

SLOVENSKI STANDARD SIST EN 1501-3:2021

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Vozila za zbiranje odpadlov - Splošne in varnostne zahteve - 3. del: Vozila za zbiranje odpadkov z nakladanjem spredaj

Refuse collection vehicles - General requirements and safety requirements - Part 3: Front loaded refuse collection vehicles

Abfallsammelfahrzeuge Allgemeine Anforderungen und Sicherheitsanforderungen - Teil 3: Frontlader

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Véhicules de collecte de déchets - Exigences générales et exigences de sécurité - Partie 3 : Véhicules de collecte des déchets à chargement frontal 436-4b3f-b34d-

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13.030.40	Naprave in oprema za odstranjevanje in obdelavo odpadkov	Installations and equipment for waste disposal and treatment
43.160	Vozila za posebne namene	Special purpose vehicles

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Refuse collection vehicles - General requirements and safety requirements - Part 3: Front loaded refuse collection vehicles

Véhicules de collecte de déchets - Exigences générales et exigences de sécurité - Partie 3 : Véhicules de collecte des déchets à chargement frontal Abfallsammelfahrzeuge - Allgemeine Anforderungen und Sicherheitsanforderungen - Teil 3: Frontlader

This European Standard was approved by CEN on 15 February 2021.

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This European Standard exists in three official versions (English, French, German). A version in any other language made by translation under the responsibility of a **CEN member into its own language and** notified to the CEN-CENELEC Management Centre has the same status as the official versions.

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EN 1501-3:2021 (E)

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European foreword

This document (EN 1501-3:2021) has been prepared by Technical Committee CEN/TC 183 "Waste management", the secretariat of which is held by DIN.

This European Standard shall be given the status of a national standard, either by publication of an identical text or by endorsement, at the latest by September 2021 and conflicting national standards shall be withdrawn at the latest by March 2022.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CEN shall not be held responsible for identifying any or all such patent rights.

This document supersedes EN 1501-3:2008.

This document has been prepared under a standardization request given to CEN by the European Commission and the European Free Trade Association, and supports essential requirements of EU Directive(s).

For relationship with EU Directive(s), see informative Annex ZA, which is an integral part of this document.

The main changes compared to the previous edition are listed below:

- document has been completely revised and restructured;
- European foreword and Introduction have been updated;
- Clause 1, Scope, has been slightly revised and clarified.
- Clause 2, Normative references, have been updated;
- in Clause 3, new terms and definitions have been added and others revised;
- Table 1 has been updated;
- Table 2 "Basic scenarios and applicable danger zones" and a completely new Annex C with multiple figures of danger zones has been added;
- previous Table 3 "Verification" has been deleted and information integrated in Table 1;
- requirements on compaction mechanism (5.3), discharge system (5.4), lifting devices (5.5), remote controls (5.10.3.4), monitoring and warning (5.11), maintenance (5.13), stability (5.14), noise control (5.18) and many more have been revised;
- Annex A and B have been revised;
- Annex D "Illuminated areas" has been added;
- Annex ZA has been updated.

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EN 1501 consists of the following parts under the general title *Refuse collection vehicles* — *General requirements and safety requirements*:

- Part 1: Rear loaded refuse collection vehicles;
- Part 2: Side loaded refuse collection vehicles;
- Part 3: Front loaded refuse collection vehicles (this part);
- Part 4: Noise test code for refuse collection vehicles;
- Part 5: Lifting devices for refuse collection vehicles.

This document will be enforced at the same time as EN 1501-5:2021 and applied whenever the front loaded RCV is fitted with a lifting device.

For combinations of a front loaded refuse collection vehicle with rear and/or side loading capability the corresponding clauses of standards EN 1501-1:2021, EN 1501-2:2021 and EN 1501-5:2021 apply.

According to the CEN-CENELEC Internal Regulations, the national standards organizations of the following countries are bound to implement this European Standard: Austria, Belgium, Bulgaria, Croatia, Cyprus, Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, Netherlands, Norway, Poland, Portugal, Republic of North Macedonia, Romania, Serbia, Slovakia, Slovenia, Spain, Sweden, Switzerland, Turkey and the United Kingdom.

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Introduction

This document is a type-C standard as stated in EN ISO 12100:2010.

This document is of relevance, in particular, for the following stakeholder groups representing the market players with regard to machinery safety:

- machine manufacturers (small, medium and large enterprises);
- health and safety bodies (regulators, accident prevention organizations, market surveillance etc.).

Others can be affected by the level of machinery safety achieved with the means of the document by the above-mentioned stakeholder groups:

- machine users/employers (small, medium and large enterprises);
- machine users/employees (e.g. trade unions, organizations for people with special needs);
- service providers, e.g. for maintenance (small, medium and large enterprises);
- consumers (in case of machinery intended for use by consumers).

The above-mentioned stakeholder groups have been given the possibility to participate at the drafting process of this document.

The machinery concerned and the extent to which hazards, hazardous situations or hazardous events are covered are indicated in the Scope of this document h ai

When requirements of this type-C standard are different from those which are stated in type-A or type-B standards, the requirements of this type-C standard take precedence over the requirements of the other standards for machines that have been designed and built according to the requirements of this type-C standard. 57d24cf49d92/sist-en-1501-3-2021

This standard is designed for careful consideration by designers, manufacturers, suppliers and users of front loaded RCVs.

This document should be read in conjunction with EN 1501-5:2021 developed for lifting devices which are compatible with the refuse collection vehicle specified in this document.

While producing this document it was assumed that:

- for RCV the requirements of road traffic regulations apply. Where road traffic regulations are in conflict with the provisions of this standard, the road regulations have priority;
- due to the European regulations on the approval of vehicles for use on public roads, the requirements of UN/ECE R10:2019 for an RCV with regard to EMC applies. Therefore, EMC is not further considered in this standard;
- the guidelines issued by the chassis-cab manufacturer have been taken into account;
- chassis related safety items are handled by the chassis manufacturer according to their state of the art and in compliance with the public road regulations;
- that based on measurements on different types of RCVs hand-arm vibrations are in general lower than 2,5 m/s²;
- that based on measurements on different types of RCVs whole-body vibrations are lower than 0.5 m/s^2 ;

- components without specific requirements are designed in accordance with the usual engineering
 practice and calculation codes, including all failure modes, of sound mechanical and electrical
 construction and made of materials with adequate strength and of suitable quality;
- components are kept in good repair and working order, so that the required characteristics remain despite wear and tear;
- harmful materials, such asbestos, are not used as part of the front loaded RCV;
- only persons who have been appropriately trained will operate the front loaded RCV.

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1 Scope

This document applies to a front loaded refuse collection vehicle (RCV), as defined in 3.2.

This document deals with all significant hazards, hazardous situations and events relevant to the front loaded RCV, when it is used as intended and under conditions of misuse which are reasonably foreseeable by the manufacturer, throughout its foreseeable lifetime, as defined in Clause 4.

This document is applicable to the design and construction of the front loaded RCV so as to ensure that it is fitted for its intended function and can be operated, cleaned (including unblocking), adjusted and maintained during its entire lifetime. It is not applicable to the end of life of the front loaded RCV.

This document describes and defines the safety requirements of the front loaded RCV excluding the interface with the lifting device(s) and excluding the lifting device itself and excluding loader cranes, which could be mounted on the RCV.

Safety requirements for the lifting device(s), loader cranes and their interface to the RCV are defined in EN 1501-5:2021.

Safety requirements for loader cranes are defined in EN 12999:2020. Additional specific requirements to loader cranes installed on RCVs are defined in EN 1501-5:2021.

This document also applies to compactors, operated on a truck for collecting purposes.

This document is not applicable to:

- operation in severe conditions, e.g. extreme environmental conditions such as:
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 - below -20 °C and above +40 °C temperatures; (standards.iteh.ai)
 - tropical environment;

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- wind velocity in excess of [75/km]/b standards/sist/453e6049-e436-4b3f-b34d-

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- contaminating environment;
- corrosive environment;
- operation in potentially explosive atmospheres;
- handling of loads the nature of which could lead to dangerous situations (e.g. hot refuses, acids and bases, radioactive materials, contaminated refuse, especially fragile loads, explosives);
- operation on ships.

This document is not applicable to machinery which is manufactured before the date of publication of this document by CEN.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

EN 547-1:1996+A1:2008, Safety of machinery - Human body measurements - Part 1: Principles for determining the dimensions required for openings for whole body access into machinery

EN 547-2:1996+A1:2008, Safety of machinery - Human body measurements - Part 2: Principles for determining the dimensions required for access openings

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EN 894-1:1997+A1:2008, Safety of machinery - Ergonomics requirements for the design of displays and control actuators - Part 1: General principles for human interactions with displays and control actuators

EN 894-2:1997+A1:2008, Safety of machinery - Ergonomics requirements for the design of displays and control actuators - Part 2: Displays

EN 894-3:2000+A1:2008, Safety of machinery - Ergonomics requirements for the design of displays and control actuators - Part 3: Control actuators

EN 894-4:2010, Safety of machinery - Ergonomics requirements for the design of displays and control actuators - Part 4: Location and arrangement of displays and control actuators

EN 1501-1:2021, Refuse collection vehicles - General requirements and safety requirements - Part 1: Rear loaded refuse collection vehicles

EN 1501-4:2007, *Refuse collection vehicles and their associated lifting devices - General requirements and safety requirements - Part 4: Noise test code for refuse collection vehicles*

EN 1501-5:2021, Refuse collection vehicles - General requirements and safety requirements - Part 5: Lifting devices for refuse collection vehicles

EN 60204-1:2018, Safety of machinery - Electrical equipment of machines - Part 1: General requirements (IEC 60204-1:2016, modified)

EN 60529:1991,¹), Degrees of protection provided by enclosures (IP Code) (IEC 60529:1989) (standards.iten.al)

EN 61310-1:2008, Safety of machinery - Indication, marking and actuation - Part 1: Requirements for visual, acoustic and tactile signals (IEC 61310-1:2007) 1501-3:2021

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EN ISO 374-1:2016²), Protective gloves *addinst dangerous* chemicals and micro-organisms - Part 1: Terminology and performance requirements for chemical risks (ISO 374-1:2016)

EN ISO 2867:2011, Earth-moving machinery - Access systems (ISO 2867:2011)

EN ISO 4413:2010, Hydraulic fluid power - General rules and safety requirements for systems and their components (ISO 4413:2010)

EN ISO 4414:2010, Pneumatic fluid power - General rules and safety requirements for systems and their components (ISO 4414:2010)

EN ISO 7731:2008, Ergonomics - Danger signals for public and work areas - Auditory danger signals (ISO 7731:2003)

EN ISO 12100:2010, Safety of machinery - General principles for design - Risk assessment and risk reduction (ISO 12100:2010)

EN ISO 13732-1:2008, Ergonomics of the thermal environment - Methods for the assessment of human responses to contact with surfaces - Part 1: Hot surfaces (ISO 13732-1:2006)

¹⁾ As impacted by EN 60529:1991/A1:2000 and EN 60529:1991/A2:2013.

²⁾ As impacted by EN ISO 374-1:2016/A1:2018.

EN ISO 13849-1:2015, Safety of machinery - Safety-related parts of control systems - Part 1: General principles for design (ISO 13849-1:2015)

EN ISO 13849-2:2012, Safety of machinery - Safety-related parts of control systems - Part 2: Validation (ISO 13849-2:2012)

EN ISO 13850:2015, Safety of machinery - Emergency stop function - Principles for design (ISO 13850:2015)

EN ISO 13854:2019, Safety of machinery - Minimum gaps to avoid crushing of parts of the human body (ISO 13854:2017)

EN ISO 13857:2019, Safety of machinery - Safety distances to prevent hazard zones being reached by upper and lower limbs (ISO 13857:2019)

EN ISO 14118:2018, Safety of machinery - Prevention of unexpected start-up (ISO 14118:2017)

EN ISO 14120:2015, Safety of machinery - Guards - General requirements for the design and construction of fixed and movable guards (ISO 14120:2015)

EN ISO 14122-2:2016, Safety of machinery - Permanent means of access to machinery - Part 2: Working platforms and walkways (ISO 14122-2:2016)

3 Terms and definition STANDARD PREVIEW

For the purposes of this document, the terms and definitions given in EN ISO 12100:2010 and the following apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform5 available at https://www.iso.org/obp
- IEC Electropedia: available at http://www.electropedia.org/

3.1 refuse collection vehicle

RCV

vehicle used for the collection and transportation of refuse (e.g. household refuse, bulky refuse, recyclable materials) based on loading via refuse containers or by hand

Note 1 to entry: Most of the time it consists of a chassis or rigid chassis onto which a bodywork is mounted. Sometimes it can also be a truck and trailer combination.

Note 2 to entry: A RCV is a special purpose vehicle described in 2007/46/EC Annex II, Part A, 5.8.

[SOURCE: EN 1501-1:2021, 3.1]

3.2 front loaded RCV

RCV into which the refuse or recyclable materials are loaded from the front

Note 1 to entry: In front loaded RCV's refuse is transferred manually or mechanically from the front over the rave rail into a hopper. A compaction mechanism, if fitted, then transfers and compacts the refuse from the hopper into a fixed or interchangeable body of the front loaded RCV. To discharge, either the body is tilted, rotated or an ejection device is used. The trajectory of the refuse container is over the top of the cab or the front axle, regardless where the refuse container is picked up.

3.3

cab

enclosure mounted on the chassis in front of the bodywork where the operator drives and control the RCV and where other potential operator(s) can sit

[SOURCE: EN 1501-1:2021, 3.3]

3.4

bodywork

assembly of all components fitted on the chassis-cab of the RCV including the body itself

Note 1 to entry: The bodywork can be fixed or interchangeable. The bodywork also includes either a compaction mechanism, a lifting device or (a) footboard(s) or any combination of the three.

[SOURCE: EN 1501-1:2021, 3.4]Teh STANDARD PREVIEW (standards.iteh.ai)

3.5

body

part of the bodywork in which the collected refuse is transported

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Note 1 to entry: It may be fixed or interchangeable or rotate as part of the compaction mechanism.

Note 2 to entry: To discharge the collected refuse, the body is either tilted or rotated or an ejection system is used.

Note 3 to entry: See 2 in Figure A.1.

[SOURCE: EN 1501-1:2021, 3.5 — modified, Note 3 to entry added]

3.6

discharge door

part of the bodywork, connected to the body without compaction mechanism

Note 1 to entry: It is designed to be opened to discharge the collected refuse or recyclable materials.

[SOURCE: EN 1501-1:2021, 3.8]

3.7

hopper

part of the bodywork into which the refuse is loaded either manually or mechanically

[SOURCE: EN 1501-1:2021, 3.9]

3.8

capacity of the hopper

volume of non-compacted refuse the hopper contains up, measured in cubic metres rounded off to one decimal place, when the compaction mechanism is in its fully retracted position

Note 1 to entry: See V1 in Figure B.1.

[SOURCE: EN 1501-1:2021, 3.10 — modified, Note 1 to entry added]

3.9

manual mode

mechanism achieving either each movement or each sequence of movements by a hold-to-run command

Note 1 to entry: Each sequence of movements means two or more movements in one sequence.

[SOURCE: EN 1501-1:2021, 3.14]

3.10

semi-automatic mode

mechanism achieving either each movement or each sequence of movements by a manual pulse start command

Note 1 to entry: A sequence of movements means two or more movements in one sequence.

[SOURCE: EN 1501-1:2021, 3.15] (standards.iteh.ai)

3.11

automatic mode <u>SIST EN 1501-3:2021</u> mechanism achieving a sequence of movements by a pulse start command

[SOURCE: EN 1501-1:2021, 3.16]

3.12

open and closed systems

distinct configurations of the compaction mechanism in relation to its accessibility for the operator

[SOURCE: EN 1501-1:2021, 3.18]

3.12.1

open system

configuration where the operator can reach the hazardous area of the compaction mechanism from the level on which the operator is standing

3.12.2

closed system

configuration where the operator cannot reach the hazardous area of the compaction mechanism from the level on which the operator is standing

3.13

cab shield

plate fitted to the front of the hopper for protection of the cab and the space between the cab and the bodywork from falling objects

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3.14

compaction mechanism

mechanism used to compact and/or transfer refuse and recyclable materials from the hopper into the body

[SOURCE: EN 1501-1:2021, 3.17]

3.15

discharge system

mechanism and movement for emptying the body

EXAMPLE: Ejection plate, rotating drum, tipping, walking floor.

[SOURCE: EN 1501-1:2021, 3.19]

3.15.1

ejection plate

means of emptying the body by moving the ejection plate to the rear after opening the tailgate or the discharge door if needed

[SOURCE: EN 1501-1:2021, 3.19.1]

3.15.2

rotating drum

means of emptying of the body by rotation of the drum after opening the tailgate or the discharge door if needed (standards.iteh.ai)

[SOURCE: EN 1501-1:2021, 3.19.2]

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3.15.3 tipping

means of emptying of the body by tilting the body after opening the tailgate or the discharge door if needed

[SOURCE: EN 1501-1:2021, 3.19.3]

3.16

designated refuse container refuse container compatible with the lifting device

[SOURCE: EN 1501-5:2021, 3.15]

3.17

lifting device

mechanism fitted onto the RCV for loading refuse into its body

[SOURCE: EN 1501-1:2021, 3.21]

3.18

danger zone

any zone within and/or around machinery in which a person may be exposed to a potential risk to his health or safety

Note 1 to entry: See Annex C.

[SOURCE: EN 1501-1:2021, 3.24]

3.19 interlocking gu

interlocking guard

guard associated with an interlocking device so that, together with the control system of the machine, the following functions are performed:

— the hazardous machine functions "covered" by the guard cannot operate until the guard is closed;

— if the guard is opened while hazardous machine functions are operating, a stop command is given, and

— when the guard is closed, the hazardous machine functions "covered" by the guard can operate (the closure of the guards does not by itself start the hazardous machine functions)

Note 1 to entry: EN ISO 14119:2013 gives detailed provisions.

[SOURCE: ISO 12100:2010, 3.27.4]

3.20

operator

person trained to operate the RCV

[SOURCE: EN 1501-1:2021, 3.25]

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working station location where the RCV is operated during normaluse en.ai)

Note 1 to entry: Inspection, cleaning and maintenance are excluded.

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3.22 travel movement

unrestricted motorized movement of the RCV

[SOURCE: EN 1501-1:2021, 3.28]

3.23 access door door in the bodywork for maintenance purpose

[SOURCE: EN 1501-1:2021, 3.35]

3.24 hopper lid powered flap for loading refuse and covering the hopper

3.25

transport position

designated position of the equipment during travel movement and all elements of the vehicle are in a position as defined by the manufacturer

[SOURCE: EN 1501-1:2021, 3.31]