

INTERNATIONAL STANDARD



**Maritime navigation and radiocommunication equipment and systems – Class B
shipborne equipment of the automatic identification system (AIS) –
Part 1: Carrier-sense time division multiple access (CSTDMA) techniques**

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

**MARITIME NAVIGATION AND RADIOCOMMUNICATION
EQUIPMENT AND SYSTEMS –
CLASS B SHIPBORNE EQUIPMENT OF
THE AUTOMATIC IDENTIFICATION SYSTEM (AIS) –****Part 1: Carrier-sense time division multiple access
(CSTDMA) techniques**

FOREWORD

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This consolidated version of IEC 62287-1 consists of the second edition (2010) [documents 80/605/FDIS and 80/608/RVD] and its amendment 1 (2013) [documents 80/680/CDV and 80/695/RVC]. It bears the edition number 2.1.

The technical content is therefore identical to the base edition and its amendment and has been prepared for user convenience. A vertical line in the margin shows where the base publication has been modified by amendment 1. Additions and deletions are displayed in red, with deletions being struck through.

International Standard IEC 62287-1 has been prepared by IEC technical committee 80: Maritime navigation and radiocommunication equipment and systems.

The major technical changes with respect to the first edition are the following. The reference to the relevant recommendation of the ITU has been updated from M.1371-1 to M.1371-4 with some consequential small changes. A previous option of providing short safety-related messages in 6.5.1.5 has been removed on advice from the IMO. A new requirement for a default MMSI has been added in 6.4 and a further new requirement for protection from invalid control commands has been added in 6.8. Some test methods have been updated and, in particular, small revisions have been made to the frequencies used for testing in some of the test methods. The introduction has been deleted since it is only of historic interest.

Some editorial rearrangement has been made.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of the IEC 62287 series published under the general title *Maritime navigation and radiocommunication equipment and systems – Class B shipborne equipment of the automatic identification system (AIS)*, can be found on the IEC website.

The committee has decided that the contents of the base publication and its amendment will remain unchanged until the stability date indicated on the IEC web site under "<http://webstore.iec.ch>" in the data related to the specific publication. At this date, the publication will be

- reconfirmed,
- withdrawn,
- replaced by a revised edition, or
- amended.

A bilingual version of this publication may be issued at a later date.

IMPORTANT – The 'colour inside' logo on the cover page of this publication indicates that it contains colours which are considered to be useful for the correct understanding of its contents. Users should therefore print this document using a colour printer.

INTRODUCTION to Amendment 1

This amendment clarifies the conditions required for input of external GNSS position, the associated tests and required results.

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**MARITIME NAVIGATION AND RADIOCOMMUNICATION
EQUIPMENT AND SYSTEMS –
CLASS B SHIPBORNE EQUIPMENT OF
THE AUTOMATIC IDENTIFICATION SYSTEM (AIS) –**

**Part 1: Carrier-sense time division multiple access
(CSTDMA) techniques**

1 Scope

This part of IEC 62287 specifies the minimum operational and performance requirements, methods of testing and required test results for Class B shipborne AIS equipment using CSTDMA techniques. This standard takes into account other associated IEC International Standards and existing national standards, as applicable.

It is applicable for AIS equipment used on craft that are not covered by the mandatory carriage requirement of AIS under SOLAS Chapter V.

An AIS station intended to operate in receive-only mode is not considered a Class B shipborne mobile AIS station.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60945:2002, *Maritime navigation and radiocommunication equipment and systems – General requirements – Methods of testing and required test results*

IEC 61108 (all parts), *Maritime navigation and radiocommunication equipment and systems – Global navigation satellite systems (GNSS)*

IEC 61162 (all parts), *Maritime navigation and radiocommunication equipment and systems – Digital interfaces*

IEC 61993-2, *Maritime navigation and radiocommunication equipment and systems – Automatic identification systems (AIS) – Part 2: Class A shipborne equipment of the universal automatic identification system (AIS) – Operational and performance requirements, methods of test and required test results*

IEC 62320-1, *Maritime navigation and radiocommunication equipment and systems – Automatic identification systems (AIS) – Part 1: AIS Base Stations – Minimum operational and performance requirements, methods of testing and required test results*

IMO MSC.140(76), *Recommendation for the protection of the AIS VHF data link*

ITU-R Recommendation M.493-13, *Digital selective-calling system for use in the maritime mobile service*

ITU-R Recommendation M.825-3, *Characteristics of a transponder system using digital selective calling techniques for use with vessel traffic services and ship-to-ship identification*

ITU-R Recommendation M.1084-4, *Interim solutions for improved efficiency in the use of the band 156-174 MHz by stations in the maritime mobile service*

ITU-R Recommendation M.1371-4, *Technical characteristics for a universal shipborne automatic identification system using time division multiple access in the VHF maritime mobile band*

ITU Radio Regulations, Appendix 18, <http://www.itu.int/publ/R-REG-RR/en>

3 Abbreviations

AIS	Automatic Identification System
BER	Bit Error Rate
BT	Bandwidth Time product
COG	Course Over Ground
CP	Candidate Period
CPU	Central Processing Unit
CRC	Cyclic Redundancy Check
CS	Carrier-Sense
CSTDMA	Carrier-Sense Time Division Multiple Access
DGNSS	Differential Global Navigation Satellite System
DLS	Data Link Service
DSC	Digital Selective Calling
ECDIS	Electronic Chart Display and Information System
EPFS	Electronic Position Fixing System
ETA	Estimated Time of Arrival
EUT	Equipment Under Test
FCS	Frame Check Sequence
FM	Frequency Modulation
GMSK	Gaussian Minimum Shift Keying
GNSS	Global Navigation Satellite System
HDG	Heading
HDLC	High level Data Link Control
HSC	High Speed Craft
IHO	International Hydrographic Office
IMO	International Maritime Organization
Lat	Latitude
LME	Link Management Entity
Lon	Longitude
LR	Long Range
MAC	Medium Access Control
MMSI	Maritime Mobile Service Identity
NM	Nautical Miles (1 NM = 1 852 m)
NRZI	Non Return to Zero Inverted
NTT	Nominal Transmission Time

NUC	Not Under Command
OSI	Open System Interconnection model
P _{ss}	Steady state RF output power
PER	Packet Error Rate
PI	Presentation Interface
PRS	Pseudo Random Sequence
RAIM	Receiver Autonomous Integrity Monitoring
RF	Radio Frequency
RI	Reporting Interval
Rx	Receive
SINAD	Signal Interference Noise and Distortion ratio
SOG	Speed Over Ground
SOLAS	International Convention for the Safety Of Life At Sea
TDMA	Time Division Multiple Access
TI	Transmission Interval
Tx	Transmit
UTC	Universal Time Co-ordinated
VDL	VHF Data Link
VHF	Very High Frequency
VSWR	Voltage Standing Wave Ratio
VTS	Vessel Traffic Services

NOTE Abbreviations related to the IEC 61162 series are not included in the above list. For their meaning refer to that standard.

4 General requirements

4.1 General

4.1.1 Capabilities of the Class B“CS” AIS

The Class B“CS” AIS shall improve the safety of navigation by assisting in the efficient navigation of ships and small craft, protection of the environment, and operation of Vessel Traffic Services (VTS). Small craft are vessels which are not required to comply with the mandatory carriage requirements of SOLAS Chapter V, Regulation 19.

The Class B“CS” AIS shall be capable of providing information from small craft, automatically, continuously and with the required accuracy and update rate:

- in a ship-to-ship mode for collision avoidance;
- as a means for littoral States to obtain information about the craft; and
- as a VTS tool, i.e. ship-to-shore (traffic management).

The Class B“CS” AIS station shall be inter-operable and compatible with Class A or other Class B shipborne mobile AIS stations or any other AIS station operating on the AIS VHF Data Link. In particular, Class B“CS” AIS stations shall receive other stations, shall be received by other stations and shall not degrade the integrity of the AIS VHF Data Link.

The Class B“CS” AIS shall only transmit if it has verified that the time period intended for transmission does not interfere with transmissions made by AIS equipment defined in ITU-R