



Edition 2.1 2019-03 CONSOLIDATED VERSION

# INTERNATIONAL STANDARD

# NORME INTERNATIONALE



Automatic electrical controls –

Part 2-14: Particular requirements for electric actuators

Dispositifs de commande électrique automatiques – Partie 2-14: Exigences particulières pour les actionneurs électriques

IEC 60730-2-14:2017

https://standards.iteh.ai/catalog/standards/jec/cdc91251-6e8e-493c-b2e0-4bc5b10b1606/jec-60730-2-14-2017





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INTERNATIONAL ELECTROTECHNICAL COMMISSION

COMMISSION ELECTROTECHNIQUE INTERNATIONALE

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### **REDLINE VERSION**

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### INTERNATIONAL ELECTROTECHNICAL COMMISSION

#### **AUTOMATIC ELECTRICAL CONTROLS -**

#### Part 2-14: Particular requirements for electric actuators

#### **FOREWORD**

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IEC 60730-2-14 edition 2.1 contains the second edition (2017-08) [documents 72/1079/ FDIS and 72/1100/RVD] and its amendment 1 (2019-03) [documents 72/1168FDIS and 72/1175/RVD].

In this Redline version, a vertical line in the margin shows where the technical content is modified by amendment 1. Additions are in green text, deletions are in strikethrough red text. A separate Final version with all changes accepted is available in this publication.

International Standard IEC 60730-2-14 has been prepared by IEC technical committee 72: Automatic electrical controls.

This second edition constitutes a technical revision. This edition includes the following significant technical changes with respect to the previous edition:

- adapting it to the 5<sup>th</sup> Ed of IEC 60730-1,
- addition of checking electric actuators with action 1.AB or 2AB, and
- modification of tests under abnormal condition.

This part 2-14 is intended to be used in conjunction with IEC 60730-1. It was established on the basis of the fifth edition of that standard (2013) including its amendment 1 (2015). Consideration may be given to future editions of, or amendments to, IEC 60730-1.

This part 2-14 supplements or modifies the corresponding clauses in IEC 60730-1, so as to convert that publication into the IEC standard: Particular requirements for electric actuators.

Where this part 2-14 states "addition", "modification" or "replacement", the relevant requirement, test specification or explanatory matter in part 1 should be adapted accordingly.

Where no change is necessary part 2-14 indicates that the relevant clause or subclause applies.

In the development of a fully international standard it has been necessary to take into consideration the differing requirements resulting from practical experience in various parts of the world and to recognize the variation in national electrical systems and wiring rules.

The "in some countries" notes regarding differing national practice are contained in the following subclauses:

• Table 1,

- IEC 60730-2-14:2017
- •an **27**; **2.3**, **1**h.ai/catalog/standards/iec/cdc91251-6e8e-493c-b2e0-4bc5b10b1606/iec-60730-2-14-2017

In this publication:

- 1) The following print types are used:
  - requirements proper: in roman type;
  - test specifications: in italic type;
  - explanatory matter: in smaller roman type.
  - Defined terms: bold type.
- 2) Subclauses, notes or items which are additional to those in Part 1 are numbered starting from 101, additional annexes are lettered AA, BB, etc.

This document has been drafted in accordance with the ISO/IEC Directives, Part 2.

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The committee has decided that the contents of the base publication and its amendment will remain unchanged until the stability date indicated on the IEC web site under "http://webstore.iec.ch" in the data related to the specific publication. At this date, the publication will be

- reconfirmed,
- withdrawn,
- · replaced by a revised edition, or
- amended.

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#### **AUTOMATIC ELECTRICAL CONTROLS -**

#### Part 2-14: Particular requirements for electric actuators

#### 1 Scope and normative references

This clause of Part 1 is applicable except as follows:

#### 1.1 Replacement:

This part 2-14 applies to **electric actuators** for use in, on, or in association with equipment for household and similar use. The equipment may use electricity, gas, oil, solid fuel, solar thermal energy, etc., or a combination thereof.

NOTE Throughout this standard the word "equipment" means "appliance and equipment."

EXAMPLE 1 Electric actuators for appliances within the scope of IEC 60335.

This International Standard is applicable to **controls** for building automation within the scope of ISO 16484.

This part 2-14 also applies to automatic **electrical controls** for equipment that may be used by the public, such as equipment intended to be used in shops, offices, hospitals, farms and commercial and industrial applications.

EXAMPLE 2 Controls for commercial catering, heating and air-conditioning equipment.

This part 2-14 is also applicable to individual **electric actuators** utilized as part of a **control system** or **controls**, which are mechanically integral with **multifunctional controls** having non-electrical outputs.

EXAMPLE 3 Independently mounted water valves, **controls** in smart grid **systems** and **controls** for building automation systems within the scope of ISO 16484-2.

This part 2-14 does not apply to automatic **electric actuators** intended exclusively for industrial process applications unless explicitly mentioned in the relevant part 2 or the equipment standard.

This part 2-14 applies to **electric actuators** powered by primary or secondary batteries, requirements for which are contained within the standard, including Annex V.

**1.1.1** This part 2-14 applies to the inherent safety, to the **operating values**, **operating times** and **operating sequences** where such are associated with equipment safety and to the testing of **electric actuators** used in or in association with equipment.

NOTE Requirements for specific **operating values**, **operating times** and **operating sequences** may be given in the standards for appliances and equipment.

This standard is also applicable to the functional safety of low complexity safety related systems and controls.

This part 2-14 does not apply to **electric actuators** which are mechanically integrated with valves covered by a separate part 2, e.g. IEC 60730-2-8.

This part 2-14 does not apply to electric motors, requirements for which are contained in IEC 60034.

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**1.1.2** Requirements for manual switches not integral with an **electric actuator** are contained in IEC 61058-1.

#### 1.1.3 Replacement

This part 2-14 applies to a.c. or d.c. powered **electric actuators** with a rated voltage not exceeding 690 V a.c. or 600 V d.c.

#### 1.1.4 Replacement

This part 2-14 does not take into account the **response value** of an **automatic action** of an **electric actuator**, if such a **response value** is dependent upon the method of mounting the **electric actuator** in the equipment. Where a **response value** is of significant purpose for the protection of the **user**, or surroundings, the value defined in the appropriate household equipment or as determined by the manufacturer shall apply.

- **1.1.5** Void.
- **1.1.6** Void.

#### 1.1.7 Replacement:

This part 2-14 applies also to **electric actuators** incorporating **electronic devices**, requirements for which are contained in Annex H.

### 1.1.8 Replacement: https://standards.iteh.ai

This part 2-14 applies also to **electric actuators** using NTC or PTC **thermistors**, requirements for which are contained in Annex J.

#### **1.1.9** Replacement:

standards.iteh.ai/catalog/standards/iec/cdc91251-6e8e-493c-b2e0-4bc5b10b1606/iec-60730-2-14-201 This part 2-14 applies to the electrical and **functional safety** of **electric actuators** capable of

receiving and responding to communications signals, including signals for power billing rate and demand response.

The signals may be transmitted to or received from external units being part of the **electric actuator** (wired), or to and from external units, which are not part of the **electric actuator** (wireless) under test.

#### **1.1.10** Replacement:

This part 2-14 does not address the integrity of the output signal to the network devices, such as interoperability with other devices unless it has been evaluated as part of the control system.

#### 2 Terms and definitions

This clause of part 1 is applicable, except as follows:

#### 2.2 Definitions of types of control according to purpose

Additional definition:

#### 2.2.101

#### electric actuator

device in which a **prime mover** is mechanically linked to a valve, damper or similar device and which responds to **initiation** from a **control** or switch

Note 1 to entry: The **electric actuator** moves the valve, damper or similar device to defined positions and may also incorporate other functions, such as electric interlock switches and/or feedback.

#### 2.3 Definitions relating to the function of controls

Additional definitions:

#### 2.3.101

#### multi-position action

action denoting that the **electric actuator** operates in such a manner that only two or more defined positions can be reached

#### 2.3.102

#### modulating action

action denoting that the **electric actuator** operates in such a manner that every position between two defined limits can be reached

#### 2.3.103

#### travel time

time taken by an electric actuator to move from one defined position to another

#### 2.3.104

#### stroke

distance travelled by a linear actuator

#### 2.3.105

#### angular rotation

operating movement of a rotary actuator given in radians or degrees

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#### 2.3.106

#### maximum rated mechanical load

maximum mechanical resistance to the active movement of an actuator under normal operating conditions

Note 1 to entry: See also 6.4.102.1 and 6.4.102.2.

#### 3 General requirements

This clause of Part 1 is applicable.

#### 4 General notes on tests

This clause of Part 1 is applicable.

#### 5 Rating

This clause of Part 1 is applicable.

#### 6 Classification

This clause of Part 1 is applicable, except as follows:

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- 6.1 According to nature of supply
- 6.1.1 Control for a.c. only

Replacement:

Electric actuators which are designed for a.c. supply only shall not be used on d.c. supply.

#### 6.3 According to their purpose

Additional subclauses:

- 6.3.101 electric actuator;
- **6.3.102 electric actuator** as a component of a multi-purpose control or **system**.

NOTE See also H.6.18 according to classes of control functions.

#### 6.4 According to features of automatic action

Additional subclauses:

- 6.4.101 Type of action
- 6.4.101.1 Multi-position action Con Standards
- 6.4.101.2 Modulating action / standards.iteh.ai)
- 6.4.102 Type of movement

#### 6.4.102.1 Rotary movement

NOTE Maximum rated mechanical load for rotary movement actuators can be declared in terms of rated torque (for the complete angular rotation) or, alternatively, in terms of maximum torque, running torque and percentage of the angular rotation in which the maximum torque occurs. The value of the percentage of the angular rotation in which the maximum torque occurs is independent from any specific position within the travel of the actuator; maximum torque can be reached at any position within the actuator travel (e.g. at start position, at end position, at each end, in the middle, etc.).

#### 6.4.102.2 Linear movement

NOTE **Maximum rated mechanical load** for linear movement actuators can be declared in terms of rated force (for the complete **stroke**) or, alternatively, in terms of maximum force, running force and percentage of the stroke in which the maximum force occurs. The value of the percentage of the stroke in which the maximum force occurs is independent from any specific position within the travel of the actuator; maximum force can be reached at any position within the actuator travel (e.g. at start position, at end position, at each end, in the middle, etc.).

- 6.4.3 Additional subclauses:
- **6.4.3.101** –an action in which the **electric actuator** assumes a predefined position upon loss of the electrical supply and/or upon loss of the **control** signal (type 1.AA or type 2.AA);
- **6.4.3.102** an action in which the **electric actuator** operates normally between 1,1  $V_{\rm R}$  and 0,85  $V_{\rm R}$  inclusive and in which it either operates normally or assumes a predefined position between 0,85  $V_{\rm R}$  and a declared lower percentage of rated voltage (type 1.AB or type 2.AB).

#### 6.11 According to number of automatic cycles (A) of each automatic action

Modification:

Subclauses 6.11.8 to 6.11.12 inclusive are not applicable.

#### 7 Information

This clause of part 1 is applicable except as follows:

Table 1 – (7.2 of edition 3) – Required information and methods of providing information

Modi		Clause or subclause	Method
woul	fications:		
7	The type of load controlled by each external circuit	6.2, 14	D
22	Temperature limits of the actuator, if $T_{\rm min}$ lower than 0 °C or $T_{\rm max}$ other than 60 °C	6.7, 14,5, 14.7, 17.3	D
23	Temperature limits of mounting surfaces $(T_s)$	6.12.2, 14.1, 17,3	D
27	Number of automatic cycles (A) for each <b>automatic</b> action <sup>102</sup> bb	6.11	X
28	Not applicable		
34	Detail of any limitation of operating time <sup>101, 103</sup> aa	14, 17	Ccc
37	Not applicable		
38	Not applicable		
43	Not applicable		
44	Not applicable		
47	Not applicable		
Addi	tional requirements:		
101	Impedance protected motor	14.4.101	D
102	Thermally protected motor	14.4.102	D
103	Type of movement (https://standard	2.3.104, 2.3.105, 6.4.102	D
104	Type of action  Document Pr	2.3.101, 2.3.102, 6.4.101	D
105	Maximum rated mechanical load maximum rated mechanical load <sup>dd</sup> IEC 60730-2-14:20	2.3.106, 6.4.102.1, 6.4.102.2, 14.4, 15.5.102, 17.4.101	D
106	Travel time i/catalog/standards/iec/cdc91251-6e8e-4	2.3.103, 15.5.101, 10h 15.5.102	1606/iec- <b>D</b> 0730-2-14-20
107	Stroke	2.3.104	D
108	Angular rotation	2.3.105	D
109	Response time and method of measurement (for types 1.AA or 2.AA)	6.4.3.101 15.5.102	D
110	Lower percentage of rated voltage (for types 1.AB or 2.AB)	6.4.3.102	D

#### Additional footnotes:

101aa This may be given as a maximum percentage of ON time of the power supply to avoid over-heating of the windings in a declared period of time.

102bb Electric actuators are subjected to a minimum of 6 000 cycles.

103cc For integrated and incorporated electric actuators, the method is D.

For test purposes, representative physical load may be defined by agreement between the manufacturer and testing authority (e.g. dedicated test device).

#### **7.3.1** *Addition:*

NOTE Actuators of class II construction provided with a cord for connection to the **fixed wiring** which does not have a plug fitted may carry the symbol for class II construction.

#### 8 Protection against electric shock

This clause of part 1 is applicable.