

SLOVENSKI STANDARD oSIST prEN 50728:2023

01-maj-2023

Železniške naprave - Vozna sredstva - Preskušanje elektromagnetne združljivosti s tirnimi tokokrogi

Railway applications - Rolling stock - Testing for electromagnetic compatibility with track circuits

iTeh STANDARD PREVIEW

(standards.iteh.ai)

Applications ferroviaires - Matériel roulant - Essais pour la compatibilité électromagnétique avec les circuits de voie

https://standards.iteh.ai/catalog/standards/sist/80436d79-9f47-4521-9212

Ta slovenski standard je istoveten z: prEN 50728

ICS:

29.280 Električna vlečna oprema Electric traction equipment 33.100.01 Elektromagnetna združljivost Electromagnetic compatibility

na splošno in general

45.060.10 Vlečna vozila Tractive stock

oSIST prEN 50728:2023 en

EUROPEAN STANDARD NORME EUROPÉENNE EUROPÄISCHE NORM

DRAFT prEN 50728

March 2023

ICS 29.280; 45.060.10

English Version

Railway applications - Rolling stock - Testing for electromagnetic compatibility with track circuits

To be completed To be completed

This draft European Standard is submitted to CENELEC members for enquiry. Deadline for CENELEC: 2023-06-16.

It has been drawn up by CLC/SC 9XB.

If this draft becomes a European Standard, CENELEC members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this European Standard the status of a national standard without any alteration.

This draft European Standard was established by CENELEC in three official versions (English, French, German). A version in any other language made by translation under the responsibility of a CENELEC member into its own language and notified to the CEN-CENELEC Management Centre has the same status as the official versions.

CENELEC members are the national electrotechnical committees of Austria, Belgium, Bulgaria, Croatia, Cyprus, the Czech Republic, Denmark, Estonia, Finland, France, Germany, Greece, Hungary, Iceland, Ireland, Italy, Latvia, Lithuania, Luxembourg, Malta, the Netherlands, Norway, Poland, Portugal, Republic of North Macedonia, Romania, Serbia, Slovakia, Slovenia, Spain, Sweden, Switzerland, Türkiye and the United Kingdom.

Recipients of this draft are invited to submit, with their comments, notification of any relevant patent rights of which they are aware and to provide supporting documentation.

Warning: This document is not a European Standard. It is distributed for review and comments. It is subject to change without notice and shall not be referred to as a European Standard.



European Committee for Electrotechnical Standardization Comité Européen de Normalisation Electrotechnique Europäisches Komitee für Elektrotechnische Normung

CEN-CENELEC Management Centre: Rue de la Science 23, B-1040 Brussels

© 2023 CENELEC All rights of exploitation in any form and by any means reserved worldwide for CENELEC Members.

Project: 69343 Ref. No. prEN 50728 E

Contents	Page
European foreword	6
Introduction	7
1 Scope	8
2 Normative references	8
3 Terms, Definitions and Abbreviations	8
3.1 Terms and Definitions	8
3.2 Abbreviations	13
4 Test specification	14
4.1 Preparation	14
4.1.1 General	14
4.1.2 Vehicle data	14
4.1.3 Applicable requirements	15
4.1.4 Pre-analysis	15
4.2 Test plan	16
4.3 Test equipment	16
4.3.1 Sensor location	
4.3.2 Current or voltage measurement	16
4.3.3 Apparatus	
4.3.4 Other signals and information	17
4.4 Test conditions	
4.4.1 Vehicles *://standards.iteh.ai/eatalog/standards/sist/80436d79-9f47-452	1-9212- 17
4.4.2 Infrastructure 863a66e7a6c4/osist-pren-50728-2023	18
4.4.3 Environment	20
4.5 Test procedure for vehicles	21
4.5.1 Pre-tests	21
4.5.2 Static tests	21
4.5.3 Dynamic tests	21
4.5.4 Online evaluation	22
4.5.5 Long term tests	22
4.6 Test conditions for separate auxiliary converters	23
4.6.1 General	23
4.6.2 Definition of requirements	23
4.6.3 Test procedure	23
4.7 Check of input impedance	24
4.7.1 Passive Inductive impedance	24
4.7.2 Passive Capacitive impedance	24
4.7.3 Controller influence	25
5 Evaluation	25

5.1	(Jenerai metnod	25
5.2	5	Summation rules	25
5	.2.1	General	25
5	.2.2	Scaling from one to N sources	25
5	.2.3	Required number of tests and scaling of measurements of multiple sources	27
5	.2.4	Scaling Influence of Impedance	28
5.3	5	Special effects	29
5	.3.1	Interlacing of converters	29
5	.3.2	Influence of external sources	29
5	.3.3	Resonances	29
5.4	F	Phenomena to be discarded	29
5	.4.1	Variation of line voltage	29
5	.4.2	Variation of supply frequency	29
5	.4.3	Asymmetry in the public supply network and substation load	29
5	.4.4	Transients	30
5	.4.5	Other rolling stock	30
5	.4.6	Electric traction power supply system resonances	30
5.5	٦	Fest report	31
5.6	F	Pass / fail criteria	31
Annex	κ A (r	normative) Measurement equipment	32
A.1		neral	
A.2	Wh	ole measurement chain OSIST DEEN 50728:2023	32
A.3	Vol	https://standards.iteh.ai/catalog/standards/sist/80436d79-9f47-4521-9212- tage sensors 863a66e /a6c4/osist-pren-50728-2023	33
A.4	Cui	rrent sensors	33
A.5		sonance damping devices for test	
Annex	к В (r	normative) Resonances	34
B.1	Am	plification factors	34
B.2	Ме	asurement setups	36
B.3	Coi	mparison with limits	37
Annex	С (i	nformative) Handling of transients	39
C.1	Ge	neral	39
C.2	Gui	idance	39
C.3		ntification of the cause	
C.4	Red	commendations	41
C.5	Exa	amples	41
Annex	•	nformative) Substation, traction and auxiliary system structures	
D.1		neral	
D.2		erall system	
D.3		substations	
D.4	DC	substations	46

D.5	AC rolling stock	48
D.6	DC rolling stock	49
Annex	E (informative) Background on summation rules	51
E.1	Definitions	51
E.2	Scaling factors	51
E.3	Example: EMU with four power cars	53
E.4	Example: Locomotive with two independent bogies	54
E.5	Choice of summation rule	55
Annex	F (informative) Resonances	58
F.1	General	58
F.2	System definition	58
F.3	Resonance amplification	59
F.4	Relevance in railway systems	61
F.5	Identification of resonances from measurements	62
F.6	Example	65
Annex	G (informative) Converters with small input filters	69
G.1	Introduction	
G.2	Problems with such converters	69
G.3	Analysis	69
G.4	Tests (Standards iteh ai)	70
	H (informative) Superposition of interference from electric traction power supply system and rolling ste	
	SIST prEM 50728-2023	
H.1	General https://standards.iteh.ai/catalog/standards/sist/80436d79-9f47-4521-9212-	
H.2	Equivalent circuit diagram863a66e7a6c4/osist-pren-50728-2023	
H.3	AC systems	
H.4	DC systems	
	I (informative) Voltage versus current measurement in DC vehicles	
l.1	Traction system	
1.2	Goal	
1.3	Influence of a magnetic core	
1.4	Characteristics of an air cored inductor	
l.5	Resonances in the filter inductor	
	J (informative) Automatic data processing	
J.1	General	
J.2	Identification of interference source(s)	
J.3	Characterization of identified interference sources	
J.4	Justification of completeness	
J.5	Transients	
J.6	Quantify the maximum value(s) of the respective interference source(s)	
	ZZ (informative) Relationship between this European Standard and the Essential Requirements ective (EU) 2016/797 aimed to be covered	

prEN	50728	8:2023	(E)
------	-------	--------	-----

ibliography81

iTeh STANDARD PREVIEW (standards.iteh.ai)

<u>oSIST prEN 50728:2023</u> https://standards.iteh.ai/catalog/standards/sist/80436d79-9f47-4521-9212-863a66e7a6c4/osist-pren-50728-2023

European foreword

This document (prEN 50728:2023) has been prepared by CLC/SC 9XB "Electromechanical material on board rolling stock" of CLC/TC 9X "Electrical and electronic applications for railways".

This document is currently submitted to the Enquiry.

The following dates are proposed:

•	latest date by which the existence of this document has to be announced at national level	(doa)	dor + 6 months
•	latest date by which this document has to be implemented at national level by publication of	(dop)	dor + 12 months

 latest date by which this document has to be implemented at national level by publication of an identical national standard or by endorsement

> (dow) dor + 36 months (to be confirmed or modified when voting)

 latest date by which the national standards conflicting with this document have to be withdrawn

This document has been prepared under a Standardization Request given to CENELEC by the European Commission and the European Free Trade Association, and supports essential requirements of EU Directive(s) / Regulation(s).

For relationship with EU Directive(s) / Regulation(s), see informative Annex ZZ, which is an integral part of this document.

oSIST prEN 50728:2023
https://standards.iteh.ai/catalog/standards/sist/80436d79-9f47-4521-9212-863a66e7a6c4/osist-pren-50728-2023

Introduction

This document defines the testing, measurement and evaluation methods for rolling stock interference current emissions to demonstrate compatibility with track circuits. The evaluation is done at the interface between rolling stock and infrastructure (the total interference current of the IU), and not at the receiver of a track circuit.

In the context of European interoperability, interference current limits for rolling stock are defined in the TSI Interface document ERA/ERTMS/033281.

Outside European interoperability, individual limits and summation rules are defined in other documents such as NNTRs and PD CLC/TS 50238-2. In specific application cases outside the scope of Interoperability Regulations, limit values may be notified by the track circuit manufacturer, according to the process defined in EN 50617-1.

Proof of compliance of rolling stock with the interference current limits is done in three main steps. First, a test plan shall be defined, based on the specific characteristics of rolling stock to be tested (see 5). This shall ensure that the final results give a sufficient confidence level of compliance. Then the tests are performed according to the plan. Finally, the results shall be evaluated under a defined set of rules, in order to demonstrate compliance with the given limits (see 6).

Tests for the demonstration of vehicle compatibility are type tests and shall be performed before the first unit is put into regular service. When done according to this document, it is the goal to perform measurements only once per electric traction power supply system voltage and frequency.

As far as possible, common requirements are defined for both AC and DC electric traction power supply systems. However, these differ in several aspects. In AC systems, the impedance of the electric traction power supply system is small compared with the impedance of the vehicle, but resonance effects have to be considered. The main source of interference is the rolling stock. In DC systems, the impedance and, therefore, the distance from substations, is important, but resonance effects are largely neglectable. Rectifier substations have a significant contribution to the total interference current in DC systems, and also the traction and auxiliary systems of DC rolling stock are normally different from those of AC. Where necessary or appropriate, this document differentiates between AC and DC systems.

In order to limit the influence from static converters (AC) and substations (DC) on track circuits, a minimum rolling stock impedance is required. This document defines how to prove conformity with such requirements as well.

1 Scope

This document defines the measurement and evaluation methods of rolling stock interference current emissions to demonstrate compatibility with track circuits. This includes rolling stock with or without traction equipment. The established limits for compatibility are defined in ERA/ERTMS/033281, PD CLC/TS 50238-2 or NNTRs as current flowing between the vehicle and the electric traction power supply system that can disturb the track circuit receiver, as part of the track circuit system. Additionally, the referred documents can define a minimum rolling stock impedance in order to guarantee compatibility between the electric traction power supply system and track circuits.

This document is relevant to the interference current limits defined in the 'frequency management' for track circuits as defined in ERA/ERTMS/033281. It is also applicable to the demonstration of compatibility with all other types of track circuits which have established compatibility according to EN 50617-1. Finally, the methodology defined in this document can also be applied to other track circuit types, including those for which the only requirements are defined in National Notified Technical Rules.

NOTE Interface parameters between rolling stock and track circuits other than interference currents and impedance are out of the scope of this document.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

EN 50388-1:2022, Railway Applications - Fixed installations and rolling stock - Technical criteria for the coordination between electric traction power supply systems and rolling stock to achieve interoperability - Part 1: General

EN 50163:2004,1 Railway applications. Supply voltages of traction systems

ISO/IEC Guide 98-3:2008, Uncertainty of measurement - Part 3: Guide to the expression of uncertainty in measurement (GUM:1995)

UIC 550:2005-04, Power supply installations for passenger stock

3 Terms, Definitions and Abbreviations

3.1 Terms and Definitions

For the purposes of this document, the following terms and definitions apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- IEC Electropedia: available at https://www.electropedia.org/
- ISO Online browsing platform: available at https://www.iso.org/obp

3.1.1

infrastructure

all fixed railway installations

Note 1 to entry: In the given context it includes the electric traction power supply system and train detection systems.

¹ As impacted by EN 50163:2004/A1:2007, EN 50163:2004/corrigendum May 2010, EN 50163:2004/AC:2013, EN 50163:2004/A2:2020, EN 50163:2004/A3:2022.

3.1.2

electric traction power supply system

railway electric distribution network used to provide energy for rolling stock

Note 1 to entry: The system includes

- contact line systems,
- return circuit of electric traction systems,
- running rails of non-electric traction systems, which are in the vicinity of, and conductively connected to the running rails of an electric traction system,
- electric installations, which are supplied from contact lines either directly or via a transformer,
- electric installations in power plants and substations, which are utilized solely for generation and distribution of power directly to the contact line,
- electric installations of switching stations.

[SOURCE: IEC 60050-811:2017, 811-36-21], modified – "power supply" has been added in the term

3.1.3

substation

installation which supplies a contact line

Note 1 to entry: The voltage of a primary supply system, and in certain cases the frequency, is converted by the substation to the voltage and frequency of the contact line.

3.1.4

influencing unit

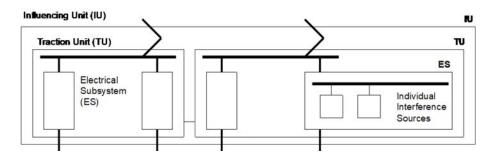
IU

rolling stock influencing the train detection system

Note 1 to entry: One influencing unit comprises all coupled / connected vehicles, e.g. complete train with single or multiple traction, single vehicle, multiple connected / coupled vehicles and wagons, e.g. one complete passenger train, consisting of one or more TUs and coaches.

Note 2 to entry: The influencing unit can consist of several "Traction Units" (TU).

See Figure 1 for clarification.



Individual sources may not be accessible for measurement directly.

Figure 1 — Definition of IU, TU and Electrical Subsystem (ES)

[SOURCE: CLC/TS 50238-2:2020, modified – Note 1 amended, Note 2 added, Figure 1 added]

3.1.5

traction unit

TU

locomotive, motor coach or train-unit

Note 1 to entry: Each TU is fed from one pantograph or collector (or UIC busbar in case of coaches / wagons). One TU may be

- one locomotive;
- one electric multiple unit, with one or several Electrical Subsystems (ES) in one or several cars;
- one complete passenger train, consisting of individual passenger coaches with or without a locomotive;
- one complete freight train, consisting of individual freight wagons with or without a locomotive.

See Figure 2 for clarification.

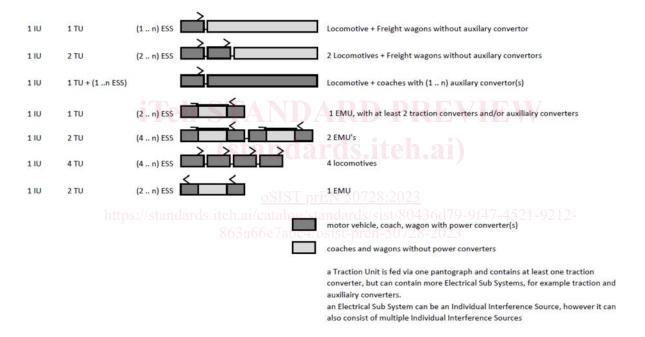


Figure 2 — Term clarification for Traction unit (TU) and Influencing Unit (IU)

[SOURCE: IEC 60050-811:2017, 811-02-04, modified – The note to entry has been added. Figure 2 has been added.]

3.1.6

electrical subsystem

ES

smallest unit which is practicably accessible for interference current measurements

Note 1 to entry: See Figure 1 and Figure 2.

Note 2 to entry: An ES is fed from the line voltage via distribution lines inside a TU. Internally, an ES may consist of one or several interference sources (such as traction and / or auxiliary converters) which cannot practicably be evaluated individually.

3.1.7

individual interference source

IIS

smallest subset of an electrical subsystem that can be identified and characterised as an interference current source

Note 1 to entry: The individual interference source is the basis for evaluation of the total interference current produced by an influencing unit.

Note 2 to entry: Individual interference sources can be various types of components and their control.

3.1.8

UIC busbar

single-pole line for the supply of auxiliaries through a whole train according to UIC 550:2005-04

Note 1 to entry: The return current flows through the rails.

3.1.9

normal operating mode

mode of operation of rolling stock with all electrical subsystems in fault-free working configuration

3.1.10

degraded mode

mode of operation of rolling stock with a reduced number of electrical subsystems, which has been anticipated in the design

Note 1 to entry: Degraded modes (failure modes) are operating modes which can be activated in order to isolate a defect and continue the operation of the rolling stock. When operating in a degraded mode the system performance might be reduced. Examples of degraded modes are deactivated traction motors or traction converters that have an impact on the remaining ones, such as increasing power and / or traction, changing the interlacing strategy or switching frequency, etc.

[SOURCE: IEC 60050-821:2017, 821-01-52, modified – reworded and note added]

3.1.11

line current

current that flows from the contact line via the pantograph(s) (or current collectors) through the IU, TU or ES to the traction return circuit

Note 1 to entry: In this document, line current is used in a more general sense and not only to the pantograph current to one TU.

3.1.12

interference current

undesired frequency content in the line current, which is in the operating frequency range of the track circuits

3.1.13

interference current limit

maximum interference current which an influencing unit is allowed to produce at a given frequency to remain compatible with a track circuit

Note 1 to entry: Interference current limits are defined in ERA/ERTMS/033281, NNTRs or PD CLC/TS 50238-2.

Note 2 to entry: Interference current limits are defined by a number of evaluation parameters, such as FFT parameters, or bandpass filter centre frequency and bandwidth and integration time.

3.1.14

interference current budget

part of the interference current limit, based on the summation rules, which can be used by an IU, TU, ES or IIS

3.1.15

summation rule

calculation method to scale a set of measurements on traction unit or electrical subsystem level to the maximum interference current for an IU with a specified confidence level

3.1.16

controlled impedance

increase of impedance by appropriate control of a connected converter

Note 1 to entry: The resulting controlled impedance is equal to the frequency response of the small signal ratio voltage divided by current.

3.1.17

interference current monitor

system or function that monitors the interference current production of an influencing unit, traction unit or electrical subsystem

Note 1 to entry: The interference current monitor is not part of the test specification as given in this European document. It might, however, be one of the safety measures required.

Note 2 to entry: In case interference currents can result in a wrong side failure, an interference current monitor which is able to switch off an interference current source is a possible mitigation measure.

3.1.18

transient

<adjective> pertaining to a phenomenon or quantity which passes from one steady state to another consecutive steady state during a time interval short compared to the timescale of interest

Note 1 to entry: The term "transient" is also used as a noun to mean a transient phenomenon or quantity.

[SOURCE: IEC 60050-103:2009, 103-05-02, modified]

3.1.19

transient

<noun> phenomenon or quantity which varies between two consecutive steady states during a time interval short compared to the timescale of interest

[SOURCE: IEC 60050-702:2009, 702-07-781]

3.1.20

steady state

operating condition of a system in which the system state variables can considered to be constant compared to time interval of interest

Note 1 to entry: For example, a varying speed should be considered as potentially constant if a train can stay at a certain speed for a longer time than the time interval of interest.

[SOURCE: IEC 60050-603:1986, 603-02-06, modified]

3.1.21

integration time

window size over which the root mean square (RMS) of the output of the bandpass filter is calculated

[SOURCE: CLC/TS 50238-2:2020, 3.1.3)

3.1.22

vehicle impedance

minimum allowed impedance of an influencing unit seen between pantograph(s) and wheels

Note 1 to entry: The minimum impedance is defined in ERA/ERTMS/033281 or NNTRs.

Note 2 to entry: The minimum impedance may be defined in terms of inductance and capacitance.

3.1.23

wrong side failure

WSF

mode of failure which may compromise the safety of trains

3.1.24

right side failure

RSF

mode of failure which does not directly compromise the safety of trains but may reduce availability

3.1.25

number of tests

number of times that a condition defined in the test specification is met

Note 1 to entry: This is not necessarily equal to the number of test runs.

3.1.26

small input filter 161 STANDARD PREVI

low pass passive input filter with a cut-off frequency which is higher than 1/3 of the centre frequency f₀ of the considered track circuit

Note 1 to entry: 1/3 is set so that the filter cut-off frequency is well below the lowest track circuit centre frequency.

https://standards.iteh.ai/catalog/standardr/sist/80436d79-9f47-4521-9212-

Note 2 to entry: For an LC filter the cut-off frequency is $\frac{1}{2\pi\sqrt{LC}}$

3.2 Abbreviations

For the purposes of this document, the following abbreviations apply.

AC Alternating Current

DC Direct Current

EC European Commission

EU European Union

ERTMS European Rail Traffic Management System

EMU Electric Multiple Unit

FFT Fast Fourier Transform

GPS Global Positioning System

LC Inductor-Capacitor

NNTR National Notified Technical Rules

PWM Pulse Width Modulation

RMS Root Mean Square

TSI Technical Specification for Interoperability

UIC International Union of Railways

4 Test specification

4.1 Preparation

4.1.1 General

Rolling stock and their traction and auxiliary system configurations as well as control systems and parameters can be very diverse. It is, therefore, necessary to prepare for interference current measurements by a preanalysis for the specific rolling stock. The compiled data serve as input to the test plan and will guarantee an efficient performance and evaluation of the measurements.

The following sections specify this data collection and its analysis.

4.1.2 Vehicle data

The following data characterize the vehicle to be tested:

- Rolling stock configuration (locomotive, or EMU, number of coaches);
- Electric traction power supply system(s) under which the rolling stock is intended to operate;
- Main circuit diagram (traction and auxiliaries);
- Main data: maximum speed, tractive effort and power at wheel;
- Dynamic braking systems (regenerative, rheostatic, mixed);
- Operational configurations (double or multiple traction, traction battery if applicable);
- Degraded modes of operation (e.g. traction or auxiliary converters isolated);
- Maximum currents of IU, TU, traction and auxiliary converters, and voltage dependency of these maxima.

Based on this information, one Influencing Unit (IU) shall be defined. Traction units (TU) and Electrical Subsystems (ES) shall be identified according to 3.1.4. This will be part of the documentation of the pre-analysis (4.1.4).

The following information about control shall be compiled:

- For each operating point, the Switching / pulse width modulation (PWM) method and frequency;
- Interlacing of PWM, including information whether after failure of one converter corresponding parameters are reassigned to the others automatically or whether remaining converters continue operation with the original parameter set;
- Use of controlled impedance;
- Limitations which can have an influence on interference current generation.

This information is not part of the documentation for interference current measurements. However, it may be shared with the other involved parties. It will remain internal with the vehicle manufacturer. However, it is essential to perform the pre-analysis (see 4.1.4).