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Adjustable speed electrical power drive systems –
Part 7-301: Generic interface and use of profiles for power drive systems –
Mapping of profile type 1 to network technologies

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ADJUSTABLE SPEED ELECTRICAL POWER DRIVE SYSTEMS –

Part 7-301: Generic interface and use of profiles for power drive systems – Mapping of profile type 1 to network technologies

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International Standard IEC 61800-7-301 has been prepared by subcommittee SC 22G: Adjustable speed electric drive systems incorporating semiconductor power converters, of IEC technical committee TC 22: Power electronic systems and equipment.

This second edition cancels and replaces the first edition published in 2007. This edition constitutes a technical revision.

This edition includes the following significant technical changes with respect to the previous edition:

- Additional mappings to communication systems are included (see Clause 6 and Clause 7).

The text of this standard is based on the following documents:

FDIS	Report on voting
22G/311/FDIS	22G/326/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

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INTRODUCTION

The IEC 61800 series is intended to provide a common set of specifications for adjustable speed electrical power drive systems.

IEC 61800-7 specifies profiles for power drive systems (PDS) and their mapping to existing communication systems by use of a generic interface model.

IEC 61800-7 describes a generic interface between control systems and power drive systems. This interface can be embedded in the control system. The control system itself can also be located in the drive (sometimes known as "smart drive" or "intelligent drive").

A variety of physical interfaces is available (analogue and digital inputs and outputs, serial and parallel interfaces, fieldbuses and networks). Profiles based on specific physical interfaces are already defined for some application areas (e.g. motion control) and some device classes (e.g. standard drives, positioner). The implementations of the associated drivers and application ~~programmers~~ programming interface~~s~~ are proprietary and vary widely.

IEC 61800-7 defines a set of common drive control functions, parameters, and state machines or description of sequences of operation to be mapped to the drive profiles.

IEC 61800-7 provides a way to access functions and data of a drive that is independent of the used drive profile and communication interface. The objective is a common drive model with generic functions and objects suitable to be mapped on different communication interfaces. This makes it possible to provide common implementations of motion control (or velocity control or drive control applications) in controllers without any specific knowledge of the drive implementation.

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There are several reasons to define a generic interface:

For a drive device manufacturer

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– less effort to support system integrators;
– less effort to describe drive functions because of common terminology;
– the selection of drives does not depend on availability of specific support;

For a control device manufacturer

– no influence of bus technology;
– easy device integration;
– independent of a drive supplier;

For a system integrator

– less integration effort for devices;
– only one understandable way of modeling;
– independent of bus technology.

Much effort is needed to design a motion control application with several different drives and a specific control system. The tasks to implement the system software and to understand the functional description of the individual components may exhaust the project resources. In some cases, the drives do not share the same physical interface. Some control devices just support a single interface, which will not be supported by a specific drive. On the other hand, the functions and data structures are often specified with incompatibilities. This requires the system integrator to write special interfaces for the application software and this should not be his responsibility.