



INTERNATIONAL STANDARD ISO 11674:2000
TECHNICAL CORRIGENDUM 1

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INTERNATIONAL ORGANIZATION FOR STANDARDIZATION • МЕЖДУНАРОДНАЯ ОРГАНИЗАЦИЯ ПО СТАНДАРТИЗАЦИИ • ORGANISATION INTERNATIONALE DE NORMALISATION

Ships and marine technology — Heading control systems

TECHNICAL CORRIGENDUM 1

Navires et technologie maritime — Systèmes de pilotage

RECTIFICATIF TECHNIQUE 1

iTeh STANDARD PREVIEW

Technical Corrigendum 1 to International Standard ISO 11674:2000 was prepared by Technical Committee ISO/TC 8, *Ships and marine technology*, Subcommittee SC 6, *Navigation*.

<https://standards.iteh.ai/catalog/standards/sist/012f3ee-9599-40e8-be3f-7c60cde9ae98/iso-11674-2000-cor-1-2001>

Page 7

4.3.15.3

Replace with the following text.

4.3.15.3 *If a heading control system is capable of digital serial communication with the ship's navigation system, the interface facilities shall comply with the relevant international marine interface standards in accordance with IEC 61162 as applicable.*

5.2

Replace "ISO/R 694" with "ISO 694".

Page 8

5.5.3.2, lines 7 and 9

Replace " ψ_i " with " ψ_{i1} ".

ICS 47.020.70

Ref. No. ISO 11674:2000/Cor.1:2001(E)

Annex A

Page 10

Line 9

Delete “, in reciprocal seconds” after “ S is the Laplace operator”.

Lines 11 and 12

Replace “ $K = \frac{K'}{L/v}$ ” with “ $K = K' \times \frac{L}{v}$ ”.

Replace “ $T = \frac{T'}{L/v}$ ” with “ $T = T' \times \frac{L}{v}$ ”.

Page 11

Line 7

Delete “, in reciprocal seconds” after “ S is the Laplace operator”.

Figure A.1

Replace with the following figure.

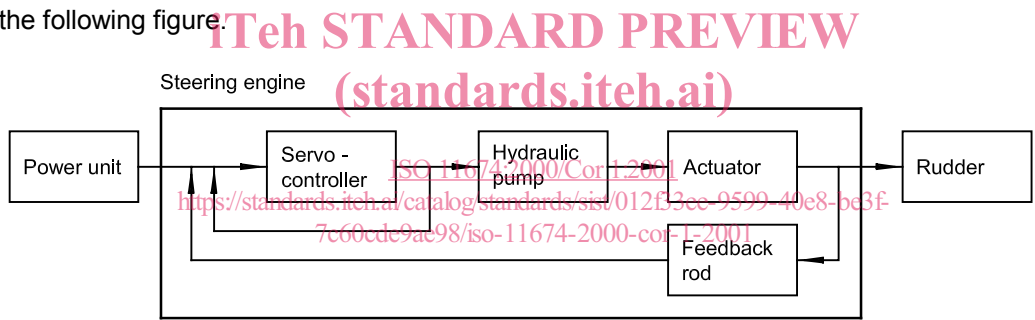


Figure A.1 — Block diagram of steering engine