## INTERNATIONAL STANDARD

Second edition 2015-08-01

Fine ceramics (advanced ceramics, advanced technical ceramics) — Mechanical properties of ceramic composites at ambient temperature in air atmospheric pressure — Determination of tensile properties

iTeh STANDARD PREVIEW Céramiques techniques — Propriétés mécaniques des céramiques (s composites à température ambiante sous air à pression atmosphérique — Détermination des propriétés en traction

ISO 15733:2015 https://standards.iteh.ai/catalog/standards/sist/18b42d58-366b-4aa5-b761b1beeb3fc97c/iso-15733-2015



Reference number ISO 15733:2015(E)

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ISO 15733:2015 https://standards.iteh.ai/catalog/standards/sist/18b42d58-366b-4aa5-b761b1beeb3fc97c/iso-15733-2015



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### Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see <a href="https://www.iso.org/directives">www.iso.org/directives</a>).

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Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ASO's adherence to the WTO principles in the Technical Barriers to Trade (TBT) see the following URL: Foreword - Supplementary information

The committee responsible for this document is ISO/TC 206, *Fine ceramics*.

This second edition cancels and replaces the first edition (ISO 15733:2001), which has been technically revised. https://standards.iteh.ai/catalog/standards/sist/18b42d58-366b-4aa5-b761-b1beeb3fc97c/iso-15733-2015

# Fine ceramics (advanced ceramics, advanced technical ceramics) — Mechanical properties of ceramic composites at ambient temperature in air atmospheric pressure — Determination of tensile properties

#### 1 Scope

This International Standard specifies the conditions for determination of tensile properties of ceramic matrix composite materials with continuous fibre reinforcement at room temperatures. This International Standard applies to all ceramic matrix composites with a continuous fibre reinforcement, unidirectional (1D), bi-directional (2D), and tri-directional (xD, with 2 <  $x \le$  3), loaded along one principal axis of reinforcement.

NOTE In most cases, ceramic matrix composites to be used at high temperature in air are coated with an antioxidation coating.

#### 2 Normative references

The following documents in whole or in part, are normatively referenced in this document and are indispensable for its application. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 3611, Geometrical product specifications (GPS), 20 Dimensional measuring equipment: Micrometers for external measurements — Design and metrological characteristics

ISO 7500-1:2004, Metallic materials  $\frac{1}{2}$  Verification  $3\bar{o}_{f}^{0}$  static uniaxial testing machines — Part 1: Tension/compression testing machines — Verification and calibration of the force-measuring system

#### 3 Terms, definitions and symbols

For the purposes of this document, the following terms and definitions apply.

#### 3.1

#### calibrated length

part of the test specimen that has uniform and minimum cross-section area

#### 3.2

#### gauge length

 $L_0$ 

initial distance between reference points on the test specimen in the calibrated length

#### 3.3 init

## **initial cross-section area** S<sub>0</sub>

initial cross-section area of the test specimen within the calibrated length

#### 3.4

#### effective cross-section area

So eff

total area corrected by a factor, to account for the presence of a coating

#### 3.5

#### longitudinal deformation

#### A

increase in the gauge length between reference points under a tensile force

#### 3.6

#### longitudinal deformation under maximum tensile force

Am increase in the gauge length between reference points under maximum tensile force

#### 3.7

#### tensile strain

ε

relative change in the gauge length defined as the ratio  $A/L_0$ 

#### 3.8

#### tensile strain under maximum force

ε<sub>m</sub>

relative change in the gauge length defined as the ratio  $A_{\rm m}/L_{\rm o}$ 

#### 3.9

#### tensile stress

tensile force supported by the test specimen at any time in the test divided by the initial cross-section area  $(S_0)$ 

## iTeh STANDARD PREVIEW (standards.iteh.ai)

#### effective tensile stress

 $\sigma_{\rm eff}$ 

3.10

tensile force supported by the test specimen at any time in the test divided by the effective crosssection area (S<sub>o eff</sub>) https://standards.iteh.ai/catalog/standards/sist/18b42d58-366b-4aa5-b761-

b1beeb3fc97c/iso-15733-2015

#### 3.11

#### maximum tensile force

 $F_{\rm m}$ highest recorded tensile force in a tensile test on the test specimen when tested to failure

#### 3.12

#### tensile strength

 $\sigma_{
m m}$ 

ratio of the maximum tensile force to the initial cross-section area (So)

#### 3.13

#### effective tensile strength

 $\sigma_{\rm m\,eff}$ 

ratio of the maximum tensile force to the effective cross-section area

#### 3.14

#### proportionality ratio or pseudo-elastic modulus EP

slope of the initial linear section of the stress-strain curve, if any

Note 1 to entry: Examination of the stress-strain curves for ceramic matrix composites allows definition of the following cases:

a) Material with an initial linear domain in the stress-strain curve.

For ceramic matrix composites that have a mechanical behaviour characterized by an initial linear section, the proportionality ratio is defined as:

$$\textit{EP}(\sigma_1,\sigma_2) = \frac{(\sigma_2 - \sigma_1)}{(\varepsilon_2 - \varepsilon_1)}$$

where  $(\varepsilon_1, \sigma_1)$  and  $(\varepsilon_2, \sigma_2)$  lie near the lower and the upper limits of the linear section of the stress-strain curve.

The proportionality ratio or pseudo-elastic modulus is termed the elastic modulus, *E*, in the single case where the linearity starts near the origin.

b) Material with no-linear section in the stress-strain curve.

In this case only stress-strain couples can be fixed.

#### 3.15

#### effective proportionality ratio

*EP*<sub>eff</sub>

slope of the linear section of the stress-strain curve, if any, when the effective tensile stress is used

#### **4** Principle

A test specimen of specified dimensions is loaded in tension. The test is performed at constant crosshead displacement rate, or constant deformation rate (or constant loading rate). Force and longitudinal deformations are measured and recorded simultaneously.

NOTE The use of constant loading rate only gives a valid tensile curve when the material behaves linearly up to failure.

#### **5** Apparatus

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#### 5.1 Test machine

## (standards.iteh.ai)

The test machine shall be equipped with a system for measuring the force applied to the test specimen conforming to grade 1 or better according to ISO 7500-1:2004.

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#### 5.2 Load train

The load train configuration shall ensure that the load indicated by the load cell and the load experienced by the test specimen are the same.

The load train shall align the specimen axis with the direction of load application without introducing bending or torsion in the specimen. The alignment should be verified and documented in accordance with, for example, the procedure described in ISO 17161.

The maximum percent bending shall not exceed 5 at an average strain of  $500 \times 10^{-6}$ .

The grip design shall prevent the test specimen from slipping.

NOTE The choice of gripping system depends on material, on test specimen design and on alignment requirements.

#### 5.3 Extensometer

The extensometer shall be capable of continuously recording the longitudinal deformation at test temperature and adapted for small deformation

For mechanical extensometer, the extensometer class should be  $\leq 2$  (see ISO 9513).

The use of an extensometer with the greatest gauge length is recommended.

The gauge length shall be the longitudinal distance between the two locations where the extensometer rods contact the test specimen.

Care should be taken to correct for changes in calibration of the extensometer that may occur as a result of operating under conditions different from calibration.

If an electro-optical extensometer is used, electro-optical measurements in transmission require reference marks on the test specimen. For this purpose, rods or flags shall be attached to the surface perpendicularly to its axis. The gauge length shall be the distance between the two reference marks. The material used for marks (and adhesive if used) shall be compatible with the test specimen material and shall not modify the stress field in the specimen.

The use of integral flags as parts of the test specimen geometry is not recommended because of stress concentration induced by such features.

Electro-optical extensometer is not recommended in the case where it is not possible to distinguish the colour of the reference marks and the test specimen.

#### 5.4 Data recording system

A calibrated recorder may be used to record force-deformation curve. The use of a digital data recording system is recommended.

#### 5.5 Micrometers

Micrometers used for the measurement of the dimensions of the test specimen shall conform to ISO 3611.

#### 6 Test specimens

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**6.1** The choice of the specimen geometry depends on several parameters:

- the nature of the material and of the reinforcement structure;
- the type of the gripping system.
   <u>ISO 15733:2015</u>

https://standards.iteh.ai/catalog/standards/sist/18b42d58-366b-4aa5-b761-

Total length  $l_t$ , depends on the type of machine; on the type of grips and on the type of extensometer. It is recommended to use a total length of at least 100 mm.

The volume in the gauge length shall be representative for the material.

Two types of specimen can be distinguished:

- as fabricated specimens, where only the length and the width are machined to give to the specimens the proper size, in the case the two faces of the specimen may present an irregular surface,
- machined specimens where the length and the width and also the two sides of the specimen have been machined.

Tolerance on thickness is only for machined specimens. For as-fabricated specimens the difference in thickness taken out of three measurements (as the centre and at each end of the calibrated length) shall not exceed 5 % of the average of the three measurements.

**6.2** Type 1 specimen is represented in <u>Figure 1</u> and dimensions are given in <u>Table 1</u>.



Figure 1 — Type 1 specimen geometry

1 able 1 - 1 y be 1 specimen unnensions
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Parameter	Dimensions mm	
lt, total lengtheh STANDARD PREVI	<b>∏</b> ≩ 100	±0,5
<i>l</i> , calibrated length	≥ 40	±0,2
h, thickness (standards.iten.al)	≥ 3	±0,2
$b_1$ , width in the calibrated length 15733-2015	≥8	±0,2
b <sub>2</sub> , widths://standards.iteh.ai/catalog/standards/sist/18b42d58-366b-	4aa5- <b>≥10</b> 1-	±0,2
r, shoulder radius b1beeb3fc97c/iso-15733-2015	≥ 30	±2
Plane parallelism of machined parts	0,05	

**6.3** Type 2, is a straight-sided specimen. It is represented in Figure 2 and dimensions are given in Table 2.

NOTE This test specimen is easy to machine and its use allows mainly the determination of modulus.

Type 2 specimen should not be used for strength measurement.



