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Optics and photonics — Preparation of drawings for optical elements and systems —

Part 12: **Aspheric surfaces —**

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(stopfique et photonique préparation des dessins pour éléments et systèmes optiques —

ISO 10110-12:2007/And 1:2013 *Partie 12: Surfaces aspheriques* https://standards.iteh.ai/catalog/standards/sist/53ae58ea-1/8c-4e4b-87e2-0f534dbAMENDEMENT212007-amd-1-2013



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Optics and photonics — **Preparation of drawings for optical elements and systems** —

Part 12: **Aspheric surfaces**

AMENDMENT 1

Page iv, Foreword

In the list of part titles of ISO 10110, update the part title of Part 8 to read:

- Surface texture; roughness and waviness

Page 2, 3.1.2

Number the NOTE to become NOTE 1 and add the following NOTE 2 after NOTE 1:

NOTE 2 In this case, "left" and "right" presume *z* is increasing from left to right. When the *Z*-axis is reversed as a result of a reflection (a 180° rotation about the *Y*-axis), the sign convention for radius and sagitta is also reversed. This is discussed further in 3.3.2.3.

Page 5, 3.3.2.1

1 ISO 10110-12:2007/Amd 1:2013 https://standards.iteh.ai/catalog/standards/sist/53ae58ea-178c-4e4b-87e2-

Immediately after Equation (12), i.e. before the sentence about Schmidt surface, insert the following new paragraph:

The first order and second order aspheric terms, A_1h and A_2h^2 , may be added to Equation (12).

Page 6, 3.3.2.3

Add the following new subclause after 3.3.2.3:

3.3.2.4 Combined surface based on an orthogonal polynomial

A surface of higher order can also be generated by combining a spherical surface [Equation (5)] with a set of orthogonal polynomials of the following type possessing orthonormal derivatives (see Reference [3]).

$$z = f(x, y) + f_1(x, y)$$
(17)

$$f_{1}(x,y) = \frac{\left(\frac{h}{h_{0}}\right)^{2} \left[1 - \left(\frac{h}{h_{0}}\right)^{2}\right]}{\sqrt{1 - \left(\frac{h}{R}\right)^{2}}} \left[A_{0}Q_{0}\left(\frac{h^{2}}{h_{0}^{2}}\right) + A_{1}Q_{1}\left(\frac{h^{2}}{h_{0}^{2}}\right) + \cdots\right]$$
(18)

where h_0 marks the upper limit of h. The description z is valid for $0 \le h \le h_0$ only. R is the radius of curvature that intersects the surface at h_0 .

For a detailed description of the recursion formulae, see Annex B.

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NOTE Another description that combines a conic with a set of orthogonal polynomials, orthogonal in amplitude, is also permitted [see Reference [4], Equations (2) to (3) and (8) to (9)].

Page 14, Annex A

In the table, add a new row for "Sphere", under "Surfaces rotationally symmetric about *Z*-axis". For the sake of clarity, the amended table of Annex A is given hereafter in its entirety.

Class	Basic surface	Basic equation $f(x,y) =$	Power series $f1(x,y) = [for toric surfaces, g1(x)]$
Non- rotationally- symmetric surfaces	Ellipsoid Hyperboloid Paraboloid	$\frac{\frac{x^2}{R_{\chi}} + \frac{y^2}{R_{\gamma}}}{1 + \sqrt{1 - (1 + \kappa_{\chi}) \left(\frac{x}{R_{\chi}}\right)^2 - (1 + \kappa_{\gamma}) \left(\frac{y}{R_{\gamma}}\right)^2}}$	$A_{4}x^{4} + B_{4}y^{4} + A_{6}x^{6} + B_{6}y^{6} + \dots$ C_{3} x ^{3} + + D_{3} y ^{3} +
$R_{\rm X} \neq R_{\rm Y}^{\ a}$ $\kappa_{\rm X} \neq \kappa_{\rm Y}$	Cone (a ≠ b)	$c\sqrt{\frac{x^2}{a^2} + \frac{y^2}{b^2}}$	
$A_{2i} \neq B_{2i}$ $C_{2i-1} \neq D_{2i-1}$	Cylinder	$\frac{u^2}{R_{\rm U} \left[1 + \sqrt{1 - (1 + \kappa_{\rm U}) \left(\frac{u}{R_{\rm U}}\right)^2}\right]}$	$A_{4}x^{4} + A_{6}x^{6} + \dots + C_{3} x ^{3}$ for $u = x$ $B_{4}y^{4} + B_{6}y^{6} + \dots + D_{3} y ^{3}$ for $u = y$
Surfaces rotationally symmetric about Z axis	Ellipsoid Hyperboloid Paraboloid Sphere	h ² ISO 121 0-12:2007/A IRS 1/#tar14er(11-#tac)hi/cathlog/standards/sis 0f534db4/Real/isp-10110-12-2	$\frac{12013}{12013}$ $\frac{12013}{12013}$ $\frac{12013}{12013}$ $\frac{12013}{12013}$ $\frac{12013}{12013}$ $\frac{12013}{12013}$ $\frac{12013}{12013}$ $\frac{12013}{12013}$ $\frac{12013}{12013}$
$R_{\rm X} = R_{\rm Y} = R$ $\kappa_{\rm X} = \kappa_{\rm Y} = \kappa$	Cone (<i>a</i> = <i>b</i>)	$\frac{c}{a}h$	where $h = \sqrt{x^2 + y^2}$
	Plane (Schmidt surface)	0	
$h^2 = x^2 + y^2$	Sphere	$\frac{h^2}{R\left[1+\sqrt{1-\frac{h^2}{R^2}}\right]}$	$\frac{\left(\frac{h}{h_0}\right)^2 \left[1 - \left(\frac{h}{h_0}\right)^2\right]}{\sqrt{1 - \left(\frac{h}{R}\right)^2}} \left[A_0 Q_0 \left(\frac{h^2}{h_0^2}\right) + A_1 Q_1 \left(\frac{h^2}{h_0^2}\right) + \cdots\right]$
Surfaces of revolution; not coincident with coordi- nate axis	Toric surface	$f(x,y) = R_{Y} \mp \sqrt{\left[R_{Y} - g(x)\right]^{2} - y^{2}}$ $g(x) = \frac{x^{2}}{R_{X} \left[1 + \sqrt{1 - (1 + \kappa_{X})\left(\frac{x}{R_{X}}\right)^{2}}\right]}$	$g_{1}(x) = A_{4}x^{4} + A_{6}x^{6} + \dots + C_{3} x ^{3} + C_{5} x ^{5} + \dots$
a If at least one of these inequalities is valid.			

Page 15, new Annex B

Add the following annex:

Annex B (informative)

Description of an orthogonal polynomial

$$Q_{m+1}\left(\frac{h^{2}}{h_{0}^{2}}\right) = \frac{P_{m+1}\left(\frac{h^{2}}{h_{0}^{2}}\right) - g_{m}Q_{m}\left(\frac{h^{2}}{h_{0}^{2}}\right) - k_{m-1}Q_{m-1}\left(\frac{h^{2}}{h_{0}^{2}}\right)}{l_{m+1}}$$
(B.1)
starting with $Q_{0}\left(\frac{h^{2}}{h_{0}^{2}}\right) = 1$ and $Q_{1}\left(\frac{h^{2}}{h_{0}^{2}}\right) = \frac{13 - 16\left(\frac{h^{2}}{h_{0}^{2}}\right)}{\sqrt{19}}$
 $P_{m+1}\left(\frac{h^{2}}{h_{0}^{2}}\right) = (2 - 4\frac{h^{2}}{h_{0}^{2}})P_{m}\left(\frac{h^{2}}{h_{0}^{2}}\right) - P_{m-1}\left(\frac{h^{2}}{h_{0}^{2}}\right)$
starting with $P_{0}\left(\frac{h^{2}}{h_{0}^{2}}\right) = 2$ and $P_{1}\left(\frac{h^{2}}{h_{0}^{2}}\right) = 6 - 8\left(\frac{h^{2}}{h_{0}^{2}}\right).$
(B.2)

The following auxiliary polynomials (B.3) (B14) and (B.5) have to be solved in the order given here and are valid for $m \ge 2$.

$$k_{m-2} = \frac{-m(m-1)_{\text{https://standards.iteh.ai/catalog/standards/sist/53ae58ea-178c-4e4b-87e2-}}{2 l_{m-2} 0f534db47caf/iso-10110-12-2007-amd-1-2013}$$
(B.3)

$$g_{m-1} = \frac{-(1+g_{m-2}k_{m-2})}{l_{m-1}} \tag{B.4}$$

$$l_m = \left[m(m+1) + 3 - g_{m-1}^2 - k_{m-2}^2 \right]^{\frac{1}{2}}$$
(B.5)

starting with
$$g_0 = -\frac{1}{2}$$
 , $l_0 = 2$ and $l_1 = \frac{1}{2}\sqrt{19}$.

Based on the recursion the first six *Q*s are the following:

$$Q_{0}\left(\frac{h^{2}}{h_{0}^{2}}\right) = 1$$

$$Q_{1}\left(\frac{h^{2}}{h_{0}^{2}}\right) = \frac{13 - 16\left(\frac{h^{2}}{h_{0}^{2}}\right)}{\sqrt{19}}$$

$$Q_{2}\left(\frac{h^{2}}{h_{0}^{2}}\right) = \sqrt{\frac{2}{95}}\left[29 - 4\left(\frac{h^{2}}{h_{0}^{2}}\right)(25 - 19\left(\frac{h^{2}}{h_{0}^{2}}\right))\right]$$

$$\begin{aligned} Q_{3}\left(\frac{h^{2}}{h_{0}^{2}}\right) &= \sqrt{\frac{2}{2545}} \left\{ 207 - 4\left(\frac{h^{2}}{h_{0}^{2}}\right) \left[315 - \left(\frac{h^{2}}{h_{0}^{2}}\right) (577 - 320\left(\frac{h^{2}}{h_{0}^{2}}\right)) \right] \right\} \\ Q_{4}\left(\frac{h^{2}}{h_{0}^{2}}\right) &= \frac{1}{3\sqrt{131831}} \left(7737 - 16\left(\frac{h^{2}}{h_{0}^{2}}\right) \left\{ 4653 - 2\left(\frac{h^{2}}{h_{0}^{2}}\right) \left[7381 - 8\left(\frac{h^{2}}{h_{0}^{2}}\right) (1168 - 509\left(\frac{h^{2}}{h_{0}^{2}}\right)) \right] \right\} \right) \\ Q_{5}\left(\frac{h^{2}}{h_{0}^{2}}\right) &= \frac{1}{3\sqrt{6632213}} \left[66657 - 32\left(\frac{h^{2}}{h_{0}^{2}}\right) \left[28338 - \left(\frac{h^{2}}{h_{0}^{2}}\right) \left[135325 - 8\left(\frac{h^{2}}{h_{0}^{2}}\right) \left[35884 - \left(\frac{h^{2}}{h_{0}^{2}}\right) (34661 - 12432\left(\frac{h^{2}}{h_{0}^{2}}\right)) \right] \right\} \right) \end{aligned}$$

Page 15, Bibliography

Add the following bibliography references:

- [2] KROSS, J., OERTMANN, F.-W., SCHUHMANN, R., *On aspherics in optical system*, SPIE Proceedings 656 (1986)
- [3] FORBES, G.W., Robust, efficient computational methods for axially symmetric optical aspheres, Opt. Express 18, 19700-19712 (2010)
- [4] FORBES, G.W., Shape specification for axially symmetric optical surfaces, Opt. Express 15, 5218-5226 (2007)

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