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SAFETY OF MACHINERY – REQUIREMENTS FOR CABLELESS CONTROL SYSTEMS OF MACHINERY

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The text of this standard is based on the following documents:

FDIS	Report on voting
44/783/FDIS	44/785/RVD

Full information on the voting for the approval of this International Standard can be found in the report on voting indicated in the above table.

This document has been drafted in accordance with the ISO/IEC Directives, Part 2.

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INTRODUCTION

Cableless control systems (CCS) are increasingly being used to provide an operator interface on a wide range of machinery. The functionality of a CCS and the way in which it interfaces with the overall machine control system can therefore affect the safety of the machinery.

IEC 62745 specifies requirements for the functionality of a CCS that is interfaced with or is part of a machine control system for use as an operator control station on a machine.

The extent to which the functionality of a CCS is relied upon to minimise risk on a machine is a key selection criterion. It is therefore important to select a CCS that provides suitable control functions with an appropriate safety integrity in accordance with the risk assessment at the machine.

In some particular applications, the requirements for a CCS can exceed those specified in this document.

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SAFETY OF MACHINERY – REQUIREMENTS FOR CABLELESS CONTROL SYSTEMS OF MACHINERY

1 Scope

This standard specifies requirements for the functionality and interfacing of cableless (for example, radio, infra-red) control systems that provide communication between operator control station(s) and the control system of a machine. Specific requirements are included for such operator control stations that are portable by the operator.

NOTE The part of the cableless control system that is used as an operator control station is sometimes referred to as the 'transmitter' and the part that interfaces with the machine control system is sometimes referred to as the 'receiver'. However, to take account of the possibility of bi-directional communication, this standard refers to these individual parts as the 'remote station' and the 'base station' respectively.

This document does not deal with cableless communication between parts of a machine(s) that are not operator control stations.

This document is not intended to specify all of the requirements that are necessary for the design and construction of a cableless control system. For example, it does not specify communication protocols, frequency or bandwidth aspects, nor the full range of constructional requirements such as impact resistance, ingress protection, electromagnetic compatibility, etc.

The provisions of this document are intended to be applied in addition to the requirements for electrical equipment in the IEC 60204-1.

This document is a type-B2 standard as stated in ISO 12100.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60068-2-31:2008, *Environmental testing – Part 2-31: Tests – Test Ec – Rough handling shocks, primarily for equipment-type specimens*

IEC 60204-1:2005, *Safety of machinery – Electrical equipment of machines – Part 1: General requirements*

IEC 60947-5-1:2016, *Low-voltage switchgear and controlgear – Part 5-1: Control circuit devices and switching elements – Electromechanical control circuit devices*

IEC 60947-5-5, *Low-voltage switchgear and controlgear – Part 5-5: Control circuit devices and switching elements – Electrical emergency stop device with mechanical latching function*

IEC 62061, *Safety of machinery – Functional safety of safety-related electrical, electronic and programmable electronic control systems*

ISO 13849-1, *Safety of machinery – Safety-related parts of control systems – Part 1: General principles for design*

ISO 13849-2, *Safety of machinery – Safety-related parts of control systems – Part 2: Validation*

ISO 13850, *Safety of machinery – Emergency stop function– Principles for design*

3 Terms, definitions and abbreviations

For the purposes of this document, the following terms and definitions apply.

For an alphabetical list of definitions, see Table 1.

For list of abbreviations see Table 2.

Table 1 – Alphabetical list of definitions

Term	Definition number
active stop	3.17
address code	3.7
automatic stop (ATS)	3.19
base station	3.13
cableless control	3.1
cableless control system (CCS)	3.2
disabling of a remote station	3.22
error detection code	3.9
frame	3.6
Hamming distance	3.11
manual stop	3.20
neutral frame	3.10
OFF-state	3.15
operating command signal	3.8
operator control station	3.5
passive stop	3.18
receiver	3.3
remote station	3.12
safety-related stop function	3.16
stop output	3.14
transmitter	3.4
valid signal	3.21

Table 2 – Abbreviations

Term	Abbreviation
automatic stop (4.7.3.5)	ATS
cableless control system (3.2)	CCS
emergency stop (4.7.3.4)	EMS
general safe stop (4.7.3.3)	GSS

3.1**cableless control**

transmission of the machine operator's commands without any wired connection

3.2**cableless control system****CCS**

system consisting of at least one remote station and one base station, which uses cableless control to transmit commands between them

3.3**receiver**

part of a cableless control system which receives frames from a transmitter

3.4**transmitter**

part of a cableless control system which sends frames to a receiver

3.5**operator control station**

assembly of one or more control actuators (part of a device to which an external manual action is to be applied) fixed on the same panel or located in the same enclosure

Note 1 to entry: An operator control station can also contain related equipment, for example, potentiometers, signal lamps, instruments, display devices, etc.

3.6**frame**

"package" of information exchanged between a remote station and a base station, and consisting of, for example:

- a) address code;
- b) operating commands;
- c) error detection code;
- d) other commands, signals or information

Note 1 to entry: A "frame" is sometimes referred to as a "telegram" or "message".

3.7**address code**

part of a frame that enables a base station or a remote station to recognise frames that are intended to convey commands to it

Note 1 to entry: The base station or remote station respond to commands that are recognised as having the relevant address code.

3.8**operating command signal**

control signal that is intended to initiate, modify or maintain a machine function

3.9**error detection code**

additional information added to each frame to enable the detection of transmission errors

3.10**neutral frame**

frame in which all operating command signals are in a state such that when it is received at the base station it does not activate any outputs intended for control of hazardous operations of the machine