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Železniške naprave - Udobnost vožnje potnikov - Meritve in vrednotenje

Railway applications - Ride comfort for passengers - Measurement and evaluation

Bahnanwendungen - Fahrkomfort für Fahrgäste - Messung und Auswertung

iTeh STANDARD PREVIEW

Applications ferroviaires - Confort de marche des voyageurs - Mesurage et évalutation (standards.iten.ai)

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Vibration and shock with respect to human beings

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Railway applications - Ride comfort for passengers - Measurement and evaluation

Applications ferroviaires - Confort de marche des voyageurs - Mesurage et évalutation

Bahnanwendungen - Fahrkomfort für Fahrgäste - Messung und Auswertung

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Foreword

This document (EN 12299:2009) has been prepared by Technical Committee CEN/TC 256 "Railway applications", the secretariat of which is held by DIN.

This European Standard shall be given the status of a national standard, either by publication of an identical text or by endorsement, at the latest by October 2009, and conflicting national standards shall be withdrawn at the latest by October 2009.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN [and/or CENELEC] shall not be held responsible for identifying any or all such patent rights.

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1 Scope

This standard specifies methods for quantifying the effects of vehicle body motions on ride comfort for passengers and vehicle assessment with respect to ride comfort. The effect considered is:

discomfort, associated with relatively low levels of acceleration and roll velocity.

Other effects, not included in the standard, are associated with higher acceleration levels:

health risk effect: physical damage and psychological deterioration.

The standard applies to passengers travelling in railway vehicles on railway lines, including main, secondary and suburban lines. This standard could be used as a guide for other railway vehicles, for example locomotives, metros, trams, etc.

The standard applies to passengers in good health.

This standard applies to measurements of motions. It also applies to simulated motions.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition of the referenced document (including any amendments) applies.

(standards.iteh.ai)
EN 14363, Railway applications — Testing for the acceptance of running characteristics of railway vehicles — Testing of running behaviour and stationary tests

EN ISO 5353, Earth-moving machinery, and tractors and machinery for agriculture and forestry - Seat index point (ISO 5353:1995)

EN ISO 8041, Human response to vibration - Measuring instrumentation (ISO 8041:2005)

ISO 2631-1, Mechanical vibration and shock — Evaluation of human exposure to whole-body vibration — Part 1: General requirements

ISO 5348, Mechanical vibration and shock — Mechanical mounting of accelerometers

3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

3.1

passengers

people travelling in a railway vehicle, without specific activities related to the transport

3.2

ride comfort

complex sensation produced during the application of oscillations and/or inertia forces, via whole-body transmission caused by the railway vehicle body motions

3.3

interfaces

contact parts between the vehicle body or seat and the passenger with the function of sustaining and guiding the passenger and of transmitting the weight of the same to the vehicle body itself, e.g. floor-feet

3.4

Mean Comfort

perceived comfort level, continuously adjusted, as evaluated through measurement on a long-time basis (at least some minutes)

3.5

Continuous Comfort

level of accelerations, ISO frequency weighted continuously evaluated as a set of rms (root mean square) values in vertical, lateral and longitudinal direction over a short time period (typical 5 s)

3.6

Comfort on Curve Transition

discomfort, due to a perceived curve transition

3.7

Comfort on Discrete Event

discomfort, due to a perceived transient oscillation

3.8

whole-body transmission

motion transmitted to the whole body through the interfaces between vehicle body and passenger

3.9

indirect measurement

measurement of motion environment by different motion quantities, such as acceleration or roll velocity

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3.10

direct measurement

(standards.iteh.ai)

measurement of actual passenger reactions, for example by asking passengers to fill in a questionnaire

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vehicle assessment with respect to ride comfort 1279 / 14 1 1220 2020

identifying the vehicle's contribution to the ride comfort by relating the measured ride comfort to the condition of the track (geometry, irregularities, turnout, bridges, etc.) and operation condition (speed, cant deficiency, etc.)

3.12

test section

part of a line used for the comfort test

3.13

test zone

continuous five-minute period, which is used for Mean Comfort evaluation

3.14

five-second time period

sampling period, of which 60 forms the test zone

3.15

reference system

local reference system for a vehicle body is defined through:

Origin: on the floor of the vehicle body, in the central position between the two body-bogie centre pivots (existing or ideally defined)

Axis:

— x-axis: longitudinal

— y-axis: lateral

— z-axis: vertical

Roll motions (φ) are defined as rotation around the x-axis.

For human body reference system, right hand system is used with vertical direction defined upwards.

A more detailed definition of the reference system is given in Annex A.

4 Symbols, units and abbreviations

Table 1 defines the symbols, units and abbreviations used in this standard.

Table 1 — Symbols, units and abbreviation

Table 1 — Symbols, units and appreviation					
General parameters					
Parameter	Symbol			Unit	
Time	t			[s]	
Time period	T		[s]		
Integration variable	τ		[s]		
Vehicle speed	V		[km/h]		
Frequency	f			[Hz]	
Interface, the floor (Plancher in French)	D DDFY/IE			[-]	
Interface, the seat pan (Assise in French)	itah ai) ^A	→ ▼		[-]	
Interface, the seat back (Dossier in French)	D			[-]	
Frequency weighting curve for vertical direction teh ai/catalog/standard	10000 0000	6f-8d1c-		[-]	
Frequency weighting curve for longitudinal direction (backrest),	11-12299-2009 W _c		[-]		
Frequency weighting curve for lateral/longitudinal direction,	W_{d}		[-]		
Low-pass filter	W_{p}		[-]		
n-tile	k		[-]		
Percentile	n		[%]		
Number of samples	N		[-]		
Imaginary unit	i	[-]		[-]	
Root mean square	rms		[-]		
Parameter	Longitudinal axis	Latera	l Axis	Vertical Axis	
Translational Accelerations on running gear [m/s²]					
Wheel set <i>i</i> –		ÿ	ÿ _i –		
Translational Accelerations	s in vehicle body [m/s				
Leading end of passenger compartment	-	$\ddot{\mathcal{Y}}_{E}^{'}$	<u>≣l</u> _	* Ž _{EI}	
Over leading bogie	-	$\ddot{\mathcal{Y}}_{I}$	*	;;* ;;*	
Body centre	\ddot{x}_{M}^{\star}	\ddot{y}_{1}^{i}	* M	ä* M	

Table 1 (continued)

Parameter	Longitudinal axis	Lateral Axis	Vertical Axis
Over trailing bogie	-	$\ddot{\mathcal{Y}}_{II}^{\star}$	$\ddot{z}_{\rm II}^{\star}$
Trailing end of passenger compartment	-	$\ddot{{\cal Y}}_{E\!I\!I}^*$	ä* E⊪
Floor, rms	a_{XP}	a_{YP}	a_{ZP}
Translational Weighte	d accelerations [m/s2]		•
Seat, weighted $W_{\mathbf{c}}$, $W_{\mathbf{b}}$	$\ddot{x}_{D,Wc}^{\star}$	-	* ^Z A,Wb
Vehicle body, weighted $W_{\mathbf{d}}$, $W_{\mathbf{b}}$	$\ddot{x}_{P,Wd}^{\star}$	$\ddot{\mathcal{Y}}_{P,Wd}^{\star}$	$\ddot{z}^*_{P,Wb}$
Vehicle body, weighted $W_{\mathbf{p}}$	_	$\ddot{\mathcal{Y}}_{P,Wp}^{\star}$	-
Seat, weighted $W_{\mathbf{c}}$, $W_{\mathbf{d}}$, $W_{\mathbf{b}}$, rms	$a_{XD}^{w_c}$	$a_{YA}^{w_{d}}$	$a_{\sf ZA}^{\sf w_b}$
Floor, weighted $W_{\mathbf{d}}$, $W_{\mathbf{b}}$, rms	$a_{XP}^{w_d}$	$a_{\mathtt{YP}}^{\mathtt{w}_{\mathtt{d}}}$	$a_{\sf ZP}^{\sf w_b}$
Floor, Weighted $W_{\mathbf{d}}$, $W_{\mathbf{b}}$, rms, 50 th percentile	a w _d χP50	$a_{\mathtt{YP50}}^{\mathtt{w_d}}$	a ^{w_b} ZP50
Seat, weighted $W_{\mathbf{c}}$, $W_{\mathbf{d}}$, $W_{\mathbf{b}}$, rms, 95 th percentile	<i>a</i> ^w c xD95	a _{YA95}	a w _b ZA95
Floor, weighted $W_{\bf d}$, $W_{\bf b}$, rms, 95 th percentile	aw _d XP95	а ^{w_d} үр ₉₅	a ^w _b 2P95
One-second average	-	$\ddot{y}_{1s}(t)$	_
Two-second average SIST EN 1 https://standards.iteh.ai/catalog/stand	<u>2299:2009</u> ards/sist/d9f3f 4 4e-2866-4	e6f-8d1ÿ _{2s} (t)	_
Peak to peak 3e170da0478a/sis	st-en-12299-2 <u>0</u> 09	$\ddot{y}_{pp}(t)$	_
One-second average, maximum absolute value	-	$\left \ddot{\mathcal{Y}}_{1s}\right _{max}$	_
Two-second average, absolute value	-	$\left \ddot{y}_{2s}(t)\right $	_
Translational jerk in	vehicle body [m/s ³]		
One-second average	-	$\ddot{y}_{1s}(t)$	_
One-second average, maximum absolute value	_	$ \ddot{y}_{1s} _{max}$	_
Angular velocity in	vehicle body [rad/s]		1
Body	$\dot{\varphi}^{\star}(t)$	-	_
Weighted $W_{\mathbf{p}}$	$\dot{arphi}_{Wp}^{\star}(t)$	-	_
One-second average	$\dot{arphi}_{1s}(t)$	-	_
One-second average, maximum absolute value	$\left \dot{arphi}_{1s} ight _{max}$	_	-

Table 1 (continued)

Parameter	Longitudinal axis	Lateral A	Axis	Vertical Axis
Comfort in	dexes [-]			
Mean Comfort Standard Method $N_{ m MV}$				
Mean Comfort Standard Method, partial index	N _{MVx} N _{MVy}		$N_{ m MVz}$	
Mean Comfort Complete Method, seated passenger	N_{VA}			
(in French: VA=voyageur assis) Mean Comfort Complete Method, standing passenger				
(in French: VD=voyageur debout)		$N_{\mathbf{v}_{\mathbf{D}}}$)	
Continuous Comfort	C_{Cx}	C_{Cy}		$C_{\mathtt{Cz}}$
Comfort on Curve Transitions	Pc	т		_
Comfort on Discrete Events	-	P_{DE}		_
Constants for Passenger Comfort on c	urve transitions and o	discrete eve	nts	
Parameter	Symbol		Unit	
Constant in acceleration component in Curve Transitions DAR	D PREVIE	ZW		[s²/m]
Constant in acceleration component in Curve transitions dard	s.iteh.ai) _B		[s³/m]	
Constant in acceleration component in Curve Transitions 122	299:2009 C		[-]	
https://standards.iteh.ai/catalog/standards. Constant in roll velocity component in Curve Transitions 0478a/sist-	s/sist/d9f3f44e-2866-4e6f-8d1c- n-12299-2009 <i>D</i>		[s/rad]	
Constant in roll velocity component in Curve Transitions	E		[-]	
Constant in acceleration component in Discrete Events	a		[s²/m]	
Constant in acceleration component in Discrete Events	b		[s²/m]	
Constant in acceleration component in Discrete Events	e		[-]	
Transfer fu	ınctions			
Parameter	Symbol		Unit	
Corner frequencies, n=1,2,3,4,5,6	f_{n}		[Hz]	
Resonant quality factors, n=1,2,3,4	Q_{n}		[-]	
Gain	K		[-]	
High pass transfer function	$H_{\mathbf{h}}(f)$		[-]	
Low pass transfer function	$H_1(f)$		[-]	
Acceleration to velocity transfer function	$H_{\mathbf{t}}(f)$		[-]	
Upward gradient transfer function	$H_{\mathbf{s}}(f)$			[-]

General description 5

5.1 General

The comfort of passengers in a railway vehicle is influenced by a number of different factors (temperature, noise, vibration, etc.). This standard considers only that part of the comfort influenced by the vibrations and motions of the vehicle. This is described as ride comfort or as passenger comfort. The standard can also be used for vehicle assessment with respect to ride comfort.

This standard defines as the Standard Method:

The Standard Method for Mean Comfort evaluation, taking into account the effects of vibration exposure measured on the floor of the vehicle body.

This standard also defines several methods for special applications:

- taking into account the short time effects of vibration exposure measured on the floor of the vehicle body as Continuous Comfort for the longitudinal, lateral, and vertical direction;
- c) taking into account the vibration exposure measured on the seat or other interfaces on ride comfort as the Complete Method for Mean Comfort evaluation;
- taking into account the effects of:
 - 1) discrete events (Comfort on Discrete Events) and RD PREVIEW
 - running on curve transitions (Comfort on Curve Transitions) on ride comfort.
- taking into account the vibration exposure measured on the floor of the vehicle body for the purpose of vehicle assessment with respect to ride comfort.

https://standards.iteh.ai/catalog/standards/sist/d9f3f44e-2866-4e6f-8d1c-5.2 Passenger exposure to vibrations 3e170da0478a/sist-en-12299-2009

Railway transport exposes passengers to vibrations related to the dynamic motions of the vehicle body.

The motions of the vehicle body transmit their effects to the human body through the following interfaces:

- in the standing position:
 - 1) floor feet
- in the seated position:
 - headrest neck
 - arm rest arms
 - 3) seat hip
 - backrest back
 - floor feet 5)

The type of transmission is whole-body transmission which acts on the whole body through the interfaces.

5.3 Application

Table 2 lists the items included or excluded from this standard:

Table 2 — Items considered by this standard

Item	Included	Excluded
Effects of vibration exposure	— on ride comfort	— on health
	— on vehicle assessment with	— on activities
	respect to ride comfort	— on motion sickness
Vibration transfer	— on whole body through	— on single body part
	interfaces — through floor interface	— on whole surface
Test procedure	— definitions	— notes or attributes related to
	— reference system	service quality and/or passenger expectation
	— requirements	— limiting values
	 measurement and evaluation rules 	
	— report guidance	
Posture and activities of passenger	— standing	— lying
iTeh	STANDARD PREV	performing specific actions (reading, writing etc.)
Type of measurement	(s indirect measurement, i.e. ai) measurement of motion	direct measurements (by asking test subjects)
hitris //standar	environment by different motion quantities EN 12299:2009 ts. itel ai/catalog/standards/sist/19/3/44c-26	— combined measurements

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5.4 Characteristics of railway vehicle motions

The basic typical motion characteristics, referred to the type of measurement and evaluation, are:

- a) Different properties, depending on the type of evaluation:
 - 1) quasi-stationary (Mean Comfort)
 - 2) non-stationary (Comfort on Curve Transitions and Comfort on Discrete Events).
- b) The frequency range of motions expected in rail vehicles includes, in the lateral direction:
 - 1) up to 15 Hz: due to track characteristics, vehicle body swing-roll and yaw modes at lower frequencies, and suspensions characteristics and vehicle body modes at higher frequencies;
- c) The frequency range of motions expected in rail vehicles includes, in the vertical direction:
 - 1) up to 40 Hz: due to track characteristics, suspensions characteristics, wheel defects, vehicle body modes;
- d) Range of frequencies from 0 Hz (quasi-static) to 2 Hz for Comfort on Curve Transitions and for Discrete Events.

5.5 Ride comfort

The ride comfort for passengers is the complex sensation, produced on the passenger by the vehicle body motions of the railway vehicle, transmitted to the whole body through the interfaces.