
**Rolling bearings — Needle roller
bearings with machined rings —
Boundary dimensions, geometrical
product specifications (GPS) and
tolerance values**

*Roulements — Roulements à aiguilles avec bagues usinées —
Dimensions d'encombrement, spécification géométrique des produits
(GPS) et valeurs de tolérance*

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ISO copyright office
CP 401 • Ch. de Blandonnet 8
CH-1214 Vernier, Geneva, Switzerland
Tel. +41 22 749 01 11
Fax +41 22 749 09 47
copyright@iso.org
www.iso.org

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

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For an explanation on the voluntary nature standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see the following URL: www.iso.org/iso/foreword.html. (standards.iteh.ai)

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This fourth edition cancels and replaces the third edition (ISO 1206:2001), which has been technically revised. It also incorporates the amendment ISO 1206:2001/Amd 1:2013.

The main changes to the previous edition are as follows:

- the scope has been extended to dimensions series 59 and special series dimensions;
- the geometrical product specification (GPS) system has been applied.

Introduction

This document is a machine element geometry standard as defined in the geometrical product specification (GPS) system as presented in the matrix model of ISO 14638.

The fundamental rules of ISO/GPS given in ISO 8015 apply to this document and the default decision rules given in ISO 14253-1 apply to specifications made in accordance with this document, unless otherwise indicated.

The connection between functional requirements, measuring technique and measuring uncertainty is always intended to be considered. For measurement uncertainty, it is intended that ISO 14253-2 be considered.

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Rolling bearings — Needle roller bearings with machined rings — Boundary dimensions, geometrical product specifications (GPS) and tolerance values

1 Scope

This document specifies the boundary dimensions and normal class tolerance values for needle roller bearings with machined rings.

This document specifies dimensional and geometrical characteristics, and limit deviations from nominal sizes.

These specifications apply to complete needle roller bearings and to bearings without inner ring.

Recommended values for the tolerances for shaft raceways for needle roller bearings without inner ring are given in [Annex A](#).

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 1101, *Geometrical product specifications (GPS) — Geometrical tolerancing — Tolerances of form, orientation, location and run-out*

ISO 5593, *Rolling bearings — Vocabulary*

ISO 14405-1, *Geometrical product specifications (GPS) — Dimensional tolerancing — Part 1: Linear sizes*

ISO/TS 17863, *Geometrical product specification (GPS) — Tolerancing of moveable assemblies*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 1101, ISO 5593, ISO 14405-1, and ISO/TS 17863 apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <http://www.electropedia.org/>

4 Symbols

Descriptions for symbols are in accordance with GPS terminology; relationships with traditional terms are described in [Annex B](#), [Table B.1](#). The dimensional and geometrical specifications are described in [Table 1](#).

Tolerance value associated to a characteristic is symbolized by t , followed by the symbol of characteristic, for example, $t_{\Delta Cs}$.

In this document, the ISO default specification operator for size is in accordance with ISO 14405-1; i.e. the two-point size is valid.

Table 1 — Symbols for nominal sizes, characteristics and specification modifiers

Symbol for nominal size ^a	Symbol for characteristic	GPS symbol and specification modifier ^{b,c}	Description ^d
<i>B</i>			nominal inner ring width
	VBs	Ⓕ Ⓒ	range of two-point sizes of inner ring width
	ΔBs	Ⓕ	deviation of a two-point size of inner ring width from its nominal size
<i>C</i>			nominal outer ring width
	VCs	Ⓕ Ⓒ	range of two-point sizes of outer ring width
	ΔCs	Ⓕ	deviation of a two-point size of outer ring width from its nominal size
<i>d</i>			nominal bore diameter
	Vdmp	Ⓕ Ⓒ ACS Ⓒ	range of mid-range sizes (out of two-point sizes) of bore diameter in any cross-section of a cylindrical bore
	Δdmp	Ⓕ Ⓒ ACS	deviation of a mid-range size (out of two-point sizes) of bore diameter in any cross-section from its nominal size
<i>D</i>			nominal outside diameter
	VDmp	Ⓕ Ⓒ ACS Ⓒ	range of mid-range sizes (out of two-point sizes) of outside diameter in any cross-section
	ΔDmp	Ⓕ Ⓒ ACS	deviation of a mid-range size (out of two-point sizes) of outside diameter in any cross-section from its nominal size
<i>F_w</i>			nominal bore diameter of needle roller complement
	ΔFws	Ⓔ Ⓒ ^f	deviation of the smallest maximum inscribed cylinder size of bore diameter of needle roller complement from its nominal size

^a Symbols as defined in ISO 15241 except for the format used.

^b Symbols as defined in ISO 1101 and ISO 14405-1.

^c Specification modifier Ⓕ is not indicated on a drawing if the two-point size is applied for both specified limits.

^d Description based on ISO 1101, ISO 5459 and ISO 14405-1.

^e Symbols for direction of gravity, G, fixed parts, FP and movable parts, MP, in accordance with ISO/TS 17863 and specific flagnotes (see [Figures 1](#) and [2](#)).

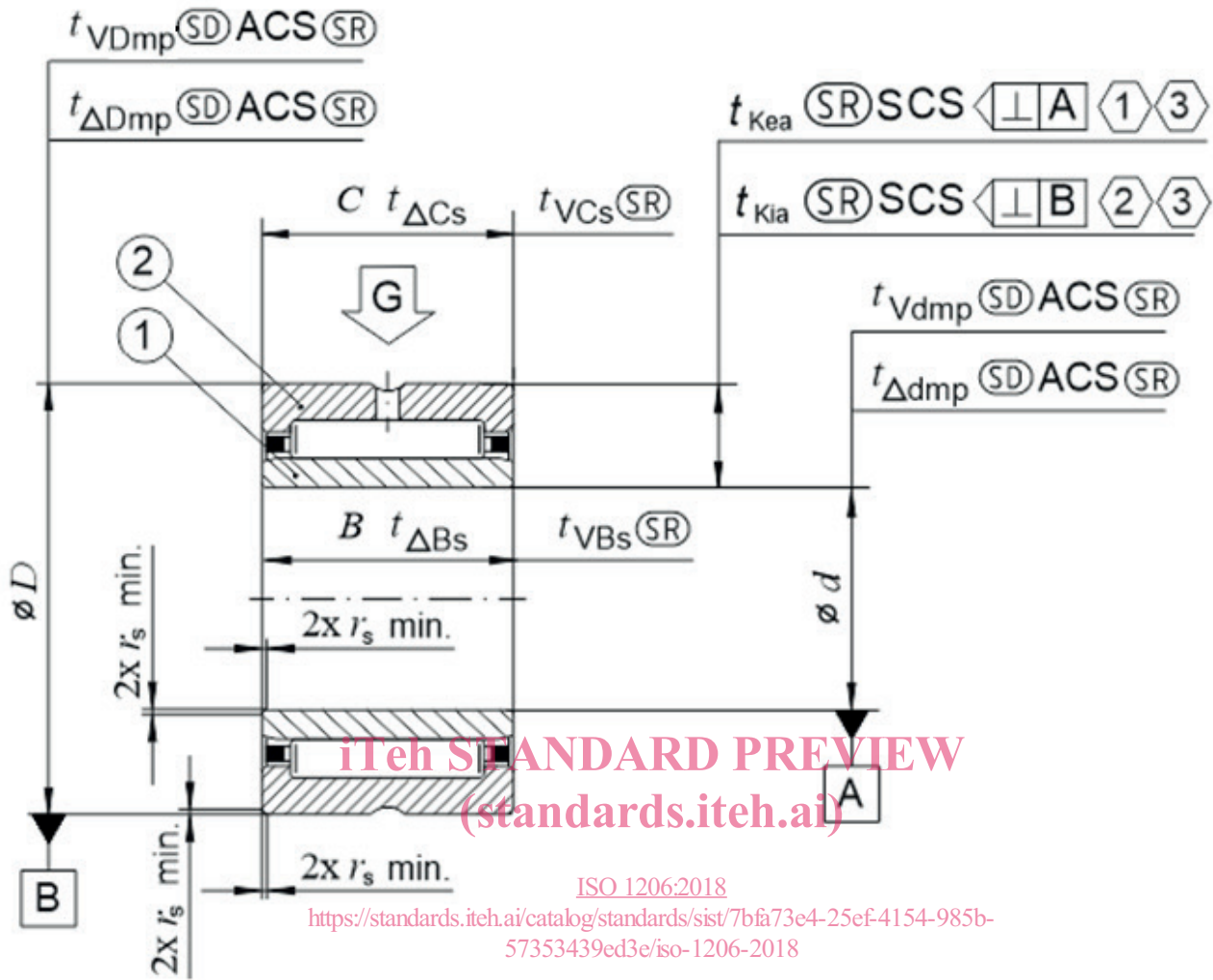
^f Considering the influence of rotation of needle roller complement.

Table 1 (continued)

Symbol for nominal size ^a	Symbol for characteristic	GPS symbol and specification modifier ^{b,c}	Description ^d
	Kea	ⓁⓅ ⓈⓇ SCSⓁⓁA ^e	range of two-point sizes of section height between inner ring bore surface and outer ring outside surface of assembled needle roller set and fixed inner ring in a specific cross section perpendicular to datum, i.e. axis, established from the inner ring bore surface
	Kia	ⓁⓅ ⓈⓇ SCSⓁⓁB ^e	range of two-point sizes of section height between outer ring outside surface and inner ring bore surface of assembled needle roller bearing, obtained from a specific cross section of turning inner ring and needle roller set and fixed outer ring perpendicular to datum, i.e. axis, established from the outer ring outside surface
<i>r</i>			nominal chamfer dimension
	<i>r_s</i>		single chamfer dimension
<p>^a Symbols as defined in ISO 15241 except for the format used.</p> <p>^b Symbols as defined in ISO 1101 and ISO 14405-1.</p> <p>^c Specification modifier ⓁⓅ is not indicated on a drawing if the two-point size is applied for both specified limits.</p> <p>^d Description based on ISO 1101, ISO 5459 and ISO 14405-1.</p> <p>^e Symbols for direction of gravity, G, fixed parts, FP and movable parts, MP, in accordance with ISO/TS 17863 and specific flagnotes (see Figures 1 and 2).</p> <p>^f Considering the influence of rotation of needle roller complement.</p>			

Figures 1 and 2 show GPS specifications for needle roller bearings with and without inner ring, respectively.

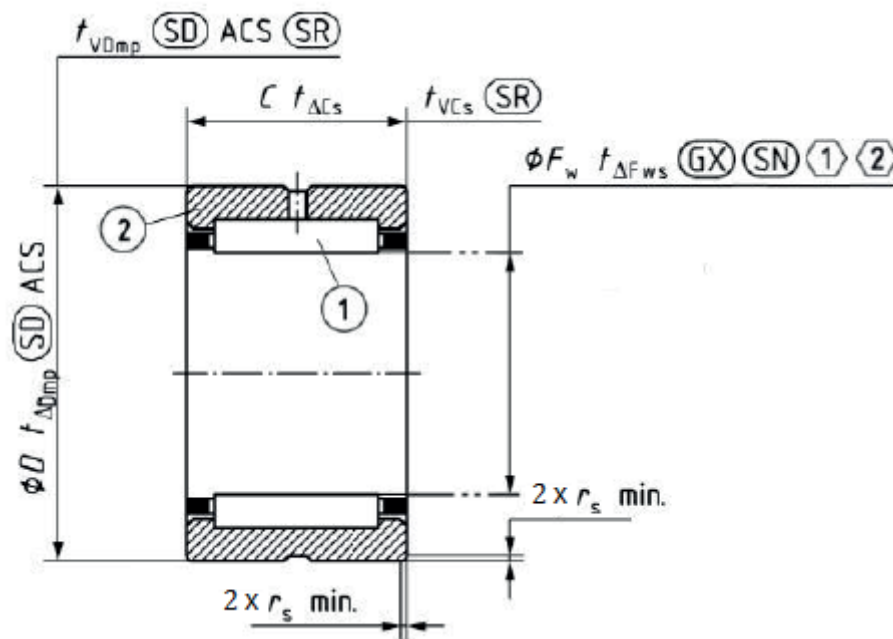
These principles shall be applied for all types of needle roller bearings (e.g. with or without cage, with one row or two rows of needle rollers and with or without lubrication groove and lubrication holes in the outer ring).



Key

- 1 FP ① - MP ②, G
- 2 FP ② - MP ①, G
- 3 the requirements apply at any specific location of the FP for any location of the MP relation to the direction of gravity where the needle rollers are in contact with both raceways of the inner and outer ring

Figure 1 — GPS specifications for needle roller bearing with inner ring



Key

① considering the influence of rotation of needle roller complement

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Figure 2 — GPS specifications for needle roller bearing without inner ring

5 Nominal boundary and chamfer dimensions

The dimension series described in Tables 2 to 5 are defined in ISO 15. Maximum chamfer dimensions are in accordance with ISO 582.

Special series dimension are given in Table 6 for needle roller bearings with inner ring and in Table 7 for needle roller bearings without inner ring.

Table 2 — Dimension series 48

Dimensions in millimetres

Complete bearings and bearings without inner ring				
d	F_w	D	B and C	r_s min.
110	120	140	30	1
120	130	150	30	1
130	145	165	35	1,1
140	155	175	35	1,1
150	165	190	40	1,1
160	175	200	40	1,1
170	185	215	45	1,1
180	195	225	45	1,1
190	210	240	50	1,5
200	220	250	50	1,5
220	240	270	50	1,5