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Cutting tool data representation and exchange —

Part 315: Creation and exchange of 3D models — Modelling of machine operated feed out tools

Représentation et échange des données relatives aux outils coupants —

Partie 315: Création et échanges de modèles 3D — Conception d'outils combinés réglables pour le tournage

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Foreword

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For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT) see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 29, *Small tools*.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

A list of all parts in the ISO 13399 series can be found on the ISO website.

Introduction

This document defines the concept of how to design simplified 3D models of machine operated feed out tools that can be used for NC-programming, simulation of the manufacturing processes and the determination of collision within machining processes. It is not intended to standardize the design of the cutting tool itself.

A cutting tool is used in a machine to remove material from a workpiece by a shearing action at the cutting edges of the tool. Cutting tool data that can be described by ISO 13399 include, but are not limited to, everything between the workpiece and the machine tool. Information about inserts, solid tools, assembled tools, adaptors, components and their relationships can be represented by this document. The increasing demand providing the end user with 3D models for the purposes defined above is the basis for the development of this series of International Standards.

The objective of the ISO 13399 series is to provide the means to represent the information that describes cutting tools in a computer sensible form that is independent from any particular computer system. The representation will facilitate the processing and exchange of cutting tool data within and between different software systems and computer platforms and support the application of this data in manufacturing planning, cutting operations and the supply of tools. The nature of this description makes it suitable not only for neutral file exchange, but also as a basis for implementing and sharing product databases and for archiving. The methods that are used for these representations are those developed by ISO/TC 184, *Automation systems and integration*, SC 4, *Industrial data,* for the representation of product data by using standardized information models and reference dictionaries.

Definitions and identifications of dictionary entries are defined by means of standard data that consist of instances of the EXPRESS entity data types defined in the common dictionary schema, resulting from a joint effort between ISO/TC 184/SC 4 and IEC/TC 3/SC 3D, *Product properties and classes and their identification*, and in its extensions defined in ISO 13584-24 and ISO 13584-25.

Cutting tool data representation and exchange —

Part 315:
Creation and exchange of 3D models — Modelling of machine operated feed out tools

1 Scope

This document specifies a concept for the design of machine operated feed out tools, limited to any kind of machine operated feed out tools, together with the usage of the related properties and domains of values.

This document specifies the requirements of simplified 3D models for data exchange of machine operated feed out tools.

The following are outside the scope of this document:

— applications where these standard data can be stored or referenced;

— creation and exchange of 3D for cutting tools;

— creation and exchange of 3D for cutting items;

— creation and exchange of 3D for tool items;

— creation and exchange of 3D for other adaptive items not being described in the scope of this document;

— creation and exchange of 3D for assembly items and auxiliary items.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies..

ISO/TS 13399-50, *Cutting tool data representation and exchange — Part 50: Reference dictionary for reference systems and common concepts*

ISO/TS 13399-80, *Cutting tool data representation and exchange — Part 80: Creation and exchange of 3D models — Overview and principles*

3 Terms and definitions

No terms and definitions are listed in this document.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

— ISO Online browsing platform: available at https://www.iso.org/obp

— IEC Electropedia: available at http://www.electropedia.org/

4 Starting elements, coordinate systems, planes

4.1 General

The modelling of the 3D models shall be done by means of nominal dimensions. Deviations within the tolerances are allowed.

WARNING — There is no guarantee that the 3D model, created according to the methods described in this document, is a true representation of the physical tool supplied by the tool manufacturer. If the models are used for simulation purposes — e.g. CAM simulation — it shall be taken into consideration that the real product dimensions can differ from those nominal dimensions.

NOTE Some of the definitions have been taken from ISO/TS 13399-50.

4.2 Reference system (PCS — Primary coordinate system)

The reference system consists of the following standard elements as shown in Figure 1:

— **standard coordinate system**: right-handed rectangular Cartesian system in three dimensional space, called "primary coordinate system" (PCS);

— **3 orthogonal planes**: planes in the coordinate system that contain the axis of the system, named "xy-plane" (XYP), "xz-plane" (XZP) and "yz-plane" (YZP);

— **3 orthogonal axis**: axes built as intersections of the 3 orthogonal planes lines respectively, named "x-axis" (XA), "y-axis" (YA) and "z-axis" (ZA).

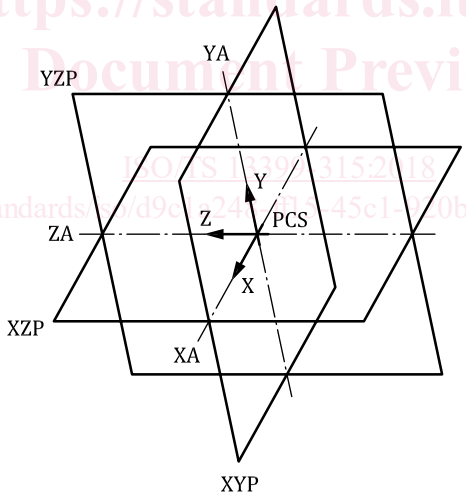

Figure 1 — Primary coordinate system

For virtually mounting of feed out tools onto an adaptive item or directly into the machine tool an additional reference system shall be defined. This reference system shall be called "mounting coordinate system (MCS)". It is located at the starting point of the protruding length of a tool item. The orientation is shown in Figure 2.

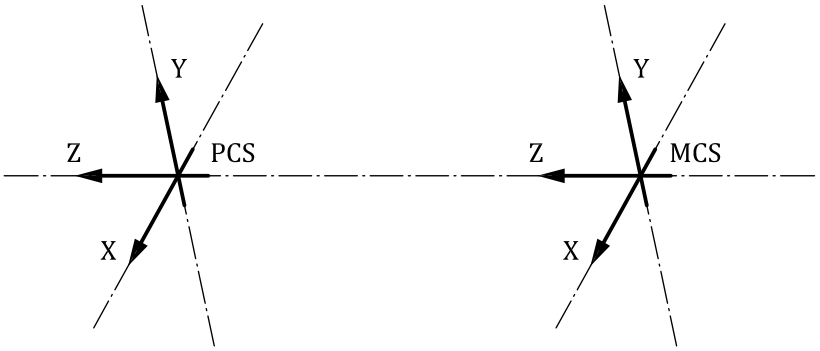

Figure 2 — Orientation of "PCS" and "MCS" reference system (example)

4.3 Coordinate system at the cutting part

For NC-programming, an additional coordinate system called “coordinate system in process — CIP”, shall be necessary. This "CIP" has a defined distance from the PCS and shall be oriented as follows:

— the origin is on a plane that is parallel to the XY-pane of PCS and is located on the most front cutting point;

— z-axis of CIP points to the PCS;

— z-axis of CIP is collinear to the z-axis of PCS;

— y-axis of CIP is parallel to the y-axis of PCS.

Figure 3 shows an example about the orientation and location of PCS, MCS and CIP.

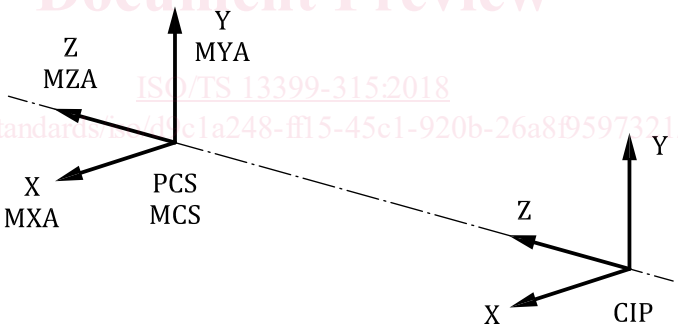

Figure 3 — Orientation of CIP

4.4 Planes

The modelling shall take place based on planes according to Figure 4, used as reference if applicable. Therefore, the model shall be able to vary, or single features of independent design features shall be deleted by means of changing the value of one or more parameter of the model design. Furthermore, the identification of the different areas shall be simplified in using the plane concept, even if they contact each other with the same size, e.g. chip flute, shank.

For the 3D visualization of drilling and countersinking tools for indexable inserts, the general planes shall be determined as follows:

— “HEP” "head end plane" is located at the most front point of the tool item regardless if this point is in a cutting process of a cutting item or if this point is determined by the tool item and influences the simulation process;

— “DRVLP” "drive length plane" is determined through the dimension of the property "drive length" and starts at the "TEP";

— “LFP” "functional length plane" is determined through the dimension of the property "functional length" and starts at the origin of the mounting coordinate system;

— “LUP” "usable length plane" is determined by the distance of LUX from the "CIP";

— “TEP” "tool end plane" is located at that end of the connection or the driving mechanism of the slides that points away from the workpiece;

— “OAL” "overall length" is the distance between "TEP" and "HEP".

Other planes, if necessary are defined in the appropriate clauses.

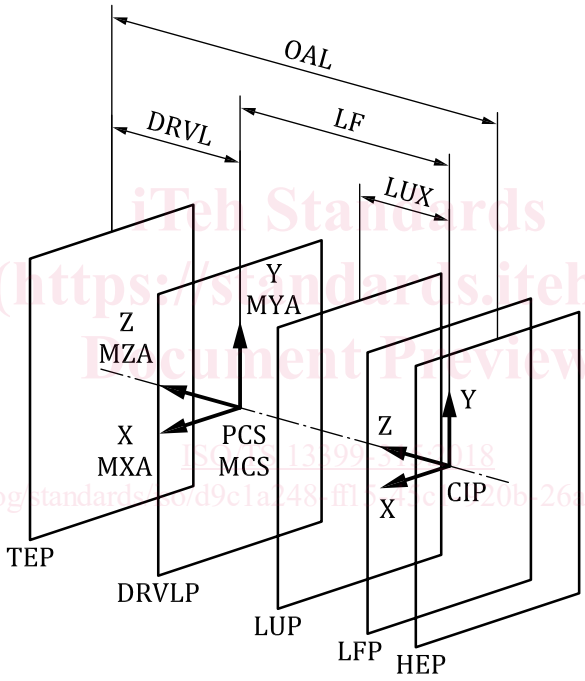

Figure 4 — Planes for design

4.5 Adjustment coordinate system on workpiece side

4.5.1 General

Additional coordinate systems for mounting components the coordinate systems "CSWx_y" (coordinate system workpiece side) shall be defined according to ISO/TS 13399-50.

4.5.2 Designation of the coordinate system workpiece side

Case 1 One coordinate system at the workpiece side shall be designated as "CSW".

Case 2 One coordinate system at workpiece side on different levels shall be designated as "CSWx", e.g. "CSW1", "CSW2". The numbering starts at the workpiece side and ends at the machine side in the direction of the positive Z-axis.

Case 3 Multiple coordinate systems at one level, but different angles and not at the centre of the tool axis shall be designated with "CSWx_y", where the "x" defines the level and the "y" defines the number of the coordinate system itself. The counting starts at the three o'clock position counting in counter-clockwise direction while looking towards the machine spindle (positive Z-axis).

Case 4 Multiple coordinate systems at one level, one angle and different diameters shall be designated as described in Case 3. The counting shall start at the smallest diameter.

Case 5 Multiple coordinate systems at one level, different angles and different diameters shall be designated as described in Case 3. The counting shall start at the smallest diameter and at the three o'clock position counting in counter-clockwise direction while looking towards the machine spindle (positive Z-axis).

An example is shown in Figure 5.

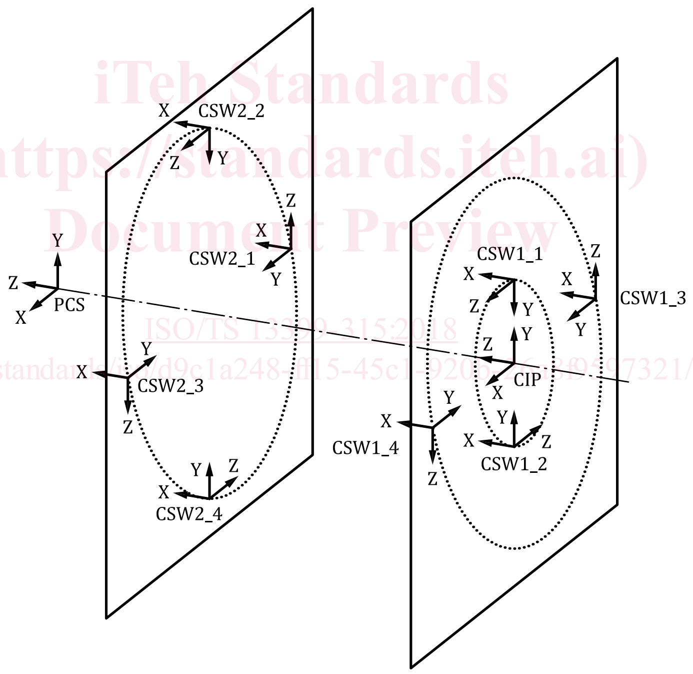

Figure 5 — Adjustment coordinate system on workpiece side

The MCS_INSERT shall be placed onto the CSWx_y of the tool with determinations as follows:

— the X-axis of CSWx_y is parallel to the X-axis of CRP;

— the Y-axis of CSWx_y is parallel to the Y-axis of CRP;

— the Z-axis of CSWx_y is parallel to the Z-axis of CRP.

An example is shown in Figure 6.

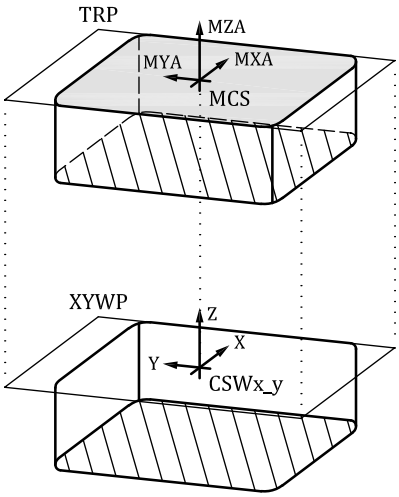

Figure 6 — Mounting of insert onto pocket seat

5 Design of the model

5.1 General

The design of the model shall be according to ISO/TS 13399-80.

5.2 Necessary parameters for the feed out motion of the slides

Information about the connection interface code for the feed out drive system shall be filed as described in Table 1.

Table 1 — Parameter list for connection interface for the drive system

Preferred symbol	Description	Source of symbol	ISO-ID number
DRVSC	drive size code	open	open
DRVTY	drive type	open	open

6 Machine operated feed out tool with one linear slide for internal machining

6.1 General

Figure 7 shows the properties used for identification and classification of motion tools with one linear slide for internal machining operations.