

SLOVENSKI STANDARD SIST EN 15714-2:2011

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Industrijski ventili - Pogoni - 2. del: Električni pogoni za industrijske ventile - Osnovne zahteve

Industrial valves - Actuators - Part 2: Electric actuators for industrial valves - Basic requirements

Industriearmaturen - Antriebe - Teil 2: Elektrische Antriebe für Industriearmaturen - Grundanforderungen iTeh STANDARD PREVIEW

Robinetterie industrielle - Actionneurs - Partie 2 : Actionneurs électriques pour robinetterie industrielle - SIST EN 15714-2:2011

Prescriptions de baseps://standards.iteh.ai/catalog/standards/sist/1c0fc13c-112b-4544-846d-ebabb1739b87/sist-en-15714-2-2011

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This European Standard was approved by CEN on 12 September 2009.

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EUROPEAN COMMITTEE FOR STANDARDIZATION COMITÉ EUROPÉEN DE NORMALISATION EUROPÄISCHES KOMITEE FÜR NORMUNG

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Foreword

This document (EN 15714-2:2009) has been prepared by Technical Committee CEN/TC 69 "Industrial valves", the secretariat of which is held by AFNOR.

This European Standard shall be given the status of a national standard, either by publication of an identical text or by endorsement, at the latest by April 2010, and conflicting national standards shall be withdrawn at the latest by April 2010.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN [and/or CENELEC] shall not be held responsible for identifying any or all such patent rights.

According to the CEN/CENELEC Internal Regulations, the national standards organizations of the following countries are bound to implement this European Standard: Austria, Belgium, Bulgaria, Cyprus, Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Norway, Poland, Portugal, Romania, Slovakia, Slovenia, Spain, Sweden, Switzerland and United Kingdom.

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1 Scope

This document provides basic requirements for electric valve actuators, used for on-off and control valves. It includes guidelines for classification, design, enclosure and corrosion protection, and methods for conformity assessment.

Combinations of electric multi-turn actuators and gearboxes supplied by the actuator manufacturer are within the scope of this document. In all other cases this European Standard applies to the electric actuator only.

It does not cover: solenoid actuators, electro-hydraulic actuators and electric actuators which are integral in the design of valves.

Other requirements or conditions of use different from those indicated in this document should be agreed between the purchaser and the manufacturer/supplier, prior to order.

The terms and definitions applicable to this European Standard are given in EN 15714-1.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

EN 12570, Industrial valves Method for sizing the operating element

EN 60529, Degrees of protection provided by enclosures (IP Code) (IEC 60529:1989)

EN ISO 5210:1996, Industrial valves — Multi-turn Valve actuator attachments (ISO 5210:1991) https://standards.iteh.ai/catalog/standards/sist/1c0fc13c-112b-4544-846d-

EN ISO 5211, Industrial valves — Part-turn valve actuator attachments (ISO 5211:2001)

3 Classification/Designation

3.1 General

Electric valve actuators are classified per type, duty and action as detailed below.

3.2 Type: Part-turn, multi-turn or linear

- **3.2.1** Part-turn: An actuator which transmits torque to the valve for less than one revolution. It does not have to be capable of withstanding thrust. A combination of a multi-turn actuator plus a part-turn gearbox can be considered, for the sake of this European Standard, a part-turn actuator.
- **3.2.2** Multi-turn actuator: An actuator which transmits torque to the valve/gearbox for at least one revolution. It may be capable of withstanding thrust. A combination of a multi-turn actuator plus a multi-turn gearbox can be considered, for the sake of this European Standard, a multi-turn actuator.
- **3.2.3** Linear actuator: An actuator which transmits thrust to the valve for a defined linear stroke. A combination of a multi-turn actuator plus a linear drive can be considered, for the sake of this European Standard, a linear actuator.

3.3 Actuator duty classification

3.3.1 General

Basic design requirements for actuator duty classification are given in 4.1 and 4.7.2.

3.3.2 Class A: On-off

The actuator is required to drive the valve through its entire travel from the fully open position to the fully closed position or vice-versa.

3.3.3 Class B: Inching/positioning

The actuator is required to occasionally drive the valve to any position (fully open, intermediate and fully closed).

3.3.4 Class C: Modulating

The actuator is required to frequently drive the valve to any position between fully open and fully closed.

3.3.5 Class D: Continuous modulating

The actuator is required to continuously drive the valve to any position between fully open and fully closed.

3.4 Action on loss of external electric power (standards.iteh.ai)

3.4.1 Standard action

On loss of external power, the actuator remains in the position achieved before loss of power.

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3.4.2 Fail safe action

On loss of external power, the actuator is able to operate the valve to a pre-defined safe position.

4 Design requirements

4.1 Endurance

4.1.1 General

The actuator shall be designed to meet the life endurance criteria as defined in Annex A.

The endurance of modulating and continuous modulating actuators shall be based on consecutive starts spread over an intermediate stroking span of maximum 30 % of full travel.

4.1.2 Part turn actuators

Table 1 — Part-turn actuator endurance test requirements (see Annex A)

Rated torque ranges ^a Nm	Class A and B On-Off Inching (number of cycles) ^b	Class C Modulating (number of starts) ^c	Class D Continuous modulating (number of starts ^c
Up to 125	10 000	1 800 000	10 000 000
126 — 1 000	10 000	1 200 000	10 000 000
1 001 — 4 000	5 000	500 000	5 000 000
4 001 — 32 000	2 500	250 000	T B A. d
Above 32 000	1 000	T.B.A. d	T.B.A. d

a Based on EN ISO 5211.

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4.1.3 Multi-turn actuators

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Table 2 — Multi-turn actuator endurance test requirements (see Annex A)

Rated torque ranges ^a	Maximum allowable thrust ^a	Class A and B On-Off Inching (number of cycles) ^b	Class C Modulating (number of starts) ^c	Class D Continuous modulating (number of starts) ^c
Nm	kN	• ,		ŕ
Up to 100	≤ to 40	10 000	1 800 000	10 000 000
101 — 700	≤ 150	10 000	1 200 000	10 000 000
701 — 2 500	≤ 325	5 000	500 000	5 000 000
2 501 — 10 000	≤ 1 100	2 500	250 000	T.B.A. ^d
Above 10 000	> 1 100	1 000	T.B.A. d	T.B.A. ^d

a Based on EN ISO 5210.

b One cycle consists of nominal 90° angular travel in both directions (i.e. 90° to open + 90° to close), based on an average load of at least 30 % of the rated torque with the ability to transmit 100 % of the rated torque for at least 5 % at each end of travel. For angular travel other than 90°, the endurance shall be agreed between the purchaser and the manufacturer/supplier.

^c One start consists of a movement of at least 1 % in either direction, with a load of at least 30 % of the rated torque.

d To be agreed between manufacturer / supplier and purchaser.

b One cycle consists of 25 turns in both directions (i.e. 25 turns to open + 25 turns to close), based on an average load of at least 30 % of the rated torque with the ability to transmit 100 % of the rated torque for at least 10 % of the travel.

^c One start consists of a movement of at least 1 % of travel in either direction, with a load of at least 30 % of the rated torque.

d To be agreed between manufacturer/supplier and purchaser.

4.1.4 Linear actuators

Table 3 — Linear actuator endurance test requirements (see Annex A)

Rated thrust ranges ^a kN	Class A and B On-Off Inching (number of cycles) ^b	Class C Modulating (number of starts) ^c	Class D Continuous modulating (number of starts) ^c
Up to 20	10 000	1 800 000	10 000 000
21 — 70	10 000	1 200 000	10 000 000
71 — 150	5 000	500 000	5 000 000
151 — 325	2 500	250 000	T.B.A. ^d
Above 325	1 000	T.B.A. ^d	T.B.A. ^d

a Based on EN ISO 5210.

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4.2 Environmental conditions

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4.2.1 General

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The following environmental conditions shall apply, unless otherwise agreed between the manufacturer/supplier and purchaser:

4.2.2 Ambient temperature and humidity

The actuator shall be designed for operation at an ambient temperature range between -20 °C and +60 °C with relative humidity up to 80 %.

4.2.3 Altitude

The actuator shall be designed for operation at an altitude up to 1 000 m above sea level.

4.2.4 Enclosure protection

Electric actuators shall have at least enclosure protection type IP 65 to EN 60529.

4.2.5 Hazardous areas

Electric actuators intended for use in hazardous areas shall be designed and certified in accordance with the requirements of the applicable regulations.

^b One cycle consists in a stroke of 40 mm, or in a minimum stroke (H) given in Table 5, in both directions (i.e. 40 mm to open + 40 mm to close), based on an average load of at least 30 % of the rated thrust with the ability to transmit 100 % of the rated thrust for at least 10 % of the travel.

c One start consists of a movement of at least 1 % of the stroke in either direction, with a load of at least 30 % of the rated thrust.

d To be agreed between manufacturer/supplier and purchaser. PRFVIRW

4.2.6 External corrosion protection

Electric actuators shall be protected against external corrosion by proper material selection and/or surface treatment. The actuator manufacturer's technical documentation shall specify the corrosion protection category according to Table 4.

Table 4 — Environmental corrosion categories

Compaign actor on	Typical environments			
Corrosion category	Exterior	Interior		
C2 (low)	Atmospheres with low level of pollution. Mostly rural areas.	Unheated buildings where condensation may occur, e.g. depots, sport halls.		
C3 (medium)	Urban and industrial atmospheres, moderate sulphur dioxide pollution. Coastal areas with low salinity.	Production rooms with high humidity and some air pollution, e.g. food-processing plants, laundries, breweries.		
C4 (high)	Industrial areas and coastal areas with moderate salinity.	Chemical plants, swimming pools, coastal shipyards.		
C5-I (very high — industrial)	Industrial areas with high humidity and aggressive atmosphere.	Buildings or areas with almost permanent condensation and with high pollution.		
C5-M (very high — marine)	Coastal and offshore areas with high salinity and ards.iteh.ai)	Buildings or areas with almost permanent condensation and with high pollution.		
Immersed in water ^a SIST EN 15714-2:2011				
Im 1 (Immersed in fresh://standar water)	1 11 1 2 0 1 0 2 1 1 1 2 0 1 0 2 1 1			
m 2 (Immersed in sea or brackish water) Harbour areas and offshore structures.				
NOTE This table is taken, for reference purposes only, from EN ISO 12944-2. The actuator corrosion protection may also be achieved by systems/methods which deviate from those specified in EN ISO 12944-5.				
^a Electric actuators covered by this European Standard are not designed for permanent immersion unless otherwise specified.				

This table may be used to define the corrosion category in order to help the actuator manufacturers to define the surface treatment for corrosion protection. Test assessment and test procedures are the responsibility of the manufacturer.

4.2.7 Vibrations, shock and seismic conditions

Actuators complying with this European Standard are designed without any specific reference to vibrations, shock and/or seismic conditions. If some of these conditions apply they shall be agreed upon between the manufacturer/supplier and the purchaser.

4.3 Actuator attachment

4.3.1 Part-turn actuators

The attachment for part-turn actuators shall comply with EN ISO 5211.