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Satellite Earth Stations and Systems (SES);
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Part 5: Performance Test Specification

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Foreword

This Technical Specification (TS) has been produced by ETSI Technical Committee Satellite Earth Stations and Systems (SES).

The present document is part 5 of a multi-part deliverable covering GNSS-based Location Systems (GBLS), as identified below:

Part 1: "Functional requirements";

Part 2: "Reference Architecture";

Part 3: "Performance requirements";

Part 4: "Requirements for location data exchange protocols";

Part 5: "Performance Test Specification".

Modal verbs terminology

In the present document "**shall**", "**shall not**", "**should**", "**should not**", "**may**", "**need not**", "**will**", "**will not**", "**can**" and "**cannot**" are to be interpreted as described in clause 3.2 of the ETSI Drafting Rules (Verbal forms for the expression of provisions).

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Introduction

The increasing proliferation of location-based services is based on several trends in user applications and devices; these include notably the widespread adoption of multi-functional smart-phones, etc., and the wider adoption of tracking devices (e.g. in transport). This need for new and innovative location-based services is generating a need for increasingly complex location systems. These systems are designed to deliver location-related information for one or more location targets to user applications.

The wide spectrum of technical features identified in ETSI TR 103 183 [i.1] calls for a new and broader concept for location systems, taking into account hybrid solutions in which GNSS technologies are complemented with other technology sensors to improve robustness and the performance.

1 Scope

The present document specifies the procedures for testing conformance of a GNSS-based Location System (GBLS) with the Performance Requirements specified in ETSI TS 103 246-3 [3].

The tests specified are of a complete GBLS, considered as "Black Box" i.e. the tests are made at outputs of the system in response to stimuli applied at the inputs. The tests are defined for laboratory testing only, and not in the "field".

2 References

2.1 Normative references

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the reference document (including any amendments) applies.

Referenced documents which are not found to be publicly available in the expected location might be found at http://docbox.etsi.org/Reference.

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The following referenced documents are necessary for the application of the present document.

[1] ETSI TS 103 246-1: "Satellite Earth Stations and Systems (SES); GNSS based location systems; Part 1: Functional requirements".

[2] ETSI TS 103 246-2: "Satellite Earth Stations and Systems (SES); GNSS based location systems; Part 2: Reference Architecture".

[3] ETSI TS 103 246-3: "Satellite Earth Stations and Systems (SES); GNSS based location systems; Part 3: Performance requirements".

[4] ETSI TS 103 246-4: "Satellite Earth Stations and Systems (SES); GNSS based location systems; Part 4: Requirements for location data exchange protocols".

2.2 Informative references

References are either specific (identified by date of publication and/or edition number or version number) or non-specific. For specific references, only the cited version applies. For non-specific references, the latest version of the reference document (including any amendments) applies.

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The following referenced documents are not necessary for the application of the present document but they assist the user with regard to a particular subject area.

[i.1] ETSI TR 103 183: "Satellite Earth Stations and Systems (SES); Global Navigation Satellite Systems (GNSS) based applications and standardisation needs".

[i.2] ETSI TS 137 571-1: "Universal Mobile Telecommunications System (UMTS); LTE; Universal Terrestrial Radio Access (UTRA) and Evolved UTRA (E-UTRA) and Evolved Packet Core (EPC); User Equipment (UE) conformance specification for UE positioning; Part 1: Conformance test specification (3GPP TS 37.571-1)".

[i.3] IEEE 802.11™: "Wireless Local Area Networks".

[i.4] IEEE 802.15.1™: for Bluetooth.

[i.5] IEEE 802.15.4a™: for low rate WPAN.

[i.6] ETSI TS 145 001: "Digital cellular telecommunications system (Phase 2+); Physical layer on the radio path; General description (3GPP TS 45.001)".

[i.7] ETSI TS 125 104: "Universal Mobile Telecommunications System (UMTS); Base Station (BS) radio transmission and reception (FDD) (3GPP TS 25.104)".

[i.8] ETSI TS 136 171: "LTE; Evolved Universal Terrestrial Radio Access (E-UTRA); Requirements for Support of Assisted Global Navigation Satellite System (A-GNSS) (3GPP TS 36.171)".

[i.9] M.M. Desu, D. Raghavarao: "Non-parametric Statistical Methods For Complete and Censored Data", CRC press, 29th September 2003.

[i.10] RINEX: The Receiver Independent Exchange Format Version 2.10.

[i.11] RINEX: The Receiver Independent Exchange Format Version 3.02.

3 Definitions, symbols and abbreviations

3.1 Definitions

For the purposes of the present document, the terms and definitions given in ETSI TS 103 246-1 [1] and the following apply:

accuracy (or error): difference between a measured or estimated value and its real value

almanac: information providing coarse orbit and coarse clock model information for GNSS satellites. Database providing location information for a reference network used for positioning

assistance: use of position data from, typically, a telecommunications network to enable a GBLS receiver to acquire and calculate position more quickly (e.g. A-GNSS)

availability: measures percentage of time when a location system is able to provide the required location-related data

class A, B, C: classes categorize the performance level of the GBLS for a given performance feature

NOTE: In all cases Class A is the highest performance class and C is the lowest.

cold-start: condition of the GBLS GNSS receiver having no accurate prior information on the position, velocity and time of the location target, or on the positions of any of the GNSS satellites

continuity: likelihood that the navigation signal-in-space supports accuracy and integrity requirements for duration of intended operation

NOTE: Continuity aids a user to start an operation during a given exposure period without an interruption of this operation and assuming that the service was available at beginning of the operation. Related to the Continuity concept, a Loss of Continuity occurs when the user is forced to abort an operation during a specified time interval after it has begun (the system predicts service was available at start of operation).

continuity risk: probability of detected but unscheduled navigation interruption after initiation of an operation

electromagnetic interference: any source of RF transmission that is within the frequency band used by a communication link, and that degrades the performance of this link

NOTE: Jamming is a particular case of electromagnetic interference.

estimator: rule in statistics for calculating an estimate of a given quantity based on observed data

GNSS Signal Generator (GSG): device or system capable of generating simulated GNSS satellite transmissions in order to create the required test environment for the GNSS sensor under test

Horizontal Dilution Of Precision (HDOP): measure of position determination accuracy that is a function of the geometrical layout of the satellites used for the fix, relative to the receiver antenna

integrity: measure of the trust in the accuracy of the location-related data provided by the location system

NOTE: Integrity is expressed through the computation of a protection level. The Integrity function includes the ability of the location system to provide timely and valid warnings to users when the system does not fulfil the condition for intended operation. Specifically, a location system is required to deliver a warning (an alert) of any malfunction (as a result of a set alert limit being exceeded) to users within a given period of time (time-to-alert). Related to the Integrity concept, a Loss of Integrity event occurs when an unsafe condition occurs without annunciation for a time longer than the time-to-alert limit.

integrity risk: risk that the positioning error is greater than the protection level

jamming: deliberate transmission of interference to disrupt processing of wanted signals (which in this case are GNSS or telecommunications signals)

location: 3-dimensional position or location

location-based application: application that is able to deliver a location-based service to one or several users

location-based service: service built on the processing of the Location-related data associated with one or several location targets

location-related data: set of data associated with a given location target, containing at least one or several of the following time-tagged information elements: location target position, location target motion indicators (velocity and acceleration), and Quality of Service indicators (estimates of the position accuracy, reliability or authenticity)

NOTE: This data is the main output of a Location system.

location system: system responsible for providing to a location based application the Location-related data of one or several location targets

location target: physical entity on whose position the location system builds the location-related data

NOTE: This entity may be mobile or stationary.

meaconing: interception and rebroadcast of navigation signals, typically with power higher than the original signal, to falsify positioning

percentile: percentage of a set of observations of a parameter which give a successful result (i.e. success rate)

performance feature: set of performance requirements for a given location-related data category produced by the GBLS

position: 3-dimensional position or location

positioning: process of determining the position or location of a location target

Protection Level (PL): upper bound to the positioning error such that the probability: $P(\varepsilon > PL) < I_{risk}$, where I_{risk} is the integrity risk and ε is the position error

NOTE: The *protection level* is provided by the location system, and with the integrity risk, is one of the two sub-features of the *integrity* system.

Pseudo-Random Noise Code (PRN): unique binary code (or sequence) transmitted by a GNSS satellite to allow a receiver to determine the travel time of the radio signal from satellite to receiver

spoofer: device or system that generates false GNSS signals intended to deceive location processing into reporting false *location target* data e.g. meaconing

spoofing: transmission of signals intended to deceive location processing into reporting false *location target* data e.g. meaconing

time-to-alert: time from when an unsafe integrity condition occurs to when an alerting message reaches the user

vertical axis: axis locally defined for the *location target*, collinear to the zenith/nadir axis

WGS84: reference coordinate system used by the Global Positioning System

3.2 Symbols

For the purposes of the present document, the symbols given in ETSI TS 103 246-1 [1] apply.

3.3 Abbreviations

For the purposes of the present document, the abbreviations given in ETSI TS 103 246-1 [1] and the following apply:

3GPP	3rd Generation Partnership Project
A-GNSS	Assisted GNSS
AT	Along-Track
BDS	BeiDou Navigation Satellite System
CL	Confidence Level
CT	Cross-Track
DGE	Data Gathering Equipment
DUT	Device Under Test
ENU	East/North/Up reference frame
EN	East/North reference frame
E-UTRA	Evolved - UMTS Terrestrial Radio Access
FFS	For Further Study
GBLS	GNSS Based Location System
GEO	Geostationary Earth Orbit
GLONASS	Global Navigation Satellite System (Russian based system)
GMLC	Gateway Mobile Location Centre
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
GSG	GNSS Signal Generator
GSM	Global System for Mobile communications
HDOP	Horizontal Dilution Of Precision
HPE	Horizontal Positioning Error
HPL	Horizontal Protection Level
ITS	Intelligent Transport Systems
LoS	Line of Sight
LPP	LTE Positioning Protocol
LPPe	LTE Positioning Protocol extension
LTE	Long-Term Evolution
n/a	Not Applicable
PL	Protection Level
PVT	Position, Velocity and Time
RF	Radio Frequency
SMLC	Serving Mobile Location Centre
SNR	Signal-to-Noise Ratio
TBD	To Be Defined
TTFF	Time-To-First-Fix
UMTS	Universal Mobile Telecommunications System
UTRA	UMTS Terrestrial Radio Access
Wi-Fi	Wireless Fidelity
WPAN	Wireless Personal Area Network

4 General

4.1 GBLS Performance Features

The following clauses define the test procedures required to test conformance with the Performance Features defined in ETSI TS 103 246-3 [3].

These Features are:

1) Horizontal Position Accuracy.

2) Vertical Position Accuracy.

3) Time-to-First-Fix (TTFF).

4) Position Authenticity.

5) Robustness to Interference.

6) GNSS Sensitivity.

7) Position Integrity (Protection Level).

NOTE: The test procedure for the feature "GNSS Time Accuracy" defined in ETSI TS 103 246-3 [3] is FFS.

4.2 Conformance Test Statistics

Performance requirements in ETSI TS 103 246-3 [3] are expressed either as a single value or, when it has a statistical nature, as a success rate.

When testing a parameter with a statistical nature, a confidence level is set in the conformance test defined herein which establishes the probability that the GBLS passing the test meets the requirement and determines how many times a test has to be repeated.

4.3 GBLS Performance Class Determination

Performance features are defined in ETSI TS 103 246-3 [3] for GBLS performance classes A, B and C.

Results of the conformance tests herein allow a GBLS to be allocated to one of the three classes according to the definition in ETSI TS 103 246-3 [3], unless otherwise specified.

5 General test conditions

5.1 Introduction

This clause defines the common test conditions required for all tests in the remainder of the document, unless otherwise specified.

5.2 Environmental conditions

The environmental conditions for test will be defined by the GBLS vendor.

5.3 GNSS signal conditions

5.3.1 Applicable GNSS constellations

The applicable GNSS's are defined in clause A.2 of ETSI TS 103 246-3 [3].

Each test defined in the following clauses shall be performed with the combination of GNSS constellation(s) and satellite signal(s) simultaneously supported by the GBLS under test.

5.3.2 GNSS signal level

The GNSS signal is defined at the GNSS antenna connector of the GBLS. For a GBLS with only an integral GNSS antenna, this is assumed to be an antenna with a gain of 0dBi. The reference input signal power levels are defined in table 5.1.

Table 5.1: Reference Power and Relative signal power levels for each GNSS signal type

	Galileo		**GPS/Modernized GPS**		**GLONASS**		**BDS** (Note 2)	
Reference power (dBm)		-130		-128,5		-131		-130
Signal power level relative to reference power level (dB)	E1	0	L1 C/A	0	G1	0	B1 D1	0
	E6	+2	L1C	+1,5	G2	-6	B1 D2	+5
	E5	+2	L5	+3,6				
NOTE 1: The GNSS signal power levels in the above table represent the total signal power per channel for pilot and data channels. NOTE 2: For test cases which involve "BeiDou", D1 represents MEO/IGSO satellites of B1I signal type and D2 represents GEO satellites of B1I signal type.								

5.3.3 GNSS frequency

GNSS signals shall be transmitted with a frequency accuracy of ±2,5 × 10E-8.

5.3.4 GNSS Multi-system Time Offsets

If more than one GNSS is used in a test, the accuracy of the GNSS-GNSS Time Offsets at the GSG shall be better than 1 ns. The particular case where the GBLS uses D-GNSS, RTK or PPP is FFS.

5.4 Operational Environments

General operational environments are as defined in clause A.3 of ETSI TS 103 246-3 [3], and specifically in each of the clauses for Performance Features in ETSI TS 103 246-3 [3].

5.5 Assistance Data

Any assistance data required by the GBLS shall relate to the scenario(s) being generated and shall be provided by the appropriate means (e.g. by simulating a server such as an SLP, GMLC, SMLC and by transmission over a suitable telecommunications link).

5.6 Test Configurations

5.6.1 General Set-Up

In general the tests for GBLS signal performance shall be conducted using RF simulators generating GNSS and telecoms transmission and reception signals and other sensor simulators, connected either:

1) using antennas in an anechoic chamber (e.g. if the GBLS has integral antennas); or

2) with wired RF connections only when access to the GBLS antenna connectors is available.

5.6.2 GNSS Signal Generator

In each case the test set-up consists of a GNSS Signal Generator (GSG) connected to the GBLS input and generating a set of emulated GNSS RF signals as defined in clause 5.3 above and in annex A of ETSI TS 103 246-3 [3].

The GSG shall simulate atmospheric effects (ionosphere, etc.) as specified in annex B.

The GSG shall simulate the satellites that satisfy all the following conditions:

- elevation > 5 degrees from the GBLS GNSS sensor position (clause B.1);
- those that are practically visible by the GBLS in sky attenuation conditions applicable to the relevant test (see clause A.3.2 of ETSI TS 103 246-3 [3]) (i.e. where sky attenuation < 100 dB).

In any case the maximum number of satellites to be simulated per constellation is given in table 5.2 below. The selection of these visible satellites shall be at the discretion of the test operator.