

SLOVENSKI STANDARD SIST EN 61300-3-35:2010

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Fibre optic interconnecting devices and passive components - Basic test and measurement procedures - Part 3-35: Examinations and measurements - Fibre optic cylindrical connector endface visual and automated inspection (IEC 61300-3-35:2009)

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Lichtwellenleiter - Verbindungselemente und passive Bauteile - Grundlegende Prüf- und Messverfahren - Teil 3-35: Untersüchungen und Messungen - Visuelle und automatisierte Inspektion der Endflächen von zylindrischen Lichtwellenleiter- Steckverbindern (IEC 61300-3-35:2009) N 61300-3-35:2010

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Dispositifs d'interconnexion et composants passifs à fibres optiques - Méthodes fondamentales d'essais et de mesure - Partie 3-35 : Examens et mesures - Inspection automatique et visuelle de la face terminale des connecteurs à fibres optiques (CEI 61300-3-35:2009)

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Fibre optic interconnecting devices and passive components -Basic test and measurement procedures -Part 3-35: Examinations and measurements -Fibre optic connector endface visual and automated inspection (IEC 61300-3-35:2009)

Dispositifs d'interconnexion et composants

passifs à fibres optiques -

Méthodes fondamentales d'essais

et de mesure -

Partie 3-35: Examens et mesures -

Inspection automatique et visuelle pund Messungen - de la face terminale des connecteurs

à fibres optiques

(CEI 61300-3-35:2009)

Lichtwellenleiter -Verbindungselemente und passive Bauteile -

Grundlegende Prüf- und Messverfahren -

Teil 3-35: Untersuchungen

Visuelle und automatisierte Inspektion

(standards.itelder Endflächen von zylindrischen Lichtwellenleiter-Steckverbindern

SIST EN 61300-3-35:20 (JEC 61300-3-35:2009)

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CENELEC

European Committee for Electrotechnical Standardization Comité Européen de Normalisation Electrotechnique Europäisches Komitee für Elektrotechnische Normung

Central Secretariat: Avenue Marnix 17, B - 1000 Brussels

Foreword

The text of document 86B/2909/FDIS, future edition 1 of IEC 61300-3-35, prepared by SC 86B, Fibre optic interconnecting devices and passive components, of IEC TC 86, Fibre optics, was submitted to the IEC-CENELEC parallel vote and was approved by CENELEC as EN 61300-3-35 on 2009-12-01.

The following dates were fixed:

 latest date by which the EN has to be implemented at national level by publication of an identical national standard or by endorsement

(dop) 2010-09-01

 latest date by which the national standards conflicting with the EN have to be withdrawn

(dow) 2012-12-01

Endorsement notice

The text of the International Standard IEC 61300-3-35:2009 was approved by CENELEC as a European Standard without any modification.

In the official version, for Bibliography, the following note has to be added for the standard indicated:

ISO 14577-2

NOTE Harmonized as EN ISO 14577-2 (not modified).

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FIBRE OPTIC INTERCONNECTING DEVICES AND PASSIVE COMPONENTS – BASIC TEST AND MEASUREMENT PROCEDURES –

Part 3-35: Examinations and measurements – Fibre optic connector endface visual and automated inspection

FOREWORD

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International Standard IEC 61300-3-35 has been prepared by subcommittee 86B: Fibre optic interconnecting devices and passive components, of IEC technical committee 86: Fibre optics.

This standard replaces IEC/PAS 61300-3-35 which was published in 2002.

The text of this standard is based on the following documents:

FDIS	Report on voting
86B/2909/FDIS	86B/2947/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

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This publication has been drafted in accordance with the ISO/IEC Directives, Part 2.

A list of all parts of IEC 61300 series, published under the general title, *Fibre optic interconnecting devices and passive components – Basic test and measurement procedures* can be found on the IEC website.

The committee has decided that the contents of this publication will remain unchanged until the maintenance result date indicated on the IEC web site under "http://webstore.iec.ch" in the data related to the specific publication. At this date, the publication will be

- · reconfirmed,
- withdrawn,
- replaced by a revised edition, or
- · amended.

A bilingual version of this standard may be issued at a later date.

IMPORTANT – The "colour inside" logo on the cover page of this publication indicates that it contains colours which are considered to be useful for the correct understanding of its contents. Users should therefore print this publication using a colour printer.

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FIBRE OPTIC INTERCONNECTING DEVICES AND PASSIVE COMPONENTS – BASIC TEST AND MEASUREMENT PROCEDURES –

Part 3-35: Examinations and measurements – Fibre optic connector endface visual and automated inspection

1 Scope

This part of IEC 61300 describes methods for quantitatively assessing the endface quality of a polished fibre optic connector. The information is intended for use with other standards which set requirements for allowable surface defects such as scratches, pits and debris which may affect optical performance. In general, the methods described in this standard apply to 125 μm cladding fibres contained within a ferrule and intended for use with sources of $\leq\!2$ W of input power. However, portions are applicable to non-ferruled connectors and other fibre types. Those portions are identified where appropriate.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

None.

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3 Measurement

3.1 General

The objective of this standard is to prescribe methods for quantitatively inspecting fibre optic endfaces to determine if they are suitable for use. Three methods are described: A: direct view optical microscopy, B: video microscopy, C: automated analysis microscopy. Within each method, there are hardware requirements and procedures for both low resolution and high resolution systems. High resolution systems are to be utilized for critical examination of the glass fibre after polishing and upon incoming quality assurance. High resolution systems are typically not used during field polishing or in conjunction with multimode connectors. Low resolution systems are to be utilized prior to mating connectors for any purpose. All methods require a means for measuring and quantifying defects.

There are many types of defects. Commonly used terminology would include: particles, pits, chips, scratches, embedded debris, loose debris, cracks, etc. For practical purposes, all defects will be categorized in one of two groups. They are defined as follows:

scratches: permanent linear surface features;

defects: all non-linear features detectable on the fibre. This includes particulates, other debris, pits, chips, edge chipping, etc.

All defects and scratches are surface anomalies. Sub-surface cracks and fractures are not reliably detectable with a light microscope in all situations and are therefore not covered within this standard. Cracks and fractures to the fibre may be detected with a light microscope and are generally considered a catastrophic failure.

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Differentiating between a scratch and all other defects is generally intuitive to a human being. However, to provide clarity, and for automated systems, scratches are defined as being less than 4 μm wide, linear in nature, and with a length that is at least 30 times their width. As the width dimension is not practical to visually measure below 3 μm , these figures can be grossly estimated.

Defects size is defined for methods A and B as the diameter of the smallest circle that can encompass the entire defect. Defect size for method C can be either the actual measured surface area or the diameter of the smallest circle than can encompass the entire defect.

Some fibre types have structural features potentially visible on the fibre endface. Fibres that use microstructures to contain the light signal, such as photonic band-gap and hole-assisted fibres, can have an engineered or random pattern of structures surrounding the core. These features are not defects.

For methods A and B below, it is recommended that visual gauge tools be developed to facilitate the measurement procedure. For method A, an eyepiece reticule is recommended. For method B, an overlay is recommended.

3.2 Measurement conditions

No restrictions are placed on the range of atmospheric conditions under which the test can be conducted. It may be performed in controlled or uncontrolled environments

3.3 Pre-conditioning Teh STANDARD PREVIEW

No minimum pre-conditioning time is required: ds.iteh.ai)

3.4 Recovery

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Since measurements are to be made at standard test conditions, no minimum recovery time is required.

4 Apparatus

4.1 Method A: direct view optical microscopy

This method utilizes a light microscope in which a primary objective lens forms a first image that is then magnified by an eyepiece that projects the image directly to the user's eye. It shall have the following features and capabilities:

- · a suitable ferrule or connector adapter;
- a light source and focusing mechanism;
- a means to measure defects observed in the image.

4.2 Method B: video microscopy

This method utilizes a light microscope in which a lens system forms an image on a sensor that, in turn, transfers the image to a display. The user views the image on the display. It shall have the following features and capabilities:

- a suitable ferrule or connector adapter;
- a light source and focusing mechanism;
- a means to measure defects observed in the image.

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4.3 Method C: automated analysis microscopy

This method utilizes a light microscope in which a digital image is acquired or created and subsequently analyzed via an algorithmic process. The purpose of such a system is to reduce the effects of human subjectivity in the analysis process and, in some cases, to improve cycle times. It shall have the following features and capabilities:

- a suitable ferrule or connector adapter;
- a means for acquiring or creating a digital image;
- · algorithmic analysis of the digital image.

A means to compare the analyzed image to programmable acceptance criteria in such a manner that a result of "pass" or "fail" is provided.

4.4 Calibration requirements for low and high resolution systems

4.4.1 General

Microscope systems for any of the methods above shall be calibrated for use in either low or high resolution applications. It is suggested that this calibration be conducted with a purpose-built calibration artefact that can serve to validate a system's ability to detect defects of relevant size. Such an artefact shall be provided with instructions on its use and shall be manufactured in a method such that it can be measured in a traceable manner. Details on the manufacture of such artefacts can be found in Annex B.

For reference, a system's optical resolution may be calculated using the formula below. Optical resolution is not equivalent to the system's detection capability. In most cases, the system will be able to detect defects smaller than its optical resolution.

Optical resolution = (0.61 × wavelength of illumination source) (system's numerical aperture

4.4.2 Requirements for low resolution microscope systems

Minimum total magnification offering a field of view of at least 250 μm (for methods B and C, this dimension is to be measured in the vertical, or most constrained, axis) capable of detecting low-contrast defects of 2 μm in diameter or width.

4.4.3 Requirements for high resolution microscope systems

Minimum total magnification offering a field of view of at least 120 μ m (for methods B and C, this dimension shall be measured in the vertical, or most constrained, axis) capable of detecting low contrast scratches of 0,2 μ m in width and 0,003 μ m in depth.