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**Napredni sistem za vodenje in nadzor gibanja po zemlji (A-SMGCS) - 4. del: Specifikacija Skupnosti za uporabo po Uredbi ES 552/2004 o medobratovalnosti na enotnem evropskem nebu za aktivno nekooperativno zaznavalo, vključno z njegovimi vmesniki - 2. poddel: Posebne zahteve za aktivno zaznavalo radarja za površinsko gibanje**

Advanced Surface Movement Guidance and Control System (A-SMGCS) - Part 4: Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for a deployed non-cooperative sensor including its interfaces - Sub-part 2: Specific requirements for a deployed Surface Movement Radar sensor

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# ETSI EN 303 213-4-2 V1.1.1 (2010-10)

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*European Standard (Telecommunications series)*

**Advanced Surface Movement Guidance  
and Control System (A-SMGCS);  
Part 4: Community Specification for application under the  
Single European Sky Interoperability Regulation EC 552/2004  
for a deployed non-cooperative sensor including its interfaces;  
Sub-part 2: Specific requirements for  
a deployed Surface Movement Radar sensor**

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## Foreword

This European Standard (Telecommunications series) has been produced by ETSI Technical Committee Aeronautics (AERO).

The present document has been produced by ETSI in response to European Commission mandate M/390 for the Interoperability of the European Air Traffic Management Network.

The present document has been developed in cooperation with Eurocae for compliance with the Essential Requirements of the Single European Sky Interoperability Regulation 552/2004 [i.1] and/or requirements given in implementing rules for interoperability based on the Single European Sky Interoperability Regulation.

The presumption of conformity which is linked to the full application of EN 303 213 (parts 1 to 4) can only be claimed after EN 303 213 (parts 1 to 4) has been listed in the Official Journal of the European Union as Community Specification.

General and specific requirements for presumption of conformity to SES Interoperability Regulation 552/2004 as amended by Regulation 1070/2009 are given in the normative annexes of the present document.

NOTE: Other requirements and other EU Regulations and/or Directives may be applicable to the product(s) falling within the scope of the present document.

If the present document gives no presumption of conformity, the manufacturer has to demonstrate the compliance for those essential requirements listed in the normative annexes of the present document by its own to the relevant supervisory authority.

The present document is part 4, sub-part 2 of a multi-part deliverable covering Advanced Surface Movement Guidance and Control System (A-SMGCS), as identified below:

- Part 1: "Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for A-SMGCS Level 1 including external interfaces";
- Part 2: "Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for A-SMGCS Level 2 including external interfaces";
- Part 3: "Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for a deployed cooperative sensor including its interfaces";
- Part 4: "Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for a deployed non-cooperative sensor including its interfaces";**
  - Sub-part 1: "Generic requirement for non-cooperative sensor";
  - Sub-part 2: "Specific requirements for a deployed Surface Movement Radar sensor".**
- Part 5: "Harmonized EN covering the essential requirements of article 3.2 of the R&TTE Directive for transmitter used in multilateration equipment";

Part 6: "Harmonized EN covering the essential requirements of article 3.2 of the R&TTE Directive for deployed surface movement radar sensors".

<b>National transposition dates</b>	
Date of adoption of this EN:	15 October 2010
Date of latest announcement of this EN (doa):	31 January 2011
Date of latest publication of new National Standard or endorsement of this EN (dop/e):	31 July 2011
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## Introduction

The European Union launched the Legislation "Single European Sky" (SES) in 2002 which was adopted in 2004 and amended by Regulation (EC) No 1070/2009 [i.5].

The SES legislation is based on a framework of 4 regulations, which includes "the Interoperability Regulation" (EC 552/2004 [i.1]). The objective of the Interoperability Regulation is to ensure interoperability of the European Air Traffic Management Network (EATMN) consistent with air navigation services. Under this regulation, the use of a European Standard referenced in the Official Journal of the European Union as Community Specification (CS) is a means of compliance to the essential requirements of the Regulation and/or the relevant implementing rules for interoperability.

The present document takes into account the Council Decision 2009/320/EC endorsing the European Air Traffic Management Master Plan of the Single European Sky ATM Research (SESAR) project [i.3].

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# 1 Scope

The present document is applicable to deployed Surface Movement Radar sensor as a constituent of an Advanced Surface Movement Guidance and Control System in addition to EN 303 213-4-1 [2].

The present document provides a European Standard for manufacturers of the non-cooperative sensor constituent, who have to demonstrate and declare conformity for their constituent to the IOP Regulation.

Any software elements related to the software assurance level of an A-SMGCS are outside of the scope of the present document. As such the essential requirements of the Interoperability Regulation are not considered for software elements within the present document.

The present document does not give presumption of conformity related to the environmental constraints, procedure level, effect of harmful interference and civil/military coordination.

NOTE 1: For these ERs, please refer to the Air Navigation Service Provider procedures.

NOTE 2: For those parts of the essential requirements, where annexes A and SA give no presumption of conformity, please refer to the Air Navigation Service Provider procedures.

Requirements in the present document which refer to "should" statements or recommendations in the normatively referenced material (clause 2.1) are to be interpreted as fully normative ("shall") for the purpose of compliance with the present document.

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# 2 References

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the reference document (including any amendments) applies.

Referenced documents which are not found to be publicly available in the expected location might be found at <http://docbox.etsi.org/Reference>.

NOTE: While any hyperlinks included in this clause were valid at the time of publication ETSI cannot guarantee their long term validity.

## 2.1 Normative references

The following referenced documents are necessary for the application of the present document.

- [1] EUROCAE ED-116 (ED-116 January 2004): "MOPS for Surface Movement Radar Sensor Systems for Use in A-SMGCS".
- [2] ETSI EN 303 213-4-1: "Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 4: Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for a deployed non-cooperative sensor including its interfaces; Sub-part 1: Generic requirements for non-cooperative sensor".

## 2.2 Informative references

The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.

- [i.1] Regulation (EC) No 552/2004 of the regulation of the European Parliament and of the Council of 10 March 2004 on the interoperability of the European Air Traffic Management network (interoperability Regulation), OJ L 96, 31.03.2004 as amended by Regulation (EC) No 1070/2009.



- [i.2] Regulation (EC) No 549/2004 of the European Parliament and of the Council of 10 March 2004 laying down the framework for the creation of the single European sky (the framework Regulation), OJ L 96, 31.03.2004 as amended by Regulation (EC) No 1070/2009.
- [i.3] Council Decision 2009/320/EC endorsing the European Air Traffic Management Master Plan of the Single European Sky ATM Research (SESAR) project, 30.03.2009.
- [i.4] ICAO Document 9830, AN/452, Advanced Surface Movement Guidance and Control Systems (A-SMGCS) Manual, First Edition, 2004.
- [i.5] Regulation (EC) No 1070/2009 of the European Parliament and of the Council of 21 October 2009 amending Regulations (EC) No 549/2004, (EC) No 550/2004, (EC) No 551/2004 and (EC) No 552/2004 in order to improve the performance and sustainability of the European aviation system, OJ L 300, 14.11.2009.
- [i.6] ETSI EN 303 213-1: "Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 1: Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for A-SMGCS Level 1 including external interfaces".
- [i.7] ETSI EN 303 213-2: "Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 2: Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for A-SMGCS Level 2 including external interfaces".
- [i.8] ETSI EN 303 213-3: "Advanced Surface Movement Guidance and Control System (A-SMGCS); Part 3: Community Specification for application under the Single European Sky Interoperability Regulation EC 552/2004 for a deployed cooperative sensor including its interfaces".

## 3

## Definitions and abbreviations

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### 3.1 Definitions

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For the purposes of the present document, the following terms and definitions apply:

**A-SMGCS Level 1:** A-SMGCS including a comprehensive Surveillance element capable of the location and classification of all aircraft and vehicles within the area of interest and the identification of cooperative aircraft and vehicles

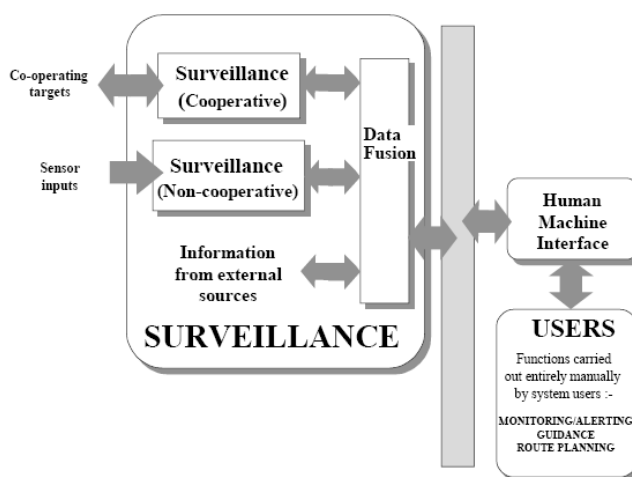
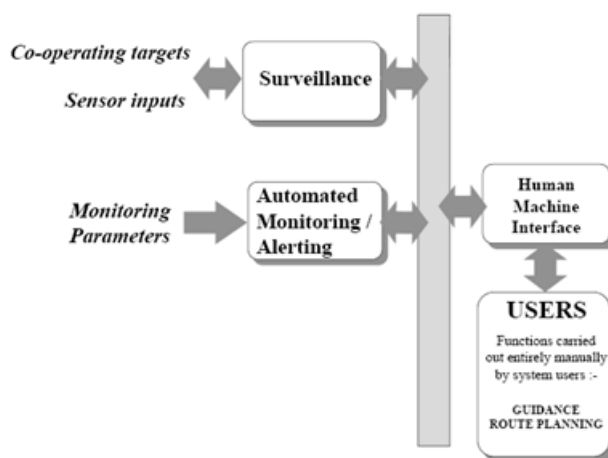


Figure 1: A-SMGCS Level 1 Functional Configuration

**A-SMGCS Level 2:** A-SMGCS including the capabilities of A-SMGCS Level 1 and uses the comprehensive surveillance data available to monitor the situation in the area of interest against a set of rules which will enable the system to alert the user to hazardous situations



**Figure 2: A-SMGCS Level 2 Functional Configuration**

**Advanced Surface Movement Guidance and Control Systems:** systems providing routing, guidance, surveillance for the control of aircraft and vehicles in order to maintain the declared surface movement rate under all local weather conditions within the aerodrome Visibility Operational Level (AVOL) while maintaining the required level of safety

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

**aerodrome:** defined area on land or water (including any buildings, installations, and equipment) intended to be used either wholly or in part for arrival, departure and surface movement of aircraft

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

**apron:** defined area on a land aerodrome, intended to accommodate aircraft for purposes of loading or unloading passengers, mail or cargo, fuelling, parking or maintenance

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

**availability:** probability that a system or an item is in a functioning state at a given point in time

**classification:** function which groups targets into various types (e.g. large, medium, small)

**constituents:** tangible objects such as hardware and intangible objects such as software upon which the interoperability of the EATMN depends

NOTE: This is the legally binding definition in the context of Single European Sky [i.2].

**manoeuvring area:** part of an aerodrome to be used for take-off, landing and taxiing of aircraft, excluding aprons

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

**movement area:** part of an aerodrome to be used for take-off, landing and taxiing of aircraft, consisting of the manoeuvring area and apron(s)

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

**procedure:** standard method for either the technical or operational use of the system, in the context of agreed and validated concepts of operation requiring uniform implementation throughout the EATMN

NOTE: This is the legally binding definition in the context of Single European Sky [i.2].

**system:** aggregation of airborne and groundbased constituents, as well as space-based equipment, that provides support for air navigation services for all phases of flight

NOTE: This is the legally binding definition in the context of Single European Sky [i.2].

**target:** aircraft, vehicle or obstacle that is displayed on a surveillance display

NOTE: This definition is derived from the ICAO Document 9830 [i.4].

**update:** renewal of target reports relating to all targets under surveillance

Further legally binding definitions in the context of Single European Sky are given in [i.2].

## 3.2 Abbreviations

For the purposes of the present document, the following abbreviations apply:

A-SMGCS	Advanced Surface Movement Guidance and Control Systems
ATM	Air Traffic Management
AVOL	Aerodrome Visibility Operational Level
CS	Community Specification
doa	date of announcement
dow	date of withdrawal
EATMN	European Air Traffic Management Network
EC	European Communities
EN	European Norm - (standard)
ER	Essential Requirement
EUROCAE	EUROpean organization for Civil Aviation Equipment
EUROCONTROL	EUROpean organization for the safety of air navigation
ICAO	International Civil Aviation Organization
IOP Regulation	InterOPERability Regulation
SES	Single European Sky
SMR	Surface Movement Radar

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## 4 Requirements for implementing Surface Movement Radar (SMR) sensor for A-SMGCS Systems

This clause defines the minimum requirements for a SMR sensor of A-SMGCS System.

### 4.1 Design Requirements for SMR sensor for A-SMGCS Systems

#### 4.1.1 General Requirements

The SMR sensor shall comply with the requirements as defined in EN 303 213-4-1 [2].

#### 4.1.2 Coverage

The constituent shall have the minimum coverage as defined in ED-116 [1], clause 2.8.

#### 4.1.3 Safety interlocks

The constituent shall comply with the requirements as defined in ED-116 [1], clause 2.14.

### 4.2 Built requirements for SMR sensors for A-SMGCS Systems

#### 4.2.1 Basic conformity tests

The basic conformity tests shall comply with the requirements as defined in ED-116 [1], clause 5.3.