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**Surface chemical analysis — Scanning-  
probe microscopy — Determination of  
cantilever normal spring constants**

*Analyse chimique des surfaces — Microscopie à sonde à balayage —  
Détermination de constantes normales en porte-à-faux de ressort*

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## Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see [www.iso.org/directives](http://www.iso.org/directives)).

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For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the WTO principles in the Technical Barriers to Trade (TBT) see the following URL: [Foreword - Supplementary information](#).

The committee responsible for this document is ISO/TC 201, *Surface chemical analysis*, Subcommittee SC 9, *Scanning probe microscopy*.

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## Introduction

Atomic force microscopy (AFM) is a mode of scanning probe microscopy (SPM) used to image surfaces by mechanically scanning a probe over the surface in which the deflection of a sharp tip sensing the surface forces mounted on a compliant cantilever is monitored. It can provide amongst other data, topographic, mechanical, chemical, and electro-magnetic information about a surface depending on the mode of operation and the property of the tip. Accurate force measurements are needed for a wide variety of applications, from measuring the unbinding force of protein and other molecules to determining the elastic modulus of materials, such as organics and polymers at surfaces. For such force measurements, the value of the AFM cantilever normal spring constant,  $k_z$ , is required. The manufacturers' nominal values of  $k_z$  have been found to be up to a factor of three in error, therefore practical methods to calibrate  $k_z$  are required.

This International Standard describes five of the simplest methods in three categories for the determination of normal spring constants for atomic force microscope cantilevers. The methods are in one of the three categories of dimensional, static experimental, and dynamic experimental methods. The method chosen depends on the purpose and convenience to the analyst. Many other methods may also be found in the literature.

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# Surface chemical analysis — Scanning-probe microscopy — Determination of cantilever normal spring constants

## 1 Scope

This International Standard describes five of the methods for the determination of normal spring constants for atomic force microscope cantilevers to an accuracy of 5 % to 10 %. Each method is in one of the three categories of dimensional, static experimental, and dynamic experimental methods. The method chosen depends on the purpose, convenience, and instrumentation available to the analyst. For accuracies better than 5 % to 10 %, more sophisticated methods not described here are required.

## 2 Normative references

The following documents, in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 18115-2, *Surface chemical analysis — Vocabulary — Part 2: Terms used in scanning-probe microscopy*

## 3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 18115-2 and the following apply.

### 3.1

**normal spring constant**  
**spring constant**  
**force constant**

DEPRECATED: cantilever stiffness

$k_z$

<AFM> quotient of the applied normal force at the *probe tip* (3.2) by the deflection of the cantilever in that direction at the probe tip position

Note 1 to entry: See lateral spring constant, torsional spring constant.

Note 2 to entry: The normal spring constant is usually referred to as the spring constant. The full term is used when it is necessary to distinguish it from the lateral spring constant.

Note 3 to entry: The force is applied normal to the plane of the cantilever to compute or measure the normal force constant,  $k_z$ . In application, the cantilever in an AFM may be tilted at an angle,  $\theta$ , to the plane of the sample surface and the plane normal to the direction of approach of the tip to the sample. This angle is important in applying the normal spring constant in AFM studies.

### 3.2

**probe tip**  
**tip**  
**probe apex**

structure at the extremity of a probe, the apex of which senses the surface

Note 1 to entry: See *cantilever apex* (3.3).

### 3.3

**cantilever apex**

end of the cantilever furthest from the cantilever support structure

Note 1 to entry: See *probe apex* (3.2), *tip apex* (3.2).

## 4 Symbols and abbreviated terms

In the list of abbreviated terms below, note that the final “M”, given as “Microscopy”, may be taken equally as “Microscope” depending on the context. The abbreviated terms are:

AFM	Atomic force microscopy
FEA	Finite element analysis
PSD	Power spectral density
SEM	Scanning electron microscopy
SPM	Scanning probe microscopy

The symbols for use in the formulae and as abbreviated terms in the text are:

$A$	amplitude of cantilever at a certain frequency
$A_0$	amplitude of a cantilever at its fundamental resonant frequency
$A_{\text{white}}$	mean amplitude of a cantilever associated with white noise
$B_{\Phi}$	gradient determined from a straight line fit to values of $L_x$ versus $\Phi_x^{1/3}$
$B_k$	gradient determined from a straight line fit to values of $L_x$ versus $(k_z^{L_x})^{-1/3}$
$C_1$	correction factor for the thermal vibration method described in 8.2
$C_2$	correction factor for the thermal vibration method described in 8.2
$d$	distance between the probe tip and the cantilever apex
$D$	height of the probe tip
$e$	width of the V-shaped cantilever at a distance $L_0$ from the apex
$E$	Young’s modulus of the material of a cantilever
$E_B$	Young’s modulus of the base material of a cantilever
$E_C$	Young’s modulus of the coating material on a cantilever
$f$	frequency
$f_0$	fundamental resonant frequency of a cantilever
$F$	force of a nanoindenter
$h$	displacement of a nanoindenter
$i$	index of $P_i$ , where $i = 1$ to 5
$k_B$	Boltzmann constant
$k_z$	normal spring constant
$k_z^{L_x}$	normal spring constant at the position $L_x$ along a cantilever



$k_z^R$	normal spring constant of a reference cantilever
$k_z^W$	normal spring constant of a working cantilever
$k_z(t_c=0)$	normal spring constant of a cantilever with a coating thickness of 0
$L$	length of a rectangular cantilever or the effective length of a V-shaped cantilever
$L_x$	distance between the base of a cantilever and the effective position of a V-shaped cantilever
$L_0$	length of a V-shaped cantilever between the apex and the start of the arms
$L_1$	length of a V-shaped cantilever between the base and the start of the arms
$P_i$	label of one of the five positions on the reference cantilever axis
$Q$	quality factor of a cantilever
$r$	term defined by Formula (7)
$t$	thickness of a cantilever
$t_B$	thickness of the bulk material of a cantilever
$t_C$	thickness of a coating on a cantilever
$T$	absolute temperature of the cantilever measured in Kelvins
$u_{A0}$	standard uncertainty in $A_0$
$u_B$	standard uncertainty in $B$
$u_{C1}$	standard uncertainty in $C_1$
$u_{C2}$	standard uncertainty in $C_2$
$u_d$	standard uncertainty in the distance between the probe tip and the cantilever apex
$u_E$	standard uncertainty in the Young's modulus of a cantilever
$u_F$	standard uncertainty due to the calibration of force in the nanoindenter
$u_{f0}$	standard uncertainty in the resonant frequency
$u_h$	standard uncertainty due to the calibration of displacement in the nanoindenter
$u_{kz}$	standard uncertainty in the normal spring constant
$u_{kzR}$	standard uncertainty in the normal spring constant of the reference cantilever
$u_L$	standard uncertainty in the length of a cantilever
$u_Q$	standard uncertainty in the quality factor of a cantilever
$u_t$	standard uncertainty in the thickness of a cantilever
$u_T$	standard uncertainty in the absolute temperature
$u_w$	standard uncertainty in the width of a cantilever
$u_{x1}$	standard uncertainty in $x_1$

$u_{\alpha 1}$	standard uncertainty in $\alpha_1$
$u_{\rho}$	standard uncertainty in the density of a cantilever
$w$	width of a cantilever
$w_1$	width of one side of a trapezium
$w_2$	width of one side of a trapezium
$w_t$	$w \cos \theta$
$x_1$	offset to account for the small uncertainty in the true position of the base of the cantilever compared to an arbitrary reference point
$x_2$	offset to account for the uncertainty in the true position of the probe tip compared to an arbitrary reference point
$Z_1$	term defined by Formula (4)
$Z_2$	term defined by Formula (5)
$\alpha$	angle of the working cantilever with respect to the reference cantilever or surface
$\alpha_1$	numeric constant used in Formula (11)
$\delta_R$	average inverse gradient of the force-distance curve obtained with the working cantilever pressing on the reference cantilever or device
$\delta_W$	average inverse gradient of the force-distance curve obtained with the working cantilever pressing on a stiff surface
$\theta$	half angle between the arms of a V-shaped cantilever
$\theta_2$	term defined by Formula (6)
$\nu$	Poisson's ratio of the cantilever material
$\rho$	density of a cantilever
$\phi_x$	term defined by Formula (16)

## 5 General information

### 5.1 Background information

The spring constant,  $k_z$ , of an AFM cantilever is needed for quantitative force measurement. It is used to convert the deflection of the cantilever into a force. Applications that need this include the measurement of material properties at the nanoscale, such as elastic modulus, adhesive forces, and for studying the breaking of covalent bonds and protein unfolding. Depending on the application,  $k_z$  will be chosen to be in the range between 0,005 Nm<sup>-1</sup> and 200 Nm<sup>-1</sup>. There are two main shapes of cantilever: the rectangular "diving board" shape and the V-shaped. Both types vary slightly in basic shape and design between manufacturers and can be rectangular or trapezoidal in cross-section. Some cantilevers are also coated with a thin metallic layer. These factors all influence the value of  $k_z$ .

Many manufacturers provide data sheets for their cantilevers giving nominal values of  $k_z$ . Unfortunately, these values can be routinely in error by up to a factor of 3. One reason why similar cantilevers have very different values of  $k_z$  is that the spring constant is proportional to the thickness cubed and the thickness

of AFM cantilevers is difficult to control accurately during manufacture. Since the cantilevers wear out, break, and need regular replacement, quick and accurate methods to determine  $k_z$  are required.

## 5.2 Methods for the determination of AFM normal spring constant

There are many methods to determine the normal spring constant and these are classified as the following.

- The dimensional methods where  $k_z$  is determined from the cantilever material and the geometrical properties. In this method, any structural defects are not included.
- The static experimental methods where  $k_z$  is determined by measurement of the static deflection of the cantilever under an applied force.
- The dynamic experimental methods where  $k_z$  is determined by measurement of the dynamic properties of the cantilever.

In this International Standard, we describe procedures for a total of five methods with one or two methods in each category. Use one or more of the methods to determine  $k_z$  and its associated uncertainty,  $u_{k_z}$ . Which method or methods are used depends on the time, equipment, and the accuracy that the user requires the spring constant to be measured to. Some advantages and disadvantages of the methods are given in [Table 1](#).

**Table 1 — Summary of the advantages and disadvantages of the methods in ISO 11775**

Clause	Method	Advantages	Disadvantages
<a href="#">6</a>	Dimensional measurement	Simple. Allows one to see why $k_z$ varies from cantilever to cantilever.	Does not include defects. Slow and time consuming.
<a href="#">7</a>	Static experimental measurement using a reference cantilever or a nanoindenter	Can be made traceable to SI. <a href="https://standards.iteh.ai/catalog/standards/sist/4b25c75b-8a28-42b3-88ff-238717ab26e7/iso-11775-2015">https://standards.iteh.ai/catalog/standards/sist/4b25c75b-8a28-42b3-88ff-238717ab26e7/iso-11775-2015</a>	May potentially damage the cantilever. Can be time consuming and in some cases, requires a nanoindenter.
<a href="#">8</a>	Dynamic experimental measurement – thermal vibrational method	Fast if AFM instrument contains relevant software and hardware. Gives very good cantilever-to-cantilever comparability for cantilevers of a given design.	Uncertainty can be higher.

NOTE This International Standard does not include all the methods for calibrating  $k_z$  that are described in the literature.

## 6 Dimensional methods to determine $k_z$

### 6.1 General

The dimensional methods involve accurate measurements of a cantilever's geometry and knowledge of the material properties to determine  $k_z$ . The procedures described here use analytical formulae and are only applicable if the geometry is suitable. For other geometries, finite element analysis (FEA) is required and is not described here. Defects in the material, such as cracks or non-ideal geometry are not generally included.

### 6.2 $k_z$ using formulae requiring 3D geometric information

#### 6.2.1 Method

In order to determine  $k_z$  for a rectangular beam with a rectangular cross-section, as shown in [Figure 1](#), measure the thickness  $t$ , the width  $w$ , and the distance  $(L - d)$ , which is the length of the cantilever,  $L$ , minus the distance from the free end of the cantilever to the probe tip,  $d$ . The measurement methods for

these are given in 6.2.2. Also, obtain or measure, using an appropriate method, the value for the Young's modulus  $E$  of the cantilever.

Make at least seven independent measurements of those parameters that you are measuring by removing and replacing the cantilever. Evaluate the average values for these parameters and use them to calculate  $k_z$  using Formula (1) as detailed in 6.2.3.1, incorporating the averages of these independent measurements.

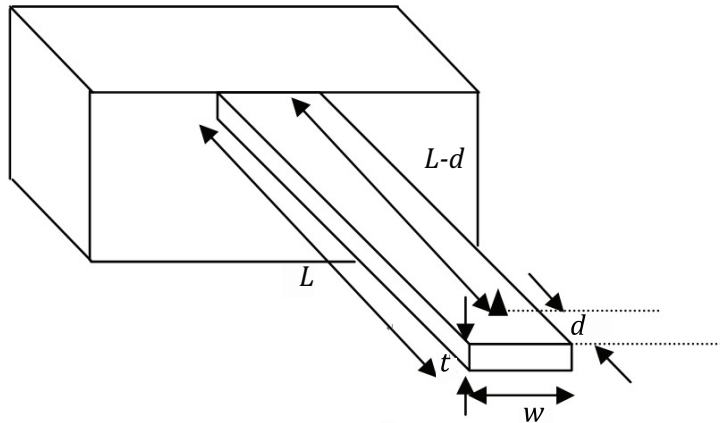
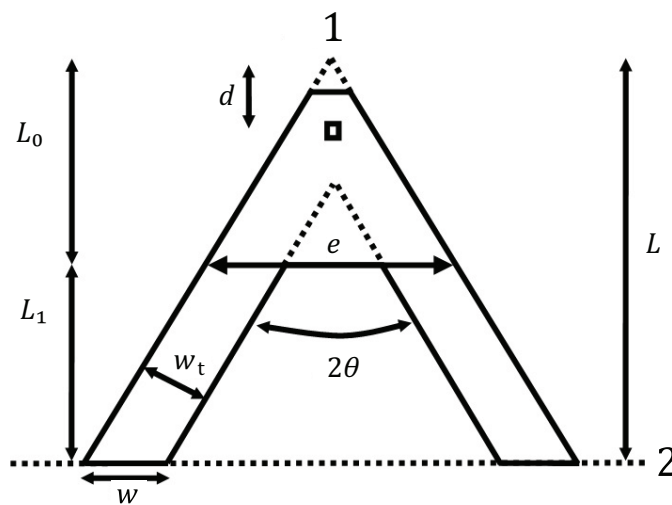


Figure 1 — Schematic of a rectangular shape cantilever with a probe tip a distance  $d$  from its free end

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Similarly, if you are using a V-shaped cantilever, as shown in Figure 2, measure  $L_0$ , the length of a V-shape cantilever between the (virtual) apex and the start of the arms;  $L_1$ , the length of a V-shape cantilever between base and the start of the arms;  $d$ , the distance between the probe tip and the cantilever apex;  $e$ , the width of the V-shaped cantilever at the distance  $L_0$  from the apex; and  $\theta$ , the half angle between the arms. Also, obtain or measure, using an appropriate method, Young's modulus  $E$  and Poisson's ratio of the cantilever  $\nu$ . Make at least seven independent measurements of those parameters that you are measuring by removing and replacing the cantilever. Evaluate the average values for these parameters and use them to calculate  $k_z$  using Formulae (3) to (7).



- Key
- 1 apex
  - 2 base

Figure 2 — Schematic of a V-shaped cantilever