

INTERNATIONAL ORGANIZATION FOR STANDARDIZATION MEXCHAPOCHAR OPEAHDBALLUS TO CTARCAPTUBALLUM ORGANISATION INTERNATIONALE DE NORMALISATION

Reciprocating internal combustion engines — Hand operated control devices — Standard direction of motion

First edition - 1972-05-01

UDC 621.434-34

Ref. No. ISO 2261-1972 (E)

Descriptors : internal combustion engines, reciprocating engines, manual controls, direction (of movement).

FOREWORD

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Draft International Standards adopted by the Technical Committees are circulated to the Member Bodies for approval before their acceptance as International Standards by the ISO Council.

International Standard ISO 2261 was drawn up by Technical Committee ISO/TC 70, Internal combustion engines.

It was approved in July 1971 by the Member Bodies of the following countries :

Australia	India	South Africa, Rep. of
Austria	Ireland	Sweden
Belgium	Italy	-Switzerland
Czechoslovakia	Japan	Turkey
Egypt, Arab Rep. of	Korea, Rep. of	United Kingdom
France	Netherlands	U.S.A.
Germany	New Zealand	U.S.S.R.

No Member Body expressed disapproval of the document.

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Printed in Switzerland

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0 INTRODUCTION

Standards regarding the direction of motion of operating devices are of particular value where stress is laid on a high degree of safety and/or a high operating speed. Often it is required that the operator has to move the operating device in the appropriate direction almost automatically. Therefore, standardization is important where a wrong operation would cause great inconvenience, damage or danger.

1 SCOPE AND FIELD OF APPLICATION

This International Standard specifies the direction of motion of hand operated devices for speed regulation and reversing of reciprocating internal combustion engines, having particular regard to reciprocating internal combustion engines for marine and rail propulsion — irrespective of whether the operator's position is near the engine or remote from it.

Valves for the control of liquids and gases are excluded.

2 EFFECTS OF ACTUATING THE OPERATING DEVICE

2.1 Where separate operating devices for reversing and speed regulation are installed

- a) Actuating the operating device for reversing results in a forward movement or a backward movement.
- b) Actuating the operating device for speed results in a speed increase or decrease.

2.2 Where combined operating devices for reversing and speed are installed

a) Actuating the operating device from the centre posi-

tion in one direction results in a forward movement with increasing speed.

b) Actuating the operating device from the centre position in the opposite direction results in a backward movement with increasing speed.

c) Actuating the operating device from the travelling position to the centre position results in a speed decrease to a full stop.

3 DESIGNATION OF OPERATIONS

Operating directions and effects caused by actuation of the control devices are co-ordinated in Tables 1 and 2.

4 PREFERRED POSITION OF OPERATOR ON INSTALLATIONS ON WHICH THE DIRECTION OF MOVEMENT OF THE VEHICLE IS VISIBLE TO OPERATOR

Operator positions should preferably be arranged in such a manner that the operator is looking towards the front of the vehicle.

If the operator's position is arranged parallel to the direction of travel of a vehicle (the operator looking sideways), the operator's position should be arranged in such a manner that the operating directions of the control devices correspond to the definitions given in this International Standard.

5 DESIGNATION

To indicate the effect resulting from the motion of an operating device, easily understandable symbols – instead of words – shall be placed next to the operating device (as shown in Table 3).

Designation Motion of of operation device	Type of operating device	Direction of motion of operating device				
		Increase o moveme	f speed or nt ahead		of speed or backward	
A ₁			/	away from the operator		towards the operator
B ₁	linear or approximately linear	hand lever	f	upwards	Ļ	downwards
C ₁				to the right		to the left
D ₁	turning	handwheel or crank handle		clockwise	$\left \begin{array}{c} \\ \end{array} \right $	counter- clockwise

TABLE 1 - Operating directions and effects with separate operating devices for reversing and for speed regulation

TABLE 2 - Operating directions and effects with a combined operating device for both reversing and speed regulation

			Direction of motion of operating device			
Designation Motion of operating device		Type of operating device	Movement ahead Movement backward with increase of speed ¹⁾ from central (stop) position			
A ₂			- 0	away from the operator	10	towards the operator
B ₂	linear or approximately linear	hand lever	_ ¦o	upwards		downwards
C ₂				to the right	→]	to the left
D ₂	turning	handwheel or crank handle	(-0-)	clockwise		counter- clockwise

1) Decrease of speed in every case will be attained by actuation of the operating device in the direction towards the central (stop) position.

	Designation of operation	Symbols for speed-progressive increase or decrease		Explanation
	A/B/C			Motion of the operating device towards the wide end of the wedge results in an increase of speed. Motion of the operating device
	D			towards the point of the wedge results in a decrease of speed.
	Designation of operation	Symbols for ve forward movement	ehicle direction backward movement	Explanation
/	A/B/C/D	Ì		With engines driving a vehicle — marine or rail — directly (without a reversing gear) the direction of rotation of the engine deter- mines the direction in which the vehicle moves. Forward movement of the vehicle is indicated by a symbol representing the vehicle with an arrow pointing towards the front end (bow) of the vehicle. Backward movement of the vehicle is indicated by a symbol representing the vehicle with an arrow pointing towards the front end (bow) of the vehicle.

TABLE 3 – Symbols for speed regulation and vehicle direction

Designation of operation	Vehicle speed	Vehicle direction	Designation of operation	Vehicle direction and speed
A 1			A ₂	
Β ₁			B ₂	
C1			C ₂	
D1			D ₂	

The actual design may differ from the illustration shown above.

The operating devices may be combined at random according to application.



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SO 2262:1972

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