
**Oprema cest - Postopek validacije in verifikacije računalniške simulacije
preskusnih trčenj v sisteme za zadrževanje vozil**

Road restraint systems - Validation and verification process for the use of virtual testing
in crash testing against vehicle restraint system

Rückhaltesysteme an Straßen - Validierungs- und Nachweisverfahren für die Nutzung
von Computersimulationen bei Anprallprüfungen an Fahrzeug-Rückhaltesysteme

Dispositifs de retenue routiers - Processus de vérification et de validation pour l'utilisation
d'essais virtuels dans les essais de choc contre un dispositif de retenue pour véhicules

Ta slovenski standard je istoveten z: prEN 16303

SIST EN 16303:2020

<https://standards.iteh.ai/catalog/standards/sist/ddc78adf-1f7d-49a4-ad82-b4469d5b6585/sist-en-16303-2020>

ICS:

13.200	Preprečevanje nesreč in katastrof	Accident and disaster control
93.080.30	Cestna oprema in pomožne naprave	Road equipment and installations

oSIST prEN 16303:2018

en,fr,de

EUROPEAN STANDARD
NORME EUROPÉENNE
EUROPÄISCHE NORM

DRAFT
prEN 16303

April 2018

ICS 13.200; 93.080.30

Will supersede CEN/TR 16303-1:2012, CEN/TR
16303-2:2012, CEN/TR 16303-3:2012, CEN/TR
16303-4:2012

English Version

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Nachweisverfahren für die Nutzung von
Computersimulationen bei Anprallprüfungen an
Fahrzeug-Rückhaltesysteme

This draft European Standard is submitted to CEN members for enquiry. It has been drawn up by the Technical Committee CEN/TC 226.

If this draft becomes a European Standard, CEN members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration.

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COMITÉ EUROPÉEN DE NORMALISATION
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prEN 16303:2018 (E)**European foreword**

This document (prEN 16303:2018) has been prepared by Technical Committee CEN/TC 226 “Road equipment”, the secretariat of which is held by AFNOR.

This document is currently submitted to the CEN Enquiry.

This document will supersede CEN/TR 16303-1:2012, CEN/TR 16303-2:2012, CEN/TR 16303-3:2012 and CEN/TR 16303-4:2012 (which have been merged).

In comparison to the previous Technical Reports, this document contains the following changes:

- some symbols and abbreviations have been modified;
- the roadmap for the validation of the numerical vehicle model has been updated and acceptance conditions have been provided;
- the validation requirements for virtual testing against roadside devices have been updated;
- the verification Evaluation Criteria for Finite Element model have been updated.

Annexes A, B, are normative and Annexes C to I are informative.

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[SIST EN 16303:2020](https://standards.iteh.ai/catalog/standards/sist/ddc78adf-1f2d-49a4-ad82-b4469d5b6585/sist-en-16303-2020)

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Introduction

This document provides a common basis for the use of virtual testing to reproduce vehicle impacts against roadside safety devices including safety barriers, crash cushions, terminals, removable barrier sections, transitions and passive safety devices in accordance with the EN 1317 series and EN 12767.

This document provides requirements to establish the degree to which the numerical models of roadside safety device and of vehicle are an accurate representation of the real world from the perspective of the intended uses of the model.

Two main modelling approaches have been considered:

- Finite Element (FE) Method;
- Multi-Body (MB) approach.

In this document a methodology is defined to validate the results obtained with computational mechanics work and to verify the reliability of the virtual test. It also includes a report template and incorporates specific content for general requirements for the competence of entities performing virtual testing.

General recommendations based on experiences for developing numerical models of roadside safety devices and vehicles for virtual tests are also given.

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<https://standards.iteh.ai/catalog/standards/sist/ddc78adf-1f2d-49a4-ad82-b4469d5b6585/sist-en-16303-2020>

1 Scope

This document defines the accuracy, credibility and confidence in the results of virtual crash test to roadside safety devices through the definition of procedures for verification, validation and development of numerical models for roadside safety application. Finally it defines a list of indications to ensure the competences of an expert/organization in the domain of virtual testing.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

EN 1317-1:2010, *Road restraint systems – Part 1: Terminology and general criteria for test methods*

EN 1317-2:2010, *Road restraint systems – Part 2: Performance classes, impact test acceptance criteria and test methods for safety barriers including vehicle parapets*

EN 1317-3:2010, *Road restraint systems – Part 3: Performance classes, impact test acceptance criteria and test methods for crash cushions*

ENV 1317-4:2001, *Road restraint systems – Part 4: Performance classes, impact test acceptance criteria and test methods for terminals and transitions of safety barriers*

EN 1317-5, *Road restraint systems – Part 5: Product requirements and evaluation of conformity for vehicle restraint systems*

CEN/TS 1317-8, *Road restraint systems – Part 8: Motorcycle road restraint systems which reduce the impact severity of motorcyclist collisions with safety barriers*

EN 12767:2007¹, *Passive safety of support structures for road equipment - Requirements, classification and test methods*

3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- IEC Electropedia: available at <http://www.electropedia.org/>
- ISO Online browsing platform: available at <http://www.iso.org/obp>

¹ Currently under review.

3.1**Numerical Model**

mathematical model of roadside safety device and vehicle

Note 1 to entry: It refers to a numerical model which might be analytical or discrete and aims to reproduce the basic physical phenomena of a subject.

3.2**roadside safety device**

device tested according to the EN 1317 series

3.3**passive safety device**

device tested according to EN 12767

3.4**test**

full-scale impact test performed at a test house according to the relevant standard

3.5**test item**

device to be assessed using virtual testing

3.6**validated model**

numerical model of the roadside device or vehicle that fulfils requirements of this document

3.7**validation procedure**

set of activities defined to assess whether a numerical model can be considered representative of a physical system or part in a specified range of conditions ²⁰

3.8**verification procedure**

set of activities defined to check whether a numerical model is reliable and numerically stable

3.9**virtual test or testing**

activities related to the use of a numerical model to reproduce a real test

4 Symbols and abbreviations

For the purposes of this document, the following symbols and abbreviations apply:

ASI	Acceleration Severity Index
CoG	Center of gravity
D	Dynamic deflection
D _m	Measured maximum Dynamic Deflection of the real test, in metres (m)
D _{VT}	Measured maximum Dynamic Deflection of the virtual test, in metres (m)
FE	Finite elements
HGV	Heavy goods vehicle

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LD	Lateral displacement
LD _m	Measured Lateral displacement of the real test, in metres (m)
LD _{VT}	Measured Lateral displacement of the virtual test, in metres (m)
MB	Multi-body
RT	Real test or testing
THIV	Theoretical Head Impact Velocity
VI	Vehicle intrusion
VI _m	Measured Vehicle Intrusion of the real test, in metres (m)
VI _{VT}	Measured Vehicle Intrusion of the virtual test, in metres (m)
VT	Virtual test or testing
W	Working width
W _m	Measured Working Width of the real test, in metres (m)
W _{VT}	Measured Working Width of the virtual test, in metres (m)

5 Requirements for numerical vehicle model**5.1 General**

A complete 3D numerical model of the vehicle shall be created. The geometry of the vehicle and all inertial properties shall be reproduced faithfully. The numerical model shall include:

- frame;
- body;
- suspensions systems, front and rear;
- wheels;
- steering system;
- windows;
- engine block.

Vehicle specifications under test conditions shall be as specified as in EN 1317-1:2010, Table 1.

The vehicle shall be fitted with, as a minimum, one accelerometer for measurement in the longitudinal (forward) direction, one for the lateral (sideways) direction, one for the vertical direction (downward) and an angular velocity sensor (rate sensor). The accelerometers shall be mounted as prescribed by the EN 1317-1. Vehicular accelerations shall be used for the calculation of the severity indices, accordingly to EN 1317-1.

Justification of chosen material models and implemented material failure and strain rate dependency shall be provided.

5.2 Validation

For the validation of the numerical vehicle model, tests shall be performed according to this standard, comparable parameters shall be measured and the results shall be fully documented.

The validation tests that shall be carried out to ensure the numerical stability and the capability of the numerical model are divided in categories dealing with vehicle setup, dynamics, handling and crashworthiness.

5.3 Test methodology

5.3.1 General

The scope of the following test is to ensure the stability and robustness of the vehicle model and the level of reliability of the results.

The finite element model and the multi body vehicle model shall be validated with the same requirements and limit.

This procedure consists of a fixed number of compulsory tests and a series of additional tests that can be performed depending on the availability of experimental tests and on the intended use of the model.

For the vehicle model in order to be considered validated all compulsory tests shall be completed without error terminations.

The test shall be performed when the vehicle development is completed. Modification(s) that might influence the result(s) of one or more test will request to perform these (those) test(s) again.

If the tests do not satisfy limits described in Table 1, the entity performing the vehicle validation activity shall explain his motivations inside the final validation report and those motivations shall be checked and agreed by the certification body.

If some of tests listed in Table 1 are not performed, the entity performing the vehicle validation activity shall explain his motivations inside the final validation report and those motivations shall be checked and agreed by the certification body.

5.3.2 Test description

5.3.2.1 Compulsory test

The tests are grouped in four different sets:

- Set 1. – Vehicle setup;
- Set 2. – Vehicle suspension and steering kinematics;
- Set 3. – Vehicle handling;
- Set 4. – Vehicle crashworthiness.

The tests included in Table 1 shall be performed to complete the vehicle validation.

The table includes the scope of the test, the results to be provided and the acceptance conditions (limits).

Table 1 — Validation Roadmap – Reduced procedure

Set 1. – Vehicle setup		
Test 1 - Idle test		
Scope: Verify stability of the vehicle model and general setup	Results to be Provided: <ul style="list-style-type: none"> — Acceleration time (filtered) — Suspensions movement time history 	Limits: <ul style="list-style-type: none"> — Filtered accelerations CG < $\pm 2,5$ G — Suspension movement < 15 mm
Set 2. – Vehicle suspension and steering kinematics		
Test 1 – Isolated suspensions system (constrained vehicle) – full compression		
Scope: Verify suspension kinematic and loading and unloading capacity	Results to be Provided: <ul style="list-style-type: none"> — Comparison between theoretical and virtual stiffness curves — identify the suspension maximum compression 	Limits: <ul style="list-style-type: none"> — Allowed variation between theoretical and virtual working curves: $\pm 5\%$
Test 2 – Isolated suspensions system (constrained vehicle) – full extension		
Verify suspension kinematic and loading capacity	Results to be Provided: <ul style="list-style-type: none"> — Comparison between theoretical and virtual stiffness curves — Identify the suspension maximum extension 	Limits: <ul style="list-style-type: none"> — Allowed variation between theoretical and virtual working curves: $\pm 5\%$
Test 3 – Isolated steering system (constrained vehicle) – full rotation both sides		
Scope: Verify steering kinematic	Results to be Provided: <ul style="list-style-type: none"> — Comparison between left and right wheel steering angle (time Vs angle curves) — Identify the steering maximum angle in compression 	Limits: <ul style="list-style-type: none"> — Verify Ackerman principle
Set 3. – Vehicle handling		
Test 1 - Linear track test		
Scope: Verify the general behavior of the vehicle (steering and suspension system) and its capability to run	Results to be Provided: <ul style="list-style-type: none"> — Trajectory plot — Energies balance in time 	Limits: