INTERNATIONAL STANDARD

ISO 9241-920

First edition 2009-03-15

Ergonomics of human-system interaction —

Part 920: **Guidance on tactile and haptic interactions**

Ten STErgonomie de l'interaction homme-système —
Partie 920: Lignes directrices relatives aux interactions tactiles et haptiques

ISO 9241-920:2009 https://standards.iteh.ai/catalog/standards/sist/ff4681a9-78dd-4440-88ea-9f37896871b0/iso-9241-920-2009



PDF disclaimer

This PDF file may contain embedded typefaces. In accordance with Adobe's licensing policy, this file may be printed or viewed but shall not be edited unless the typefaces which are embedded are licensed to and installed on the computer performing the editing. In downloading this file, parties accept therein the responsibility of not infringing Adobe's licensing policy. The ISO Central Secretariat accepts no liability in this area.

Adobe is a trademark of Adobe Systems Incorporated.

Details of the software products used to create this PDF file can be found in the General Info relative to the file; the PDF-creation parameters were optimized for printing. Every care has been taken to ensure that the file is suitable for use by ISO member bodies. In the unlikely event that a problem relating to it is found, please inform the Central Secretariat at the address given below.

iTeh STANDARD PREVIEW (standards.iteh.ai)

ISO 9241-920:2009 https://standards.iteh.ai/catalog/standards/sist/ff4681a9-78dd-4440-88ea-9f37896871b0/iso-9241-920-2009



COPYRIGHT PROTECTED DOCUMENT

© ISO 2009

All rights reserved. Unless otherwise specified, no part of this publication may be reproduced or utilized in any form or by any means, electronic or mechanical, including photocopying and microfilm, without permission in writing from either ISO at the address below or ISO's member body in the country of the requester.

ISO copyright office
Case postale 56 • CH-1211 Geneva 20
Tel. + 41 22 749 01 11
Fax + 41 22 749 09 47
E-mail copyright@iso.org
Web www.iso.org

Published in Switzerland

Contents

Page

Forewordv		
Introductionvi		
1	Scope1	
2	Applying ISO 9241-9201	
2.1	Recommendations1	
2.2	Evaluation of products1	
3	Tactile/haptic inputs, outputs, and/or combinations2	
3.1	General guidance on tactile/haptic inputs, outputs and/or combinations2	
3.1.1	Optimizing performance	
3.1.2	Providing accessible information on tactile/haptic elements2	
3.1.3	Providing contextual information	
3.1.4	Using consistent labels	
3.1.5 3.1.6	Identifying system state	
3.1.6	Providing alternative input methods	
3.1.8		
3.1.9	Maintaining coherence between modalities	
3.1.10	Presenting realistic experiences	
3.1.11	Presenting realistic experiences	
3.2	Intentional individualization5	
3.2.1	Enabling users to change modalities, 241-920 2009	
3.2.2	Enabling force feedback override	
3.2.3	Enabling users to individualise tactile parameters Unintentional user perceptions	
3.3		
3.3.1	Limiting acoustic output of tactile/haptic display5 Limiting heat gain of contact surface5	
3.3.2 3.3.3	Avoiding sensory adaptation	
3.3.4	Recovering from sensory adaptation	
3.3.5	Avoiding unintended perceptual illusions	
3.3.6	Preventing temporal masking	
4	Attributes of tactile and haptic encoding of information	
4 4.1	High level guidance on tactile/haptic encoding of information	
4.1.1	Using familiar tactile/haptic patterns	
4.1.2	Making tactile/haptic encoding obvious	
4.1.3	Conformity to user expectations	
4.1.4	Using sensory substitution	
4.1.5	Using appropriate spatial addressability and resolution7	
4.1.6	Using tactile apparent location7	
4.1.7	Using distal body parts for high spatial resolution7	
4.1.8	Using higher addressability for trained users7	
4.1.9	Using tactile apparent motion	
4.1.10	Preventing spatial masking	
4.2 4.2.1	Guidance on specific tactile/haptic attributes for encoding information	
4.2.1 4.2.2	Selecting dimensions for encoding information Discriminating between attribute values	
4.2.3	Limiting the number of attribute values	
4.2.4	Combining properties	
4.2.5	Limiting complexity	
4.2.6	Encoding by object shape	
427	Encoding information by temporal pattern	

1.2.8	Encoding information using vibration amplitude		
1.2.9	Encoding information by vibration frequency		
1.2.10	Encoding by location		
1.2.11	Encoding by temperature		
1.2.12	Encoding by thermal conductivity		
1.2.13	Identifying information values	10	
=	Content-specific encoding	11	
5.1	Encoding and text data		
5.2	Encoding and using graphical data		
5.2.1	Displaying tactile/haptic graphics		
5.2.2	Using grids on tactile graphs		
5.2.3	Using landmarks in tactile maps		
5.2.4	Providing scales for tactile maps		
5.3	Encoding and using controls	1 2 1 2	
5.3.1	Using tactile/haptic controls		
5.3.2	Using size and spacing of controls to avoid accidental activation	12	
5.3.3	Avoiding difficult control actions		
5.3.4	Using force to avoid accidental activation		
5.3.5	Interacting with controls		
).J.J			
3	Design of tactile/haptic objects and space	13	
3.1	Tactile/haptic display spaces		
6.1.1	Ease of perceiving multiple tactile/haptic objects	13	
5.1.2	Ease of identifying adjacent tactile/haptic objects		
5.1.3	Maintaining separation between surfaces of objects	13	
5.1.4	Separating tactile/haptic elements	14	
6.1.5	Avoiding empty spaces	14	
6.1.6	Avoiding volume limits	14	
6.1.7	Avoiding falling out of the tactile/haptic space	14	
6.2	Objects Using appropriate object size. Using discriminable tactile/haptic/symbols/dards/sist/ff4681a9-78dd-4440-88ea-	14	
3.2.1	Using appropriate object size <u>ISO 9241-920:2009</u>	14	
5.2.2	Creating discriminable tactile/haptic/symbols/dards/sist/ff4681a9-78dd-4440-88ea-	14	
6.2.3	Creating tactile/haptic symbols from visual symbols -920-2009	15	
6.2.4	Tactile/haptic object angles	15	
6.2.5	Tactile/haptic object corners	15	
•	Intercettor	4 -	
7	Interaction		
7.1 7.1.1	Navigating tactile/haptic space Providing navigation information		
	Supporting path planning		
7.1.2 7.1.3			
7.1.3 7.1.4	Providing well-designed paths		
7.1. 4 7.1.5	Providing appropriate navigation techniques		
7.1.6			
7.1. 6 7.1.7	Providing navigational aids		
	Understanding the tactile/haptic space		
7.1.8			
7.2 7.2.1	Reconfiguration		
7.3	Interaction techniques		
7.3.1	Implementing interaction techniques		
7.3.2	Avoiding unintended oscillation	1/	
Annex	A (informative) Overview of the ISO 9241 series	18	
` ,			
poildic	raphy	22	

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 9241-920 was prepared by Technical Committee ISO/TC 159, *Ergonomics*, Subcommittee SC 4, *Ergonomics of human-system interaction*.

ISO 9241 consists of the following parts, under the general title Ergonomic requirements for office work with visual display terminals (VDTs): (standards.iteh.ai)

- Part 1: General introduction
- ISO 9241-920:2009
- Part 2: Guidance on task requirements log/standards/sist/ff4681a9-78dd-4440-88ea-9f37896871b0/iso-9241-920-2009
- Part 4: Keyboard requirements
- Part 5: Workstation layout and postural requirements
- Part 6: Guidance on the work environment
- Part 9: Requirements for non-keyboard input devices
- Part 11: Guidance on usability
- Part 12: Presentation of information
- Part 13: User guidance
- Part 14: Menu dialogues
- Part 15: Command dialogues
- Part 16: Direct manipulation dialogues
- Part 17: Form filling dialogues

ISO 9241 also consists of the following parts, under the general title Ergonomics of human-system interaction:

- Part 20: Accessibility guidelines for information/communication technology (ICT) equipment and services
- Part 110: Dialogue principles
- Part 151: Guidance on World Wide Web user interfaces

ISO 9241-920:2009(E)

- Part 171: Guidance on software accessibility
- Part 210: Human-centred design for interactive systems
- Part 300: Introduction to electronic visual display requirements
- Part 302: Terminology for electronic visual displays
- Part 303: Requirements for electronic visual displays
- Part 304: User performance test methods for electronic visual displays
- Part 305: Optical laboratory test methods for electronic visual displays
- Part 306: Field assessment methods for electronic visual displays
- Part 307: Analysis and compliance test methods for electronic visual displays
- Part 308: Surface-conduction electron-emitter displays (SED) [Technical Report]
- Part 309: Organic light-emitting diode (OLED) displays [Technical Report]
- Part 400: Principles and requirements for physical input devices
- Part 410: Design criteria for products for physical input devices
- Part 920: Guidance on tactile and haptic interactions

The following parts are under preparation:

standards.iteh.ai)

DARD PREVIEW

- Part 100: Introduction to standards related to software ergonomics
- Part 129: Guidance on software individualization z/standards/sist/ff4681a9-78dd-4440-88ea-
- 0/iso-9241-920-2009 Part 420: Selection procedures for physical input devices
- Part 910: Framework for tactile and haptic interaction

Forms-based dialogues and design guidance for interactive voice response (IVR) applications are to form the subjects of future parts 143 and 154.

Introduction

Tactile and haptic interactions are becoming increasingly important as candidate interaction modalities in computer systems such as special-purpose computing environments (e.g. simulation) and in assistive technologies. While considerable research exists, a lack of ergonomic standards in this area could result in systems being developed without sufficient concern for either ergonomics or interoperability, leading to serious ergonomic difficulties for users of multiple, incompatible or conflicting tactile/haptic devices/applications. This part of ISO 9241 provides ergonomics recommendations for tactile and haptic hardware and software interactions, including guidance related to the design and evaluation of hardware, software, and combinations of hardware and software interactions. The guidelines are not technology-dependent and will also be applicable to future technologies.

iTeh STANDARD PREVIEW (standards.iteh.ai)

ISO 9241-920:2009 https://standards.iteh.ai/catalog/standards/sist/ff4681a9-78dd-4440-88ea-9f37896871b0/iso-9241-920-2009

© ISO 2009 – All rights reserved

iTeh STANDARD PREVIEW (standards.iteh.ai)

ISO 9241-920:2009 https://standards.iteh.ai/catalog/standards/sist/ff4681a9-78dd-4440-88ea-9f37896871b0/iso-9241-920-2009

Ergonomics of human-system interaction —

Part 920:

Guidance on tactile and haptic interactions

1 Scope

This part of ISO 9241 gives recommendations for tactile and haptic hardware and software interactions. It provides guidance on the design and evaluation of hardware, software, and combinations of hardware and software interactions, including

- the design/use of tactile/haptic inputs, outputs, and/or combinations of inputs and outputs, with general guidance on their design/use as well as on designing/using combinations of tactile and haptic interactions for use in combination with other modalities or as the exclusive mode of interaction,
- the tactile/haptic encoding of information, including textual data, graphical data and controls,
- the design of tactile/haptic objects, ANDARD PREVIEW
- the layout of tactile/haptic space, and
- interaction techniques.
 ISO 9241-920;2009
 https://standards.iteh.ai/catalog/standards/sist/ff4681a9-78dd-4440-88ea-

It does not provide recommendations specific to Braille, but can apply to interactions that make use of Braille.

The recommendations given in this part of ISO 9241 are applicable to at least the controls of a virtual workspace, but they can also be applied to an entire virtual environment — consistent, in as far as possible, with the simulation requirements.

NOTE It is recognized that some interactive scenarios might be constrained by the limitation that a real workspace is to be modelled in a virtual environment. Objects can be in suboptimal positions or conditions for haptic interaction by virtue of the situation being modelled.

2 Applying ISO 9241-920

2.1 Recommendations

Individual recommendations given in Clauses 5 to 7 should be evaluated for their applicability. The applicable recommendations should be implemented unless there is evidence that to do so would cause deviation from the design objectives.

2.2 Evaluation of products

If a product is claimed to have met the applicable recommendations in this part of ISO 9241 then the procedures used to establish the product's requirements, and to evaluate the product, shall be specified. The level of detail of the specification is a matter of negotiation between the involved parties.

© ISO 2009 – All rights reserved

3 Tactile/haptic inputs, outputs, and/or combinations

3.1 General guidance on tactile/haptic inputs, outputs and/or combinations

3.1.1 Optimizing performance

The system should be optimized to take account of the following.

- The accuracy of available devices, the accuracy of the user, and the required accuracy of the task.
- b) The ability of a user to control the speed and the force involved in operations.
 - NOTE 1 High speed of user actions is inconsistent with accurate control of force, and vice versa.
- c) Active exploration over passive exploration, when appropriate.
 - NOTE 2 This can increase kinaesthetic perception.
- d) Multiple point-of-contact operation, when possible and appropriate.
 - NOTE 3 This can reduce errors and improve tactile perception.
 - EXAMPLE The use of two hands in reading Braille can improve efficiency.
- e) The overall amount and distributed nature of cognitive and sensory task demands.
 - NOTE 4 Effectiveness of tactile and haptic inputs is affected by overall workload, conflict among multi-task demands, and/or overload or decrement of particular sensory information channels.

3.1.2 Providing accessible information on tactile/haptic elements

The system should provide accessible descriptions of all tactile/haptic user interface elements, whether those descriptions are automatically presented or not.

NOTE Information can be presented by text, sound labels, synthetic speech, sign language or as Braille text.

EXAMPLE Ability to determine file size or file location.

3.1.3 Providing contextual information

The system should provide a context to help the user to understand the meaning of the tactile/haptic perception and the environment or program.

- NOTE 1 Contextual information that is helpful includes information about the purpose of the program, and information about possibilities and pitfalls in the environment.
- NOTE 2 Contextual information can be in the form of a short text message, such as a caption under an image or model, provided as speech, sign language or Braille.

3.1.4 Using consistent labels

Labels of user interface elements that are presented in a tactile/haptic modality should

- a) be consistent in size and distances from other tactile objects,
- b) be located according to a consistent rule,
- be uniformly oriented.

NOTE Labels that contain the same information or function need to be equal in form, symbol usage and/or text.

3.1.5 Identifying system state

The system should provide information that allows the user to know which task or function is active.

3.1.6 Minimizing fatigue

The system should

- a) ensure user comfort over extended periods of time, and
- b) avoid or minimize user fatigue.

NOTE Minimization of tactile fatigue can be achieved by

- careful choice of body location for stimulation,
- careful choice of method of contact with the body,
- careful choice of stimulus frequency,
- choosing the lowest effective magnitude of the stimulus,
- reducing minute, precise joint rotations, particularly at proximal segments,
- not using static positions at or near the end of the range of motion, and/or
- not expecting users to overreach to discover the full extent of the display.

3.1.7 Providing alternative input methods

ISO 9241-920:2009

The system should enable users to accomplish the same function in a number of ways, with at least one of these not requiring fine manipulation skills on the part of the user?

NOTE The most efficient, logical or effective input/control mechanism for a majority of users might be difficult, if not impossible, to use by individual users with disabilities.

EXAMPLE One-handed (either left or right) operation is used.

3.1.8 Maintaining coherence between modalities

The system should maintain coherence, where appropriate, between the tactile/haptic modality and other modalities, including the descriptions of actions.

NOTE 1 The visual perception of objects can bias, and be biased by, the tactile/haptic perception of objects. This can also occur between the tactile/haptic modality and other modalities.

NOTE 2 Aspects of coherence (amodal attributes) can include

- size.
- orientation,
- shape,
- mapping,
- separation of objects, and
- temporal presentation.

ISO 9241-920:2009(E)

- NOTE 3 Coherence also includes relative location of on-screen controls, including the directions in which they can be moved.
- NOTE 4 Incoherence can cause confusion and control instabilities in multimodal systems.

3.1.9 Combining modalities

The combining of modalities is recommended, as it can have the following effects.

- a) Reinforcement of information obtained from purely tactile/haptic interactions.
 - EXAMPLE A sound when an object is struck.
- b) Provision of additional information not presented via tactile/haptic interactions.
 - NOTE 1 The resulting combinations can enhance spatial memory and the identification and exploration of objects and their attributes.
 - NOTE 2 Combination of modalities can contradict information obtained from purely tactile/haptic interactions. (See 3.1.8.)
 - EXAMPLE Information on the colour of an object.
- c) Compensation for sensory channels that are diminished or overloaded.
 - NOTE 3 Tactile cues can be particularly effective when audio or visual cues are less effective (e.g. high noise, low visibility).

3.1.10 Presenting realistic experiences (standards.iteh.ai)

While the use of real world experiences (e.g. following the laws of physics) can enhance the user's understanding, deviating from real world experiences may be used to

- a) simplify and focus on important features, and/or
- b) explore new experiences.

NOTE There are several cases — especially in designing interface widgets — where the slightly unreal, yet well-designed, behaviour of a virtual object makes it easier to use.

EXAMPLE Properties of an object (e.g. size, frequency of its vibration) are changed as it is approached by the user, even though these properties would not change in the real world.

3.1.11 Isolation of individual interface elements

The system should prevent unintended effects on non-activated interface elements due to the activation of a nearby interface element.

EXAMPLE 1 Because there is a high risk of unintentional vibration where the nearby actuator vibrates at the same resonant frequency, a rigid surround is installed to reduce the spreading of vibration.

EXAMPLE 2 Mechanical or electrical crosstalk between different tactile/haptic channels is reduced in order to minimize any unintentional perceptual illusion.