

---

---

**Walking aids manipulated by both arms —  
Requirements and test methods —**

**Part 1:  
Walking frames**

*Aides à la marche manipulées avec les deux bras — Exigences et  
méthodes d'essai —  
Partie 1: Cadres de marche*

[ISO 11199-1:1999](https://standards.iteh.ai/catalog/standards/sist/c32a1156-68d9-40d3-973b-72e25390f7f3/iso-11199-1-1999)

<https://standards.iteh.ai/catalog/standards/sist/c32a1156-68d9-40d3-973b-72e25390f7f3/iso-11199-1-1999>



## Contents

1 Scope .....	1
2 Normative references .....	1
3 Terms and definitions .....	1
4 Requirements .....	4
5 Test methods.....	6
6 Marking and labelling .....	12
7 Test report .....	12
Annex A (informative) Recommendations .....	13

## iTeh STANDARD PREVIEW (standards.iteh.ai)

ISO 11199-1:1999

<https://standards.iteh.ai/catalog/standards/sist/c32a1156-68d9-40d3-973b-72e25390f7f3/iso-11199-1-1999>

© ISO 1999

All rights reserved. Unless otherwise specified, no part of this publication may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying and microfilm, without permission in writing from the publisher.

International Organization for Standardization  
Case postale 56 • CH-1211 Genève 20 • Switzerland  
Internet iso@iso.ch

Printed in Switzerland

## Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 3.

Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

International Standard ISO 11199-1 was prepared by Technical Committee ISO/TC 173, *Technical systems and aids for disabled or handicapped persons*.

ISO 11199 consists of the following parts, under the general title *Walking aids manipulated by both arms — Requirements and test methods*:

— Part 1: *Walking frames*

— Part 2: *Rollators*

**iTeh STANDARD PREVIEW**  
**(standards.iteh.ai)**

Annex A of this part of ISO 11199 is for information only.

ISO 11199-1:1999

<https://standards.iteh.ai/catalog/standards/sist/c32a1156-68d9-40d3-973b-72e25390f7f3/iso-11199-1-1999>

**iTeh STANDARD PREVIEW**  
**(standards.iteh.ai)**

ISO 11199-1:1999

<https://standards.iteh.ai/catalog/standards/sist/c32a1156-68d9-40d3-973b-72e25390f7f3/iso-11199-1-1999>

# Walking aids manipulated by both arms — Requirements and test methods —

## Part 1: Walking frames

### 1 Scope

This part of ISO 11199 specifies requirements and methods of testing fatigue, static load capacity and stability of walking frames without accessories, unless specified in the particular test procedure. This part of ISO 11199 also gives the requirements relating to safety, ergonomics, performance, marking and labelling.

The requirements and tests are based on everyday usage of walking frames manufactured for a user mass of not less than 35 kg.

NOTE Recommendations further to the requirements given in this part of ISO 11199 are given in annex A.

STANDARD PREVIEW  
(standards.iteh.ai)

### 2 Normative references

ISO 11199-1:1999

<https://standards.iteh.ai/catalog/standards/sist/c32a1156-68d9-40d3-973b-2c23590715/iso-11199-1:1999>

The following normative documents contain provisions which, through reference in this text, constitute provisions of this part of ISO 11199. For dated references, subsequent amendments to, or revisions of, any of these publications do not apply. However, parties to agreements based on this part of ISO 11199 are encouraged to investigate the possibility of applying the most recent editions of the normative documents indicated below. For undated references, the latest edition of the normative document referred to applies. Members of ISO and IEC maintain registers of currently valid International Standards.

ISO 9999:1998, *Technical aids for disabled persons — Classification*.

ISO 10933-1, *Biological evaluation of medical devices — Part 1: Evaluation and testing*.

### 3 Terms and definitions

For the purposes of this part of ISO 11199, the following terms and definitions apply (see also Figures 1, 2 and 3).

#### 3.1

##### folded dimensions

height, width and length of the walking frame measured with the frame folded together without the use of tools, the height adjustment at its minimum height and the handles positioned as in 5.1.

#### 3.2

##### frame height

vertical distance from the rear handgrip reference point to the ground

See Figure 3.

**3.3****front handgrip reference point**

that point on the upper surface of the handgrip located 30 mm from the front end of the handgrip length

See Figure 2.

**3.4****handgrip**

that part of the walking frame which is normally held by the hand when the frame is in use

**3.5****handgrip length**

dimension of the handgrip measured longitudinally where the hand rests

See Figure 2.

NOTE Where the front end or the rear end of the handgrip is not clear, the full length of the handgrip that can support the weight of the user is defined as the handgrip length.

**3.6****handgrip width**

outside dimension of the handgrip measured horizontally at the thickest point where the hand rests

See Figure 2.

**3.7****handle**

that part of the walking frame to which the handgrip is attached.

**3.8****maximum length**

maximum outside dimension of a walking frame when the height adjustment is at its maximum, measured parallel to the direction of movement when the frame is in normal use

See Figure 3.

**3.9****maximum width**

maximum outside dimension of a walking frame when the height adjustment is at its maximum, measured horizontally at right angles to the direction of movement when the frame is in normal use

See Figure 3.

**3.10****rear handgrip reference point**

that point on the upper surface of the handgrip located 30 mm from the rear end of the handgrip length

See Figure 2.

NOTE If the grip protrudes further than the handle, the measurement is made from the end of the handle.

**3.11****tip**

that part of a walking frame which is in contact with the ground

**3.12****turning diameter**

diameter of the largest circle described by a walking frame when the height adjustment is at its maximum and the walking frame is turned through 360° about its own central vertical axis

See Figure 3.

**3.13****user weight**

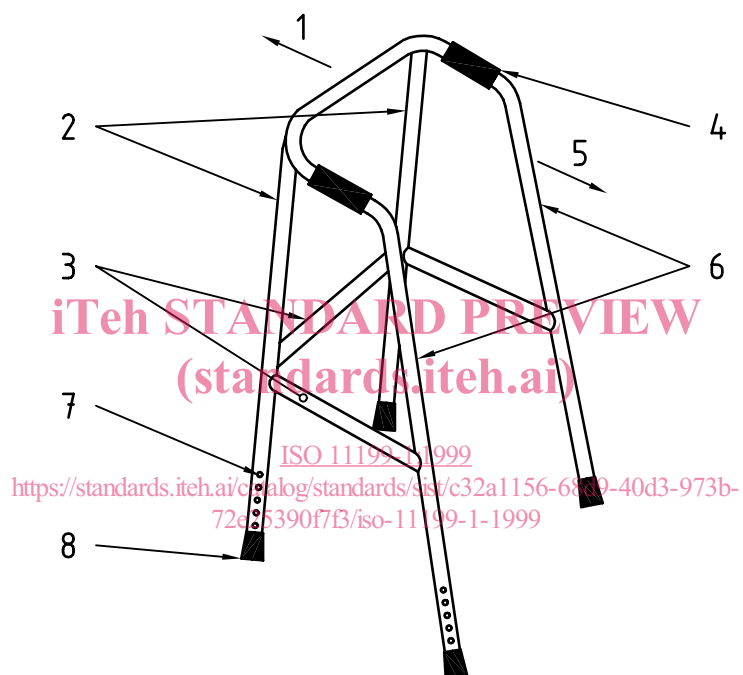
body mass of the person using the product as a technical aid

NOTE Standard user weight is 100 kg for adults and 35 kg for children.

**3.14****walking frame**

walking aid without wheels and with no support devices other than handles

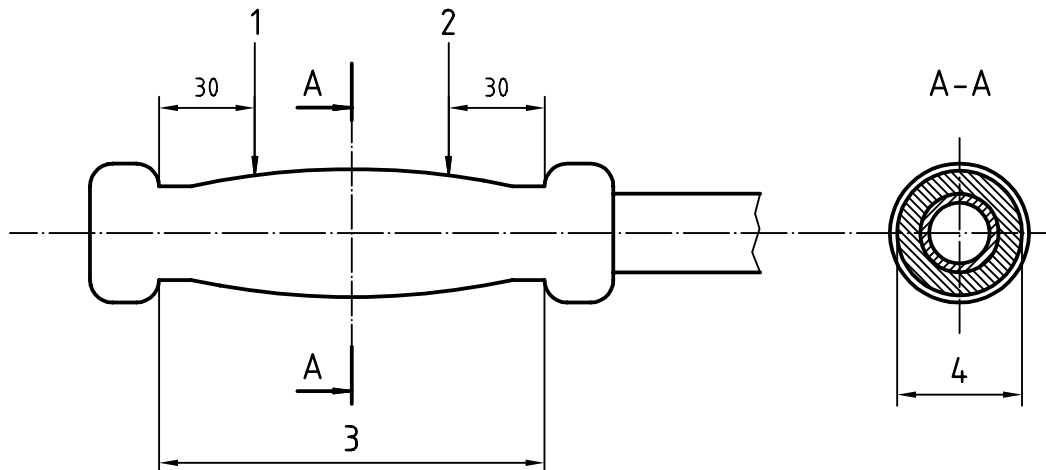
NOTE Classification No. 12 06 03 in accordance with ISO 9999:1998.

**Key**

- 1 Front
- 2 Front legs
- 3 Bracing members
- 4 Handgrip
- 5 Rear
- 6 Rear legs
- 7 Head adjustment mechanism
- 8 Tip

**Figure 1 — Example of a walking frame**

Dimensions in millimetres

**Key**

- 1 Rear handgrip reference point
- 2 Front handgrip reference point
- 3 Handgrip length
- 4 Handgrip width

**Figure 2 — Details of a handgrip**  
(standards.iteh.ai)

**4 Requirements**

ISO 11199-1:1999

<https://standards.iteh.ai/catalog/standards/sist/c32a1156-68d9-40d3-973b-72e25390f7f3/iso-11199-1-1999>

**4.1 Mechanical durability**

When tested according to the fatigue test (5.3), no part of the walking frame shall crack or break.

When tested according to the static loading test (5.4), no part of the frame shall crack or break.

When tested according to the static leg-strength test (5.5), none of the legs shall crack, break or show any permanent set of more than 15 mm, measured at the end of the leg.

**4.2 Stability**

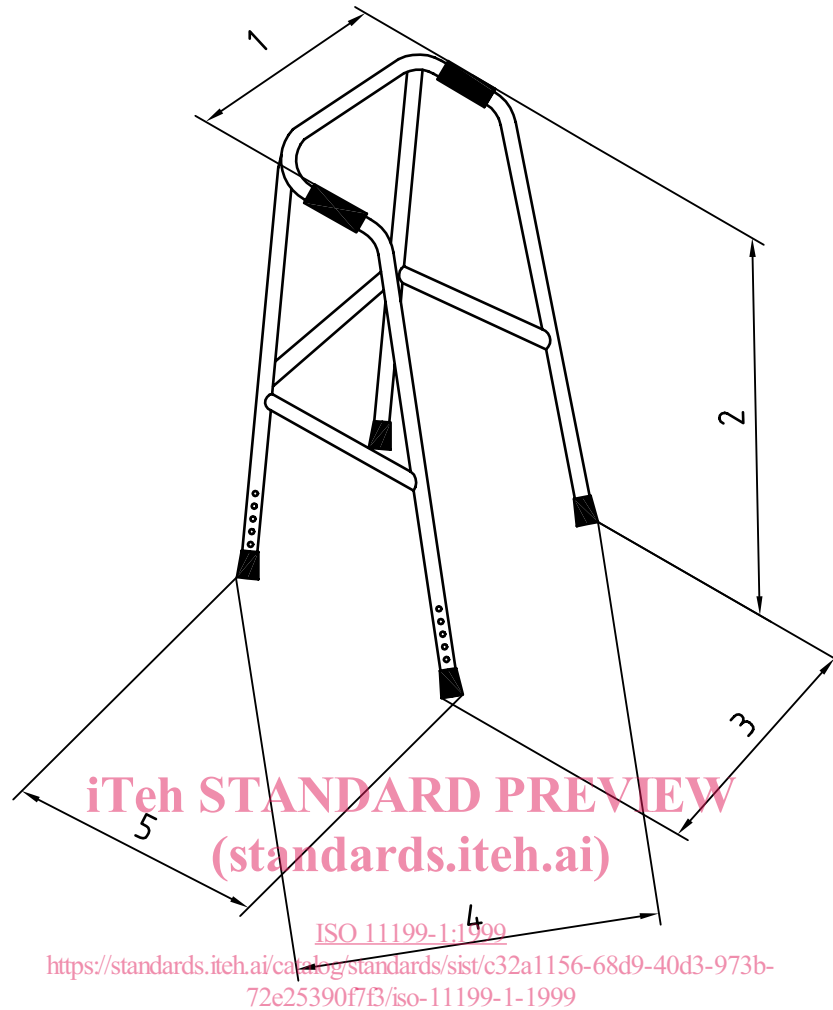
When tested according to the forward stability test (5.6), the angle of the plane at the point of walking frame tilting shall be not less than 10,0°.

When tested according to the backward stability test (5.7), the angle of the plane at the point of walking frame tilting shall be not less than 7,0°.

When tested according to the sideways stability test (5.8), the angle of the plane at the point of walking frame tilting shall be not less than 3,5°.

It is acknowledged that a reciprocal walking frame cannot meet this sideways stability requirement. Therefore, an analysis of the risks related to the instability shall be assessed by the manufacturer, and appropriate guidance and warnings on limitations for use shall be given.



**Key**

- 1 Width between handles
- 2 Height
- 3 Width
- 4 Turning diameter
- 5 Length

**Figure 3 — Dimensions of a walking frame**

### 4.3 Manoeuvrability

Maximum width of a walking frame manufactured for use in private homes shall be not larger than 650 mm.

The width of reciprocating walking frames, when reciprocated, shall be not less than 90 % of maximum width.

### 4.4 Handgrip

The handgrip width shall be not less than 20 mm and not more than 50 mm.

NOTE This requirement does not apply to anatomic handgrips.

The handgrip shall be replaceable or easy to clean.

## 4.5 Leg section and tip

The leg section shall end in a tip of a design which will prevent the leg section from piercing through it when used as intended by the manufacturer. See also 4.1.

The tip shall be replaceable.

The tip shall not cause discolouring of the walking surface, as verified by visual inspection.

That part of the tip that contacts the walking surface shall have a minimum diameter of 35 mm. Compliance shall be verified by visual inspection.

## 4.6 Adjusting devices

Each of the height adjustments shall be clearly marked with its maximum allowable elongation.

After the fatigue test (5.3), the adjustment/folding mechanisms shall operate as intended by the manufacturer.

Folding walking frames shall lock into working position when unfolded.

## 4.7 Materials and finish

Taking into account the intended use and contact by those involved in user care or transportation and storage of the product, walking frame materials which come into contact with the human body shall be assessed for biocompatibility using the guidance given in ISO 10993-1.

The walking frame materials shall not cause discolouring of skin or clothing when the frame is in normal use.

All parts of the walking frame shall be free from burrs, sharp edges or projections that could cause damage to clothing or discomfort to the user.

<https://standards.iteh.ai/catalog/standards/sist/c32a1156-68d9-40d3-973b-72e253901f73/iso-11199-1-1999>

## 5 Test methods

### 5.1 General

Walking frames are grouped into six sizes, as given in Table A.1.

All tests, if not otherwise specified, shall be performed at an ambient temperature of  $21\text{ °C} \pm 5\text{ °C}$ .

If not otherwise specified, all tests shall be performed with the height adjustments at their maximum. The handles shall be positioned at their maximum angle as specified by the manufacturer relative to the line of motion. When the longitudinal centreline of the handle and the direction of forward motion are parallel, the angle is  $0\text{ °}$ . The angle shall always be recorded.

### 5.2 Sampling and inspection

One walking frame shall be tested. The sequence of the tests shall be as follows: stability, static load, fatigue and static leg-strength.

Immediately before testing, the walking frame shall be inspected to check compliance with this part of ISO 11199. Any apparent defects shall be noted so that they shall not later be recorded as having been caused by the tests.

### 5.3 Fatigue test

#### 5.3.1 Loading geometry

The height adjustment and the handles shall be positioned as given in 5.1 and the frame shall be placed with its tips on a horizontal surface. The loading force shall be applied vertically to the walking frame as shown in Figure 4. The loading line shall pass through the midpoint of the line joining the rear handgrip reference points of the two handgrips.

### 5.3.2 Loading force

A cyclic force of  $800 \text{ N} \pm 2 \%$  shall be applied. If the maximum user weight specified for the frame deviates from the standard maximum user weight of 100 kg, a force of 8,0 N per kilogram of maximum user weight,  $\pm 2 \%$ , shall be applied. The load shall be not less than  $280 \text{ N} \pm 2 \%$ .

### 5.3.3 Loading frequency

The frequency of the cyclic loading shall not exceed 1 Hz.

### 5.3.4 Loading cycles

The number of cycles shall be 200 000.

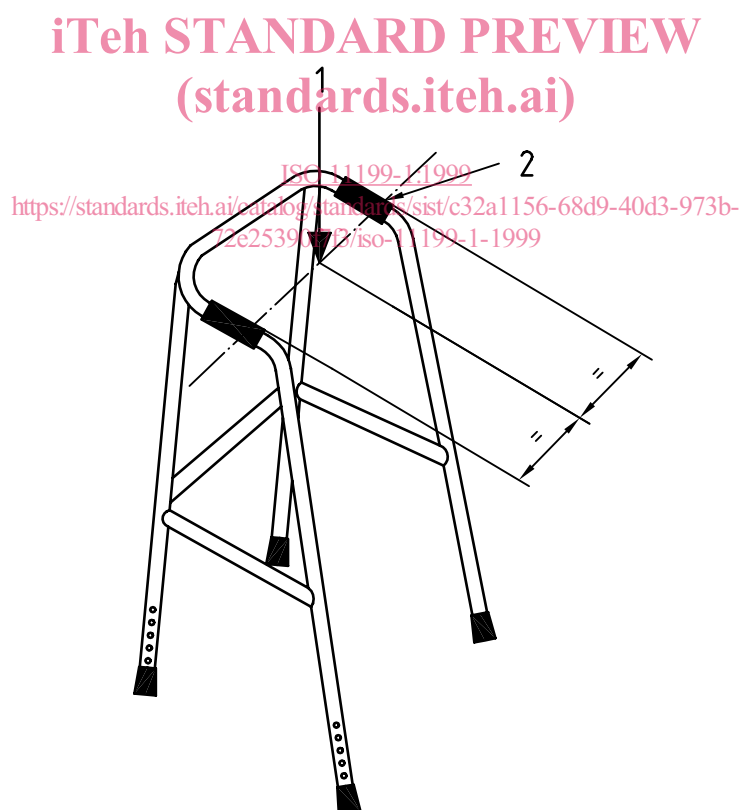
## 5.4 Static loading test

### 5.4.1 Loading geometry

A vertical loading force shall be applied to the walking frame as specified in 5.3.1 and as shown in Figure 4.

### 5.4.2 Loading force

The loading force shall be  $1\,500 \text{ N} \pm 2 \%$ . If the maximum user weight specified for the frame deviates from the standard maximum user weight of 100 kg, a force of 15,0 N per kilogram of maximum user weight,  $\pm 2 \%$ , shall be applied. The load shall be not less than  $525 \text{ N} \pm 2 \%$ .



#### Key

- 1 Load
- 2 Rear handgrip reference point

Figure 4 — Loading geometry for fatigue and static loading tests