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NORME INTERNATIONALE

Underwater acoustics - Hydrophones - Calibration of hydrophones -Part 2: Procedures for low frequency pressure calibration (Standards.iten.al)

Acoustique sous-marine – Hydrophones – Étalonnage des hydrophones – Partie 2: Procédures pour l'étalonnage à basse pression de fréquence

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Underwater acoustics A Hydrophones - Calibration of hydrophones -Part 2: Procedures for low frequency pressure calibration

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

UNDERWATER ACOUSTICS – HYDROPHONES – CALIBRATION OF HYDROPHONES –

Part 2: Procedures for low frequency pressure calibration

FOREWORD

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International Standard IEC 60565-2 has been prepared by IEC technical committee 87: Ultrasonics.

This first edition of IEC 60565-2, together with IEC 60565-1, replaces the second edition of IEC 60565 published in 2006. This edition constitutes a technical revision.

This edition includes the following significant technical changes with respect to the previous edition.

- 1) IEC 60565 has been divided into two parts:
 - Part 1: Procedures for free-field calibration;
 - Part 2: Procedures for low frequency pressure calibration (this document).
- 2) A relative calibration method has been added to Clause 8: Calibration by piezoelectric compensation.

- 3) A relative calibration method has been added to Clause 11: Calibration by **vibrating column**.
- 4) Clause 12: Calibration by static pressure transducer, has been added.
- 5) Annex A: Equivalent circuit of the excitation system for calibration with a **vibrating column**, has been deleted.
- 6) Subclauses 9.6, 9.7 and 9.8 have been moved to form a new Annex A: Advanced acoustic coupler calibration methods.

The text of this International Standard is based on the following documents:

FDIS	Report on voting
87/720/FDIS	87/723/RVD

Full information on the voting for the approval of this International Standard can be found in the report on voting indicated in the above table.

This document has been drafted in accordance with the ISO/IEC Directives, Part 2.

NOTE Words in **bold** in the text are terms defined in Clause 3.

A list of all parts in the IEC 60565 series, published under the general title *Underwater* acoustics – *Hydrophones* – *Calibration of hydrophones*, can be found on the IEC website.

The committee has decided that the contents of this document will remain unchanged until the stability date indicated on the IEC website under "http://webstore.iec.ch" in the data related to the specific document. At this date, the document will be

- reconfirmed, <u>IEC 60565-2:2019</u>
- withdrawn, https://standards.iteh.ai/catalog/standards/sist/8b556783-bad4-4b70-8750-828600b57cab/iec-60565-2-2019
- replaced by a revised edition, or
- amended.

INTRODUCTION

The purpose of this document is to establish the procedures for low frequency pressure calibrations of **hydrophone**s in the frequency range from 0,01 Hz to several kilohertz.

To ensure the correctness of the calibrations, the **hydrophone**s to be calibrated are "rigid" **hydrophone**s with small size compared to the acoustic wavelength, and are not sensitive to vibration when calibrated.

Principles, procedures, and **uncertainties** of physical calibrations such as hydrostatic excitation, piezoelectric compensation, **pistonphone**, **vibrating column**, static pressure transducer, etc., and reciprocity calibrations in acoustic **coupler**s are given in this document. Calibrations are carried out using one of these methods, depending on the different principles to be used, and its limitations to the sound field and the frequency range.

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<u>IEC 60565-2:2019</u> https://standards.iteh.ai/catalog/standards/sist/8b556783-bad4-4b70-8750-828600b57cab/iec-60565-2-2019

UNDERWATER ACOUSTICS – HYDROPHONES – CALIBRATION OF HYDROPHONES –

Part 2: Procedures for low frequency pressure calibration

1 Scope

This part of IEC 60565 specifies the methods for low frequency pressure calibration of **hydrophone**s at frequencies from 0,01 Hz to several kilohertz depending on calibration method.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 60050-801, International Electrotechnical Vocabulary – Chapter 801: Acoustics and electroacoustics (available at http://www.electropedia.org/) F.V.F.W

IEC 60500:2017, Underwater acoustics Androphones Properties of the hydrophone in the frequency range 1 Hz to 500 kHz

IEC 60565-2:2019

3 Terms and definitions 8750-828600b57cab/iec-60565-2-2019

For the purposes of this document, the terms and definitions given in IEC 60050-801, IEC 60500:2017 and the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- IEC Electropedia: available at http://www.electropedia.org/
- ISO Online browsing platform: available at http://www.iso.org/obp

3.1

coupler

apparatus comprising a rigid fluid-filled chamber into which transducers and **hydrophones** can be inserted whose largest dimension is small compared to the wavelength

Note 1 to entry: In this document, the term small chamber is used interchangeably with **coupler**.

[SOURCE: IEC 60565:2006 [1]¹, 3.3, modified – In the definition, "small dimensions" has been replaced by "whose largest dimension is small compared to the wavelength".]

¹ Numbers in square brackets refer to the Bibliography.

3.2

diffraction factor

ratio of the root-mean-square value of the sound pressure, averaged over the part of the **hydrophone** designed to receive an incident plane wave sound pressure from a given direction to the free-field root-mean-square sound pressure that would exist at the position of the reference centre of the **hydrophone** if the **hydrophone** was removed

Note 1 to entry: Spatial average is undertaken first and then time average.

[SOURCE: IEC 60500:2017, 3.3, modified – In the definition, "the root-mean-square sound pressure" has been replaced by "the root-mean-square value of the sound pressure,", and "the position of" has been added after "that would exist at".]

3.3

electrical transfer impedance

<u>Z</u>_{PH}

<of a transducer pair in a coupler> quotient of the Fourier transform of the open circuit voltage $\Im(U_{\rm H}(t))$ across the **hydrophone** electrical terminals, to the Fourier transform of the electrical current $\Im(I_{\rm P}(t))$ through the **projector**, when **projector** and **hydrophone** are mounted in a **coupler**

$\underline{Z}_{PH} = \frac{\Im(U_{H}(t))}{\Im(I_{P}(t))}$ **iTeh STANDARD PREVIEW**

(1)

Note 1 to entry: The electrical transfer impedance is a complex-valued parameter. The modulus of the electrical transfer impedance is expressed in ohm, Ω . The phase angle is expressed in degrees, and represents the phase difference between the hydrophone voltage and the projector current.

Note 2 to entry: Because the **electrical transfer impedance** depends on the field conditions, the hydrostatic pressure, water temperature and the length of the cable attached to the transducer, these parameters, as well as the frequency and the electrical terminals where the electrical impedance is measured, are specified.

[SOURCE: IEC 60565:2006 [1], 3.10, modified – In the term, "transducer pair" has been deleted. The domain "<of a transducer pair in a coupler>" has been added. In the definition, "complex ratio of the open circuit instantaneous voltage $U_{\rm H}$ " has been replaced by "quotient of the Fourier transform of the open circuit voltage $\Im(U_{\rm H}(t))$ ", "the instantaneous current $I_{\rm P}$ " has been replaced by "Fourier transform of the electrical current $\Im(I_{\rm P}(t))$ ", and "if **projector** and **hydrophone** are mounted in a free field with their principal axes in line and directed towards each other" has been replaced by "when **projector** and **hydrophone** are mounted in a free field with their principal axes in line and directed towards each other" has been replaced by "when **projector** and **hydrophone** are mounted in a

3.4

hydrophone

electroacoustic transducer that produces electrical voltages in response to water borne pressure **signal**s

Note 1 to entry: A hydrophone is designed to respond principally to underwater sound pressure.

Note 2 to entry: In general, a **hydrophone** can also produce a **signal** in response to non-acoustic pressure fluctuations (for example, those existing in a turbulent boundary layer during conditions of high water flow).

Note 3 to entry: **Hydrophone** types include reference **hydrophones** and measuring **hydrophones**. Measuring **hydrophones** are used in general measurements of sound fields, and reference **hydrophones** are principally used for calibration purposes (for example in comparison calibrations with measuring **hydrophones**).

Note 4 to entry: **Hydrophone**s are principally used as listening devices, but in reciprocity calibration, a **hydrophone** is used as **reciprocal transducer**, not only acting as a **hydrophone**, but also as a **projector** (sound source).

Note 5 to entry: A **hydrophone** which is integrated with a digital acquisition system is sometimes termed a "digital **hydrophone**", but the combination is best considered as a measuring system, not a **hydrophone** alone.

Note 6 to entry: If a **hydrophone** is connected to a charge amplifier, the sensitivity of the **hydrophone** is sometimes described in terms of charge sensitivity, which is related to the voltage sensitivity of the **hydrophone** by its electrical capacitance.

[SOURCE: IEC 60500:2017, 3.17, modified – In the definition, "electrical **signals**" has been replaced by "electrical voltages".]

3.5

pistonphone

apparatus having a rigid piston which can be given a reciprocating motion of a known frequency and amplitude to establish a known sound pressure in a closed small chamber

[SOURCE: IEC 60565:2006 [1], 3.20, modified – In the definition, "so permitting the establishment of" has been replaced by "to establish", and "a closed chamber of small dimensions" by "a closed small chamber".]

3.6

pressure sensitivity

 M_{p}

<of a hydrophone> quotient of the Fourier transform of the hydrophone open-circuit voltage signal $\Im(U_{H}(t))$ to the Fourier transform of the acoustic pressure signal $\Im(p(t))$ averaged over the hydrophone active element, at a specified frequency

iTeh STAND
$$\frac{\Im(U_{H}(t))}{\Im(p(t))}$$
 PREVIEW (2)
(standards.iteh.ai)

Note 1 to entry: The **hydrophone pressure sensitivity** is a complex-valued parameter. The modulus of the **pressure sensitivity** of a **hydrophone** is expressed in units of volt per pascal, V/Pa. The phase angle of the sensitivity is expressed in degrees, and represents the phase difference between the electrical voltage and the https://standards.iteh.ai/catalog/standards/sist/8b556/83-bad4-4b70-8750-828600b57cab/iec-60565-2-2019

Note 2 to entry: The term "response" is sometimes used instead of "sensitivity".

Note 3 to entry: The **hydrophone** active element is the electroacoustic element of the **hydrophone** which is sensitive to sound pressure.

[SOURCE: IEC 60500:2017, 3.23, modified – In the definition, "ratio of the root-mean-square output voltage" has been replaced by "quotient of the Fourier transform of the **hydrophone** open-circuit output voltage **signal** $\Im(U_H(t))$ ", and "root-mean-square of the sound pressure" has been replaced by "Fourier transform of the sound pressure $\Im(p(t))$ ". The description of the **hydrophone** active element has been moved to a Note to entry.]

3.7 pressure sensitivity level

 L_{M}

twenty times the logarithm to the base 10 of the ratio of the modulus of the **pressure** sensitivity $|\underline{M}_{p}|$ to a reference sensitivity of M_{ref} , in decibels

$$L_{\rm M} = 20 \log_{10} \frac{\left|\underline{M}_{\rm p}\right|}{M_{\rm ref}} \quad {\rm dB} \tag{3}$$

Note 1 to entry: The value of reference sensitivity $M_{\rm ref}$ is 1 V/µPa.

[SOURCE: IEC 60500:2017, 3.24, modified – In the definition, "modulus of the" has been added before "**pressure sensitivity**", and "in decibels" has been added after " M_{ref} ".]

3.8

projector

electro-acoustic transducer that converts electric **signal**s into sound **signal**s propagating in water

[SOURCE: IEC 60565:2006 [1], 3.37]

3.9 ratio of specific heats

ratio of specific heats under constant pressure and under constant volume

Note 1 to entry: For dry air and temperature 0 °C to 17 °C, γ = 1,40.

3.10

reciprocal transducer

linear, passive, and reversible electroacoustic transducer such that the coupling coefficients are equal for transduction in either direction

[SOURCE: IEC 60565:2006 [1], 3.24, modified – In the definition, "transducer" has been replaced by "electroacoustic transducer", and "such that the coupling coefficients are equal for transduction in either direction" has been added at the end of the definition.]

3.11 signal iTeh STANDARD PREVIEW

specified time-varying electric current, voltage, sound pressure, sound particle displacement, or other field quantity of interest standards.iteh.ai)

[SOURCE: ISO 18405:2017 [2], 3.1.5.8]<u>C 60565-2:2019</u>

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transmitting response to current

 $S_{I,T}$

3.12

<of a transducer in a coupler> quotient of the Fourier transform of the acoustic pressure **signal** $\Im(p(t))$ to the Fourier transform of the electrical current **signal** $\Im(I(t))$ through a transducer T inserted into the **coupler** at a given frequency

$$\underline{S}_{l,T} = \frac{\Im(p(t))}{\Im(I(t))}$$
(4)

Note 1 to entry: Transmitting response to current is expressed in units of pascal per ampere, Pa/A.

Note 2 to entry: Different with the free-field calibration, no distance term is required here.

Note 3 to entry: The acoustic pressure signal is assumed uniform in a **coupler**.

[SOURCE: IEC 60565:2006 [1], 3.36, modified – In the term, "small chamber transmitting response to current of a transducer" has been replaced by "transmitting response to current". The domain "<of a transducer in a coupler>" has been added. In the definition, "a small chamber" has been replaced by "a coupler", and "flowing through the electrical terminals of a transducer inside the chamber" by "through a transducer inserted into the coupler". Also, "current" has been replaced by "Fourier transform of the electrical current signal $\Im(U_H(t))$ ", and "ratio of the acoustical pressure (assumed uniform)" has been replaced by "quotient of the Fourier transform of the acoustic pressure signal $\Im(p(t))$ ".]

3.13

uncertainty

<of measurement> non-negative parameter characterizing the dispersion of the quantity values being attributed to a measurand, based on the information used

- 12 -

[SOURCE: ISO/IEC Guide 99:2007 [3], 2.26]

3.14

vibrating column

apparatus in which a column of water in a vertically placed cylindrical container is set in vibration, causing a depth-dependent sound pressure in the water column

Note 1 to entry: The length of the column is sufficiently small compared with the wavelength of the sound in the water. The cross-sectional dimension of the column is small compared with its length.

[SOURCE: IEC 60565:2006 [1], 3.38]

3.15 wavenumber

k

reciprocal of the acoustic wavelength multiplied by 2π

$$=2\pi/\lambda \tag{5}$$

k ρ Note 1 to entry: Wavenumber is expressed in units of per metre, m

Note 2 to entry: In different branches of physics, the term wavenumber can be considered equal to either $2\pi/\lambda$ or $1/\lambda$, but in the technical field of acoustics, $2\pi/\lambda$ is preferred. This term given in IEC 60050-103:2009, 103-10-12 is "angular wavenumber".

IEC 60565-2:2019

[SOURCE: IEC 60050726:1982 141:1726-05-02 modified 628 in the definition, "the reciprocal of the waveguide wavelength 8 50-the 00 and catfor a 5 plane wave have been deleted, and "acoustic" and "multiplied by 2π " have been added before and after "wavelength", respectively.]

4 Symbols

- C_{t} acoustic compliance of chamber
- compliance of the medium C_{M}
- speed of sound in water С
- speed of sound in a fluid C_{f}
- depth or distance of the hydrophone d
- piezoelectric modulus of the shell material d_{ik}
- Young's modulus Ε
- frequency f
- acceleration due to gravity g
- h displacement of the water surface in the open vessel
- equivalent height Η_ρ
- ΔH change of the water level
- I_{P} current through projector
- current through transducer I_{T}
- compensation current through null projector I_{c}
- Κ characteristic constant of piezoelectric null transducer

- *K*₀ hydrostatic pressure correction factor
- k wavenumber
- L length of column or **coupler**
- L_M pressure sensitivity level of the hydrophone
- *M*_H sensitivity of the **hydrophone**
- *M*_p pressure sensitivity
- $M_{\rm T}$ sensitivity of the static pressure transducer
- M_{M} sensitivity of the microphone
- p sound pressure
- p_s static pressure
- Q mechanical quality factor
- r radius of transducer shell
- S_{P} transmitting response to current of a projector in a coupler
- S_T transmitting response to current of a transducer in a coupler
- U_{C} compensation voltage
- U_H open-circuit voltage at hydrophone
- U_M open-circuit voltage at microphone
- U_{PH} open-circuit voltage at hydrophone with a projector as sound source
- $U_{\rm PT}$ open-circuit voltage at transducer with a **projector** as sound source
- U_{TH} open-circuit voltage at hydrophone with a transducer as sound source
- U_R open-circuit voltage at a reference hydrophone
- \underline{u} volume velocity_{https://standards.iteh.ai/catalog/standards/sist/8b556783-bad4-4b70-}
- $V_{\rm b}$ volume of the subsidiary $b\overline{\partial}\overline{\partial}y$ - $828600b\overline{57}$ cab/iec-60565-2-2019
- $V_{\rm t}$ total volume
- ΔV volume change
- *x*₀ vibration amplitude
- *Z* contains all the terms involving transfer impedance
- \underline{Z}_{AI} acoustic impedance
- \underline{Z}_{PH} electrical transfer impedance of projector and hydrophone in a coupler
- \underline{Z}_{PT} electrical transfer impedance of projector and transducer in a coupler
- Z_{TH} electrical transfer impedance of transducer and hydrophone in a coupler
- \underline{Z}_{TP} electrical transfer impedance of transducer to projector in a coupler
- γ ratio of specific heats
- ho density of water
- $\rho_{\rm f}$ density of fluid
- σ Poisson's modulus
- ω angular frequency
- $\omega_{\rm r}$ resonance angular frequency

5 Procedures for calibration

5.1 Principles

a) Absolute calibration