

## SLOVENSKI STANDARD oSIST prEN 50238-1:2017

01-september-2017

Železniške naprave - Združljivost voznih sredstev in sistemov za detekcijo vlaka - 1. del: Splošno

Railway applications - Compatibility between rolling stock and train detection systems - Part 1: General

Bahnanwendungen - Kompatibilität zwischen Fahrzeugen und Gleisfreimeldesystemen -Teil 1: Allgemein

Applications ferroviaires - Compatibilité entre matériel roulant et systèmes de détection de train - Partie 1 : Généralités

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29.180 Transformatorji. Dušilke Transformers. Reactors

45.060.10 Vlečna vozila Tractive stock

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### EUROPEAN STANDARD NORME EUROPÉENNE EUROPÄISCHE NORM

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#### **English Version**

### Railway applications - Compatibility between rolling stock and train detection systems - Part 1: General

Applications ferroviaires - Compatibilité entre matériel roulant et systèmes de détection de train - Partie 1 : Généralités

Bahnanwendungen - Kompatibilität zwischen Fahrzeugen und Gleisfreimeldesystemen - Teil 1: Allgemein

This draft European Standard is submitted to CENELEC members for enquiry. Deadline for CENELEC: 2017-09-22.

It has been drawn up by CLC/SC 9XA.

If this draft becomes a European Standard, CENELEC members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration.

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#### **European foreword**

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- 127 This document (prEN 50238-1:2017) has been prepared by CLC/SC 9XA "Communication, signalling and
- processing systems" of CLC/TCTC 9X "Electrical and electronic applications for railways". 128
- 129 This document is currently submitted to the Enquiry.
- 130 The following dates are proposed:
  - latest date by which the existence of this document has dor + 6 months (doa) to be announced at national level dor + 12 months
  - latest date by which this document has to be implemented at national level by publication of an identical national standard or by endorsement
  - latest date by which the national standards conflicting (dow) dor + 36 months with this document have to be withdrawn (to be confirmed or modified when voting)

(dop)

- 131 This document will supersede EN 50238-1:2003.
- 132 This European Standard was prepared under a mandate given to CENELEC by the European
- 133 Commission and the European Free Trade Association and supports the essential requirements of
- Directive 2008/57/EC. 134
- For the relationship with EU Directive(s) see informative Annex ZZ, which is an integral part of this 135
- 136 document.
- 137 The significant technical changes with respect to EN 50238-1:2003 are listed below:
- Generic compatibility process to be followed irrespective of whether the trigger is a change to the 138 signalling system, rolling stock or the power system: 139
- 140 generic Compatibility Process, which is broken into:
- 141 two stage process for assessing compatibility under Interoperability Régulations;
- single stage process for light rail and metro type railways; 142
- 143 2) rules for characterisation of interface between train and train detection systems;
- 144 rules for characterisation of Rolling Stock;
- 145 rules for characterisation of the Power System;
- references are provided to established CENELEC standards for compatibility; 146
- 147 terminology is updated and made consistent with Interoperability Régulations.
- 148 This European Standard is intended to be read in conjunction with the EN 50121 series.
- 149 Annexes designated "informative" are given for information only.
- 150 In this standard Annexes A, B, C and D are informative.

#### Introduction

151

- This European Standard defines a process to obtain the assurance that specific rolling stock operating on a specific route does not interfere with train detection systems installed on this route.
- 154 Compatibility problems between train detection systems and rolling stock are a significant obstacle to 155 cross-acceptance of rolling stock in Europe and to a degree, still an open point for assessment under the 156 Interoperability Directive. Unfortunately it is not possible to fully define general rules for the maximum
- levels of interference allowed, which are valid for every country. This is due to the great diversity of rolling
- stock, power supply and return current systems, and train detection systems installed in Europe. This diversity leads to consideration of compatibility of rolling stock and train detection systems on a 'route by
- route' or "network by network" basis, to avoid unnecessarily restrictive specifications.
- 161 The compatibility process described in this standard is generic, although reference to published limits in
- TS50238-parts two and three and ERA/ERTMS/033281 Frequency Management (FrM) rules are made, if
- 163 applicable.
- The process refers to all types of TDS (not only axle counters and track circuits), which may be influenced
- 165 by electromagnetic emissions.
- 166 Compatibility is determined by both physical and electromagnetic considerations. With regard to EMC, the
- need is not for general values for maximum levels of interference permitted, but for convenient methods
- by which to specify the level of interference allowed for operation on specific routes.
- 169 Main interference sources are considered to be:
- 170 rail currents and voltage sources;
- 171 electromagnetic fields;
- 172 differential voltage between adjacent axles of the train;
- as shown in Figure 1. It should be noted that interference sources may affect an
- as shown in Figure 1. It should be noted that interference sources may affect any railway equipment trainborne or trackside.

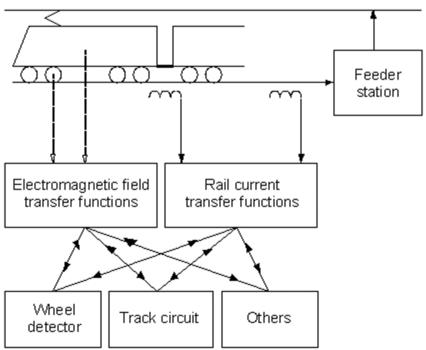


Figure 1 — Sources of electromagnetic interference

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- 177 In practice, the susceptibility of the system is determined by:
- 178 the sensitivity of individual components of the system and the type of interference it is susceptible to;
- 179 the application of the components, i.e. the configuration of the system.
- Therefore the problems concerning TDS are considered separately for each type.
- TS50238-2 defines compatibility limits for track circuits;
- 182 TS50238-3 defines compatibility limits for axle counters and wheel detectors:
- Compatibility with other types of wheel detectors (mechanical or magnetic) is described in 5.4;
- Compatibility with loops can be established following the guidance in 5.5;
- Compatibility with any other type of TDS not explicitly covered by this standard can also be established following the generic process in this standard:
- ERA/ERTMS/033281 defines in relation with TSI compatibility requirements and (partly) limits for axle counters, wheel sensors, loops and track circuits.
- 189 For determining the susceptibility of signalling systems, laboratory/simulation testing methods and in situ
- 190 tests on the "real railway" are proposed. Modelling enables worst-case conditions to be simulated. In
- addition, particular test sites are selected because, from experience, they are known to provide the test
- 192 evidence required.
- 193 Then, taking account of the experience of the railways, it is possible to establish a general method for
- determining the susceptibility of train detection systems, described in this European Standard. General
- requirements how to establish immunity have been defined in EN 50617-1 and EN 50617-2.
- 196 Before assessing the electromagnetic emissions of rolling stock, sufficient knowledge of the electric circuit
- 197 diagram of the power equipment is required, including switching frequencies of on-board power
- 198 converters, type of regulation used for power converters, resonant frequency of each filter, operating
- 199 limits under high and low supply voltages, degraded modes of operation etc.

#### 1 Scope

200

- 201 This European Standard describes a process to demonstrate compatibility between Rolling Stock (RST)
- 202 and Train Detection Systems (TDS) for specific routes. It references the methods of measurement of
- 203 interference currents and magnetic fields, the methods of measurement of the susceptibility of train
- detection systems and the characterization of traction power supplies. The process described in this
- standard is equally applicable to mainline, lightrail and metro type railways.
- 206 The basic parameters of compatibility for mainline railways are covered by the ERA Interface document
- 207 (ERA/ERTMS/033281).
- 208 It should be noted that the demonstration of compatibility between the rolling stock and infrastructure with
- respect to physical dimensions is not detailed in this standard.
- 210 Under the Interoperability Directive, two stages of compatibility are defined. The first stage is for
- authorization for putting into service against generic limits, and the second stage for putting into use,
- 212 when specific limits for compatibility with TDS are addressed which are outside the general limits or non
- interoperable TDS are installed on the line over which the RST will run.
- 214 Compatibility requirements for non-mainline or isolated light rail/metro type lines are addressed in one
- 215 stage of authorization.
- This European Standard is not generally applicable to those combinations of rolling stock, traction power
- 217 supply and train detection system which were accepted as compatible prior to the issue of this European
- 218 Standard. However, as far as is reasonably practicable, this European Standard may be applied to
- 219 modifications of rolling stock, traction power supply or train detection systems which may affect
- 220 compatibility.

221

## 2 Normative references standards.iteh.ai)

- 222 The following documents, in whole or in part, are normatively referenced in this document and are
- 223 indispensable for its application. For dated references, only the edition cited applies. For undated
- references, the latest edition of the referenced document (including any amendments) applies.
- 225 EN 50617-1, Railway applications Technical parameters of train detection systems for the
- 226 interoperability of the trans-European railway system Part 1: Track circuits
- 227 EN 50617-2, Railway Applications Technical parameters of train detection systems for the
- 228 interoperability of the trans-European railway system Part 2: Axle counters
- 229 EN 50121-5, Railway applications Electromagnetic compatibility Part 5: Emission and immunity of fixed
- 230 power supply installations and apparatus

#### 3 Terms, definitions and abbreviations

#### 232 3.1 Terms and definitions

- For the purposes of this document, the following terms and definitions apply.
- 234 **3.1.1**

- 235 competent body
- 236 body responsible for the independent evaluation of the compatibility case
- Note 1 to entry: This can be an accredited body (NoBo/DeBo/AsBo) or an Independent Safety Assessor. This role is
- 238 not limited to external parties, unless mandated under the applicable legislation.

239 240 241 242	3.1.2 compatibility case suite of documents which records the evidence demonstrating the degree of compatibility between rolling stock, traction power supplies and train detection systems for a specific route or specific railway network
243 244 245	3.1.3  Authorisation Body body responsible for autorisation to allow the new or modified systems to be put into service/use
246	Note 1 to entry: This may be subject to conditions/limitations.
247 248 249 250	3.1.4 degraded mode mode of operation in the presence of faults which have been anticipated in the design of the rolling stock., that will normally allow the rolling stock to complete its journey
251 252 253 254	3.1.5  Frequency Management The frequency management defines the maximum permissible levels of RST electromagnetic emissions, with respect to frequencies, duration and parameters for evaluation
255 256 257	3.1.6 Infrastructure Manager body responsible for the asset management of the infrastructure
258 259 260	3.1.7 rolling stock operator body responsible for the operation and maintenance of the rolling stock
261 262 263 264	3.1.8  wheel detector  sensor which detects the passage of a wheel. It may be used as part of an axle counter system or as a treadle  en-50238-1-2021
265	3.2 Abbreviations
266	For the purposes of this document, the following abbreviations apply.
	FrM Frequency Management
	IM Infrastructure Manager
	NTR National Technical Rule
	RINF Register of Infrastructure
	RSF Right Side Failure
	RST Rolling Stock
	TDS Train Detection System
	WSF Wrong side failure
267	4 Compatibility process

In the following flowdiagram, the compatibility process is described by explaining the role of the parties

involved and the processes performed by these parties. The result of the compatibility process can be an

4.1 General

acceptance certificate.

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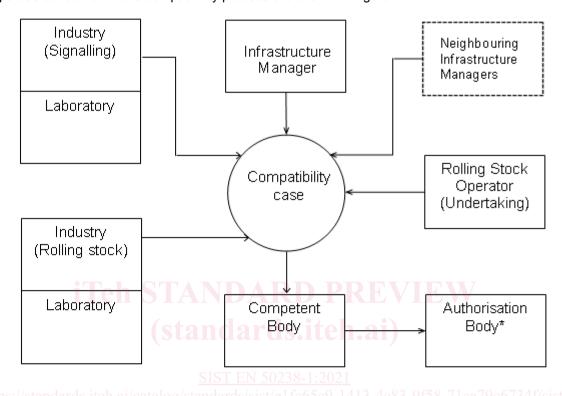
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Under Interoperability, the Authorization Body issues a letter of authorization, based on evidence presented in the Technical File (or Files). The Infrastructure Manager is consulted and their agreement is documented, as part of the evidence presented.

#### 4.2 Overview

 The parties concerned in the compatibility process are shown in Figure 2:



\*Specific arrangements may exist for local transport authorities

#### Figure 2 — Parties involved in the compatibility process

The party which introduces a new element or introduces a change of an existing element or system is responsible for demonstrating compatibility between rolling stock, train detection, traction power supply systems and neighbouring infrastructure, if applicable. The party is responsible for intiating the compatibility process. The relevant data shall be made available to the party responsible for constructing/amending the compatibility case. If data are not available or not sufficient, alternative arrangements can be made by both the responsible party and the affected party to demonstrate compatibility, for example by making specific compatibility tests. It is recommended that a competent body assesses the compatibility case if the modification is deemed a significant change. If applicable the compatibility case will be submitted to the Authorization Body, and shall be reviewed when any modification is carried out. Hereunder the specific tasks of the parties depicted in Figure 2 are listed and explained.

#### 4.3 Roles and Responsibilities

#### 4.3.1 Infrastructure Manager

In case of new or modified infrastructure the Infrastructure Manager is responsible for maintaining compatibility with the RST using the infrastructure and – as far as concerned - neighbouring infrastructures (e.g. other railways, power networks or utilities). For a defined route (the application of interest), the Infrastructure manager shall provide the relevant parameters of all train detection systems and the traction power supply systems, necessary for the compatibility case.

298	NOTE This information can be available from RINF (Register of Infrastructure), if one exists.
299	4.3.2 Rolling Stock Operator/Undertaking
300 301 302 303 304 305	The user/operator is responsible for maintaining compatibility over the full life cycle of the equipment. In case of new or modified rolling stock the (future) operator of the rolling stock is responsible. The rolling stock operator shall characterize the emissions which may be generated and propagated by the rolling stock. These emissions shall be in accordance with the specified infrastructure parameters for the considered route of operation. The emission levels may form part of the relevant entry in the Register of RST for this type of train.
306 307	NOTE The rolling stock operator may need to appoint the Rolling Stock manufacturer to characterize these emissions.
308	4.3.3 Competent Body
309 310 311	The Competent Body receives the compatibility case from the responsible party and will assess the credibility of the compatibility argument against established parameters (e.g. limits declared in the RINF or the Register of RST if applicable under the Interoperability Directive).
312	4.3.4 Authorization Body
313 314	The Authorization Body shall review the submitted documents and issue a letter of authorization or certificate of acceptance as applicable.

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4.4 Detailed compatibility process

The compatibility process is summarized in Figure 3:

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