
Plain bearings — Testing under conditions of hydrodynamic and mixed lubrication in test rigs

*Paliers lisses — Essai des paliers lisses dans les conditions de
lubrification hydrodynamique et mixte dans des machines d'essai pour
paliers*

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Case postale 56 • CH-1211 Geneva 20
Tel. + 41 22 749 01 11
Fax + 41 22 749 09 47
E-mail copyright@iso.org
Web www.iso.org

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Contents

Page

Foreword.....	iv
1 Scope	1
2 Symbols	1
3 Test objectives for bearing properties	2
4 Test rigs	3
5 Test procedures	6
6 Testing and test report.....	8
Bibliography	15

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Foreword

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International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 6281 was prepared by Technical Committee ISO/TC 123, *Plain bearings*, Subcommittee SC 2, *Materials and lubricants, their properties, characteristics, test methods and testing conditions*.

This first edition of ISO 6281 cancels and replaces ISO/TR 6281:1990, of which it constitutes a technical revision.

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Plain bearings — Testing under conditions of hydrodynamic and mixed lubrication in test rigs

1 Scope

This International Standard establishes guidelines for the testing of lubricated plain journal bearings in test rigs, running under conditions of hydrodynamic or mixed lubrication, during bearing and/or material development. It deals with both static and dynamic loading in solid and multi-layer journal bearings. It is not applicable to the testing of dynamic characteristics of lubricant film in journal bearings applied in calculation of vibration and stability of turbo-rotors. Further details of test procedures will need to be established when carrying out testing based on these guidelines.

2 Symbols

See Table 1.

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Table 1 — Symbols

Symbol	Description	Unit
a	Length of period	s
B	Bearing width	mm
F	Bearing load	N
F^*	Bearing load per unit bearing width	N/mm
f	Coefficient of friction of journal bearing	—
t	Time	s
U	Sliding velocity	m/s
β	Direction of bearing load	°
ω	Angular velocity	rad/s
η	Dynamic viscosity of lubricant	N·s/m ²

3 Test objectives for bearing properties

The test objectives for plain journal bearing test rigs operating under conditions of hydrodynamic or mixed lubrication are to obtain information, among others, on the following bearing properties, which can serve as critical variables when designing and applying the bearing (see ISO 4378):

- a) running-in ability;
- b) wear resistance;
- c) compatibility between bearing and journal materials (resistance to adhesion);
- d) embeddability (foreign particles absorption);
- e) resistance to journal scoring and abrasion;
- f) conformability;
- g) deformability (compressive strength);
- h) resistance to erosion (cavitation erosion, fluid erosion, particle erosion);
- i) static load carrying capacity;
- j) dynamic load carrying capacity (fatigue strength);
- k) friction characteristics;
- l) lubricant flow rate characteristics;
- m) temperature increase characteristics

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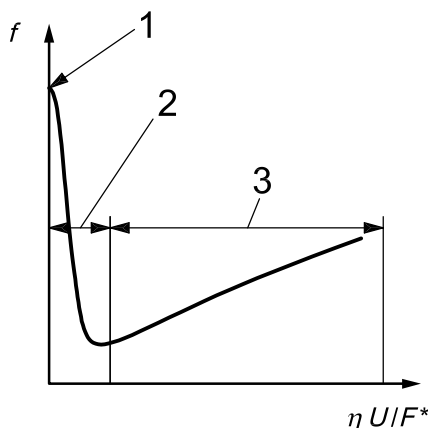
Of these bearing properties, the first group, a) to h), depends primarily on the mechanical and tribological properties of sliding materials under specified conditions. The second group, i) to m), depends primarily on hydrodynamic variables, and therefore also on

- viscosity as a function of temperature, pressure and shear rate,
- energy dissipation in the lubricant film (shear heating and heat dissipation), and
- elastic and thermal deformation of the bearing and journal, and hence change of lubricant film thickness (thermo-elastohydrodynamic lubrication).

The determination of these bearing properties, or test objectives, requires lubrication conditions that can involve boundary, mixed or hydrodynamic lubrication — the three modes of lubrication regime. In certain cases, a repeated, time-dependent change between mixed and hydrodynamic lubrication can be required.

NOTE Specific test methods may not yet exist for all of the above-mentioned bearing properties.

Figure 1 depicts the typical relation between the dimensionless number, $\eta U/F^*$, and the coefficient, f , of friction of the journal bearing, where η , U and F^* denote dynamic viscosity of the lubricant, sliding velocity and bearing load per unit bearing width ($F^* = F/B$), respectively. It shows the three regimes of boundary, mixed and hydrodynamic lubrication and qualitatively indicates the dependence between these important parameters.

**Key**

- 1 boundary lubrication
- 2 mixed lubrication
- 3 hydrodynamic lubrication

Figure 1 — Three modes of lubrication regime

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4 Test rigs**4.1 General recommendations**

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It is often more practical and efficient to investigate the bearing in a test rig than in an actual application. The design of the bearing test rig should be such as to simulate as far as possible all the relevant characteristic parameters (geometric, dynamic, hydrodynamic, thermal, thermodynamic, etc.) of the actual application.

In addition, the following is recommended for the test rig.

- a) Simple mechanical construction.
- b) Simple dismantling and assembly procedures for the test objects; with well-defined positioning of the bearing and housing; preferably it should be possible to inspect the test bearing *in situ*. In addition, the test rig should be equipped with an emergency stop mechanism, both for safety reasons and to allow the inspection of the sliding surface before the onset of catastrophic damage.
- c) Well-defined dimensions for the test bearing.
- d) High dimensional stability with little shaft deflection. The test rig should be as rigid as possible, with a high natural frequency. In special cases, however, it may be necessary to vary the dimensional stability or the shaft deflection in order to simulate the operating condition of the actual application.
- e) Appropriate lubricant supply condition. When the lubricant flow within the bearing clearance has to be simulated exactly, the circumferential and axial position of the lubricant supply in the test rig should be the same as in the actual application.
- f) Well-defined and experimentally verifiable lubrication conditions.
- g) The regime of laminar or turbulent flow should be the same in the test rig and in the actual application.
- h) The rig should replicate as far as possible the temperature and stress range that can occur in practice.
- i) Appropriate measuring techniques or equipment should be employed.

4.2 Generic types of test rig

Generic types of test rig for plain journal bearings are shown in Figures 2 and 3. Figure 2 a) and b) depict the rotational motion of the journal, where a combination of both is also possible. In practice, many more patterns of journal motion other than rotation may occur, such as inclination, bending, axial, conical and their combinations. In addition, the bearing itself can rotate or oscillate or even move in space instead of, or together with, the journal, as with a crank-pin bearing. In any case, the relative motion of the journal to the bearing has to be known (measurable) exactly. However, constant rotational speed of journal and the parallel movement of journal to bearing are the simplest and most preferable for testing.

Figure 3 shows patterns of the bearing load. In the case of statically loaded journal bearing [Figure 3 a)], the magnitude, F , and the direction, β , of the bearing load are constant. In a special case of dynamically loaded bearing, F is constant, but β increases or decreases with time [Figure 3 b)]. In the general case of dynamically loaded bearing [Figure 3 c)], both or at least one of F and β change periodically, while the remaining variable can be constant. The periodic form of F (also β) is then arbitrary, such as sinusoidal with or without constant offset, curving steeply up and downwards, as, for example, in engine bearing loading.

With regard to the loading of the test bearing, it is often more practical to load the test bearing directly supported by the journal [Figure 4 a)], than to load the test bearing indirectly through the journal [Figure 4 b)]. For static loading, a dead weight system, with or without lever, or hydraulic or pneumatic actuation can be used. For dynamic loading, a rotating or vibrating mass system, with or without lever, an electromagnetic exciter, hydraulic actuation, etc., can be applied. Dynamic loading by means of a mass fixed to the journal seems to be simple, but the amplitude of the bearing load is then determined primarily by the rotational speed of the journal. Therefore, it is not easy to change the load amplitude independently of the rotational speed. Furthermore, the magnitude and direction of the bearing load have to be precisely measured, and it is important to let the journal move freely inside the bearing clearance without hindrance from the loading mechanism.

Besides such bearing test rigs operating under hydrodynamic or mixed lubrication, as described above, many other kinds of test apparatus and test methods may be used to investigate the tribological or mechanical properties of bearing materials, including coefficient of friction, mechanical strength, hardness, elasticity, plasticity and bond strength. The study of the tribological properties of boundary films has also led to the development of other test apparatus and methods; these are, however, outside the scope of this International Standard (see ISO 4384-1, ISO 4384-2, ISO 4385, ISO 7148-1, ISO 7148-2, ISO 7905-2, ISO 7905-3 and ISO 7905-4).

NOTE The testing of the resistance to corrosion of bearing materials by the lubricant is the subject of ISO 10129.

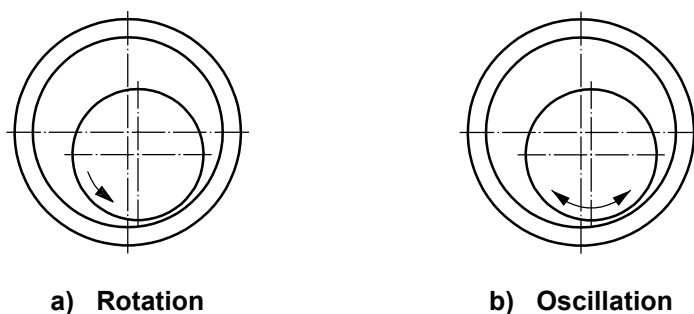
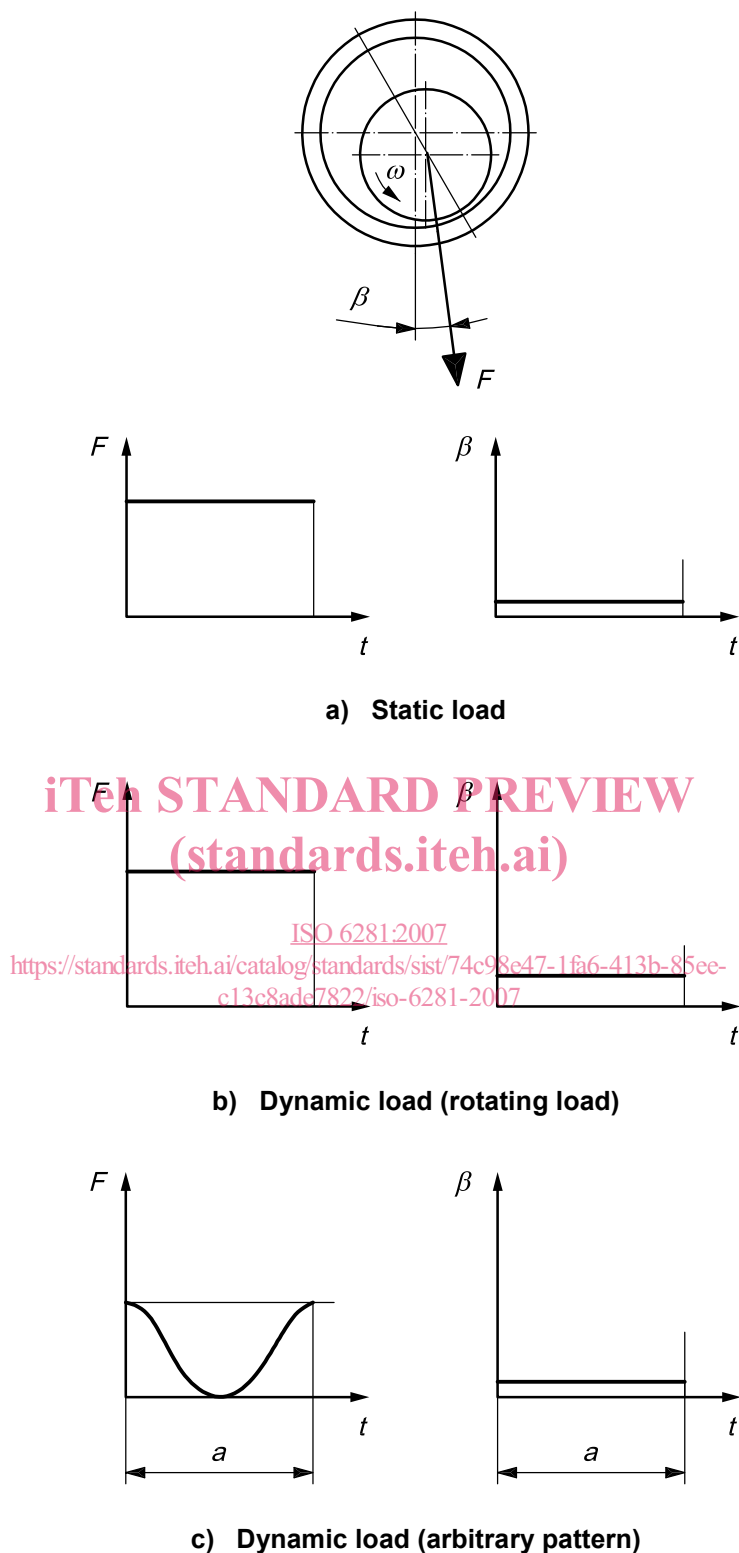
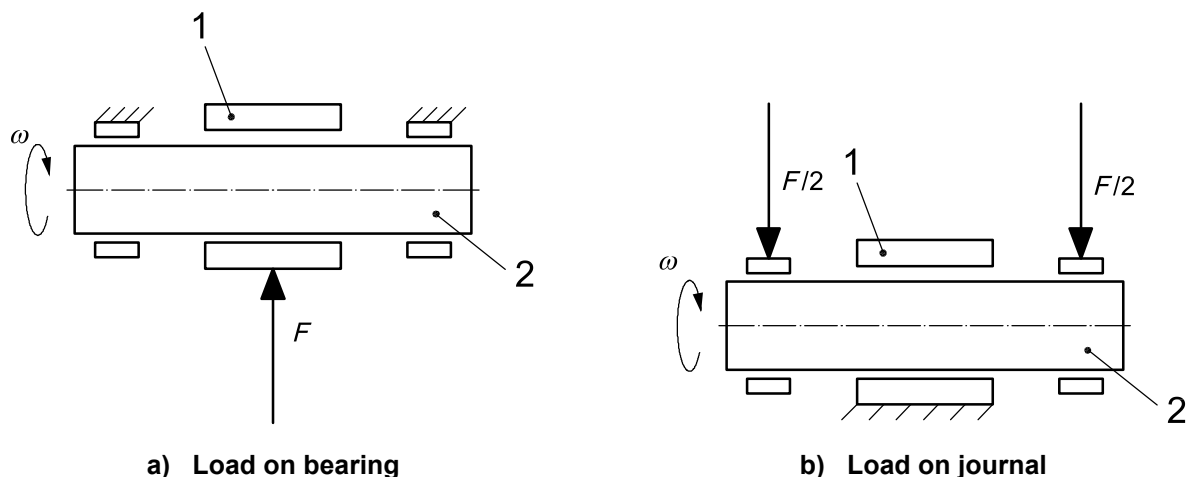


Figure 2 — Rotational motion of journal

**Key**

- a length of period
- F bearing load
- β direction of bearing load
- t time
- ω angular velocity

Figure 3 — Examples of bearing load patterns

**Key**

- F bearing load
 ω angular velocity
 1 test bearing
 2 journal

Figure 4 — Two modes of load application

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5 Test procedures

The actual test procedure depends on the property to be determined. It is important to establish the test conditions in order to ensure that test results obtained on test rigs are applicable in practice and that results obtained on different test rigs are mutually compatible.

In the following, guidelines or examples of test procedures for obtaining the bearing properties according to Clause 3, a) to m), are described together with the evaluation of the results. Bearing properties a) to h) depend primarily on mechanical and tribological characteristics of the bearing material itself, and in some cases, may be determined qualitatively by proper material testing. However, they can be evaluated quantitatively only by testing in bearing test rig. When stepwise increase or decrease of bearing load or severity of operating condition is prescribed, thermal equilibrium must be achieved in the test object at each step to assure reproducibility of the results. During the test, it is important to be aware of the eventual change of the test object itself, even under seemingly constant operating conditions, through wear, foreign particles embedding, diffusion, chemical reaction, lubricant degradation, etc. This should be verified and documented in the test report.

a) Running-in ability

The change of surface topography, roughness, friction torque, wear rate¹⁾ or wear intensity²⁾ of the bearing, or the temperature of the lubricant and/or bearing should be measured from the initial state of the sliding surfaces under the specified operating condition. From the characteristic change of these variables with time, the completion of running-in process can be detected. The shorter the time until running-in is completed, the higher the running-in ability.

1) Ratio of wear extent to the time interval during which it has developed.

2) Ratio of wear extent to the specified distance on which wear developed or to the volume of the work done.

b) Wear resistance

The severity of the operating condition of the bearing should be increased until wear occurs. Wear can be mechanical or mechano-chemical in nature. The former can be adhesive wear, seizure, scoring or scratching, abrasion, fatigue wear, spalling, cavitation wear, erosive wear or fretting wear. The latter can be oxidative wear, fretting corrosion or electro-erosive wear. The more severe the operating condition under which wear begins to occur and the smaller the wear rate and/or the wear intensity, the higher the wear resistance.

c) Compatibility between bearing and journal material (resistance to adhesion)

The frictional torque and/or the temperature of the lubricant and bearing should be measured during the stepwise increase in the severity of the operating condition (i.e. increase in inlet lubricant temperature, specific bearing load, sliding velocity), and the occurrence of adhesion should be detected. The more severe the operating condition under which the adhesion begins to occur, or the less the sliding surface suffers adhesion damage, the higher the compatibility and the resistance to adhesion.

d) Embeddability (foreign particles absorption)

Foreign particles of known hard material (i.e. hardness, quantity and size) should be mixed with the lubricant, and the quantity and depth to which the foreign particles have embedded into the bearing surface in a specified time, together with the grade of damage of the journal surface, should be measured under the specified operating condition. The larger the quantity and the greater the depth to which the foreign particles have embedded, or the less the damage of the journal surface by the foreign particles, the higher the embeddability.

e) Resistance to journal scoring and abrasion

The severity of the operating condition of the bearing should be increased stepwise and the occurrence of the journal scoring (severe scratches) or abrasion verified. The more severe the operating condition under which the damage begins to occur, and the less the scoring and abrasion caused to the journal (or the smaller the wear rate and the wear intensity), the higher the resistance to journal scoring and abrasion.

f) Conformability

The bearing load should be increased stepwise under a specified operating condition such that a high specific local load or edge load is applied to the bearing, which in consequence deforms elastically and plastically towards the form of the journal. The more the bearing deforms without showing any other bearing damage, or the higher the grade of similarity of form of the sliding surfaces reached, the greater the conformability.

g) Deformability (compressive strength)

The specific bearing load should be increased stepwise under a specified operating condition until the compressive strength of the bearing material is almost reached. The higher the deformation of the bearing, the greater the deformability.

h) Resistance to erosion (cavitation erosion, fluid erosion, particle erosion)

The bearing should be run under a specified erosive operating condition, until a predetermined quantity of damage by erosion is detected. The longer the time or sliding distance until damage is detected and the more severe the operating condition (i.e. higher specific bearing load, temperature, sliding velocity), the greater is the resistance to erosion. The resistance to erosion may be also measured by the grade of damage caused by erosion during a given period of time or by the rate of wear by erosion.