



SLOVENSKI STANDARD

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Nadomešča:

SIST EN 15595:2009+A1:2011

Železniške naprave - Zavore - Preprečevanje zdrsa koles

Railway applications - Braking - Wheel slide protection

Bahnanwendungen - Bremse - Gleitschutz

Applications ferroviaires - Freinage - Anti-enrayeur

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Ta slovenski standard je istoveten z: ~~SIST EN 15595:2019~~ EN 15595:2018

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ICS:

45.040	Materiali in deli za železniško tehniko	Materials and components for railway engineering
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This European Standard was approved by CEN on 3 August 2018.

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Contents	Page
European foreword.....	6
Introduction	7
1 Scope.....	8
2 Normative references.....	8
3 Terms and definitions	9
4 Symbols and abbreviations	12
5 Requirements.....	12
5.1 Functional requirements.....	12
5.1.1 Objectives of wheel slide protection.....	12
5.1.2 General functional requirements.....	13
5.1.3 Control of the brake force	13
5.1.4 Wheel slide protection watchdog (safety timer)	14
5.1.5 Air supply.....	14
5.1.6 Wheel diameter differences.....	14
5.1.7 Wheel rotation monitoring (WRM).....	14
5.1.8 Diagnostics	15
5.2 Design requirements	16
5.2.1 Environmental specification	16
5.2.2 Fire behaviour.....	16
5.2.3 RAMS.....	17
5.2.4 Mechanical construction	17
5.2.5 Power management	17
5.2.6 Software.....	18
5.2.7 Electronic control unit Input/Output (I/O).....	18
5.2.8 Sensor - axle speed acquisition.....	18
5.2.9 Actuator - modification of brake force	18
5.3 Installation recommendations.....	19
5.3.1 General installation requirements	19
5.3.2 Air system	19
5.3.3 Power supply and electrical system.....	19
5.4 Performance requirements for WSP.....	20
5.4.1 Performance	20
5.4.2 Stopping distance and adhesion improvement.....	21
5.4.3 Wheelset slide limits.....	21
5.4.4 Track damage	22
5.4.5 Maximum deceleration	22
5.4.6 Air consumption.....	23
5.4.7 Output based on speed information provided by WSP	23
6 Range of tests.....	24
6.1 General.....	24
6.1.1 Test classifications.....	24
6.1.2 Assessor	24
6.2 Type Test.....	24
6.2.1 General.....	24

6.2.2	Test requirements.....	24
6.2.3	Individual component Type Test.....	24
6.3	Vehicle Implementation Test.....	25
6.3.1	General.....	25
6.3.2	Test requirements.....	26
6.3.3	Conformity of previous vehicle tests.....	26
6.4	List of tests.....	26
6.4.1	Standard tests.....	26
6.4.2	Drag tests.....	26
6.4.3	Test methods for speeds from 160 up to 200 km/h.....	27
6.4.4	Test methods for speeds > 200 km/h.....	27
6.4.5	Supplementary higher deceleration tests.....	27
6.4.6	Supplementary approval tests for WSP acting in vehicles with brakes that are independent of adhesion.....	27
6.4.7	Supplementary approval tests involving tractive units and trainsets having dynamic brakes.....	27
6.4.8	Testing of wheel rotation monitoring (WRM).....	28
6.5	Re-testing.....	34
6.5.1	General.....	34
6.5.2	Hardware.....	34
6.5.3	Software.....	35
7	Test methods.....	35
7.1	General.....	35
7.2	Measurement.....	36
7.3	Tests on vehicle.....	37
7.3.1	General.....	37
7.3.2	Generation of degraded adhesion.....	38
7.3.3	Environmental conditions.....	38
7.4	Test in simulation environment.....	39
7.4.1	General.....	39
7.4.2	Tests on simulation rig.....	39
7.4.3	Additional specific simulator tests.....	40
7.4.4	Optional tests.....	40
8	Evaluation of test.....	40
8.1	Correcting the stopping distances.....	40
8.2	Number and validity of dry tests.....	40
8.3	Evaluation of slide test.....	40
8.3.1	General.....	40
8.3.2	Evaluation of stopping performance.....	41
8.3.3	Evaluation of test validity.....	42
8.3.4	Evaluation of relative air consumption.....	51
9	Documentation of tests.....	52
9.1	Test Specification.....	52
9.2	Test report.....	53
10	Routine test and inspection.....	54
11	Designation, identification and marking.....	54
Annex A (normative)	Tables linking the WSP / WRM Requirements to Tests and Test Criteria.....	55
Annex B (normative)	Minimum requirements for a WSP simulator.....	75
B.1	General.....	75

EN 15595:2018 (E)

B.1.1	General.....	75
B.1.2	Use of the simulator model.....	75
B.2	Adhesion model.....	81
B.2.1	General.....	81
B.2.2	Constant adhesion condition.....	81
B.2.3	Variable adhesion condition.....	81
B.2.4	Adhesion conditioning factors.....	82
B.3	Test and performance model.....	82
B.3.1	General.....	82
B.3.2	Simulator performance.....	82
B.3.3	Test requirements.....	82
B.3.4	Stopping performance.....	82
B.3.5	Wheel damage.....	83
B.3.6	Air system.....	83
B.3.7	Pass/fail limits.....	83
B.3.8	Fault conditions.....	83
B.3.9	WSP outputs.....	84
B.4	Vehicle performance model.....	84
B.4.1	General.....	84
B.4.2	Friction material.....	84
B.4.3	Pneumatic actuator/brake demand.....	84
B.4.4	Body/Bogie/wheel dynamics.....	84
B.5	Vehicle functional model.....	85
B.5.1	General.....	85
B.5.2	Functional inputs.....	85
B.6	Simulator validation.....	85
B.6.1	General.....	85
B.6.2	Validation of test benches.....	85
B.6.3	Management.....	88
Annex C	(informative) Example of customer specific simulator tests.....	89
C.1	Naturally occurring variable adhesion tests.....	89
C.1.1	General.....	89
C.1.2	Sequence.....	89
C.1.3	Measurement and pass/fail criteria.....	91
C.2	Sustained low adhesion track condition (SLAC) Tests.....	92
C.2.1	Sequence.....	92
C.2.2	Measurement/pass fail criteria.....	93
C.2.3	WSP speed reference (v_{ref}).....	93
C.3	Operating speeds above 160 km/h.....	93
C.3.1	Criteria.....	93
C.3.2	Sequence.....	94
C.3.3	Measurement and pass/fail criteria.....	94
Annex D	(informative) Optional tests.....	95
D.1	Sander system tests — Criteria.....	95
D.2	Dynamic braking system tests — Criteria.....	96
D.3	Peripheral output tests — Criteria.....	96
Annex E	(informative) Typical diagram of a real WSP test.....	98
Annex F	(informative) In-service monitoring.....	100
Annex G	(informative) Braking configurations.....	101
G.1	Per bogie control.....	101

G.2 Per wagon control	101
Annex H (informative) Changes between Revision 1 and Revision 2 of EN 15595	102
Annex ZA (informative) Relationship between this European Standard and the Essential Requirements of EU Directive 2008/57/EC aimed to be covered.....	103
Bibliography	105

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SIST EN 15595:2019

<https://standards.iteh.ai/catalog/standards/sist/493921d7-3757-4467-a49c-fa3c900b9b32/sist-en-15595-2019>

EN 15595:2018 (E)**European foreword**

This document (EN 15595:2018) has been prepared by Technical Committee CEN/TC 256 “Railway applications”, the secretariat of which is held by DIN.

This European Standard shall be given the status of a national standard, either by publication of an identical text or by endorsement, at the latest by June 2019, and conflicting national standards shall be withdrawn at the latest by June 2019.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN shall not be held responsible for identifying any or all such patent rights.

This document supersedes EN 15595:2009+A1:2011.

This document has been prepared under a standardization request given to CEN by the European Commission and the European Free Trade Association, and supports essential requirements of EU Directive 2008/57/EC.

For relationship with EU Directive 2008/57/EC, see informative Annex ZA, which is an integral part of this document.

The rationale behind the changes between Revision 1 and this Revision of this standard is given in Annex H.

According to the CEN-CENELEC Internal Regulations, the national standards organisations of the following countries are bound to implement this European Standard: Austria, Belgium, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Finland, Former Yugoslav Republic of Macedonia, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Norway, Poland, Portugal, Romania, Serbia, Slovakia, Slovenia, Spain, Sweden, Switzerland, Turkey and the United Kingdom.

Introduction

A Wheel Slide Protection (WSP) system is designed to make the best use of available adhesion and to improve adhesion by a controlled reduction and restoration of the brake force to prevent wheel sets from locking and uncontrolled sliding due to low adhesion. Thus the braking performance is optimized and the occurrence of wheelset damage is minimized.

The Wheel Rotation Monitoring (WRM) system is designed to detect locked wheels and to give immediate information in this case.

Trains fitted with WSP systems may consist of single vehicles, locomotive and trailing vehicles or may be high speed trains, multiple units, commuter trains, Light Rail Vehicles (LRV) and Tram Trains of any track gauge, etc.

Such trains will be equipped with friction brakes and may also be equipped with additional braking systems, e.g. dynamic brakes, wheel/rail adhesion independent brakes, and may also be fitted with adhesion improving systems, e.g. sanding.

This European Standard is not intended to be used to determine the stopping performance of a WSP equipped train under all environmental conditions.

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EN 15595:2018 (E)**1 Scope**

This document specifies the criteria for system acceptance and type approval of a wheel slide protection (WSP) system. It also specifies criteria for the implementation of WSP to specific vehicle applications and specific operating conditions, as well as requirements for wheel rotation monitoring (WRM). This includes the design, testing and quality assessment of the WSP and WRM systems and their components.

This European Standard does not apply to vehicles on rubber tyred wheels or vehicles equipped with hydraulic brakes.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

EN 14478:2017, *Railway applications - Braking - Generic vocabulary*

EN 15663, *Railway applications - Vehicle reference masses*

EN 16834:—¹, *Railway applications - Braking - Brake performance*

EN 45545 (all parts), *Railway applications - Fire protection on railway vehicles*

EN 50121-3-2, *Railway applications - Electromagnetic compatibility - Part 3-2: Rolling stock - Apparatus*

EN 50125-1, *Railway applications - Environmental conditions for equipment - Part 1: Rolling stock and on-board equipment*

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EN 50126-1, *Railway Applications - The Specification and Demonstration of Reliability, Availability, Maintainability and Safety (RAMS) - Part 1: Generic RAMS Process*

EN 50128, *Railway applications - Communication, signalling and processing systems - Software for railway control and protection systems*

EN 50129, *Railway applications - Communication, signalling and processing systems - Safety related electronic systems for signalling*

EN 50155, *Railway applications - Rolling stock - Electronic equipment*

EN 60529, *Degrees of protection provided by enclosures (IP Code) (IEC 60529)*

EN 61373, *Railway applications - Rolling stock equipment - Shock and vibration tests (IEC 61373)*

EN ISO 228-2, *Pipe threads where pressure-tight joints are not made on the threads - Part 2: Verification by means of limit gauges (ISO 228-2)*

EN ISO/IEC 17025, *General requirements for the competence of testing and calibration laboratories (ISO/IEC 17025)*

¹ Under preparation. Stage at time of publication: FprEN 16834:2018.

ISO 8573-1, *Compressed air — Part 1: Contaminants and purity classes*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in EN 14478:2017 and the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- IEC Electropedia: available at <http://www.electropedia.org/>
- ISO Online browsing platform: available at <http://www.iso.org/obp>

3.1

adhesion profile

predefined set of data representing the adhesion characteristics of a section of running line

3.2

relative air consumption

ratio of the total volume of air consumed during a braking stop with WSP activity against that which would be consumed during a stop with no WSP activity

3.3

supplementary reservoir

pressure reservoir used for determination of relative air consumption during WSP testing

3.4

crush laden

vehicle load condition based on the design mass under exceptional payload in accordance with EN 15663

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3.5

dry rail

conditions where 100 % of the brake force of the vehicle can be applied with no axle sliding more than 2 %

3.6

dry rail stopping distance

actual measured stopping distance in dry rail conditions

3.7

low adhesion

conditions where the wheel/rail adhesion is in the range 0,08 to 0,05

3.8

very low adhesion

conditions where the wheel/rail adhesion is in the range 0,05 to 0,03

3.9

extremely low adhesion

conditions where the wheel/rail adhesion is below 0,03

EN 15595:2018 (E)**3.10****reference speed**

signal generated and generally used by the WSP or WRM to determine an approximation to the true train speed

3.11**nominal initial train speed**

specified speed at start of braking during brake tests

Note 1 to entry: True train speed can slightly differ.

Note 2 to entry: This may be known as target speed.

3.12**uncoupled test**

method of brake testing where the vehicle (or single unit) under test is uncoupled from the rear of the test train and brakes separately, also referred to as a slip test

3.13**brake to stop test**

brake test starting from a nominal initial speed going to a stop, performed with either an individual vehicle (locomotive, coach) or a train set as the tested unit

3.14**absolute wheel slide**

difference between true train speed and circumferential speed

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3.15**relative wheel slide**

absolute wheel slide divided by true train speed

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3.16**undesired brake force reduction**

reduction in brake force not justified by behaviour of wheelsets

3.17**brake blending curve**

curve describing the characteristics of blending of dynamic and pneumatic brakes as function of speed

3.18**WSP controller**

device having the electronic hardware and software to receive the signals from the speed sensors and provide the outputs to the WSP brake control elements, for example dump valves, enabling the modulation of the brake force

3.19**WSP actuator**

device used by the WSP controller to control the brake force

3.20**WSP dump valve**

WSP actuator to control the brake cylinder pressure

3.21**speed sensor**

device used to generate an individual wheelset or wheel speed signal to a WSP controller

3.22**service interface**

access point for diagnostic information and maintenance test

3.23**validation**

process of analysis followed by a judgment based on evidence to determine whether an item (e.g. process, documentation, software or application) fits the user needs, in particular with respect to safety and quality and with emphasis on the suitability of its operation in accordance to its purpose in its intended environment

3.24**verification**

process of examination followed by a judgment based on evidence that output items (process, documentation, software or application) of a specific development phase fulfils the requirements of that phase with respect to completeness, correctness and consistency

Note 1 to entry: Verification is mostly based on document reviews (design, implementation, test documents, etc.).

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3.25**designed deceleration**

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maximum deceleration which is provided by the brake system of the vehicle, in a normal manner on level track and which is defined by calculation

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3.26**slide test**

test performed under degraded adhesion conditions

3.27**dry rail test**

test performed where the adhesion conditions will support the maximum brake force

3.28**drag test**

test to simulate braking on a falling gradient, performed with an auxiliary tractive unit to achieve a constant speed with a constant brake application

3.29**brake test**

test where the brakes are applied to achieve a deceleration

3.30**tare laden**

vehicle load condition based on the design mass in working order in accordance with EN 15663

Note 1 to entry: This can have to include additional test equipment and personnel.

EN 15595:2018 (E)**4 Symbols and abbreviations**

For the purposes of this document, the following symbols and abbreviations apply.

g	acceleration due to gravity, in m/s^2
v_{nom}	nominal initial train speed, in km/h
v_{ref}	WSP vehicle reference speed, in km/h
v_t	true train speed, in km/h
μ	adhesion coefficient
ρ	coefficient of inertia of rotating masses
τ	initial adhesion coefficient
AR	auxiliary reservoir
BP	brake pipe
BSR	brake supply reservoir; may also be referred to as an auxiliary reservoir
EB	emergency brake
ER	(fr: événement redouté) anticipated event – used in safety analysis
MMI	Man Machine Interface
MTB	magnetic track brake
NI	normal litre
RAMS	reliability, availability, maintainability and safety
VIT	Vehicle Implementation Test
WRM	wheel rotation monitoring system (sometimes called DNRA, detection of non-rotating axle)
WSP	wheel slide protection

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5 Requirements**5.1 Functional requirements****5.1.1 Objectives of wheel slide protection**

The objectives of fitting WSP systems to trains are to assist in achieving the following:

- minimum extension in stopping distance compared to stopping on clean dry rails (i.e. good adhesion conditions);
- minimum level of wheelset damage due to wheel slide or wheel lock;
- minimum level of track damage;
- for pneumatic brake systems, minimum increase in air consumption compared to a dry rail stop with no WSP activity.

The particular priority of these objectives may vary for different classes of applications or even for a particular application.

The objectives are deemed to be fulfilled, if the requirements of this standard are met.

5.1.2 General functional requirements

One independent WSP/WRM system shall control no more than eight axles.

In the case of tractive units that are capable of running alone, any single fault of the WSP system shall not result in a loss of brake force on more than 50 % of the braked axles. This may be achieved by multiple WSP systems or an independent braking system that cannot be influenced by WSP.

The circumferential speed of the wheelsets is calculated on the basis of information provided by sensors, and monitored by regulators or automatic control systems (WSP controller).

The WSP controller may use additional information (e.g. signals from pressure sensors) about the status of the train for WSP control.

The WSP controller transmits commands to the WSP actuators (e.g. WSP dump valves) to reduce, hold or restore brake force, either totally or partially.

The WSP shall not reduce the brake force below a low speed threshold. This threshold shall not be higher than 5 km/h and not lower than 0,5 km/h. If the brake force is already reduced when the train speed falls below this threshold, the WSP system shall restore the brake force to the demanded value.

When starting the train the WSP shall be available for operation before the speed achieves 6 km/h. For freight applications where power supply is not provided at low speed, this threshold may be increased up to 15 km/h.

The WSP system shall remain operative whilst there is brake force present (i.e. until the brakes are fully released).

The WSP shall not be capable of increasing the brake force above that demanded by the braking system.

The WSP shall not alter the demanded brake force at standstill except during system test.

All speed thresholds defined in this standard shall be related to nominal mean wheel diameter if the true wheel diameter is not known.

5.1.3 Control of the brake force

5.1.3.1 Requirements for pneumatic actuation of the friction brake

WSP-actuators (e.g. WSP dump valves or other pneumatic control devices - integrated brake valve) are used to modify brake force.

The WSP-system shall not allow a direct connection between supply and exhaust.

5.1.3.2 Dynamic brake

Dynamic brakes shall have either WSP control in accordance with this standard or means to switch them off in the event of sliding.

If the dynamic brake is used for emergency brake applications a WSP control of the dynamic brake shall be provided.

If the dynamic brake is commanded by an independent control command, separate from the regular train wide control command, the maximum slide criteria, as defined in 5.4.3.1, shall at least be met.

The dynamic brake may be equipped with its own WSP. As long as the friction brake is not activated the slide can be controlled by the WSP of the dynamic brake alone.

A WSP strategy shall be adopted for the two systems if dynamic brake and friction brake are coordinated by a blending function or operated independently to fulfil the requirements of this standard.