# INTERNATIONAL STANDARD

# ISO 14839-1

First edition 2002-05-01

AMENDMENT 1 2010-11-01

# Mechanical vibration — Vibration of rotating machinery equipped with active magnetic bearings —

Part 1: Vocabulary

### iTeh STAMENDMENTREVIEW

### (standards.iteh.ai)

Vibrations mécaniques — Vibrations de machines rotatives équipées de paliers magnétiques actifs —

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Published in Switzerland

### Foreword

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Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

Amendment 1 to ISO 14839-1:2002 was prepared by Technical Committee ISO/TC 108, *Mechanical vibration*, shock and condition monitoring, Subcommittee SC 2, *Measurement and evaluation of mechanical vibration* and shock as applied to machines, vehicles and structures **DREVIEW** 

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# Mechanical vibration — Vibration of rotating machinery equipped with active magnetic bearings —

# Part 1: Vocabulary

### **AMENDMENT 1**

### Page v, Foreword

Add the following to the list of parts:

- Part 3: Evaluation of stability margin
- The following part is under preparation:
- Part 4: Technical guidelines

### (standards.iteh.ai)

Page 1, Clause 1

ISO 14839-1:2002/Amd 1:2010

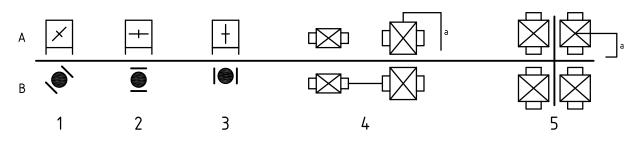
**ANDARD PREVIEW** 

After "active magnetic pearings" insert "and touch down bearings" 8-7153-474f-947d-

19acdff1910b/iso-14839-1-2002-amd-1-2010

Page 1, Clause 1

Replace Figure 1 by the following.



Key

- A simplified symbols (see ISO 8826-2)
- B conventional symbols
- 1 angular ball bearing
- 2 deep-groove ball bearing
- 3 thrust ball bearing
- 4 radial active magnetic bearing
- 5 axial active magnetic bearing
- <sup>a</sup> With sensor.

Page 2, 1.4, definition

Replace "equipment supporting" by "means to support".

Page 3, 1.8, term

Replace "based" by "biased".

Page 4, 1.9, definition

Insert "horizontal" before "rotor".

Page 4, 1.9, Figure 4, Key 1

Replace "core" by "coil".

Page 6, 1.11, term and definition

Replace the existing text by the following, but retain references to figures.

### nominal magnetic gap

distance between the magnetic materials of the rotor and the stator inside the AMB when the journal centre of the rotor is located in the clearance centre of the bearing stator

Page 16, 4.1, Figure 12

# Replace the existing legend by the following. (standards.iteh.ai)

### Figure 12 — Current-force characteristic: linearization by AMB bias current I<sub>0</sub> https://stafor.a.typical.2-quadrant.power.amplifies\_474f-947d-

Page 20, 5.7, term, definition, and reference to figure

Replace the existing text by the following.

### operation mode of AMB power amplifier

characteristic of AMB power amplifiers:

- 2-quadrant: output voltage positive or negative while current always positive;
- 4-quadrant: output voltage positive or negative while current arbitrarily positive or negative

See Figure 12.

Page 21, 5.7, Figure 14

Delete this figure and renumber all following figures and their references.

Page 24, 6.1, term and definition

Replace the existing text by the following.

#### touch-down bearing

bearing installed in the magnetic bearing rotor system, which is designed to limit the rotor motion and to prevent contact with the AMB stator or rotor surface

NOTE Other designations include: auxiliary bearing, emergency bearing, retainer bearing, back-up bearing, catcher bearing.

Page 26, Bibliography

Update the title of ISO 2041 to read "*Mechanical vibration, shock and condition monitoring* — Vocabulary" Add the following entry.

[3] ISO 8826-2, Technical drawings — Rolling bearings — Part 2: Detailed simplified representation

Page 27, Alphabetical index

Delete the following entry.

AMB clearance 1.11

Add the following entries.

back-up bearing 6.1

catcher bearing 6.1

nominal magnetic gap 1.11

Replace "permanent-magnet-based AMB" by "permanent-magnet-biased AMB".

Replace "operation class of AMB power amplifier" by "operation mode of AMB power amplifier".

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ICS 01.040.17; 17.160 Price based on 3 pages