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**Road vehicles — Injury risk functions  
for advanced pedestrian legform  
impactor (aPLI)**

*Véhicules routiers — Critères lésionnels et courbes de risques pour  
l'impacteur en forme de jambe de piéton (aPLI).*

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# Contents

	Page
Foreword.....	iv
Introduction.....	v
<b>1 Scope.....</b>	<b>1</b>
<b>2 Normative references.....</b>	<b>1</b>
<b>3 Terms and definitions.....</b>	<b>1</b>
<b>4 Symbols and abbreviated terms.....</b>	<b>3</b>
4.1 Symbols.....	3
4.2 Abbreviated terms.....	4
<b>5 IPFs for an aPLI.....</b>	<b>4</b>
5.1 General.....	4
5.2 Thigh.....	6
5.3 Leg.....	7
5.4 Knee.....	8
<b>Annex A (informative) Rationale regarding background and methodology to develop IPFs for the aPLI.....</b>	<b>11</b>
<b>Annex B (informative) Adjustment of IPFs for real-world relevance.....</b>	<b>103</b>
<b>Annex C (informative) Supplemental data.....</b>	<b>133</b>
<b>Annex D (informative) Influence of PMHS test data (dfbetas &gt; 0,3) against IPFs for human.....</b>	<b>134</b>
<b>Bibliography.....</b>	<b>152</b>

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## Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see [www.iso.org/directives](http://www.iso.org/directives)).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see [www.iso.org/patents](http://www.iso.org/patents)).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see [www.iso.org/iso/foreword.html](http://www.iso.org/iso/foreword.html).

This document was prepared by Technical Committee ISO/TC 22, *Road vehicles*, Subcommittee SC 36, *Safety and impact testing*.

ISO/PRF TS 20459

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at [www.iso.org/members.html](http://www.iso.org/members.html).

## Introduction

This document has been prepared on the basis of the existing injury probability functions (IPFs) to be used with an advanced pedestrian legform impactor (aPLI) standard build level B (SBL-B). The purpose of this document is to document the IPFs for an aPLI in a form suitable and intended for worldwide harmonized use.

In 2014, development of the aPLI hardware and associated IPFs started, with the aim of defining a globally accepted next-generation pedestrian legform impactor with enhanced biofidelity and injury assessment capability, along with its IPFs, suitable for harmonized use. Participating in the development were research institutes, dummy and instrumentation manufacturers, governments, and car manufacturers from around the world.

IPFs for aPLI specified in this document predict injury probability to specific regions of the lower limb of a pedestrian that correspond to maximum values of injury metrics obtained by the aPLI in a subsystem test, as described in References [1] and [2]. As the IPFs do not provide any threshold values, users will need to determine target injury probability, based on their specific needs, to define injury assessment reference values to be used for their test protocol.

It is also important to note that the subsystem test procedure (STP) for pedestrian protection may not be representative of pedestrian accidents for specific injury metrics, depending on their sensitivity to pedestrian impact conditions such as lower-limb posture and muscle tone. The IPFs for aPLI have been validated against accident data and some ideas to compensate for the discrepancy against accident data are presented in [Annex B](#).

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# Road vehicles — Injury risk functions for advanced pedestrian legform impactor (aPLI)

## 1 Scope

This document provides definitions, symbols and injury probability functions (IPFs) for the thigh, leg and knee intended to be used with an advanced pedestrian legform impactor (aPLI), a standardized pedestrian legform impactor with an upper mass for pedestrian subsystem testing of road vehicles. They are applicable to impact tests using an aPLI at 11,1 m/s involving:

- vehicles of category M1, except vehicles with a maximum mass above 2 500 kg and which are derived from N1 category vehicles and where the driver's position, the R-point, is either forward of the front axle or longitudinally rearwards of the front axle transverse centreline by a maximum of 1 100 mm;
- vehicles of category N1, except where the driver's position, the R-point, is either forward of the front axle or longitudinally rearwards of the front axle transverse centreline by maximum of 1 100 mm;
- impacts to the bumper test area defined by References [1] and [2];
- pedestrian subsystem tests involving use of a legform for the purpose of evaluating compliance with vehicle safety standards.

## 2 Normative references

There are no normative references in this document.

## 3 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <https://www.electropedia.org/>

### 3.1

#### **adult**

person who is sixteen years old or older

### 3.2

#### **advanced pedestrian legform impactor**

#### **aPLI**

modified pedestrian legform impactor which incorporates a mass representing the inertial effect of the upper part of a pedestrian body to enhance biofidelity and *injury assessment capability* (3.10) of conventional pedestrian legforms

### 3.3

#### **biofidelity**

aspect of an *advanced pedestrian legform impactor (aPLI)* (3.2) capability to represent the impact response of human subjects

3.4

**BLE height**

bonnet leading edge height

height of the geometric trace of the upper most points of contact between a straight edge and the front-end of a car

3.5

**bumper test area**

test area of the legform to bumper impact test

3.6

**bumper system**

component installed at the hip joint inside the upper mass composed of the bumper, the bumper mount and the compression surface, designed to apply a force on the upper part of the femur in adduction to enhance *injury assessment capability* (3.10) of an *advanced pedestrian legform impactor (aPLI)* (3.2)

3.7

**EE method**

energy-equivalent method

method of developing *injury probability functions (IPFs)* (3.11) for an *advanced pedestrian legform impactor (aPLI)* (3.2) by transferring human injury values to those of an aPLI using the absorbed energy

3.8

**high-bumper car**

car with a *lower bumper reference line height* (3.14) of 425 mm or more

3.9

**hip joint**

uniaxial joint that allows abduction and adduction and connects the upper mass with the lower limb

3.10

**injury assessment capability**

aspect of an *advanced pedestrian legform impactor (aPLI)* (3.2) capability to produce peak injury values that correlate with those obtained from human body model impact simulations

3.11

**IPF**

**injury probability function**

function which defines the relationship between a peak value of an injury metric and probability of injury for a specific load case

3.12

**ISO metric**

objective rating metric used in this document to verify time histories of sensor output against experimentally or computationally produced target time histories

3.13

**low-bumper car**

car with a *lower bumper reference line height* (3.14) less than 425 mm

3.14

**LBRL height**

lower bumper reference line height

height of the geometric trace of the lowermost points of contact between a straight edge and the bumper, measured from the ground

3.15

**low-pass filter**

filter which permits only low-frequency (100 Hz or less) oscillations



**3.16****paired test method**

method of developing *injury probability functions (IPFs)* (3.11) by correlating human injury occurrence in a specific impact configuration with the injury value measured by an ATD subjected to the same impact as detailed in ISO/TR 12350:2013

**3.17****subsystem test**

test to evaluate safety performance of cars where subsystem impactors representing individual body regions of a pedestrian are propelled into a front end of a stationary car, in impact conditions representing specific load cases in car-pedestrian accidents

**3.18****transfer function****TF**

linear regression function between human injury values predicted by human body models and *advanced pedestrian legform impactor (aPLI)* (3.2) injury values

**3.19****TF method**

transfer-function method

method of developing *injury probability functions (IPFs)* (3.11) for an *advanced pedestrian legform impactor (aPLI)* (3.2) by converting human IPFs to those of aPLI using corresponding *transfer functions* (3.18)

**4 Symbols and abbreviated terms****4.1 Symbols**

See [Table 1](#).

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**Table 1 — Symbols and their meanings**

Symbol	Meaning
$C_{Scale}$	Parameter determined for the Weibull distribution for human IPFs
$C_{Shape}$	Parameter determined for the Weibull distribution for human IPFs
$C_{Slope}$	Slope of the transfer function
$C_{\mu}$	Parameter determined for the Log-Normal distribution for human IPFs
$C_{\sigma}$	Parameter determined for the Log-Normal distribution for human IPFs
$C_{TA1}$	Correction factor determined to adjust to the real-world accident data
$C_{TA2}$	Correction factor determined to adjust to the real-world accident data
$F$	IPF for human
$G$	Transfer function
$I_{human}$	Injury metric for human
$I_{aPLI}$	Injury metric for an aPLI
$P$	Injury probability of human
$P_{adj}$	Adjusted injury probability for the MCL
$x_{aPLI}$	Value of the injury metric for an aPLI
$x_{human}$	Value of the injury metric for human

## 4.2 Abbreviated terms

See [Table 2](#).

**Table 2 — Abbreviated terms and their meanings**

Abbreviation	Meaning
ACL	Anterior Cruciate Ligament
aPLI	advanced Pedestrian Legform Impactor
ATD	Anthropometric Test Device
BLE	Bonnet Leading Edge
BM	Bending Moment
EE	Energy Equivalent
EEVC	European Enhanced Vehicle-safety Committee
FE	Finite Element
HBM	Human Body Model
IPF	Injury Probability Function
LBRL	Lower Bumper Reference Line
MCL	Medial Collateral Ligament
PCL	Posterior Cruciate Ligament
PMHS	Post Mortem Human Subjects
RCM	Real Car Model
SCM	Simplified Car Model
STP	Subsystem Test Procedure
TF	Transfer Function
TG	Task Group

## 5 IPFs for an aPLI

### 5.1 General

The IPFs specified in this document are to be used with the aPLI for the thigh, leg and knee to predict the probability of injuries to pedestrians when involved in real-world car-pedestrian accidents. The IPFs provide a statistically derived relationship between the maximum values of injury metrics obtained from a test conducted using an aPLI by following the subsystem test procedure (STP), and the probability of injury to a corresponding body region of a pedestrian when subjected to load cases representative of the majority of real-world accidents.

The specific load case represented by the subsystem legform test is described below:

- pedestrian size and weight: 175,1 cm and 76,7 kg representing a 50<sup>th</sup> percentile adult male (Reference [3]);
- impact speed: 11,1 m/s;
- impact direction: lateral-to-medial direction to a pedestrian lower limb;
- lower-limb posture: upright (vertical to the ground) with the knee fully extended;
- impact height: sole of the foot positioned 25 mm above the ground to represent a shoe sole height.

First, human IPFs were determined using human biomechanical data available from the literature. Data obtained by the experiments conducted under the loading conditions equivalent to those specified in the STP were referred to. The statistical method used to derive human IPFs follows that recommended

by ISO/TS 18506 with the covariates of pedestrian size, weight and age. The pedestrian size and weight were determined from those specified in STP. The age was set at 60 years old that corresponds to the average age of the subjects of the biomechanical data as this choice was found to provide the most reasonable set of assumptions when the IPFs were fitted to the accident data. The recommended method estimates parameters of any one of the Weibull, Log-Normal or Log-Logistic distribution (choose the one that best fits to data) with survival analysis method. In this document, one of the three distributions (Weibull distribution, Log-Normal distribution or Log-Logistic distribution) is used to define human IPFs for each of the injury metrics. The formulae of the aPLI IPFs for these distributions are presented below.

The injury probability when the Weibull distribution is applied following [Formula \(1\)](#):

$$P = 1 - \exp \left\{ - \left( \frac{C_{\text{Slope}} \times x_{\text{aPLI}}}{C_{\text{Scale}}} \right)^{C_{\text{Shape}}} \right\} \quad (1)$$

where

- $P$  is the injury probability of human;
- $C_{\text{Scale}}$  is the parameter determined for the Weibull distribution for human IPFs;
- $C_{\text{Shape}}$  is the parameter determined for the Weibull distribution for human IPFs;
- $C_{\text{Slope}}$  is the slope of the transfer function (TF);
- $x_{\text{aPLI}}$  is the value of the injury metric for aPLI.

The injury probability when the Log-Normal distribution is applied following [Formula \(2\)](#):

$$P = \frac{1}{C_{\sigma} \sqrt{2\pi}} \int_0^{C_{\text{Slope}} \times x_{\text{aPLI}}} \frac{1}{t} \exp \left\{ \frac{-(\ln t - C_{\mu})^2}{2C_{\sigma}^2} \right\} dt \quad (2)$$

where

- $P$  is the injury probability of human;
- $C_{\mu}$  is the parameter determined for the Log-Normal distribution for human IPFs;
- $C_{\sigma}$  is the parameter determined for the Log-Normal distribution for human IPFs;
- $C_{\text{Slope}}$  is the slope of the TF;
- $x_{\text{aPLI}}$  is the value of the injury metric for the aPLI.

The injury probability when the Log-Logistic distribution is applied following [Formula \(3\)](#):

$$P = \frac{1}{1 + \left( \frac{C_{\text{Slope}} \times x_{\text{aPLI}}}{\exp(C_{\text{Scale}})} \right)^{C_{\text{Shape}}}} \quad (3)$$

where

- $P$  is the injury probability of human;
- $C_{\text{Scale}}$  is the parameter determined for the Log-Logistic distribution for human IPFs;
- $C_{\text{Shape}}$  is the parameter determined for the Log-Logistic distribution for human IPFs;

$C_{Slope}$  is the slope of the TF;

$x_{aPLI}$  is the value of the injury metric for the aPLI.

For each of the thigh, leg and knee, IPFs for a human body are then transferred to those of the aPLI using a TF, which is a linear function between the maximum values of a human and aPLI injury metrics. Due to the lack of biomechanical data, the TFs were determined from the results of computational impact simulations using FE human body models (HBMs) and aPLI FE models in loading conditions specified in the STP. Details of the human IPFs from which IPFs for the aPLI are derived can be found in [A.2.3](#). For the determination of TFs, see [A.2.4](#) for more details.

As the IPFs converted from human IPFs using TFs are for the specific load case defined in the STP, the number of injuries calculated from each of the injury probabilities predicted by the IPFs were compared with that of real-world accidents. The IPFs for the knee and the leg were compensated for the real-world observations for the injury metrics showing a significant inconsistency with accident data. Details of the compensation to real-world accidents can be found in [Annex B](#).

Supplemental information related to the TFs and IPFs for human is provided in [Annex C](#) and [Annex D](#), respectively.

## 5.2 Thigh

The IPF for the thigh defines probability of femur shaft fracture to a pedestrian subjected to the load cases representative of the majority of real-world accidents as a function of maximum value of the femur bending moment measured by the aPLI.

[Figure 1](#) presents the IPF for the thigh. The injury probability function is shown in a solid line, with the 95 % confidence interval shown in dotted lines. The horizontal axis represents the maximum value of the femur bending moment measured by the aPLI, and the vertical axis represents the probability of injury.

The IPF for the thigh is given by [Formula \(4\)](#):

$$P = 1 - \exp \left\{ - \left( \frac{C_{Slope} \times x_{aPLI}}{C_{Scale}} \right)^{C_{Shape}} \right\} \quad (4)$$

where

$P$  is the injury probability for the femur shaft of human;

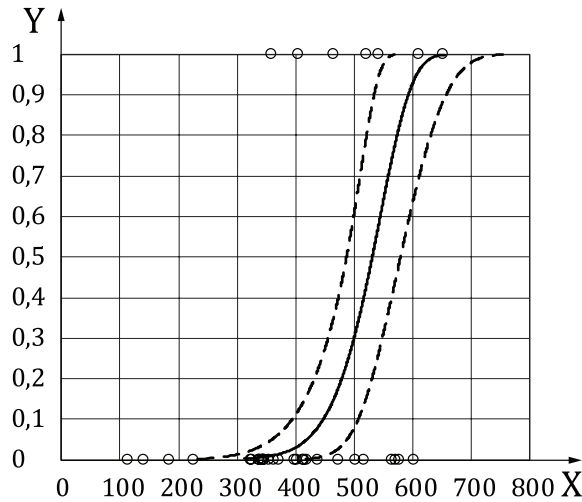
$C_{Scale}$  is the parameter determined for the Weibull distribution for the human IPF for the femur shaft as described in [A.2.3.4.1](#);

$C_{Shape}$  is the parameter determined for the Weibull distribution for the human IPF for the femur shaft as described in [A.2.3.4.1](#);

$C_{Slope}$  is the slope of the TF for the thigh as described in [A.2.4.4.1](#);

$x_{aPLI}$  is the femur BM measured by the aPLI in Nm.

The parameters needed to define the IPF ( $C_{Scale}$ ,  $C_{Shape}$  and  $C_{Slope}$ ) for the function are described in [Table 3](#).



**Key**

- X aPLI femur BM [Nm]
- Y probability of femur shaft fracture
- aPLI IPF for femur shaft
- - - - 95 % confidence interval
- o observed data

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**Figure 1 — IPF for the femur shaft**

**Table 3 — Parameters of IPF for the femur shaft**

$C_{Scale}$	$C_{Shape}$	$C_{Slope}$
571	11,0	1,04

**5.3 Leg**

The IPF for the leg defines probability of tibia shaft fracture to a pedestrian subjected to the specific load cases representative of the majority of real-world accidents as a function of maximum value of the tibia bending moment measured by the aPLI.

Figure 2 presents the IPF for the leg. The injury probability function is shown in a solid line, with the 95 % confidence interval shown in dotted lines. The horizontal axis represents the maximum value of the tibia bending moment measured by the aPLI, and the vertical axis represents the probability of injury.

The IPF for the leg is given by the Formula (5):

$$P = 1 - \exp \left\{ - \left( \frac{C_{Slope} \times x_{aPLI}}{C_{Scale}} \right)^{C_{Shape}} \right\} \tag{5}$$

where

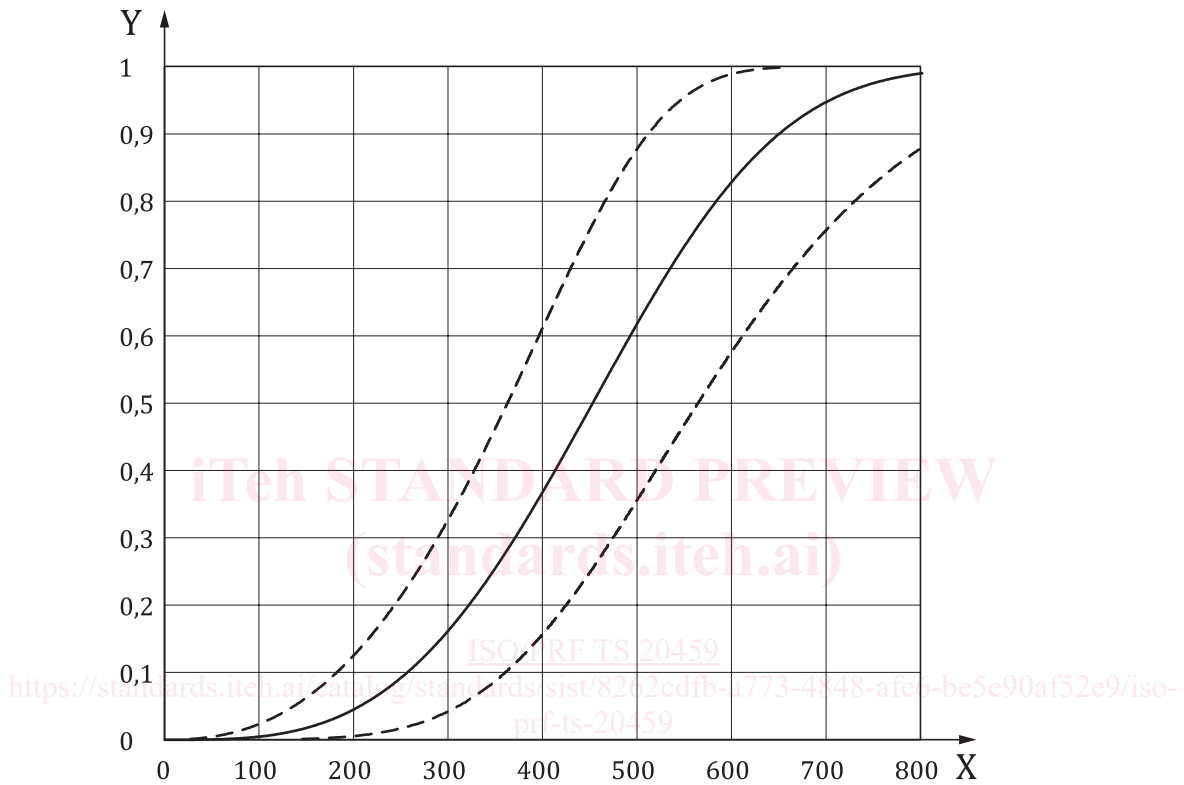
- $P$  is the injury probability for the tibia shaft of human;
- $C_{Scale}$  is the parameter determined for the Weibull distribution for the human IPF for the tibia shaft as described in B.3.3;

$C_{Shape}$  is the parameter determined for the Weibull distribution for the human IPF for the tibia shaft as described in B.3.3;

$C_{Slope}$  is the slope of the TF for the leg as described in A.2.4.4.2;

$x_{aPLI}$  is the tibia BM measured by the aPLI in Nm.

The parameters needed to define the IPF ( $C_{Scale}$ ,  $C_{Shape}$  and  $C_{Slope}$ ) for the function are described in Table 4.



**Key**  
 X aPLI tibia BM [Nm]  
 Y probability of tibia shaft fracture  
 ——— aPLI IPF for tibia shaft  
 - - - 95 % confidence interval

**Figure 2 — IPF for the tibia shaft**

**Table 4 — Parameters of IPF for the tibia shaft**

$C_{Scale}$	$C_{Shape}$	$C_{Slope}$
446	3,32	0,881

**5.4 Knee**

The IPF for the knee defines probability of complete failure of the MCL to a pedestrian subjected to the specific load cases representative of the majority of real-world accidents as a function of maximum value of MCL elongation measured by the aPLI.

[Figure 3](#) presents the IPF for the knee. The injury probability function is shown in a solid line, with the 95 % confidence interval shown in dotted lines. The horizontal axis represents the maximum value of the MCL elongation measured by the aPLI, and the vertical axis represents the probability of injury.

The IPF for the knee is given by [Formula \(6\)](#):

$$P = \frac{1}{C_{\sigma} \sqrt{2\pi}} \int_0^{C_{\text{slope}} \times x_{\text{aPLI}} \times C_{\text{TA1}} \times C_{\text{TA2}}} \frac{1}{t} \exp \left\{ \frac{-(\ln t - C_{\mu})^2}{2C_{\sigma}^2} \right\} dt \quad (6)$$

where

- $P$  is the injury probability for the MCL of human;
- $C_{\mu}$  is the parameter determined for the Log-Normal distribution for human IPFs for the MCL as described in [A.2.3.4.3](#);
- $C_{\sigma}$  is the parameter determined for the Log-Normal distribution for human IPFs for the MCL as described in [A.2.3.4.3](#);
- $C_{\text{slope}}$  is the slope of the TF for the knee as described in [A.2.4.4.3](#);
- $C_{\text{TA1}}$  is the correction factor for lower-limb posture and impact angle determined to adjust to the real-world accident data as described in [B.3.2.2.4](#);
- $C_{\text{TA2}}$  is the correction factor for muscle tone determined to adjust to the real-world accident data as described in [B.3.2.3](#);
- $x_{\text{aPLI}}$  is the MCL elongation measured by the aPLI in mm.

The parameters needed to define the IPF ( $C_{\mu}$ ,  $C_{\sigma}$ ,  $C_{\text{slope}}$ ,  $C_{\text{TA1}}$  and  $C_{\text{TA2}}$ ) for the function are described in [Table 5](#).