IEC 61757-1-2

Edition 1.0 2023-08

INTERNATIONAL STANDARD

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Fibre optic sensors – Part 1-2: Strain measurement – Distributed sensing based on Brillouin scattering

Capteurs fibroniques – Partie 1-2: Mesure de déformation – Détection répartie basée sur la diffusion de Brillouin

IEC 61757-1-2:2023-08(en-fr)

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

COMMISSION ELECTROTECHNIQUE INTERNATIONALE

ICS 33.180.99

ISBN 978-2-8322-7396-8

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

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Part 1-2: Strain measurement – Distributed sensing based on Brillouin scattering

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The text of this International Standard is based on the following documents:

Draft	Report on voting
86C/1857/CDV	86C/1872/RVC

Full information on the voting for its approval can be found in the report on voting indicated in the above table.

The language used for the development of this International Standard is English.

This document was drafted in accordance with ISO/IEC Directives, Part 2, and developed in accordance with ISO/IEC Directives, Part 1 and ISO/IEC Directives, IEC Supplement, available at www.iec.ch/members_experts/refdocs. The main document types developed by IEC are described in greater detail at www.iec.ch/publications.

A list of all parts in the IEC 61757 series, published under the general title *Fibre optic sensors*, can be found on the IEC website.

The committee has decided that the contents of this document will remain unchanged until the stability date indicated on the IEC website under webstore.iec.ch in the data related to the specific document. At this date, the document will be

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INTRODUCTION

This document is part of the IEC 61757 series, which is dedicated to fibre optic sensors. Generic specifications for fibre optic sensors are defined in IEC 61757.

The individual parts of the IEC 61757 series are numbered as IEC 61757-M-T, where M denotes the measure and T the technology of the fibre optic sensor. The IEC 61757-1-T series is concerned with strain measurements.

FIBRE OPTIC SENSORS –

Part 1-2: Strain measurement – Distributed sensing based on Brillouin scattering

1 Scope

This part of IEC 61757 defines detailed specifications for distributed strain measurements with a fibre optic sensor, also known as "fibre optic distributed strain sensing". It is applicable to distributed strain sensing systems (DSS) based on spontaneous or stimulated Brillouin scattering in the optical fibre sensor (strain sensitive element), that is, to sensors capable of measuring absolute strain.

This document specifies the most important DSS performance parameters and defines the procedures for their determination.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

IEC 61757:2018, *Fibre optic sensors – Generic specification*

IEC 61757-2-2:2016, *Fibre optic sensors – Part 2-2: Temperature measurement – Distributed sensing*

IEC 61757-3-2:2022, *Fibre optic sensors – Part 3-2: Acoustic sensing and vibration measurement – Distributed sensing*

ISO/IEC Guide 98-3, *Uncertainty of measurement – Part 3: Guide to the expression of uncertainty in measurement (GUM:1995)*

3 Terms, definitions, abbreviated terms and symbols

3.1 Terms and definitions

For the purposes of this document, the terms and definitions given in IEC 61757, IEC 61757-2-2, IEC 61757-3-2, and the following apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- IEC Electropedia: available at https://www.electropedia.org/
- ISO Online browsing platform: available at https://www.iso.org/obp

NOTE For the following definitions, the relevant test procedures and parameters are defined in Clause 4.

3.1.1
distributed fibre optic strain sensing system
DSS
measurement set-up consisting of a distributed fibre optic sensor connected to an interrogation unit, including processor, data archive, and user interface, which provides a spatially resolved strain measurement

[SOURCE: IEC 61757-3-2:2022, 3.1.2, modified − adapted to distributed strain measurement]

3.1.2
distance measurement range
maximum distance from the DSS interrogation unit output connector along the fibre optic sensor within which the DSS measures strain with specified measurement performance under defined conditions

Note 1 to entry: Defined conditions are spatial resolution (3.1.8), spatial strain uncertainty (3.1.9) and measurement time (3.1.5).

Note 2 to entry: This supporting parameter is closely related to the total accumulated optical loss (one way) tolerated by the interrogation unit without affecting specified measurement performance. In test cases used to prove or verify the reported specifications, the total fibre length shall be equal to or greater than the specified distance measurement range, for the tolerated total accumulated optical loss.

Note 3 to entry: The distance measurement range is usually expressed in km.

Note 4 to entry: For fibre loop configurations, the distance measurement range is given by half the fibre length between the output and input connector of the interrogation unit.

[SOURCE: IEC 61757-2-2:2016, 3.2, and ISO/IEC Guide 99:2007, 4.7, modified − adapted to distributed strain measurement]

3.1.3
strained spot
ΔL
length of fibre optic sensor that experiences a small elongation (δL), which causes strain that is significantly bigger than the strain repeatability of the interrogation unit and which is confirmed by a reference strain measurement

Note 1 to entry: The applied strain ε is equal to ($\delta L/\Delta L$).

Note 2 to entry: It is useful to define strain in με, where 1 με corresponds to a δL of 1 μm over a ΔL of 1 m.

[SOURCE: IEC 61757-2-2:2016, 3.6, modified − adapted to distributed strain measurement]

3.1.4
location
L
optical distance from the DSS interrogation unit output connector to a desired strain sample point along the fibre optic sensor

Note 1 to entry: The farthest location from the DSS interrogation unit output connector for the particular test is quantified as $L_{F,long}$ km and is often chosen to be the same as the distance measurement range for purposes of comparing the measurement results with quoted specifications.

Note 2 to entry: The location is usually expressed in km.

[SOURCE: IEC 61757-2-2:2016, 3.7, modified − adapted to distributed strain measurement]

3.1.5
measurement time
time between independent strain measurements when making successive measurements on a single fibre optic sensor

Note 1 to entry: Equivalently, it is the time interval between successive strain trace timestamps under these conditions.

Note 2 to entry: This parameter includes acquisition time and processing time for the measured data. This parameter is typically selectable by the user in some limited fashion. Multiple independent strain measurements may be averaged together to provide an overall measurement time.

[SOURCE: IEC 61757-2-2:2016, 3.8, modified − adapted to distributed strain measurement]

3.1.6
point defect
local deviation of a fibre optic sensor from its nominal optical and mechanical properties occurring at a single location, or over a length substantially less than the DSS spatial resolution

Note 1 to entry: The definition of a point defect encompasses a wide range of situations, which can produce similar effects on the strain trace. Examples include

– a point loss, like a bad fibre splice,
– a back reflection (or return loss), as can be introduced by a fibre connector,
– a localized region of high loss, such as a bend or kink in the fibre, and
– a physical discontinuity in the fibre, like a splice between two fibres of different core diameters.

[SOURCE: IEC 61757-2-2:2016, 3.9, modified − adapted to distributed strain measurement]

3.1.7
sample spacing
distance between two consecutive strain sample points in a single strain trace

Note 1 to entry: Sample spacing can be a user-selectable parameter in the interrogation unit.

Note 2 to entry: The sample spacing is usually expressed in m.

Note 3 to entry: See Figure 1.

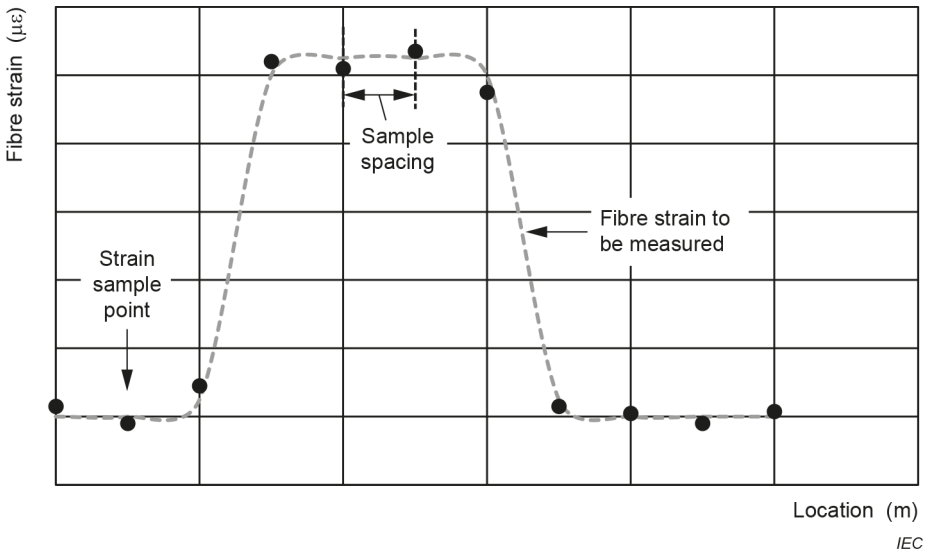


Figure 1 – Optical fibre strain profile and related strain sample points

[SOURCE: IEC 61757-2-2:2016, 3.11, modified − adapted to distributed strain measurement]

3.1.8
spatial resolution
smallest length of strain-affected fibre optic sensor for which a DSS can measure and confirm the reference strain of a defined strained spot within the specified strain measurement error of the DSS

Note 1 to entry: The spatial resolution is usually expressed in m.

[SOURCE: IEC 61757-2-2:2016, 3.12, modified − adapted to distributed strain measurement]

3.1.9
spatial strain uncertainty
uncertainty of the location of strain data in a single strain trace, expressed by twice the standard deviation of a specified number of adjacent strain sample points, with the fibre optic sensor held at constant strain and temperature

Note 1 to entry: Due to a potential cross-sensitivity of DSS to temperature, it can be necessary to stabilize the temperature of the fibre optic sensor.

Note 2 to entry: The spatial strain uncertainty is usually expressed in units of με and noted as a tolerance (e.g. ±xx με), where 1 με corresponds to a δL of 1 µm over a ΔL of 1 m.

[SOURCE: IEC 61757-2-2:2016, 3.13, modified − adapted to distributed strain measurement]

3.1.10
strain dead zone
limited zone of a strain trace, where the strain sample points deviate from the undisturbed parts of the trace by a specified limit due to a point defect

Note 1 to entry: The strain dead zone is usually expressed in m.

[SOURCE: IEC 61757-1-2:2023, 3.14, modified − adapted to distributed strain measurement]

3.1.11
strain measurement error
maximum difference between a centred and uniformly weighted moving average of the measured strain and a reference strain for all data points of the fibre optic sensor over the full operating temperature range and all acquisition times

Note 1 to entry: Single value (worst case) is expressed like a tolerance in units of με (e.g. ±xx με).

Note 2 to entry: The number of elements used for the moving average is defined later in the document. In practical applications, other methods of smoothing might be applicable.

[SOURCE: IEC 61757-2-2:2016, 3.15, modified − adapted to distributed strain measurement]

3.1.12
strain repeatability
precision of strain data based on repeated strain traces at a given location expressed by twice the standard deviation of corresponding strain sample points in each strain trace, with the fibre optic sensor held at constant strain and temperature

Note 1 to entry: The strain repeatability is expressed like a tolerance in units of με (e.g. ±xx με).

[SOURCE: IEC 61757-2-2:2016, 3.16, modified − adapted to distributed strain measurement]

3.1.13
strain sample point
measured strain value associated with a single point at a known location along a fibre optic sensor

Note 1 to entry: Due to signal averaging effects, the measured value represents the strain along a very small section of the fibre optic sensor that includes the strain sample point.

Note 2 to entry: See Figure 1.

[SOURCE: IEC 61757-2-2:2016, 3.17, modified − adapted to distributed strain measurement]

3.1.14
strain trace
set of strain sample points distributed along a fibre optic sensor and spaced by the sample spacing

Note 1 to entry: All sample points are associated with a common time of measurement, often called "trace timestamp". The measured values represent the strain during a time period that includes the timestamp.

Note 2 to entry: All sample points in a strain trace are measured values produced by the DSS, and not interpolated or smoothed values produced by subsequent processing outside the interrogation unit.

[SOURCE: IEC 61757-2-2:2016, 3.18, modified − adapted to distributed strain measurement]

3.1.15
total fibre length
$L_{\mathrm{F,tot}}$
distance from the DSS interrogation unit output connector to the final end of the fibre optic sensor

Note 1 to entry: The final end of the fibre optic sensor can be either a purposely cut or terminated end of the fibre, physically located far from the interrogation unit (in a single-ended configuration), or the end of a loop consisting of a connector that is connected to the same interrogation unit (in a loop configuration).

Note 2 to entry: This parameter is either equal to or greater than the distance measurement range and usually expressed in km.

[SOURCE: IEC 61757-2-2:2016, 3.19, modified − adapted to distributed strain measurement]

3.1.16
warm-up time
duration between the instant after which the power supply of the DSS interrogation unit is energized and the instant when the interrogation unit may be used as specified by the manufacturer

Note 1 to entry: Warm-up time is usually expressed in seconds or minutes.

Note 2 to entry: The warm-up time helps to upload software and to stabilize operating temperatures of optical and electronic components.

[SOURCE: IEC 60050-311:2001, 311-03-18, modified − adapted to distributed strain measurement]

3.2 Abbreviated terms

DSS	distributed fibre optic strain sensing system
FAT	factory acceptance test
LVDT	linear variable differential transformer
VOA	variable optical attenuator

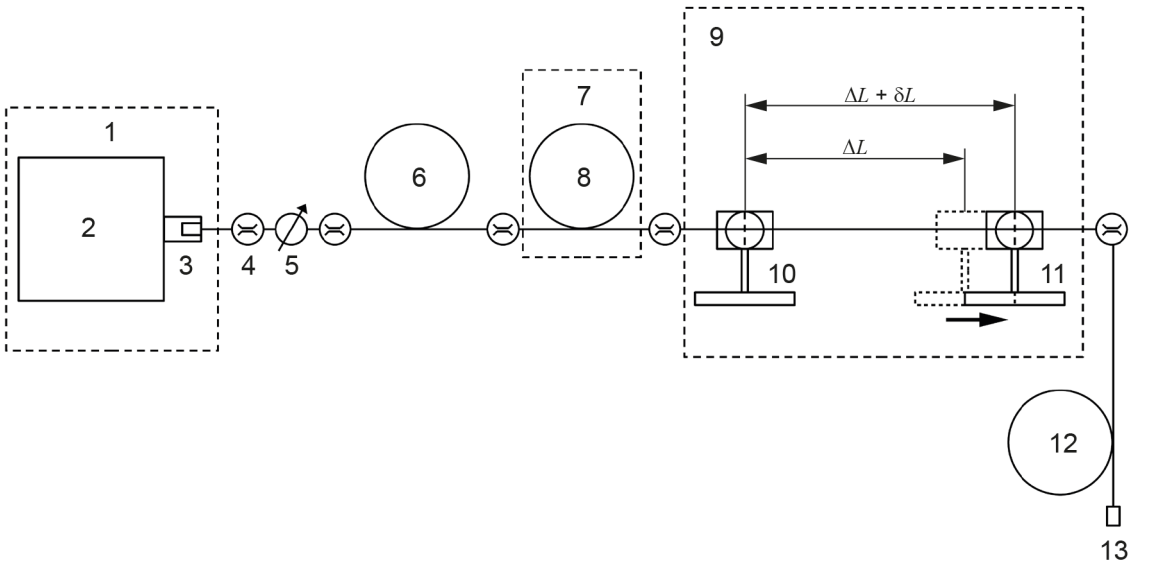
3.3 Symbols

A	cross-sectional area
E	Young's modulus
F	force
L	optical distance from the output connector to a desired strain sample point
$L_{F,opt}$, $L_{F,short}$	fibre lengths
$L_{F,loop}$, $L_{F,long}$	fibre lengths
$L_{F,tot}$	total fibre length
ΔL	length of fibre optic sensor to be strained (strained spot)
δL	small change in length of ΔL
N, n	number of traces, number of data points
S	standard deviation
T	temperature
T_{low}, T_{op}, T_{high}	minimum, typical, and maximum DSS operating temperature
T_{STC}	ambient operating temperature of the strain test section
ε	strain
ε_{rep}	strain repeatability
ε_{unc}	spatial strain uncertainty
σ	stress

4 General test setups for measurement of performance parameters

4.1 General and test setup requirements

General test setups for single-ended and loop configurations are schematically shown in Figure 2 and Figure 3, respectively. The aim of these setups is to provide a common base for determining the measurement specifications while at the same time minimizing complexity, cost, reconfiguration requirements, and test execution time. Temperature stabilisation is used to avoid crosstalk from temperature.



Key

1 temperature-controlled encasement (e.g. temperature chamber)

2 DSS interrogation unit

3 DSS interrogation unit output connector

4 fibre fusion splice

5 optional variable optical attenuator

6 optional long fibre length $L_{F,opt}$ (normal spool)

7 temperature-controlled environment for stable ambient conditions

8 long fibre length $L_{F,long}$ (loose and strain free wound)

9 strain test section with temperature-controlled environment for stable ambient conditions

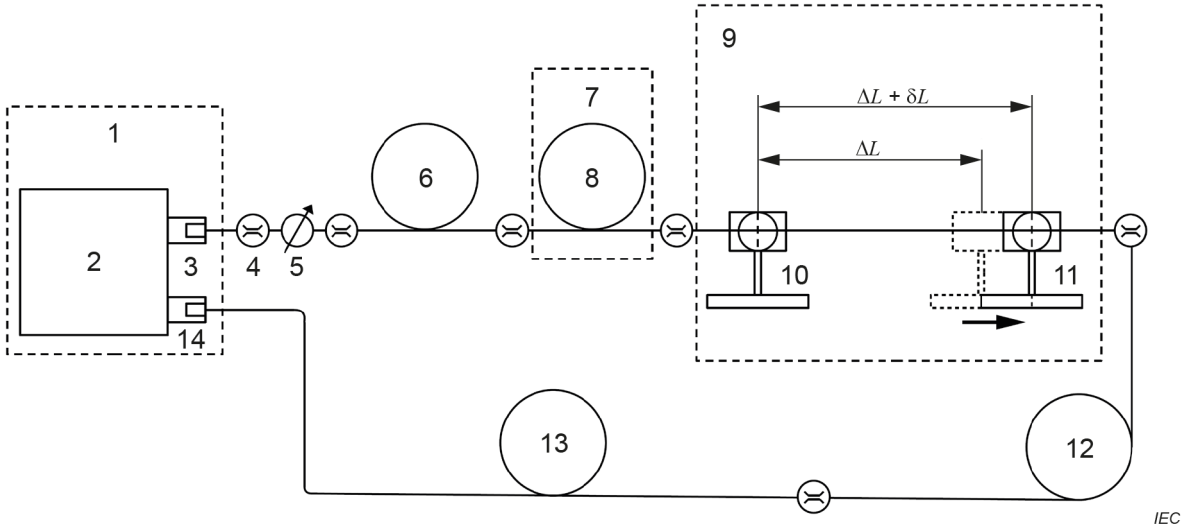
10 fixed fibre clamping unit

11 movable fibre clamping unit

12 short fibre length $L_{F,short}$ (loose wound), longer than 5 times the spatial resolution

13 fibre termination

Figure 2 – General test setup for single-ended configuration



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8 long fibre length $L_{F,long}$ (loose and strain free wound)

9 strain test section with temperature-controlled environment for stable ambient conditions

10 fixed fibre clamping unit

11 movable fibre clamping unit

12 long fibre length $L_{F,short}$ (loose wound), longer than 5 times the spatial resolution

13 long fibre length $L_{F,loop}$ (normal spool), with $L_{F,loop} > (L_{F,opt} + L_{F,long} + \Delta L + L_{F,short})$

14 DSS interrogation unit input connector

Figure 3 – General test setup for loop configuration

The temperature-controlled encasement containing the DSS interrogation unit shall provide a steady temperature, for an extended period of time, within the temperature operating range ($T_{low} \leq T_{op} \leq T_{high}$) of the device under test. It is recommended to use commercial off-the-shelf temperature chambers for determining the performance parameters. Minimum requirements for such a device are:

– minimum and maximum temperature shall exceed the minimal and maximal operating temperature of the interrogation unit under test;

– temperature variation in time (steady state): less than (±0,5 °C);

– temperature homogeneity in volume: less than (±1,5 °C).

For the optical power adjustment, a calibrated optical attenuator or an optical attenuator that can be self-calibrated shall be used. Recommendations for a variable optical attenuator are:

– calibrated for the wavelength of operation (or self-calibrated with a power meter);

– variable attenuation range from 2 dB to 6 dB;

– resolution of attenuation setting as needed, assumed to be accurate within 0,1 dB.