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**Inteligentni transportni sistemi - Kooperativni sistem (ITS) - Uporaba komunikacij V2I in I2V za aplikacije v zvezi s signali v križiščih (ISO/TS 19091:2017)**

Intelligent transport systems - Cooperative ITS - Using V2I and I2V communications for applications related to signalized intersections (ISO/TS 19091:2017)

Intelligente Transportsysteme - Kooperative ITS - Nutzung von V2I und I2V-Kommunikation für Anwendungen bezogen auf Signalanlagen an Kreuzungen (ISO/TS 19091:2017)

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Systèmes intelligents de transport - Coopérative ITS - Utilisation de communications V2I et I2V pour des applications relatives aux intersections signalées (ISO/TS 19091:2017)

**Ta slovenski standard je istoveten z: CEN ISO/TS 19091:2017**

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35.240.60	Uporabniške rešitve IT v prometu	IT applications in transport

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**Intelligent transport systems - Cooperative ITS - Using V2I  
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Systèmes intelligents de transport - Coopérative ITS -  
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Nutzung von V2I und I2V-Kommunikation für  
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## European foreword

This document (CEN ISO/TS 19091:2017) has been prepared by Technical Committee ISO/TC 204 “Intelligent transport systems” in collaboration with Technical Committee CEN/TC 278 “Intelligent transport systems” the secretariat of which is held by NEN.

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**Intelligent transport systems —  
Cooperative ITS — Using V2I and I2V  
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*Systèmes intelligents de transport — Coopérative ITS — Utilisation  
de communications V2I et I2V pour des applications relatives aux  
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### Foreword

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## Introduction

Cooperative-ITS (C-ITS) is a promising and remarkable advancement of intelligent transport systems (ITS). Numerous cooperative applications are specified that open up new possibilities to make traffic safer, more efficient, and smarter. Technologies are developed and improved to realize and support those new services and applications. To enable those applications, information needs to be reliably communicated between the stationary infrastructure and mobile vehicles.

This document describes the use cases for several applications that address safety, mobility, and ecological sustainability. Each use case has information needs that communication between vehicles and the infrastructure facilitate. It then identifies the information needs for the applications and the requirements to satisfy them. In turn, it maps the requirements into data frames and data elements to fulfil the requirements within the specified message set.

ISO 22951 has a relationship to this document. PRESTO addresses its user needs through the implementation of a specific system architecture similar to that described in NTCIP 1211. This architecture includes traffic signals, message signs, routing systems, human machine interfaces, and fixed detection locations. Many of PRESTO's data value details are "left undefined to allow for discretionary definition by each country." The PRESTO architecture detects priority requesting vehicles by installing specific detection equipment at these locations.

This document uses a similar set of user needs to develop the message set between vehicles and the roadside equipment they interface. This document does not address the system architecture other than data needed to fulfil the user needs that will be managed elsewhere in the architecture. It details data values and structures in order to define the interface between these two devices. Routing information is supported in the architecture through other mechanisms and is not a need supported by the vehicle to roadside equipment information flows. The user needs also provide for priority by approach, a preconfigured strategy, and ingress/egress lane requests. This document is based on vehicles periodically broadcasting their location and trajectory information to other vehicles and the roadside infrastructure. This document complements ISO 22951 as it provides for vehicle location and request information directly from connected vehicles rather than the detection of the vehicles from other fixed sensing equipment. It does not address the architecture data flows and operations that are detailed within ISO 22951. In other terms, this document provides a connected vehicle alternative for request and status communication without impacting the back office or local intersection operations of priority management.

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# Intelligent transport systems — Cooperative ITS — Using V2I and I2V communications for applications related to signalized intersections

## 1 Scope

This document defines the message, data structures, and data elements to support exchanges between the roadside equipment and vehicles to address applications to improve safety, mobility and environmental efficiency. In order to verify that the defined messages will satisfy these applications, a systems engineering process has been employed that traces use cases to requirements and requirements to messages and data concepts.

This document consists of a single document that contains the base specification and a series of annexes. The base specification lists the derived information requirements (labelled informative) and references to other standards for message definitions where available. [Annex A](#) contains descriptions of the use cases addressed by this document. [Annex B](#) and [Annex C](#) contain traceability matrices that relate use cases to requirements and requirements to the message definitions (i.e. data frames and data elements). The next annexes list the base message requirements and application-oriented specific requirements (requirements traceability matrix) that map to the message and data concepts to be implemented. As such, an implementation consists of the base plus an additional group of extensions within this document.

Details on information requirements, for other than SPaT, MAP, SSM, and SRM messages are provided in other International Standards. The focus of this document is to specify the details of the SPaT, MAP, SSM, and SRM supporting the use cases defined in this document. Adoption of these messages varies by region and their adoption may occur over a significant time period.

This document covers the interface between roadside equipment and vehicles. Applications, their internal algorithms, and the logical distribution of application functionality over any specific system architecture are outside the scope of this document.

## 2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 22951, *Data dictionary and message sets for preemption and prioritization signal systems for emergency and public transport vehicles (PRESTO)*

ISO 26684, *Intelligent transport systems (ITS) — Cooperative intersection signal information and violation warning systems (CIWS) — Performance requirements and test procedures*

SAE J2735<sup>TM</sup>:2016, *Dedicated Short Range Communications (DSRC) Message Set Dictionary*

EN 302 637-2 V1.3.2, *Intelligent Transport Systems (ITS); Vehicular Communications; Basic Set of Applications; Part 2: Specification of Cooperative Awareness Basic Service*

ARIB STD-T109, *700 MHz Band Intelligent Transport Systems*

ITS FORUM RC-010, *700 MHz Band Intelligent Transport Systems — Extended Functions Guideline, published on March 15, 2012*

ETSI/TS 102 894-2 V1.2.2, *Intelligent Transport Systems (ITS); Users and applications requirements; Part 2: Applications and facilities layer; common data dictionary*