



Designation: E 215 – 98

Standard Practice for Standardizing Equipment for Electromagnetic Examination of Seamless Aluminum-Alloy Tube¹

This standard is issued under the fixed designation E 215; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon (ϵ) indicates an editorial change since the last revision or reapproval.

This specification has been approved for use by agencies of the Department of Defense.

1. Scope

1.1 This practice² is intended as a guide for standardizing eddy-current equipment employed in the examination of seamless aluminum-alloy tube. Artificial discontinuities consisting of flat-bottomed or through holes, or both, are employed as the means of standardizing the eddy-current system. General requirements for eddy-current testing procedures are included.

1.2 Procedures for fabrication of reference standards are given in Appendixes X1.1 and X1.2.

1.3 This practice is intended for the examination of tubular products having nominal diameters up to 4 in. (101.6 mm) and wall thicknesses up to the standard depth of penetration (SDP) of eddy currents for the particular alloy (conductivity) being examined and the test frequency being used.

NOTE 1—This practice may also be used for larger diameters or heavier walls up to the effective depth of penetration (EDP) of eddy currents as specified by the using party or parties.

1.4 The values stated in inch-pound units are to be regarded as the standard.

1.5 This practice does not establish acceptance criteria. They must be established by the using party or parties.

1.6 *This standard does not purport to address all of the safety problems, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety and health practices and determine the applicability of regulatory limitations prior to use.*

2. Referenced Documents

2.1 ASTM Standards:

E 543 Practice for Agencies Performing Nondestructive Testing³

E 1316 Terminology for Nondestructive Examinations³

¹ This practice is under the jurisdiction of ASTM Committee E-7 on Nondestructive Testing and is the direct responsibility of Subcommittee E07.07 on Electromagnetic Methods.

Current edition approved Dec. 10, 1998. Published February 1999. Originally published as E 215 – 63. Last previous edition E 215 – 87(1992)⁴.

² For ASME Boiler and Pressure Vessel Code applications see related Practice SE-215 in the Code.

³ *Annual Book of ASTM Standards*, Vol 03.03.

2.2 Federal Standard:

Fed Std. No. 245D Tolerance for Aluminum Alloy and Magnesium Alloy Wrought Products⁴

2.3 Other Documents:

SNT-TC-1A Recommended Practice for Personnel Qualification and Certification in Nondestructive Testing⁵

ANSI/ASNT-CP-189 ASNT Standard for Qualification and Certification of Nondestructive Testing Personnel⁵

MIL-STD-410E Nondestructive Testing Personnel Qualification and Certification⁴

NAS-410 NAS Certification and Qualification of Nondestructive Personnel (Quality Assurance Committee)⁶

3. Terminology

3.1 Standard terminology relating to electromagnetic examination may be found in Terminology E 1316, Section C, Electromagnetic Testing.

4. Significance and Use

4.1 The test is performed by passing the tube lengthwise through or near an eddy current sensor energized with alternating current of one or more frequencies. The electrical impedance of the eddy current sensor is modified by the proximity of the tube. The extent of this modification is determined by the distance between the eddy current sensor and the tube, the dimensions, electrical conductivity, and electrical conductivity of the tube. The presence of metallurgical or mechanical discontinuities in the tube will alter the apparent impedance of the eddy current sensor. During passage of the tube, the changes in eddy current sensor characteristics caused by localized differences in the tube produce electrical signals which are amplified and modified to actuate either an audio or visual signalling device or a mechanical marker to indicate the position of discontinuities in the tube length. Signals can be produced by discontinuities located either on the

⁴ Available from Standardization Documents Order Desk, Bldg. 4 Section D, 700 Robbins Ave., Philadelphia, PA 19111-5094, Attn: NPODS.

⁵ Available from American Society for Nondestructive Testing, 1711 Arlington Plaza, P.O. Box 28518, Columbus, OH 43228-0518.

⁶ Available from Aerospace Industries Association of America, Inc., 1250 Eye Street, N.W., Washington, DC 20005.

external or internal surface of the tube or by discontinuities totally contained within the tube wall.

4.2 The depth of penetration of eddy currents in the tube wall is influenced by the conductivity (alloy) of the material being examined and the test frequency employed. As defined by the standard depth of penetration equation, the eddy-current penetration depth is inversely related to conductivity and test frequency (Note 2). Beyond one standard depth of penetration (SDP), the capacity to detect discontinuities by eddy currents is reduced. Electromagnetic examination of seamless aluminum alloy tube is most effective when the wall thickness does not exceed the SDP or in heavier tube walls when discontinuities of interest are within one SDP. The limit for detecting metallurgical or mechanical discontinuities by way of conventional eddy current sensors is generally accepted to be approximately three times the SDP point and is referred to as the effective depth of penetration (EDP).

NOTE 2—The standard depth of penetration is defined by the following equations:

$$SDP = 503.3 \sqrt{\frac{1}{f\sigma}}$$

where:

SDP = one standard depth of penetration,
 f = frequency, Hz (cycles per second), and
 σ = conductivity, siemens-metre/mm².

or:

$$SDP = 26 \sqrt{\frac{1}{f\sigma}}$$

where:

SDP = one standard depth of penetration, in
 f = frequency in Hz (cycles per second), and
 σ = conductivity, % IACS.

5. Basis of Application

5.1 If specified in the contractual agreement, personnel performing examinations to this practice shall be qualified in accordance with a nationally recognized NDT personnel qualification practice or standard such as ANSI/ASNT-CP-189, SNT-TC-1A, MIL-STD-410, NAS-410, ASNT-ACCP, or a similar document and certified by the certifying agency's as applicable. The practice or standard used and its applicable revision shall be identified in the contractual agreement between the using parties.

NOTE 3—MIL-STD-410 is canceled and has been replaced with NAS-410, however, it may be used with agreement between contracting parties.

5.2 If specified in the contractual agreement, NDT agencies shall be qualified and evaluated in accordance with Practice E 543. The applicable edition of Practice E 543 shall be specified in the contractual agreement.

6. Apparatus

6.1 *Electronic Apparatus*—The electronic apparatus shall be capable of energizing eddy current sensors with alternating currents of suitable frequencies and shall be capable of sensing

the changes in the electromagnetic characteristics of the eddy current sensors. Equipment may include a detector, phase discriminator, filter circuits, gating circuits, and signalling devices as required for the particular application.

6.2 *Eddy Current Sensors*—Eddy current sensors shall be capable of inducing currents in the tube and sensing changes in the electrical characteristics of the tube. The eddy current sensors may be of the encircling coil (annular) type or surface probe type.

7. Standardization of Apparatus

7.1 The apparatus shall be adjusted with an appropriate reference standard to ensure that the equipment is operating at the proper level of sensitivity, with the following considerations:

7.1.1 Primary reference standards employed for this purpose shall be prepared in accordance with the methods described in Appendix X1.1.

7.1.2 Equivalent secondary reference standards, prepared in accordance with methods described in Appendix X1.2, also may be employed for standardizing the apparatus.

7.1.3 Reference standards normally are of the same alloy, temper, and dimensions as the tube to be tested.

7.1.4 Tests shall not be conducted unless the equipment can be set to the levels required by this standardization procedure.

7.1.5 For practical applications, reference standards also may be employed to establish quality control levels.

8. Procedure

8.1 Standardize the testing instrument using the appropriate reference standard prior to testing and check at least every 4 h during continuous operation, or whenever improper functioning of the testing apparatus is suspected. If improper functioning occurs, restandardize the apparatus in accordance with Section 7, and retest all tubes tested since the last successful standardization.

8.2 Tubes may be tested in the final drawn, annealed, or heat-treated temper, or in the drawn temper prior to the final anneal or heat treatment.

8.3 The length of tube over which end effect is significant may be determined by placing a series of holes or notches in special reference tubes and determining the distance from the tube end at which the signal amplitude from the discontinuities begins to decrease.

9. Application

9.1 This application covers the electromagnetic testing of aluminum-alloy seamless tube using primary and secondary reference standards.

9.2 Primary and secondary reference standards, described in Appendixes X1.1 and X1.2, respectively, when used as acceptance standards, will establish probable detection of defects that are of a severity likely to cause leaks or substantial weakening of the tube.

9.3 Using electronic apparatus and eddy current sensors described in Section 6, the equipment sensitivity shall be standardized in accordance with Section 7 under the following test conditions:

9.3.1 *Frequency*—The frequency shall be in the range from 1 to 125 KHz. The test frequency should be adjusted to provide optimum penetration of the tube wall or to place discontinuities of interest within one SDP. Discontinuities located deeper than the SDP point will be detected with less sensitivity. The SDP point will vary as a function of the tube alloy (conductivity) and test frequency and may be determined by the depth of penetration equation given in Section 4, Note 2.

9.3.2 *Speed of Inspection*—The testing rate, or speed of the tube with respect to the eddy current sensor, may vary with the application. In encircling coil applications, inspection speeds of 15.2 m/min (50 fpm) to 152 m/min (500 fpm) are recommended where possible, but inspection speeds as high as 305 m/min (1000 fpm) are permissible. In surface probe applications, inspection speeds are inherently slower due to reduced surface coverage and the necessity to rotate the eddy current sensor or the tube to produce a helical scan. All instrument adjustments, that is, frequency, phase setting, filter setting, sensitivity setting, threshold-level setting, etc., shall be made with the reference standard or acceptance standard or both passing through or by the eddy current sensor at the same speed at which the test of tube is to be conducted.

9.3.3 *Phase Setting*—The phase setting should be selected to provide the best signal-to-noise ratio for the reference standard employed, that is, the maximum ratio of indication height from the appropriate artificial discontinuities to the indication height from nondetrimental discontinuities.

9.3.4 *Filter Setting*—The filter setting should be selected commensurate with the testing speed to provide optimum

filtering of non-detrimental, time-varying discontinuities such as geometry, pathline variation, high-frequency noise, etc.

9.3.5 *Sensitivity Setting*—The sensitivity setting shall be adjusted to provide clearly discernible indications of a convenient height for the appropriate accept holes (A or d_a), but it shall not be high enough to cause off-scale or saturated indications for the appropriate reject holes ($2A$ or d_b) of the reference standard.

9.3.6 *Threshold-Level Setting*—The threshold-level setting (reject level) shall be adjusted to automatically trigger an audio or visual-signalling device or a mechanical marker when the appropriate artificial discontinuity (or discontinuities) of the acceptance standard passes through or by the eddy current sensor.

9.4 When using reference standards as acceptance standards the threshold level should be adjusted to accept tubes exhibiting eddy-current responses smaller than those obtained from the appropriate reject holes ($2A$ or d_b) and to reject those with responses equivalent to or greater than those obtained from the appropriate reject holes ($2A$ or d_b) in the reference standard. Experience shows that this procedure will aid in the rejection of severe defects and, at the same time, minimize erroneous rejection of tubes that might exhibit noise from non-detrimental discontinuities.

10. Keywords

10.1 aluminum alloy; eddy currents; electromagnetic testing; equipment standardization; NDT; nondestructive testing; tubing

APPENDICES

(Nonmandatory Information)

X1. PURPOSE, DESCRIPTION, FABRICATION, AND CHECKING OF PRIMARY REFERENCE STANDARDS

X1.1 Purpose

X1.1.1 Primary reference standards are used to standardize testing equipment under operating conditions to establish acceptable limits of sensitivity, reproducibility, and capability for detecting defects of a severity likely to cause leaks or substantial weakening of the tube.

X1.1.2 The dimensions of the appropriate primary reference standard are determined by the size of the tube to be tested. A primary reference standard shall be a tube of the same alloy, temper, outside diameter, D , and wall thickness, t , as the tube to be tested. This appendix covers the preparation of primary standards for test of seamless aluminum-alloy tube.

X1.2 Description

X1.2.1 The primary reference standard shall contain six artificial discontinuities in the form of flat-bottomed drilled holes in a 183-cm (6-ft) length of tube which is free of significant natural discontinuities. Fig. X1.1 describes the primary reference standard for aluminum-alloy seamless tube.

X1.2.2 The six flat-bottomed holes shall be of equal diameter, d , and shall be located in the mid-portion of the tube. The

distance between adjacent holes is 152 mm (6 in.). The minimum distance between a hole and either end of the tube shall be approximately 500 mm (20 in.).

X1.2.3 Three of each of the reference standard holes A and $2A$ shall be drilled consecutively to depths of one third and two thirds the wall thickness, respectively in radial longitudinal planes $120 \pm 5^\circ$ apart.

X1.2.4 The diameter, d , of the flat-bottomed drill used to make a primary reference standard hole shall be determined mathematically with the following equation:

$$d = k(D/t) \times 10^{-3} \quad (X1.1)$$

where:

d = drill diameter of A and $2A$ flat-bottom holes, mm (in.),

k = 76.2 mm (3 in.),

D = tube outside diameter, mm (in.), and

t = tube wall thickness, mm (in.).

X1.2.5 In computing the appropriate drill diameters, it is recommended that the nominal dimensions for D and t listed in Table X1.1 be used for tubes having heavy or very thin wall