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# INTERNATIONAL STANDARD

# NORME INTERNATIONALE



Adjustable speed electrical power drive systems + VIEW Part 5-2: Safety requirements - Functional (Standards.iteh.ai)

Entraînements électriques de puissance à vitesse variable – Partie 5-2: Exigences de sécurité – Fonctionnelle 39-8d2e-4771-9e3e-

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# INTERNATIONAL STANDARD

# NORME INTERNATIONALE



Adjustable speed electrical power drive systems EVIEW Part 5-2: Safety requirements a Functional iteh.ai)

Entraînements électriques de puissance à vitesse variable – Partie 5-2: Exigences de sécurité of Fonctionnelle 39-8d2e-4771-9e3e-

06aa795de80d/iec-61800-5-2-2016

INTERNATIONAL ELECTROTECHNICAL COMMISSION

COMMISSION ELECTROTECHNIQUE INTERNATIONALE

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## INTERNATIONAL ELECTROTECHNICAL COMMISSION

# ADJUSTABLE SPEED ELECTRICAL POWER DRIVE SYSTEMS –

# Part 5-2: Safety requirements - Functional

## **FOREWORD**

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International Standard IEC 61800-5-2 has been prepared by subcommittee 22G: Adjustable speed electric drive systems incorporating semiconductor power converters, of IEC technical committee 22: Power electronic systems and equipment.

This second edition cancels and replaces the first edition published in 2007. This edition constitutes a technical revision.

This edition includes the following significant technical changes with respect to the previous edition:

- a) rational added in the scope why low demand mode is not covered by this standard
- b) definition added for: "category" and "safety function"
- c) "Other sub-functions" sorted into "Monitoring sub-functions" and "Output functions"
- d) deleted "proof test" throughout the document because for PDS(SR) a proof test is not applicable

- e) replaced the term "safety function" by "safety sub-function" throughout the document
- f) Updated references to IEC 61508 series Ed.2010
- g) Added the principle rules of ISO 13849-1 and reference to tables of ISO 13849-2
- h) 6.1.6 Text replaced by Table 2
- i) 6.1.7 Integrated circuits with on-chip redundancy matched to changed requirement in IEC 61508-2: 2010, Annex E
- i) 6.2.8 Design requirements for thermal immunity of a PDS(SR)
- k) 6.2.9 Design requirements for mechanical immunity of a PDS(SR)
- 1) 6.1.6 SIL for multiple safety sub-functions within one PDS(SR)
- m) 6.1.7 Integrated circuits with on-chip redundancy
- n) 6.2.1 Basic and well-tried safety principles
- o) 6.2.2.1.4 Diagnostic test interval when the hardware fault tolerance is greater than zero
- p) 6.2.5.2.7 *PDS(SR)* parameterization
- q) 9 Test requirements
- r) 9.3 Electromagnetic (EM) immunity testing
- s) 9.4 Thermal immunity testing
- t) 9.5 Mechanical immunity testing
- u) Annex A Sequential task table
- v) Annex D, D.3.16, Motion and position feedback sensors updated
- w) Annex E Electromagnetic immunity (EM) requirement for PDS(SR)
- x) Annex F Estimation of PFD<sub>avg</sub> value for low demand with given PFH value

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FDIS	Report on voting
22G/332/FDIS	22G/335/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of the IEC 61800 series, published under the general title *Adjustable speed electric drive systems*, can be found on the IEC website.

The committee has decided that the contents of this publication will remain unchanged until the stability date indicated on the IEC website under "http://webstore.iec.ch" in the data related to the specific publication. At this date, the publication will be

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## INTRODUCTION

As a result of automation, demand for increased production and reduced operator physical effort, control systems of machinery and plant items play an increasing role in the achievement of overall safety. These control systems increasingly employ complex electrical/electronic/programmable electronic devices and systems.

Prominent amongst these devices and systems are adjustable speed electrical power drive systems (PDS) that are suitable for use in safety-related applications (PDS(SR)).

Examples of industrial applications are:

- machine tools, robots, production test equipment, test benches;
- papermaking machines, textile production machines, calendars in the rubber industry;
- process lines in plastics, chemicals or metal production, rolling-mills;
- cement crushing machines, cement kilns, mixers, centrifuges, extrusion machines;
- · drilling machines;
- conveyors, materials handling machines, hoisting equipment (cranes, gantries, etc.);
- pumps, fans, etc.

This standard can also be used as a reference for developers using *PDS(SR)* for other applications.

Teh STANDARD PREVIEW

Users of this standard should be aware that some type C standards for machinery currently refer to ISO 13849-1 for safety-related control systems. In this case, *PDS(SR)* manufacturers may be requested to provide further information (e.g., category and performance level PL) to facilitate the integration of a *PDS(SR)* into the safety-related control systems of such machinery.

One of this standard should be aware that some type C standards for machinery currently refer to ISO 13849-1 for safety-related control systems of such machinery.

NOTE "Type C standards" are defined in ISO 12100 as machine safety standards dealing with detailed safety requirements for a particular machine or group of machines.

There are many situations where control systems that incorporate a *PDS(SR)* are employed, for example as part of safety measures that have been provided to achieve risk reduction. A typical case is guard interlocking in order to exclude personnel from *hazards* where access to the dangerous area is only possible when rotating parts have stopped. This part of IEC 61800 gives a methodology to identify the contribution made by a *PDS(SR)* to identified *safety subfunctions* and to enable the appropriate design of the *PDS(SR)* and verification that it meets the required performance.

Measures are given to co-ordinate the safety performance of the PDS(SR) with the intended risk reduction taking into account the probabilities and consequences of its random and systematic faults.

# ADJUSTABLE SPEED ELECTRICAL POWER DRIVE SYSTEMS –

# Part 5-2: Safety requirements – Functional

# 1 Scope

This part of IEC 61800, which is a product standard, specifies requirements and makes recommendations for the design and development, integration and validation of safety related power drive systems (PDS(SR)) in terms of their functional safety considerations. It applies to adjustable speed electrical power drive systems covered by the other parts of the IEC 61800 series of standards as referred in IEC 61800-2.

NOTE 1 The term "integration" refers to the PDS(SR) itself, not to its incorporation into the safety-related application.

NOTE 2 Other parts of IEC 61800 cover rating specifications, EMC, electrical safety, etc.

This International Standard is applicable where functional safety of a *PDS(SR)* is claimed and the *PDS(SR)* is operating mainly in the high demand or continuous mode (see 3.15)

While low demand mode operation is possible for a *PDS(SR)*, this standard concentrates on high demand and continuous mode. *Safety sub-functions* implemented for high demand or continuous mode can also be used in low demand mode. Requirements for low demand mode are given in IEC 61508 series. Some guidance for the estimation of average probability of dangerous failure on demand (PFD<sub>avg</sub>) value is provided in Annex F.

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This part of IEC 61800 sets out safety-related considerations of PDS(SR)s in terms of the framework of IEC 61508, and introduces requirements for PDS(SR)s as subsystems of a safety-related system. It is intended to facilitate the realisation of the electrical/ electronic/programmable electronic (E/E/PE) parts of a PDS(SR) in relation to the safety performance of safety sub-function(s) of a PDS.

Manufacturers and suppliers of PDS(SR)s by using the normative requirements of this part of IEC 61800 will indicate to users (system integrator, original equipment manufacturer) the safety performance for their equipment. This will facilitate the incorporation of a PDS(SR) into a safety-related control system using the principles of IEC 61508, and possibly its specific sector implementations (for example IEC 61511, IEC 61513, IEC 62061 or ISO 13849).

By applying the requirements from this part of the IEC 61800 series, the corresponding requirements of IEC 61508 that are necessary for a PDS(SR) are fulfilled.

This part of IEC 61800 does not specify requirements for:

- the hazard and risk analysis of a particular application;
- the identification of *safety sub-functions* for that application;
- the initial allocation of SILs to those safety sub-functions;
- the driven equipment except for interface arrangements;
- secondary hazards (for example from failure in a production or manufacturing process);
- the electrical, thermal and energy safety considerations, which are covered in +IEC 61800-5-1;
- the PDS(SR) manufacturing process;
- the validity of signals and commands to the PDS(SR).

security aspects (e.g. cyber security or PDS(SR) security of access)

NOTE 3 The functional safety requirements of a PDS(SR) are dependent on the application, and can be considered as a part of the overall risk assessment of the *installation*. Where the supplier of the PDS(SR) is not responsible for the driven equipment, the *installation* designer is responsible for the risk assessment, and for specifying the functional and safety integrity requirements of the PDS(SR).

This part of IEC 61800 only applies to *PDS(SR)*s implementing *safety sub-functions* with a *SIL* not greater than *SIL* 3.

Figure 1 shows the installation and the functional parts of a *PDS(SR)* that are considered in this part of IEC 61800 and shows a logical representation of a *PDS(SR)* rather than its physical description.

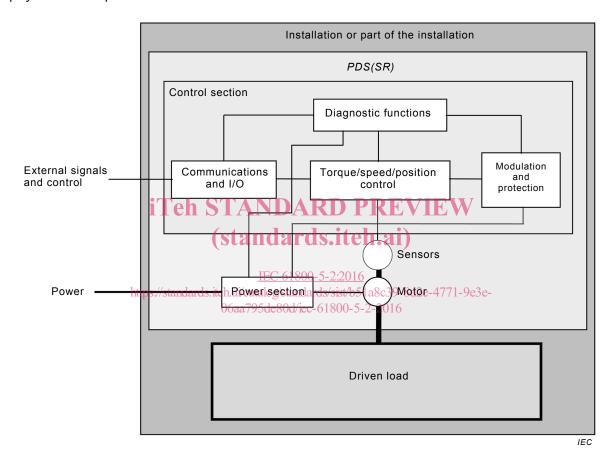


Figure 1 – Installation and functional parts of a PDS(SR)

## 2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60204-1, Safety of machinery – Electrical equipment of machines – Part 1: General requirements

IEC 61000-2-4:2002, Electromagnetic compatibility (EMC) – Part 2-4: Environment – Compatibility levels in industrial plants for low-frequency conducted disturbances

IEC 61000-4-2:2008, Electromagnetic compatibility (EMC) – Part 4-2: Testing and measurement techniques – Electrostatic discharge immunity test

IEC 61000-4-3:2006, Electromagnetic compatibility (EMC) – Part 4-3: Testing and measurement techniques – Radiated, radio-frequency, electromagnetic field immunity test IEC 61000-4-3:2006/AMD1:2007 IEC 61000-4-3:2006/AMD2:2010

IEC 61000-4-4:2012, Electromagnetic compatibility (EMC) – Part 4-4: Testing and measurement techniques – Electrical fast transient/burst immunity test

IEC 61000-4-5:2014, Electromagnetic compatibility (EMC) – Part 4-5: Testing and measurement techniques – Surge immunity test

IEC 61000-4-6:2013, Electromagnetic compatibility (EMC) – Part 4-6: Testing and measurement techniques – Immunity to conducted disturbances, induced by radio-frequency fields

IEC 61000-4-29:2000, Electromagnetic compatibility (EMC) – Part 4-29: Testing and measurement techniques – Voltage dips, short interruptions and voltage variations on d.c. input power port immunity tests

IEC 61000-4-34:2005, Electromagnetic compatibility (EMC) – Part 4-34: Testing and measurement techniques – Voltage dips, short interruptions and voltage variations immunity tests for equipment with input current more than 16 A per phase

IEC 61000-6-7:2014, Electromagnetic compatibility (EMC) - Part 6-7: Generic standards – Immunity requirements for equipment intended to perform functions in a safety-related system (functional safety) in industrial locations dards.iteh.ai)

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IEC 61800-5-1:2007, Adjustable speed electrical power drive systems – Part 5-1: Safety requirements – Electrical, thermal and energy

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ISO 13849-2:2012, Safety of machinery – Safety-related parts of control systems – Part 2: Validation

# 3 Terms and definitions

For the purposes of this document, the following terms and definitions apply. Table 1 shows an alphabetical list of terms and definitions

safety sub-function(s) (of a 3.1 basic drive module 3.12 hazard 3.23 PDS(SR)) **BDM** 3.13 installation 3/24 3 2 category safety integrity 3.3 complete drive module 3,14 mission time 3.25 safety integrity level டிards.iteh. stal CDM SIL 3.4 common cause failure 3.15 mode of operation 3.26 safety-related system 3.5 3.27 safety requirements dangerous failureps://standards.i 13.a16.a RQS(SR)ards/sist/b51a8c39 specification 5de80d/jec-61800-5-2-2016 )6aa79 3.6 diagnostic coverage 3.17 average frequency of a 3.28 SIL capability dangerous failure Performance Level 3.7 diagnostic test(s) 3.18 3.29 subsystem РΙ fail safe safe failure systematic failure 3.8 3.19 3.30 3.9 fail safe state 3.20 safe failure fraction 3.31 systematic safety integrity SFF 3.10 fault reaction function 3.21 3.32 safe state validation functional safety 3.11 3.22 safety function 3.33 verification

Table 1 - Alphabetical list of terms and definitions

NOTE Throughout this International Standard, references to the following definitions are identified by writing them in *italic* script.

#### 3.1

# basic drive module

#### **BDM**

electronic power converter and related control, connected between an electric supply and a motor

Note 1 to entry: The BDM is capable of transmitting power from the electric supply to the motor and can be capable of transmitting power from the motor to the electric supply.

Note 2 to entry: The *BDM* controls some or all of the following aspects of power transmitted to the motor and motor output: current, frequency, voltage, speed, torque, force.

Note 3 to entry: This note applies to the French language only.

[SOURCE: IEC 61800-3:2004/AMD1:2011, 3.1.1]

#### 3.2

#### category

classification of the safety-related parts of a PDS(SR) in respect of their resistance to faults and their subsequent behaviour in the fault condition, and which is achieved by the structural arrangement of the parts, fault detection and/or by their reliability

[SOURCE: ISO 13849-1, definition 3.1.2, modified] "control system" replaced by "PDS(SR)"

#### 3.3

# complete drive module

#### **CDM**

drive module consisting of, but not limited to, the BDM and extensions such as protection devices, transformers and auxiliaries, but excluding the motor and the sensors which are mechanically coupled to the motor shaft

Note 1 to entry: This note applies to the French language only.

[SOURCE: IEC 61800-3:2004/AMD1:2011, 3.1.2]

#### 3.4

common cause failure ch STANDARD PREVIEW failure, which is the result of one or more events, causing concurrent failures of two or more separate channels in a multiple channel system, deading to failure of the safety sub-function

[SOURCE: IEC 61508-4:2010, 3.6.10 modified 7.20 leading to system failure replaced by "leading to failure of the safety sub-function" - 2.2.2.5.5.1 (leading to failure of the safety sub-function and sub-function

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### 3.5

#### dangerous failure

failure of a component and/or subsystem and/or system that plays a part in implementing the safety sub-function that:

- a) causes a safety sub-function of a PDS(SR) to fail such that the equipment or machinery driven by the PDS(SR) is put into a hazardous or potentially hazardous state; or
- b) decreases the probability that the safety sub-function operates correctly

[SOURCE: IEC 61508-4:2010, 3.6.7, modified - "EUC" replaced by "PDS(SR)", "when required" deleted]

#### 3.6

# diagnostic coverage

fraction of dangerous failures detected by automatic diagnostic tests

Note 1 to entry: This can also be expressed as the ratio of the sum of the detected dangerous failure rates  $\lambda_{DD}$  to the sum of the total dangerous failure rates  $\lambda_D$ :  $DC = \Sigma \lambda_{DD} / \Sigma \lambda_D$ .

Note 2 to entry: Diagnostic coverage can exist for the whole or parts of a safety-related system. For example, diagnostic coverage can exist for sensors and/or logic subsystems and/or output subsystem.

Note 3 to entry: This note applies to the French language only.

[SOURCE: IEC 61508-4: 2010; 3.8.6, modified - "on-line" deleted from "online diagnostic tests"]