

INTERNATIONAL STANDARD ISO 10303-109:2004

TECHNICAL CORRIGENDUM 2

Published 2014-07-01

INTERNATIONAL ORGANIZATION FOR STANDARDIZATION • МЕЖДУНАРОДНАЯ ОРГАНИЗАЦИЯ ПО СТАНДАРТИЗАЦИИ • ORGANISATION INTERNATIONALE DE NORMALISATION

Industrial automation systems and integration — Product data representation and exchange —

Part 109:

Integrated generic resource: Kinematic and geometric constraints for assembly models

TECHNICAL CORRIGENDUM 2

Systèmes d'automatisation industrielle et intégration - Représentation et échange de données de produits -

Partie 109: Ressources génériques intégrées: Contraintes cinématiques et géométriques pour les modèles -2004-cor-2-2014 d'assemblage RECTIFICATIF TECHNIQUE 2

Technical Corrigendum 2 to International Standard ISO 10303-109:2004 was prepared by Technical Committee ISO/TC 184, *Automation systems and integration*, Subcommittee SC 4, *Industrial data*.

The purpose of the modification is to the text of ISO 10303-109:2004 is to correct editorial issues.

ICS 25.040.40

Ref. No. ISO 10303-109:2004/Cor.2:2014(E)

© ISO 2014 - All rights reserved

ISO 10303-109:2004/Cor.1:2010(E) (Only Reference)

Modifications to the text of ISO 10303-109:2004

Page 2, Clause 2, Normative references

Add the following to the list of normative references:

ISO 10303-59, Industrial automation systems and integration— Product data representation and exchange—Part 59: Integrated generic resource—Quality of product shape data

Page 5, 4.1

Remove the existing EXPRESS specification and NOTE 1 and replace them with the following new EXPRESS specification and NOTE 1:

EXPRESS specification:

```
*)
SCHEMA assembly_feature_relationship_schema;

REFERENCE FROM assembly_constraint_schema; -- 10303-109
REFERENCE FROM geometry_schema; -- 10303-42
REFERENCE FROM kinematic_motion_representation_schema; -- 10303-105
REFERENCE FROM kinematic_structure_schema; -- 10303-105
REFERENCE FROM product_definition_schema; -- 10303-41
REFERENCE FROM product_property_definition_schema; -- 10303-41
REFERENCE FROM product_property_representation_schema; -- 10303-41
REFERENCE FROM product_structure_schema; -- 10303-44
REFERENCE FROM representation_schema; -- 10303-43
REFERENCE FROM support_resource_schema; -- 10303-41
REFERENCE FROM shape_data_quality_inspection_result_schema
   (using_product_definition_of_shape_representation); -- 10303-59

(*
```

NOTE 1 The schemas referenced above can be found in the following parts of ISO 10303:

```
assembly_constraint_schema ISO 10303-109 geometry_schema
ISO 10303-42 kinematic_motion_representation_schema ISO 2014
10303-105 kinematic_structure_schema ISO 10303-105
product_definition_schema ISO 10303-41
product_property_definition_schema ISO 10303-41
product_property_representation_schema ISO 10303-41
product_structure_schema ISO 10303-44 representation_schema
ISO 10303-43 support_resource_schema ISO 10303-41
shape_data_quality_inspection_result_schema ISO 10303-59
```

Pages 22 to 24, 4.5.10, 4.5.11 and 4.5.12

Delete the whole of subclause 4.5.10 and renumber subclauses 4.5.11 and 4.5.12 as 4.5.10 and 4.5.11.

Page 46, Index

Remove the line "Using product definition of shape representation".

Modifications to the text of ISO 10303-109:2004

Page iii, Contents

Removal of the line regarding Using product definition of shape representation

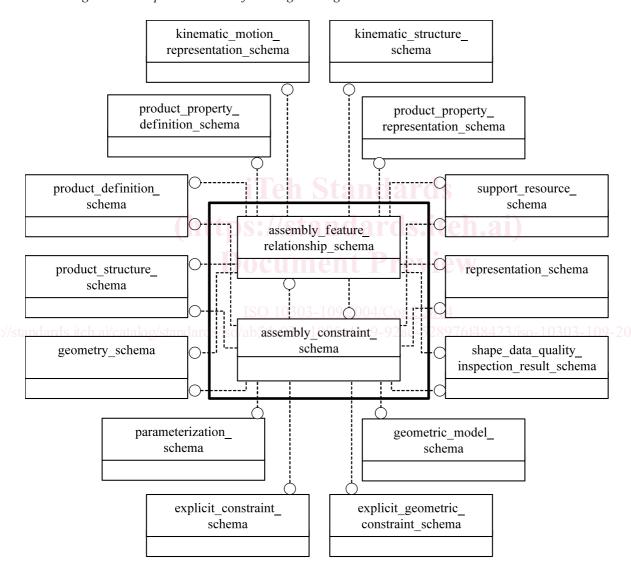
Page vii, Introduction

Addition of the following two lines at the end of the page

shape_data_quality_inspection_result_schema ISO 10303-59 support resource schema ISO 10303-41

Page viii, Figure 1

Remove Figure 1 and replace it with the following new Figure



Page 5, 4.1

Remove the existing EXPRESS specification and Note 1, and replace them with the following new EXPRESS

```
*)
SCHEMA assembly_feature_relationship_schema;
REFERENCE FROM assembly_constraint_schema; --10303-109
REFERENCE FROM geometry_schema; -- 10303-41
REFERENCE FROM kinematic_motion_representation_schema; -- 10303-105
REFERENCE FROM kinematic_structure_schema; -- 10303-105
REFERENCE FROM product_definition_schema; -- 10303-41
REFERENCE FROM product_property_definition_schema; -- 10303-41
REFERENCE FROM product_property_representation_schema; -- 10303-41
REFERENCE FROM product_structure_schema; -- 10303-44
REFERENCE FROM representation_schema; -- 10303-43
REFERENCE FROM shape_data_quality_inspection_result_schema; -- ISO 10303-59
REFERENCE FROM support_resource_schema; -- 10303-41
```

NOTE 1 The schemas referenced above can be found in the following parts of ISO 10303:

9
)5
)5
,
;

Page 7, 4.4.1

iTeh Standards

Remove the existing EXPRESS specification, and replace it with the following new EXPRESS

EXPRESS specification:

```
ENTITY shape_aspect_relationship_representation_association;
  represented_shape_aspect_relationship: shape_aspect_relationship;
  representing representation relationship: representation relationship;
WR1: ('ASSEMBLY FEATURE RELATIONSHIP SCHEMA.REPRESENTATIVE SHAPE REPRESENTATION'
    IN TYPEOF (representing representation relationship representation relationship.
    rep 1)) AND
     ('ASSEMBLY FEATURE RELATIONSHIP SCHEMA.REPRESENTATIVE SHAPE REPRESENTATION'
    TYPEOF (representing representation relationship representation relationship.
    rep 2));
WR2: (represented shape aspect relationship.relating shape aspect IN
      using shape aspect of shape representation
      (representing representation relationship.rep 1)) AND
     (represented shape aspect relationship.related shape aspect IN
      using shape aspect of shape representation
      (representing representation relationship.rep 2));
WR3: ((find representative shape representation of product definition
     (using_product_definition_of_shape_aspect
     (represented_shape_aspect_relationship.relating_shape_aspect)).
     context of items) :=:
     (find_representative_shape_representation_of_shape_aspect
     (represented_shape_aspect_relationship.relating_shape_aspect).
     context of items)) AND
     (\ ( \verb|find_representative_shape_representation_of\_product \ definition\\
     (using\_product\_definition\_of\_shape\_aspect
     (represented shape aspect relationship.related shape aspect)).
```

Page 10, 4.4.3

Remove the existing EXPRESS specification, and replace it with the following new EXPRESS

EXPRESS specification:

```
ENTITY free kinematic motion representation
        SUBTYPE OF (representation relationship with transformation);
      SELF¥representation relationship.rep 1:
          representative shape representation;
      SELF¥representation relationship.rep 2:
          representative shape representation;
      motion : kinematic path;
      WHERE
      WR1: 'REPRESENTATION SCHEMA.ITEM DEFINED TRANSFORMATION' IN TYPEOF
            (SELF¥representation relationship with transformation.
            transformation operator);
      WR2: ('GEOMETRY SCHEMA.GEOMETRIC REPRESENTATION ITEM' IN TYPEOF
            (SELF\$representation relationship with transformation.
             transformation operator¥item defined transformation.transform item 1)) AND
            ('GEOMETRY SCHEMA.GEOMETRIC REPRESENTATION ITEM' IN TYPEOF
            (SELF¥representation relationship with transformation.
             transformation operator¥item defined transformation.
      transform item 2));
      WR3: ((dimension of
            (SELF¥representation relationship with transformation.
https://standards.transformation_operator\forallitem_defined_transformation.423/iso-10303-109-2004-cor-2-2014
             transform item 1) = 3 ) AND
            (dimension of
            (SELF¥representation relationship with transformation.
             transformation operator¥item defined transformation.
             transform_item_2) = 3);
      WR4: (SELF¥representation relationship.rep 1 IN
            (using representations
            ({\tt SELFYrepresentation\_relationship\_with\_transformation.}
            {\tt transformation\_operator} {\tt Yitem\_defined\_transformation.transform\ item\ 1)\ +}
            using representation with mapping
            ({\tt SELFY-epresentation\_relationship\_with\_transformation.}
            transformation operator¥item defined transformation.transform item 1)))
           AND
            (SELF¥representation relationship.rep 2 IN
            (using representations
            ({\tt SELF} \verb| Y representation\_relation \verb| ship\_with\_transformation.
            transformation_operator\( \) transformation.transform_item_2\( ) +
            using representation with mapping
            (SELF¥representation relationship with transformation.
           transformation operator¥item defined transformation.transform item 2)));
      END ENTITY; -- free kinematic motion representation
       (*
```

Page 12, 4.4.4

Remove the existing EXPRESS specification, and replace it with the following new EXPRESS

EXPRESS specification:

```
*)
      ENTITY constrained kinematic motion representation
        SUBTYPE OF (representation relationship with transformation);
      SELF¥representation relationship.rep 1:
          representative shape representation;
      SELF¥representation relationship.rep 2:
          representative shape representation;
      WR1: ('GEOMETRY SCHEMA.AXIS2 PLACEMENT 3D' IN TYPEOF
            (SELF¥representation relationship with transformation.
           transformation operator \( \) item defined transformation.transform item 1)) AND
            ('GEOMETRY SCHEMA.AXIS2 PLACEMENT 3D' IN TYPEOF
            (SELF¥representation relationship with transformation.
           transformation operator¥item defined transformation.transform item 2));
      WR2: ((dimension of
            (SELF¥representation relationship with transformation.
           transformation operator¥item defined transformation.
           transform item 1) = 3 ) AND
            (dimension of
            (SELF¥representation relationship with transformation.
           {\tt transformation\_operator} \\ {\tt item\_defined transformation}.
           transform item 2) = 3);
      WR3: (SELF¥representation relationship.rep 1 IN
            (using representations
            (SELF\u00e4representation_relationship_with_transformation.
           transformation_operator\( \) transformation.transform_item_1) +
           using representation with mapping
            (SELF¥representation relationship with transformation.
           transformation operator item defined transformation.transform item 1))) AND
            (SELF¥representation relationship.rep 2 IN
            (using representations
            (SELF¥representation relationship with transformation.
           transformation operator¥item defined transformation.transform item 2) +
           using representation with mapping
            (SELF¥representation relationship with transformation.
          transformation operator \( \) item defined transformation.transform item 2)));
https://scwr4:d.kinematic.structure.schema.kinematic.pair.cin.typeof423/so-10303-109-2004-cor-2-2014
            (SELF¥representation relationship with transformation.
            transformation operator);
      END ENTITY; -- constrained kinematic motion representation
```

Page 13, 4.5.1

Remove the existing EXPRESS specification, and replace it with the following new EXPRESS

EXPRESS specification: