

**SLOVENSKI STANDARD**  
**SIST EN 50318:2019/A1:2022**

**01-julij-2022**

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**Železniške naprave - Sistemi tokovnega odjema - Veljavnost simuliranja medsebojnih dinamičnih vplivov med tokovnim odjemnikom in kontaktnim vodnikom - Dopolnilo A1**

Railway applications - Current collection systems - Validation of simulation of the dynamic interaction between pantograph and overhead contact line

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Bahnanwendungen - Stromabnahmesysteme - Validierung von Simulationssystemen für das dynamische Zusammenwirken zwischen Dachstromabnehmer und Oberleitung

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Applications ferroviaires - Systèmes de captage de courant - Validation des simulations de l'interaction dynamique entre le pantographe et la caténaire

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**ICS:**

29.280      Električna vlečna oprema      Electric traction equipment

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**EUROPEAN STANDARD**  
**NORME EUROPÉENNE**  
**EUROPÄISCHE NORM**

**EN 50318:2018/A1**

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ICS 29.280

English Version

**Railway applications - Current collection systems - Validation of simulation of the dynamic interaction between pantograph and overhead contact line**

Applications ferroviaires - Systèmes de captage de courant  
- Validation des simulations de l'interaction dynamique  
entre le pantographe et la caténaire

Bahnanwendungen - Stromabnahmesysteme - Validierung  
von Simulationssystemen für das dynamische  
Zusammenwirken zwischen Dachstromabnehmer und  
Oberleitung

This amendment A1 modifies the European Standard EN 50318:2018; it was approved by CENELEC on 2022-01-10. CENELEC members are bound to comply with the CEN/CENELEC Internal Regulations which stipulate the conditions for giving this amendment the status of a national standard without any alteration.

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European Committee for Electrotechnical Standardization  
Comité Européen de Normalisation Electrotechnique  
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CEN-CENELEC Management Centre: Rue de la Science 23, B-1040 Brussels

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## European foreword

This document (EN 50318:2018/A1:2022) has been prepared by CLC/SC 9XC, "Electric supply and earthing systems for public transport equipment and ancillary apparatus (fixed installations)", of Technical Committee CLC/TC 9X, "Electrical and electronic applications for railways".

The following dates are fixed:

- latest date by which this document has to be implemented at national level by publication of an identical national standard or by endorsement (dop) 2023-01-10
- latest date by which the national standards conflicting with this document have to be withdrawn (dow) 2025-01-10

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. CENELEC shall not be held responsible for identifying any or all such patent rights.

This document has been prepared under a Standardization Request given to CENELEC by the European Commission and the European Free Trade Association, and supports essential requirements of EU Directive(s) / Regulation(s).

For relationship with EU Directive(s) / Regulation(s), see informative Annex ZZ, which is an integral part of this document.

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## 1 Modification to the whole standard

Replace "LOC&PAS TSI" by "TSI LOC & PAS".

Replace "ENE TSI" by "TSI ENE".

Replace "contact line" by "overhead contact line".

## 2 Modification to Clause 2, Normative references

Replace "EN 50119:2009" by "EN 50119:2020".

Replace "EN 50367:2012, Railway applications — Current collection systems — Technical criteria for the interaction between pantograph and overhead line (to achieve free access)" by "EN 50367:2020, Railway applications - Fixed installations and rolling stock - Criteria to achieve technical compatibility between pantographs and overhead contact line".

## 3 Modification to 3.6, standard deviation

After the term "standard deviation" add the specific use between angle brackets "<of contact force>".

## 4 Modification to 3.15, transfer function <of a pantograph>

Replace the definition by "ratio of an applied input on pantograph head to the response of the pantograph, depending on frequency".

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## 5 Modification to 3.21, wave propagation speed of the contact wire

Replace the term in 3.21 by "wave propagation velocity <of the contact wire>".

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## 6 Modification to 3.25, dynamic interaction

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Replace the definition by "behaviour between pantograph(s) and overhead contact line when in contact, described by contact forces and vertical displacements of contact point(s)".

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## 7 Modification to Clause 3, Terms and definitions

Add the following new entry:

"**3.29**

**height at operating position**

vertical distance between actual operating position of the pantograph and pantograph housed height"

## 8 Modification to Clause 4, Symbols and abbreviations

Add under the fourth line of the subclause "Abbreviations":

"FFT fast Fourier transformation"

Add under the 9<sup>th</sup> line of the subclause "Abbreviations":

"ROCL rigid overhead contact line"

## 9 Modification to 6.1, General requirements

Replace the last paragraph by "Aerodynamic effects on the pantograph shall as a minimum be considered by adjusting the mean contact force as a function of speed.".

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**10 Modification to 6.2.1, General***In the second paragraph, add to the terms in brackets after "operation height" the term "contact wire height".**In the NOTE, add after "operation height" the term "contact wire height".***11 Modification to 6.2.2, Mass – spring – damper – models (lumped parameter models)***Replace the second bullet point by**"— stiffness characteristics of joints connecting the discrete masses, including any nonlinearity (if applicable);"**Replace the third bullet point by:**"— damping characteristics of joints connecting the discrete masses, including any nonlinearity (if applicable);"**Delete the last bullet point"— application points of static and aerodynamic forces".***12 Modification to 6.2.3, Multi-body models***Replace the first paragraph by "For multi-body models, the input set out in 6.2.2 and the following input is required:".**Delete the last bullet point"— application points of static and aerodynamic forces".***13 Modification to 6.3, Validation of pantograph models***Replace in the fourth paragraph "EN 50367:2012" by "EN 50367:2020".**Replace the 13th paragraph by "For the calculation of Q, the frequencies with a measured apparent mass below 2 kg shall be excluded.".*SIST EN 50318:2019/A1:2022**14 Modification to 7.1, General requirements**<https://standards.iteh.ai/catalog/standards/sist/7fc4cc18-8773-42be-a174-638b1c8c9c1d/sist-en-50318-2019-a1>*Replace the third paragraph by "ROCL has very small vertical displacements in operation. The validation of these models and interaction simulations is only possible for the contact force in direct comparison with the measured results.".***15 Modification to 7.2, Data requirements***Replace the text of the first bullet point by "length of each span, or distance between supports;".***16 Modification to 9.3, Contact wire displacement***Replace the paragraph after the bullet point by "The time history of the vertical position of the contact wire at any specified point shall be available for output."**Replace in the third paragraph "EN 50119:2009, 5.10.4" by "EN 50119:2020, 5.10.4.2".***17 Modification to 9.4, Pantograph displacement***Replace in the second paragraph "EN 50119:2009, 5.10.7" by "EN 50119:2020, 5.10.4.5".***18 Modification to 10.3.2, Deviations of pantograph characteristics***Replace the title of 10.3.2 by "10.3.2 Permissible changes of pantograph characteristics".*

## **19 Modification to 10.3.3, Deviations of overhead contact line parameters**

*Replace the title of 10.3.3 by “10.3.3 Permissible changes of overhead contact line parameters”.*

## **20 Modification to 10.3.4, Deviations of simulation parameters**

*Replace the title of 10.3.4 by “10.3.4 Permissible changes of simulation parameters”.*

*Replace in the first paragraph “EN 50119:2009, 5.2.4” by “EN 50119:2020, 5.2.4“.*

## **21 Modification to 11.4, Reference model results**

*Replace the third paragraph by “Simulation results shall be filtered in the frequency domain with the defined cut off frequencies.”.*

## **22 Modification to A.2.2, Special data for the contact line reference model - AC - Simple**

*Replace the first paragraph by “The overhead contact line is defined by a simple catenary equipment with a single contact wire according to Figure A.1.”.*

## **23 Modification to A.2.3, Special data for the reference model of contact line AC – Stitched**

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*Replace the first paragraph by “The overhead contact line is defined by a simple catenary equipment with a single contact wire and stitched catenary suspensions according to Figure A.2.”.*

## **24 Modification to A.2.4, Special data for the reference model of contact line DC – simple**

*Replace the first sentence in the first paragraph by “The overhead contact line is defined by a simple catenary equipment with twin contact wires (two contact wires suspended from a single catenary wire).”.  
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## **25 Modification to B.1, Measurement results of simple AC high speed contact line**

*Replace the title by “B.1 Measurement results of simple AC high speed overhead contact line”.*

## **26 Modification to B.1.1.2, Parameters of simulation**

*Replace the first sentence of the last paragraph by “The overhead contact line is defined by a simple catenary equipment with a single contact wire and a single catenary wire.”.*

## **27 Modification to B.1.1.3, Model parameter and mechanical data of OCL**

*In Table B.1, replace “EI” as symbol for Young’s Modulus by “E”.*

## **28 Modification to B.1.1.4, Geometrical data of overhead contact line**

*Replace the first sentence of the first paragraph by “The overhead contact line is defined by a simple catenary equipment with a single contact wire and a single catenary wire on straight track.”.*

## 29 Modification to B.1.1.6, Support definition

Replace Table B.8 by the following:

"

**Table B.8 — Support definition of tension length 1**

Support number	1	2	3	4	5	6	7	8	9	10
Cumulative position [m]	0,00	42,25	86,95	132,25	177,75	222,75	267,75	312,75	357,75	402,75
CW height [m]	6,35	5,63	5,08	5,08	5,08	5,08	5,08	5,08	5,08	5,08
MW height [m]	6,85	6,88	7,08	6,48	6,48	6,48	6,48	6,48	6,48	6,48
CW stagger [m]	-	0,65	0,3	-0,25	0,1	-0,2	0,1	-0,2	0,1	-0,2
MW stagger [m]	-	0,65	0,3	-0,25	0,1	-0,2	0,1	-0,2	0,1	-0,2

Support number	11	12	13	14	15	16	17	18	19	20
Cumulative position [m]	452,25	501,75	551,25	600,75	650,25	699,75	749,25	798,75	848,25	897,75
CW height [m]	5,08	5,08	5,08	5,08	5,08	5,08	5,08	5,08	5,08	5,08
MW height [m]	6,48	6,48	6,48	6,48	6,48	6,48	6,48	6,48	6,48	6,48
CW stagger [m]	0,1	-0,2	0,1	-0,2	0,1	-0,2	0,1	-0,2	0,1	-0,2
MW stagger [m]	0,1	-0,2	0,1	-0,2	0,1	-0,2	0,1	-0,2	0,1	-0,2

Support number	21	22	23	24	25
Cumulative position [m]	947,25	997,25	1047,05	1096,25	1145,25
CW height [m]	5,08	5,08	5,08	5,63	6,35
MW height [m]	6,48	6,48	7,08	6,88	6,85
CW stagger [m]	0,2	-0,15	0,1	0,35	-
MW stagger [m]	0,2	-0,15	0,1	0,35	-