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ISO 14230-2

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Road vehicles — Diagnostic communication over K-Line (DoK-Line) —

Part 2: **Data link layer**

iTeh STVéhicules routiers — Communication de diagnostic sur la ligne K (DoK-Line) — (Stantage de liaison de données

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Co	ntent	S	Page
Fore	eword		v
Intr	oductio	n	vi
1	Scon	e	1
2	_	native references	
3		us, definitions, symbols and abbreviated terms	
	3.1 3.2	Terms and definitions Symbols and abbreviated terms	
		•	
4	Conv	entions	3
5	Docu	ment overview	4
6	Phys	ical bus topology	5
7		link layer overview	
•	7.1	General	
	7.2	Format description of data link layer services	7
	7.3	Services provided by the data link layer to higher layers	7
	7.4	Specification of DoK-Line data link layer service primitives	8
		7.4.1 DL_Data.request	
		7.4.2 DL_Data.confirm	
		7.4.3 DL_Data_FB indication PREVIEW 7.4.4 DL_Data_indication	9
		7.4.5 DoK-Line Init request with a large state of the large state of t	9
		7.4.5 DoK-Line Init request 1.1.5 itch ai 7.4.6 DoK-Line Initialize confirm	9
		7.4.7 DoK-Line ChangeParameter.request	10
		7.4.8 DoK-Line_ChangeParameter.confirm Service data unit specification and ards/sist/b3ba9e8a-d800-4936-a739- 7.5.1 SA, Source Address 738c2/iso-14230-2-2016	10
	7.5	Service data unit specification and ards/sist/b3ba9e8a-d800-4936-a739-	10
		7.5.2 TA, Target Address	
		7.5.3 TAtype, target address type	
		7.5.5 <messagedata></messagedata>	
		7.5.6 <result_dok-line></result_dok-line>	
		7.5.7 <initializationmodeidentifier></initializationmodeidentifier>	
		7.5.8 <initializationresultdata></initializationresultdata>	12
		7.5.9 <result_initialization></result_initialization>	
		7.5.10 <parameter_value></parameter_value>	
		7.5.11 <result_changeparameter></result_changeparameter>	13
8		ocol initialization	
	8.1	General	14
	8.2	Timing parameters for 5-BAUD_INIT	
	8.3	Protocol determination 8.3.1 5-BAUD_INIT according to ISO 9141	
		8.3.2 5-BAUD_INIT according to this document	
		8.3.3 FAST_INIT according to this document	
		8.3.4 FAST_INIT according to ISO 14230–4	
		8.3.5 Client protocol determination by server (ECU) key bytes	
	_	8.3.6 Initial data exchange after successful completion of initialization	
	8.4	Protocol specific key bytes	
		8.4.1 Format of key bytes	
		8.4.2 Key bytes for emissions-related OBD protocols of ISO 9141-2	
		8.4.4 Key bytes for enhanced diagnostics with support of ISO 14230-4	
		8 4 5 Calculation of decimal value of key bytes	25

ISO 14230-2:2016(E)

9	Mess	age definition	25
	9.1	Message structure	
	9.2	Message header	26
		9.2.1 Format byte (FMT)	
		9.2.2 Target address byte (TA)	
		9.2.3 Source address byte (SA)	
		9.2.4 Length byte (LEN)	
	0.0	9.2.5 Message header configurations	
	9.3 9.4	Protocol data unit (PDU)	
10		col timing requirements	
	10.1	General timing measurement requirements	
	10.2	Protocol timing parameter definition	29 20
		10.2.1 Inter-byte and inter-message tilling parameters	25 20
	10.3	Inter-byte message timing	
	10.3	Data link layer timing at T-Data interface	
11		nunication services	
11	11.1	StartCommunication service	
	11.1	11.1.1 Service definition	
		11.1.2 Implementation	
	11.2	StopCommunication service	
		11.2.1 Service definition 11.2.2 Implementation TANDARD PREVIEW	36
	11.3	AccessTimingParameter service 11.3.1 Service definition Standards.iteh.ai)	37
		11.3.1 Service definition Standards.iteh.ai)	37
		11.3.2 Implementation	
	11.4	SendData service <u>ISO 14230-2.2016</u>	40
		11.4.1 Service definition del ai/catalog/standards/sist/b3ba9e8a-d800-4936-a739-	
12	Data	collisions 1aac270738c2/iso-14230-2-2016	41
13	Error	handling	41
	13.1	Error handling during physical/functional 5-BAUD initialization	
		13.1.1 Client (external test equipment) error handling during physical/functional 5-BAUD-INIT	41
		13.1.2 Server (ECU) error handling during physical/functional 5-BAUD_INIT	
	13.2	Error handling during physical/functional FAST_INIT	42
		13.2.1 Client (external test equipment) error handling during physical/	
		functional FAST_INIT	42
		13.2.2 Server (ECU) error handling during physical FAST_INIT	43
		13.2.3 Server (ECU) error handling during functional FAST_INIT (normal timing on	
	13.3	Error handling after physical/functional initialization	44
		13.3.1 Client (external test equipment) communication error handling (after	4.4
		physical/functional initialization)	
		13.3.2 Server (ECU) communication error handling after physical initialization	
A	A (
		rmative) Server and client addresses for 5-BAUD_INIT	
		ormative) Recommended server and client addresses	
Anne	ex C (inf	ormative) Protocol comparison of initialization sequence	48
Bibli	ograph	V	49

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

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For an explanation on the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see the following URL: www.iso.org/iso/foreword.html.

The committee responsible for this document is ISO/TC 22, Road vehicles, Subcommittee SC 31, Data communication.

ISO 14230-2:2016

This third edition cancels and replaces the second edition (ISO 14230-2:2013), which has been technically revised. 1aac 270738c2/iso-14230-2-2016

A list of parts in the ISO 14230 series can be found on the ISO website.

Introduction

This document has been established in order to define common requirements for vehicle diagnostic systems implemented on K-Line (UART based) communication link, as specified in ISO 14230-1.

To achieve this, it is based on the Open Systems Interconnection (OSI) Basic Reference Model in accordance with ISO/IEC 7498-1 and ISO/IEC 10731, which structures communication systems into seven layers. When mapped on this model, the services specified by ISO 14230 are broken into the following:

- Diagnostic services (layer 7), specified in ISO 14229-1, ISO 14229-6;
- Presentation layer (layer 6):
 - vehicle manufacturer specific;
 - legislated WWH-OBD: ISO 27145-2, SAE 1930-DA, SAE J1979-DA, SAE J2012-DA, SAE J1939:2011, Appendix C (SPN), SAE J1939-73:2010, Appendix A (FMI);
- Session layer services (layer 5):
 - legislated OBD: specified in ISO 14229-2;
 - legislated WWH-OBD: specified in ISO 14229-2;
- Transport layer services (layer 4), specified in ISO 14230-2.
- Network layer services (layer 3), specified in ISO 14230-2;
- Data link layer (layer 2), specified in ISO 14230-4, ISO 14230-2;
- Physical layer (layer 1), specified in ISO 14230-1730-2001
 Physical layer (layer 1), specified in ISO 14230-1730-2001

in accordance with Table 1.

Table 1 — Enhanced and legislated OBD diagnostic specifications applicable to the OSI layers

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OSI seven layera	Enhanced diagnostics	Legislated OBD (On-Board Diagnostics)		Legislated WWH-OBD (On-Board Diagnostics)				
Application (layer 7)	ISO 14229-1, ISO 14229-6	ISO 15031-5		ISO 14229-1, ISO 27145-3				
Presentation (layer 6)	vehicle manufacturer specific	ISO 15031-2, ISO 15031-5, ISO 15031-6, SAE J1930-DA, SAE J1979-DA, SAE J2012-DA		ISO 27145-2, SAE 1930-DA, SAE J1979-DA, SAE J2012-DA, SAE J1939:2011, Appendix C (SPN), SAE J1939–73:2010, Appendix A (FMI)				
Session (layer 5)	ISO 1422			9-2				
Transport (layer 4)	ISO 14230-2	ISO 15765-2 ISO 11898-1		ISO 15765-4,				
Network (layer 3)	130 14230-2			ISO 15765-2				
Data link (layer 2)	ISO 14230-2		ISO 15765-4	ISO 15765-4, ISO 11898-1	ISO 27145-4			
Physical (layer 1)	ISO 14230-1	ISO 11898-1, ISO 11898-2		ISO 11898-1, ISO 11898-2				
^a Seven layers according to ISO/IEC 7498-1 and ISO/IEC 10731.								

The application layer services covered by ISO 14229-6 have been defined in compliance with diagnostic services established in ISO 14229-1 and ISO 15031-5, but are not limited to use only with them.

ISO 14229-6 is also compatible with most diagnostic services defined in national standards or vehicle manufacturer's specifications.

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Road vehicles — Diagnostic communication over K-Line (DoK-Line) —

Part 2:

Data link layer

1 Scope

This document specifies data link layer services tailored to meet the requirements of UART-based vehicle communication systems on K-Line as specified in ISO 14230-1. It has been defined in accordance with the diagnostic services established in ISO 14229-1 and ISO 15031-5, but is not limited to use with them and is also compatible with most other communication needs for in-vehicle networks. The protocol specifies an unconfirmed communication.

The diagnostic communication over K-Line (DoK-Line) protocol supports the standardized service primitive interface as specified in ISO 14229-2.

This document provides the data link layer services to support different application layer implementations like the following: $ANDARD\ PREVIEW$

- enhanced vehicle diagnostics (emissions-related system diagnostics beyond legislated functionality, non-emissions-related system diagnostics)
- emissions-related OBD as specified in ISO 15031, SAE J1979-DA and SAE J2012-DA;
- in addition, this document clarifies the differences in initialization for K-line protocols defined in ISO 9141 and ISO 14230. This is important since a server supports only one of the protocols mentioned above and the client has to handle the coexistence of all protocols during the protocol determination procedure.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 14230-4, Road vehicles — Diagnostic systems — Keyword Protocol 2000 — Part 4: Requirements for emission-related systems

3 Terms, definitions, symbols and abbreviated terms

3.1 Terms and definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- IEC Electropedia: available at http://www.electropedia.org/
- ISO Online browsing platform: available at http://www.iso.org/obp

3.1.1

5 baud initialization

5-BAUD_INIT

starts with bus idle and ends with inverted address byte sent by the server

3.1.2

fast initialization

FAST INIT

starts with bus idle and ends with the reception of all positive responses of the StartCommunication service from all addressed servers

3.1.3

topology

serial link between client and servers and consists of a K-Line and an optional L-Line

server

function that is part of an electronic control unit and that provides the diagnostic services

client

function that is part of the tester and that makes use of the diagnostic services

Note 1 to entry: A tester normally makes use of other functions such as database management, specific interpretation, human-machine interface.

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3.2 Symbols and abbreviated terms

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5-BAUD_INIT 5-baud initialization

ISO 14230-2:2016 ISO 9141-2 5-BAUD_INIT http://protocol.on.kr.Line.according.to.ISO 9141-2 including 5-BAUD_INIT

laac270738c2/iso-14230-2-2016 Protocol on K-Line according to ISO 14230-2 including 5-BAUD_INIT ISO 14230-2 5-BAUD_INIT

ISO 14230-2 FAST_INIT Protocol on K-Line according to ISO 14230-2 including FAST_INIT

ISO 14230-4 5-BAUD_INIT Protocol on K-Line according to ISO 14230-4 including 5-BAUD_INIT

ISO 14230-4 FAST INIT Protocol on K-Line according to ISO 14230-4 including FAST_INIT

bus converter electronic control unit that links bus systems

client external test equipment

confirm confirmation service primitive

Convention: M = mandatory, C = conditional, U = user-optional Cvt

ECU electronic control unit

FAST_INIT fast initialization

FB first byte

format byte **FMT**

linking hardware between bus systems gateway

destination address DA

DoK-Line Diagnostic communication over K-Line DoK-Line_SA data link source address

DoK-Line_TA data link target address

DoK-Line_TAtype data link target address type

indication indication service primitive

LEN Length byte

Mtype message type

request request service primitive

DL_Data data link data

DoK-Line_PCI data link protocol control information

DoK-Line_PCItype data link protocol control information type

DoK-Line_PDU data link protocol data unit

DoK-Line_SA data link source address

DoK-Line_SDU data link service data unit

P1_{Receiver} iTe inter-byte timing parameter of the server

P2_{Server} time between client request and server response or two server responses

P3_{Client} time between end of server responses and start of new client request

P4_{Sender} https://standards.iteh.ai/catalog/standards/sist/b3ba9e8a-d800-4936-a739-inter-byte-timing parameter of the client

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SA source address

server electronic control unit (ECU)

TA target address

UART universal asynchronous receiver and transmitter

WUP wake up pattern

4 Conventions

This document is based on the conventions discussed in the OSI Service Conventions (ISO/IEC 10731) as they apply for diagnostic services.

These conventions specify the interactions between the service user and the service provider. Information is passed between the service user and the service provider by service primitives, which may convey parameters.

Figure 1 summarizes the distinction between service and protocol.

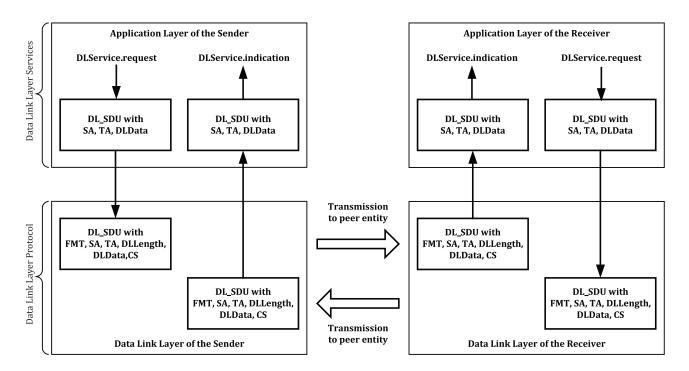


Figure 1 — Services and protocol

NOTE Figure 1 does not show the confirmation generated on the transmitter side of the message.

This document defines confirmed services. The confirmed services use the three service primitives request, indication and confirmation.

ISO 14230-2:2016

For all services defined in this document the request and indication service primitives always have the same format and parameters.

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5 Document overview

Figure 2 shows the diagnostic communication over K-Line document reference according to OSI model.

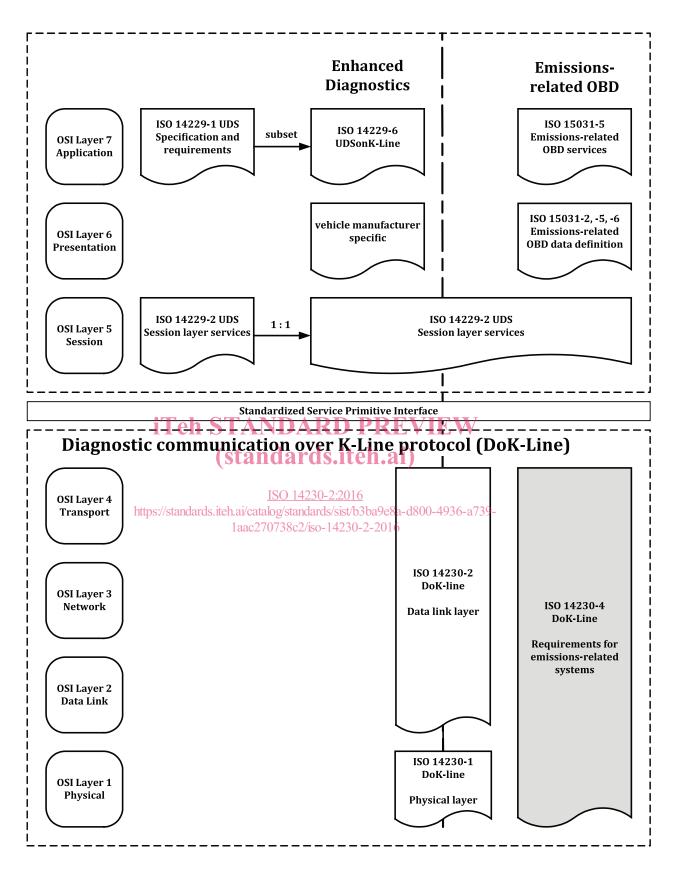
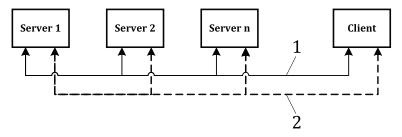


Figure 2 — DoK-Line document reference according to OSI model

6 Physical bus topology

DoK-Line is a bus concept based on a serial link consisting of one or two physical lines.

Figure 3 shows the server and client topology.



Key

- 1 K-Line
- 2 L-Line (optional)

Figure 3 — Server and client topology

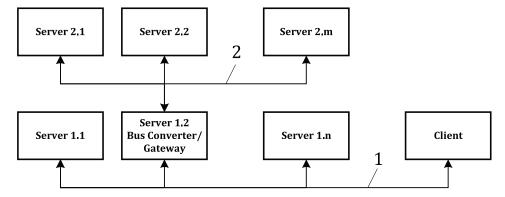
"K-Line" is used for communication and initialization, "L-Line" (optional) is used for initialization only. Special cases are node-to-node connection that means only one server (ECU) on the line, which also can be a bus converter.

The following recommendations apply:

- it is recommended to no longer support the L-Line in server (ECU) hardware;
- client (external test equipment) hardware shall support the L-Line if compliance to ISO 15031-4 is required.

For more detail, refer to ISO 14230-1 "K-/L-line configurations".

Figure 4 illustrates an example of multiple servers (ECUs) connected with the K-Line to the client (external test equipment). Server 1.2 (ECU 1.2) functions as a gateway (bus converter) and is operating on a bus system (e.g. ISO 15765, SAE J1850).



Key

- 1 K-Line
- 2 arbitrary bus system

Figure 4 — Gateway topology example

7 Data link layer overview

7.1 General

This document specifies the data link layer services which are used in client-server based systems to transmit data from one to the other entity. The client, referred to as external test equipment, uses the data link layer services to transfer diagnostic request data to one or more servers, referred to as an ECU. The server, usually a function that is part of an ECU, uses the data link layer services to send response data, provided by the requested diagnostic service, back to the client. The client is usually external test equipment, but can in some systems also be an on-board test equipment. The usage of data link layer services is independent from the external test equipment being an off-board or on-board test equipment. It is possible to have more than one client (test equipment) in the same vehicle system.

In order to describe the function of the data link layer, services provided to higher layers and the internal operation of the data link layer has to be considered.

7.2 Format description of data link layer services

All data link layer services have the same general format. Service primitives are written in the form:

```
service_name.type

[parameter 1, parameter 2, parameter 3, ...]

where

service_name

is the name of the diagnostic service (i.e. DL_Data);

type

indicates the type of the service primitive (i.e. request);

[parameter 1, ...] are parameters that depend on the specific service (i.e. parameter 1 can be the httpsource address of the sender). The brackets indicate that this part of the parameter list may be empty 8c2/iso-14230-2-2016
```

7.3 Services provided by the data link layer to higher layers

The data link layer service interface defines a set of services that are needed to access the functions offered by the data link layer, i.e. transmission/reception of data, setting of data link layer parameters.

The service access point of the data link layer provides the following service primitives as specified.

- Using the service primitive request (service_name.request), a service user requests a service from the service provider.
- Using the service primitive indication (service_name.indication), the service provider informs a
 service user about an internal event of the network layer or the service request of a peer protocol
 layer entity service user.
- With the service primitive confirm (service_name.confirm), the service provider informs the service user about the result of a preceding service request of the service user.

The following three types of services are defined.

a) Initialization services

These services, of which the following are defined, provide the functionality to perform the initialization of the DoK-Line communication.

- DoK-Line_Initialize.request: this service is used to request the DoK-Line communication.
- DoK-Line_Initialize.confirm: this service confirms to the higher layers that the DoK-Line communication has been carried out (successfully or not).