as appropriate.

In addition, the AIS installation, when operating shall not be damaged by the effects of open circuited or short circuited antenna terminals.

https://standards.ite.bla.kata.o/standards/st/97c30-823a-4c90-88fd-fa58c0ae8a81/jec

6 Performance requirements

6.1 Internal processes

(See 10.1.1)

The Class B "SO" AIS shall comprise:

- a communication processor, capable of operating in the VHF Maritime Mobile Service band:
- at least one transmitter and two receiving processes for TDMA operation;
- a third receiving process for DSC channel management;
- a means for automatic channel switching in the maritime mobile band (by Message 22 and by DSC). Manual channel switching shall not be provided;
- an internal GNSS position sensor, which provides a resolution of one ten thousandth of a minute of arc and uses the WGS-84 datum only.