

Edition 1.0 2000-11

INTERNATIONAL STANDARD

NORME INTERNATIONALE

Programmable controller STANDARD PREVIEW

Part 5: Communications (standards.iteh.ai)

Automates programmables -

IEC 61131-5:2000

Partie 5: Communications itch.ai/catalog/standards/sist/fa68ac4f-c965-4e2d-b24aec35cb6019c5/iec-61131-5-2000





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INTERNATIONAL
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PRICE CODE CODE PRIX

ICS 25.040.40; 35.240.50 ISBN 978-2-83220-262-3

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

PROGRAMMABLE CONTROLLERS -

Part 5: Communications

FOREWORD

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International Standard IEC 61131-5 has been prepared by subcommittee 65B: Devices, of IEC technical committee 65: Industrial-process measurement and control.

This bilingual version (2012-08) corresponds to the monolingual English version, published in 2000-11.

The text of this standard is based on the following documents:

FDIS	Report on voting
65B/411/FDIS	65B/420/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

The French version of this standard has not been voted upon.

This publication has been drafted in accordance with the ISO/IEC Directives, Part 3.

This part should be read in conjunction with the other parts of IEC 61131. IEC 61131 consists of the following parts under the general title: *Programmable controllers*.

Part 1:1992, General information.

Part 2:1992, Equipment requirements and tests.

Part 3:1993, Programming languages.

Part 4:1994, User guidelines (published as technical report IEC TR 61131-4)

Part 5:2000, Communications

Part 8:2000, Guidelines for the application and implementation of programming languages (published as technical report IEC TR 61131-8)

Annexes A and B form an integral part of this standard.

Annex C is for information only.

Where a conflict exists between this and other IEC standards (except basic safety standards), the provisions of this standard should be considered to govern in the area of programmable controllers and their associated peripherals.

The committee has decided that the contents of this publication will remain unchanged until 2006. At this date, the publication will be

- reconfirmed;
- withdrawn;
- · replaced by a revised edition, or
- amended.

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PROGRAMMABLE CONTROLLERS -

Part 5: Communications

1 Scope

This part of IEC 61131 specifies communication aspects of a programmable controller. It specifies from the viewpoint of a PC how any device can communicate with a PC as a server and how a PC can communicate with any device. In particular, it specifies the behavior of the PC as it provides services on behalf of other devices and the services the PC application program can request from other devices. It is not intended to specify how any device can communicate with any device using a PC as a router or gateway. The behavior of the PC as a communication client and server is specified independent of the particular communication subsystem, but the communication functionality may be dependent on the capabilities of the communication subsystem used.

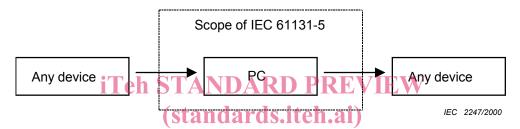


Figure 1 – Scope of this part of IEC 61131

The scope of this part is a subset of the communication model. Shown in figure 2 of IEC 61131-3; namely figures 2c and 2d are included in the scope of this part. Additionally, the means defined in this part of IEC 61131 may be used for communications within a program or between programs.

The mapping of the PC behavior to some particular communications subsystems is provided in the annexes.

2 Normative references

The following normative documents contain provisions which, through reference in this text, constitute provisions of this part of IEC 61131. For dated references, subsequent amendments to, or revisions of, any of these publications do not apply. However, parties to agreements based on this part of IEC 61131 are encouraged to investigate the possibility of applying the most recent editions of the normative documents indicated below. For undated references, the latest edition of the normative document referred to applies. Members of ISO and IEC maintain registers of currently valid International Standards.

IEC 60050-351:1998, International Electrotechnical Vocabulary – Part 351: Automatic control

IEC 61131-1:1992, Programmable controllers – Part 1: General Information

IEC 61131-2:1992, Programmable controllers – Part 2: Equipment requirements and tests

IEC 61131-3:1993, Programmable controllers – Part 3: Programming languages

ISO/IEC 2382-1:1993, Information technology – Vocabulary – Part 1: Fundamental terms

ISO/IEC 9506-1:1990, Industrial automation systems – Manufacturing Message Specification – Part 1: Service definition

ISO/IEC 9506-2:1990, Industrial automation systems – Manufacturing Message Specification – Part 2: Protocol specification

3 Definitions

For the purpose of this part of IEC 61131, the following definitions apply.

This part of IEC 61131 is based on the concepts of parts 1 to 3 of IEC 61131 and makes use of the following terms defined in other international standards.

Definitions from other publications

```
IEC 60050-351
   control
   monitoring
IEC 61131-1
   application program (2.1)
   application program archiving (4.6.4) cold restart (2.56) iTeh STANDARD PREVIEW
   input (2.25)
                                (standards.iteh.ai)
   main processing unit (2.32)
   modifying the application program (4.6.2.6)31-5:2000
                    https://standards.iteh.ai/catalog/standards/sist/fa68ac4f-c965-4e2d-b24a-
   output (2.40)
                                   ec35cb6019c5/iec-61131-5-2000
   programmable controller (2.50)
   programmable controller system (2.51)
   testing the application program (4.6.2.5)
   warm restart (2.56)
IEC 61131-3
   access path (1.3.2)
   direct representation (1.3.23)
   invocation (1.3.43)
   program (verb, 1.3.60)
   sub-element (2.3.3.1)
ISO/IEC 2382-1
   data
```

ISO/IEC 9506-1

client
download
event (clause 15)
server
uninterruptible variable access (12.1.1.1)
upload
variable

Definitions of this part

3.1

alarm

event which signals a specific condition

3.2

data acquisition

collection of data for the purpose of process monitoring and report generation

3.3

direct operator interface

when the client can communicate to the operator interface via the communication system with no application program interaction (standards.iteh.ai)

3.4

device verification

IEC 61131-5:2000

allows other devices pto/sdetermine afcathe Podsdable at Saperform 4 its 1-intended function in the control system ec35cb6019c5/iec-61131-5-2000

3.5

health

the health of a PC or its subsystems is specified by returning one, and only one, of the three possible values. They are, in order of decreasing health: GOOD, WARNING and BAD

3.6

interlocked control

control through the synchronization of data exchanges between two parties. At various points in time, one party is waiting for the other party to deliver some expected data

3.7

local

internal to the PC; opposite of remote

3.8

parametric control

control by the client writing to control variables residing in the PC

3.9

processing unit

part of the main processing unit. It is the portion of a PC system which is responsible for the storage of the application program and data and the execution of the application program. A PC system has one or more processing units

3.10

program verification

testing of a PC application program to verify that it performs the function(s) it was designed to do in the process environment

3.11

recipe

description of procedures, or data for those procedures, or both, for making a product which uses the process or machinery that the controller is attached to, which is different from a previous product

3.12

remote

external to the PC; opposite of local

3.13

state

the state of the PC system is indicated by a list of attributes, each of which may be TRUE or FALSE. Zero, one, or more of these attributes may be TRUE at the same time

3.14

unsolicited

performed without an explicit request

iTeh STANDARD PREVIEW

4 Symbols and abbreviations (Standards.iteh.ai)

These are some abbreviations frequently used in this part of IEC 61131. These terms are defined or referenced in clause 3 of this part of IEC 61131.

https://standards.iteh.ai/catalog/standards/sist/fa68ac4f-c965-4e2d-b24a-

CFB Communication function blockb6019c5/iec-61131-5-2000

FB Function block

I/O Input and output
IEC International Electrotechnical Commission

ISO International Organization for Standardization

MMS Manufacturing Message Specification, ISO/IEC 9506-1 and ISO/IEC 9506-2

OSI Open Systems Interconnection
PADT Programming and debugging tool

PC Programmable controller

PU Processing unit

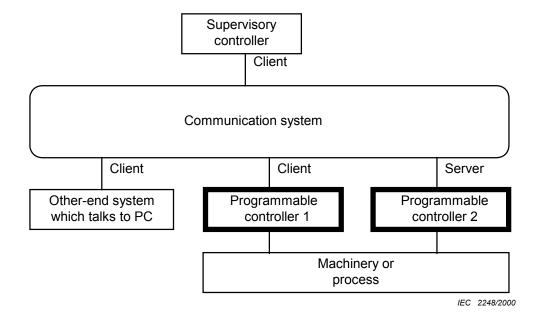
5 Models

This clause specifies the models which are used in the remainder of this part of IEC 61131.

5.1 PC network communication model

A programmable controller supplies some specific application functions to the rest of the control system. It may also request functions from other programmable controllers. The communication functions defined in this part of IEC 61131 are based on a communication subsystem that can report communication errors to the signal processing function of the PC (see 5.2).

The following diagram illustrates the devices in a communication network, showing three possible devices that request PC functions (clients) from PC 2. The two highlighted PCs are in the scope of this part of IEC 61131.



NOTE From the communication viewpoint the 'supervisory controller' and the 'other-end system which talks to PC' mentioned in this figure exhibit the same behavior to a PC communication server, i.e., they submit requests to the PC2.

(standards.iteh.ai)

Figure 2 – PC communication model

IEC 61131-5:2000

A PC may use its client function to communicate with any device if it behaves like a PC. ec35cb6019c5/iec-61131-5-2000

5.2 PC functional model

A PC consists of several functions (see figure 3). For a PC within the scope of this part of IEC 61131, at least one communication function is present.

The following diagram is taken from IEC 61131-1, figure 1. It is designed to illustrate some of the subsystems of a typical PC.

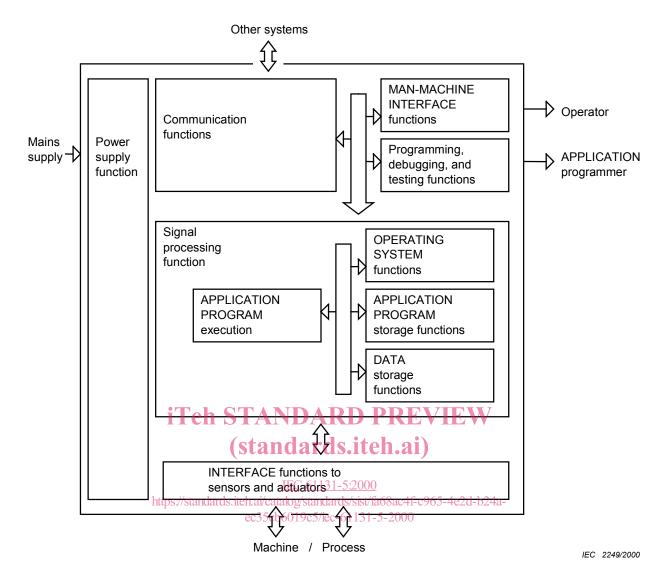


Figure 3 - Programmable controller functional model

There is a function that is part of the PC system, but usually external to the PC itself, known as the programming and debugging tool (PADT). The PADT is modelled as interacting with the PC via the communications function.

The Interface Function to Sensors and Actuators can have I/O which are local or remote to the Main Processing Unit (see 5.3 for the hardware model). The Interface Function to Sensors and Actuators has two attributes for each Application Program which defines how the PC is monitoring and controlling the machine/process. The input attribute has the following states:

- inputs provided to the Application Program are being supplied by the sensors,
- inputs provided to the Application Program are being held in the current state.

The output attribute has the following states:

- the actuators are being controlled by the Application Program,
- the actuators are being held in the current state.