



**INTERNATIONAL STANDARD ISO 9409-1:1996
TECHNICAL CORRIGENDUM 1**

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INTERNATIONAL ORGANIZATION FOR STANDARDIZATION • МЕЖДУНАРОДНАЯ ОРГАНИЗАЦИЯ ПО СТАНДАРТИЗАЦИИ • ORGANISATION INTERNATIONALE DE NORMALISATION

Manipulating industrial robots — Mechanical interfaces —

**Part 1:
Plates (form A)**

TECHNICAL CORRIGENDUM 1

Robots manipulateurs industriels — Interfaces mécaniques —

Partie 1: Interfaces à plateau (forme A)

RECTIFICATIF TECHNIQUE 1

**iTeh STANDARD PREVIEW
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Technical Corrigendum 1 to International Standard ISO 9409-1:1996 was prepared by Technical Committee ISO/TC 184, *Industrial automation systems and integration*, Subcommittee SC 2, *Robots for manufacturing environment*.

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Replace Figure 1 by the following.

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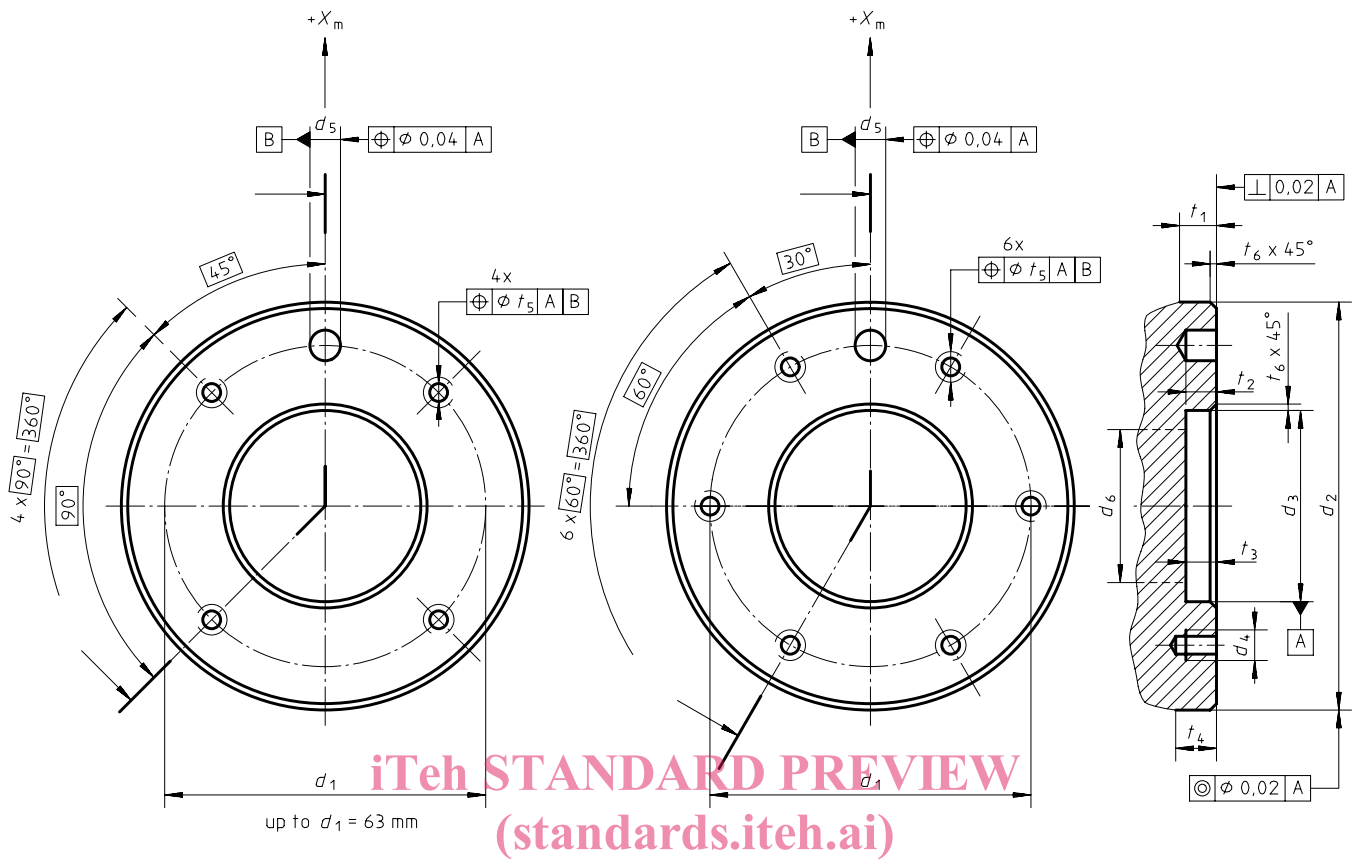


Figure 1 — Basic layout of the circular mechanical interface

ISO 9409-1:1996/Cor 1:1998

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